Suppose that 
$$\mathbb{F} = \mathbb{Z}_2$$
 and  $A = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$ .

## Problem.

Find a rational canonical form R of A.

Solution.

First we find a characteristic polynomial of A.

Note that

$$A - tI = \begin{pmatrix} -t & 1 & 0 & 1\\ 1 & -t & 1 & 0\\ 0 & 1 & 1 - t & 1\\ 1 & 0 & 1 & 1 - t \end{pmatrix}.$$

Using the Laplacian expansion along the first column, we see that

$$\det(A - tI) = -t \det\begin{pmatrix} -t & 1 & 0\\ 1 & 1 - t & 1\\ 0 & 1 & 1 - t \end{pmatrix}$$
 (1)

$$-\det\begin{pmatrix} 1 & 0 & 1\\ 1 & 1-t & 1\\ 0 & 1 & 1-t \end{pmatrix} - \det\begin{pmatrix} 1 & 0 & 1\\ -t & 1 & 0\\ 1 & 1-t & 1 \end{pmatrix}$$
 (2)

$$= -t\left(-t[(1-t)^2 - 1] - [1-t-0]\right) \tag{3}$$

$$-\left((1-t)^2 - 1 - 1(0-1)\right) \tag{4}$$

$$-(1+(-t(1-t)-1)) (5)$$

$$= -t(-t(-t)(2-t)+t-1) - ((-t)(2-t)+1) + t-t^2$$
(6)

$$= -t(2t^2 - t^3 + t - 1) - (-2t + t^2 + 1) + t - t^2$$
(7)

$$= t^4 - 2t^3 - t^2 + t + 2t - t^2 - 1 + t - t^2$$
(8)

$$= t^4 - 2t^3 - 3t^2 + 4t - 1 (9)$$

$$= t^4 - 3t^3 + t^2 + t^3 - 4t^2 + 4t - 1 (10)$$

$$= t^{2}(t^{2} - 3t + 1) + t^{3} - 3t^{2} + t - t^{2} + 3t - 1$$
(11)

$$= t^{2}(t^{2} - 3t + 1) + t(t^{2} - 3t + 1) - (t^{2} - 3t + 1)$$
(12)

$$= (t^2 - 3t + 1)(t^2 + t - 1) \tag{13}$$

Since  $\mathbb{F} = \mathbb{Z}_2$ , then  $f(t) = \det(A - tI) = (t^2 + t + 1)^2$ .

Note that

$$A^{2} = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$
(14)

$$= \begin{pmatrix} 1+1 & 0 & 1+1 & 1\\ 0 & 1+1 & 1 & 1+1\\ 1+1 & 1 & 1+1+1 & 1+1\\ 1+1 & 1+1 & 1+1 & 1+1+1 \end{pmatrix}$$
 (15)

$$= \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}, \tag{16}$$

and thus

$$A^{2} + A + I = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix} + \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(17)

$$= \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}. \tag{18}$$

Since  $A^2 + A + I \neq 0$ , while the only divisor of the minimal polynomial p(t) is  $t^2 + t + 1$ , we deduce that  $p(t) = f(t) = (t^2 + t + 1)^2 = t^4 + t^2 + 1$ .

Therefore, there exists a canonical basis  $\beta$  such that

$$[A]_{\beta} = R = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix},$$

where the signs were omitted since -1 = 1.

## Problem.

Find an invertible matrix Q such that  $R = Q^{-1}AQ$ .

Solution.

First we find the basis of  $K_{\phi}$ , where  $\phi = t^2 + t + 1$ .

Note that, by Theorem 7.18, since  $p(t) = (t^2 + t + 1)^2$  and  $t^2 + t + 1$  is irreducible,

then 
$$K_{\phi} = \ker \phi(A)^2$$
. Since  $\phi A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$ , we know that  $phi(A)^2 = 0$  and thus

 $\ker \phi(A)^2 = V = K_{\phi}.$ 

We now look for the cycle basis of  $K_{\phi} = V$ , which has a length of dim V = 4.

Take 
$$v = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$
.

Therefore, 
$$Av = \begin{pmatrix} 0\\1\\0\\1 \end{pmatrix}$$
,  $A(Av) = A^2v = \begin{pmatrix} 0\\0\\0\\1 \end{pmatrix}$  and  $A^3v = \begin{pmatrix} 1\\0\\1\\1 \end{pmatrix}$ .

Let 
$$\beta = \left\{ \begin{pmatrix} 1\\0\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0\\1 \end{pmatrix}, \begin{pmatrix} 0\\0\\0\\1 \end{pmatrix}, \begin{pmatrix} 1\\0\\1\\1 \end{pmatrix} \right\}.$$

Note that, since  $\phi(A)^2x = 0$  for any  $x \in \beta$ , then span  $\beta \subseteq K_{\phi}$ .

We now prove that  $\beta$  is linearly independent:

$$\begin{bmatrix}
1 & 0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 \\
0 & 1 & 1 & 1 & 0
\end{bmatrix}$$
 $\rightsquigarrow$ 
(19)

$$R_1 \to R_1 - R_3, R_4 \to R_4 - R_2 - R_3 \iff \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}.$$
 (20)

Therefore,  $\beta$  is linearly independent.

Since  $|\beta| = 4$  and span  $\beta \subseteq K_{\phi}$ , then  $\beta$  is a cyclic basis of  $K_{\phi} = V$ .

$$\text{Let } Q = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix}.$$

We invert Q:

$$\begin{bmatrix}
1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\
0 & 1 & 1 & 1 & 0 & 0 & 0 & 1
\end{bmatrix}$$
 $\rightsquigarrow$ 
(21)

$$R_{1} \to R_{1} - R_{3}, R_{4} \to R_{4} - R_{2} - R_{3} \leadsto \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$

$$R_{3} \Leftrightarrow R_{4} \leadsto \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$(22)$$

$$R_3 \Leftrightarrow R_4 \sim \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$
 (23)

Thus, 
$$Q^{-1} = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$
.

By the change-of-matrix formula, we know that  $R = Q^{-1}AQ$ , since  $\beta$  is a cycle basis of  $K_{\phi}$  and thus a rational canonical basis.

## Problem.

Find an  $L_A$ -invariant subspace  $W \subseteq \mathbb{F}^4$  of dimension 2.

Solution.

Let 
$$\gamma = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\} \subseteq \beta$$
, and let  $T = L_A$ .

Note that  $\gamma$  is linearly independent, since  $\beta$  is linearly independent.

Let  $W = \operatorname{span} \gamma$ .

Since 
$$T \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} \in W$$
 and  $T \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \in W$ , then  $W$  is  $T$ -invariant ( $T$  is defined by its action on a basis).