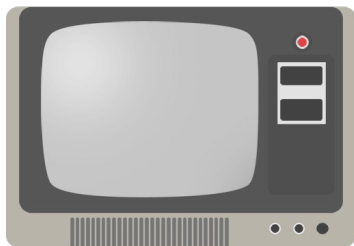


# Tinkering with the TRS80's I/O Bus

Arno Puder



## Outline:

1. My Story
2. TRS80 I/O Bus
3. Boolean Logic
4. Connecting Arduino with the I/O Bus

**\*\* OBSTACLE RUN \*\***

Mission: Top Secret !

Use arrow keys to move in all directions  
Press "SPACEBAR" to fire missiles forward  
and left & right arrow keys together  
to shoot to the sides  
Play until all ships are exhausted  
Depress "BREAK" & "CLEAR" to abort game

**High Scores**

Arno	180,020
ALL	91,760
A&C	75,770
A2	73,640
A&P!	64,220
Arno	49,990
A.P.	23,500
A1	9,920
UWE2	7,750
UWE2	6,900

Program written by Arno Puder    Hohner Str.16    5206 Neunkirchen-S

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Program written by Arno Puder Hohner Str.1 5206 Neunkirchen-S

# Good Old Days



- TRS-80 Model III
- Manufactured by Radio Shack Corporation
- Released in 1980
- 8-bit Z80 CPU @ 1.7 MHz, 48kB RAM
- Great for tinkering!

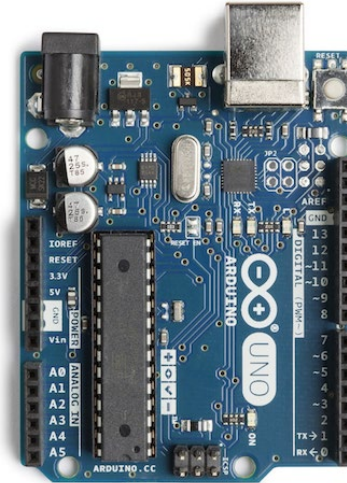
# Modern Devices are Tinker Resistant!



# Arduino



- Open source specification for a programmable microcontroller.
- Started in 2003 in Italy.
- Main purpose is to interface with sensors and actuators via GPIO/I2C and SPI.
- CPUs: Atmel AVR, ARM Cortex, Intel Quark (x86)
- Does not run an operating system!
- Arduino Uno R3:
  - CPU: ATmega328P @ 16 MHz
  - Flash memory: 32 kB
  - SRAM: 2 kB
  - Interface: GPIO, UART, SPI, I2C.
  - Size: 68 x 53 mm
  - Power consumption: 225 mW
  - Arduino Pro Mini: 15  $\mu$ W - 12 mW  
(4 years on a 9V battery)
- Homepage: <https://www.arduino.cc/>



# TRS-80 I/O Bus

- 50 pin connector; 25 pins are ground.
- Uses TTL (Transistor-Transistor Logic). High = 5V
- 8 bits data bus D0-D7.
- 8 bits for address lines A0-A7.
- Control lines for read, write, wait, interrupts
- BASIC:
  - Input: **INP (p)**
  - Output: **OUT p, n**
- Z80:
  - **out (p) , n**
  - **in r, (p)**
- I/O bus needs to be enabled first via OUT 236,16

**Radio Shack**


# **Service Manual**

26-1061/1062/1063

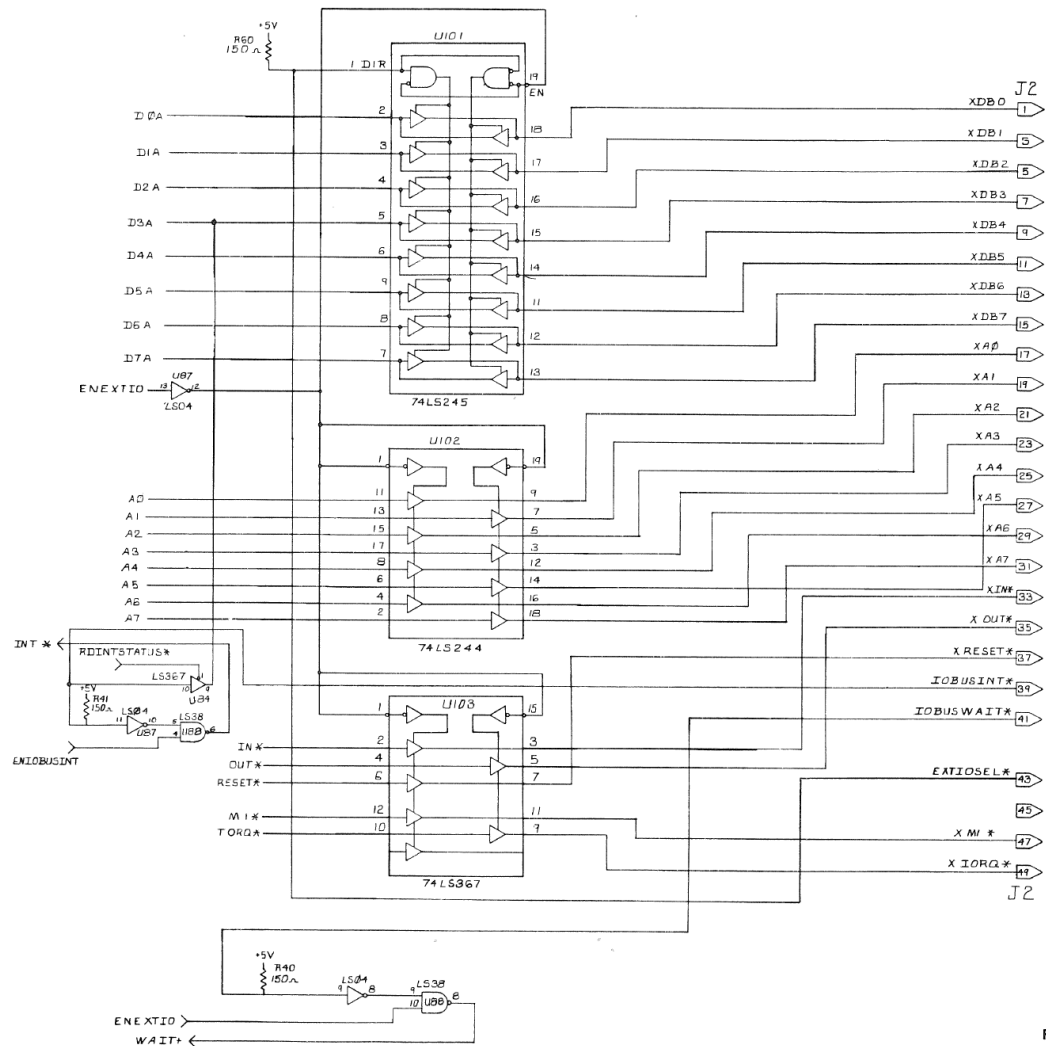
## **TRS-80<sup>®</sup> MODEL III MICROCOMPUTER**

Catalog Numbers 26-1061/1062/1063

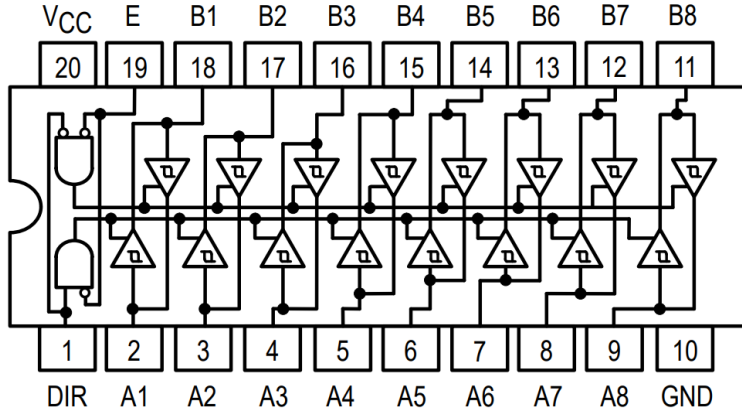


CUSTOM MANUFACTURED IN U.S.A. BY RADIO SHACK  A DIVISION OF TANDY CORPORATION

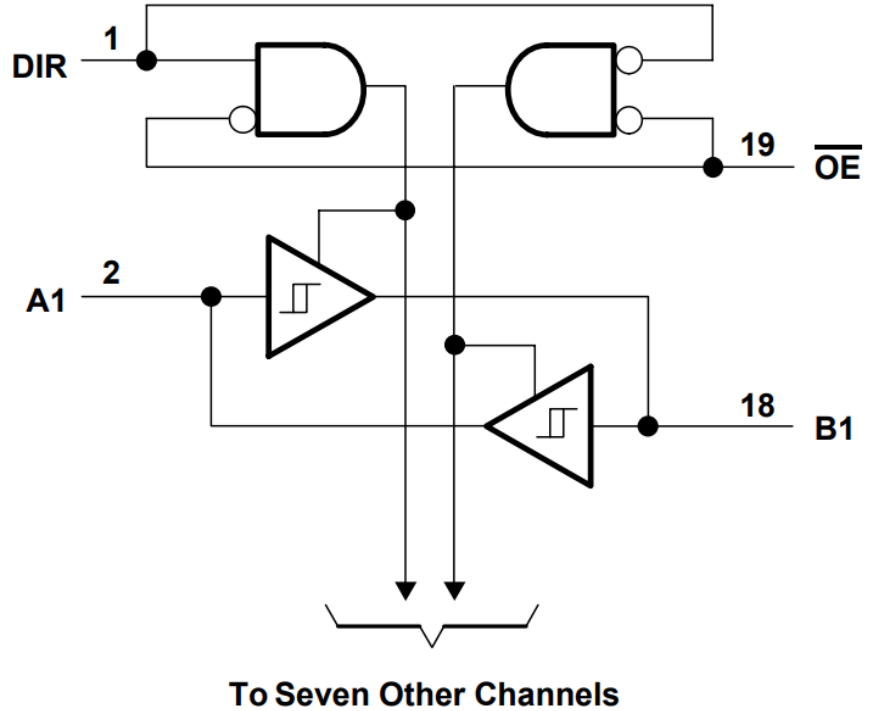




- Octal bus tri-state buffers
- 3-state output



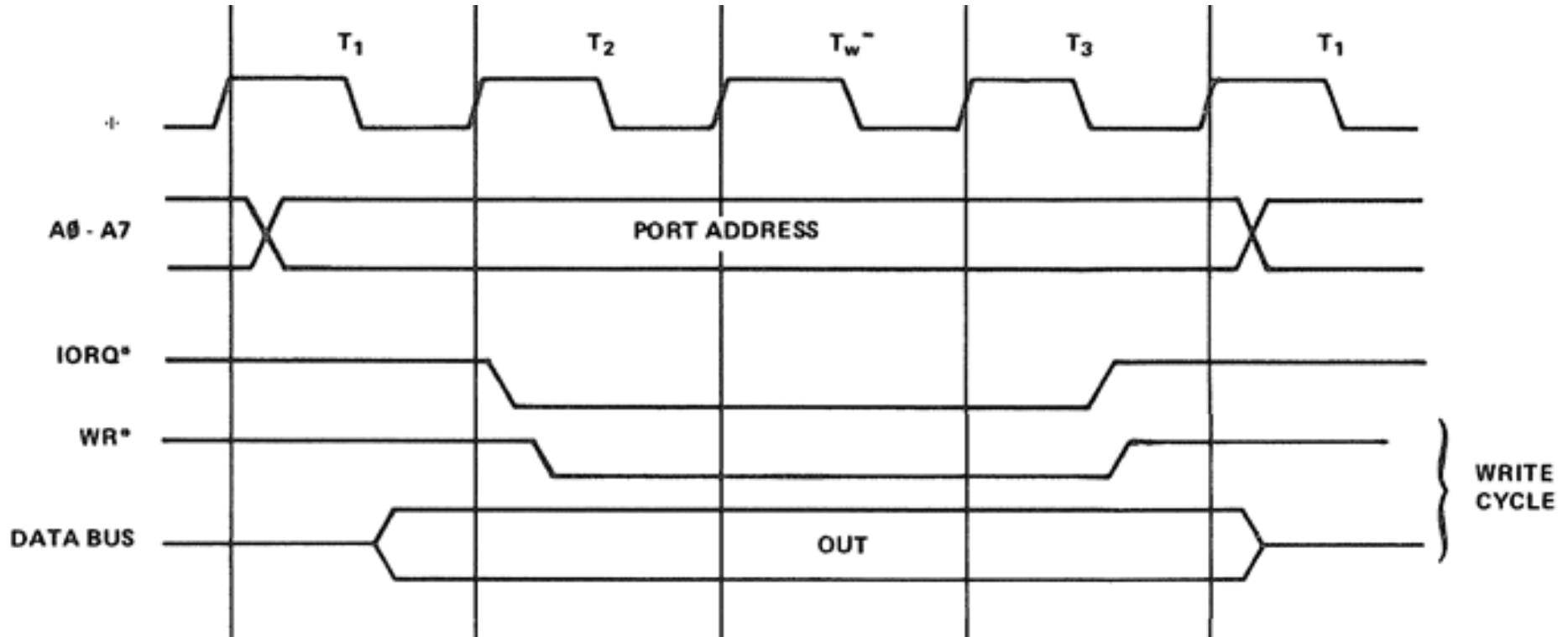
- Octal bus transceiver
- 3-state outputs



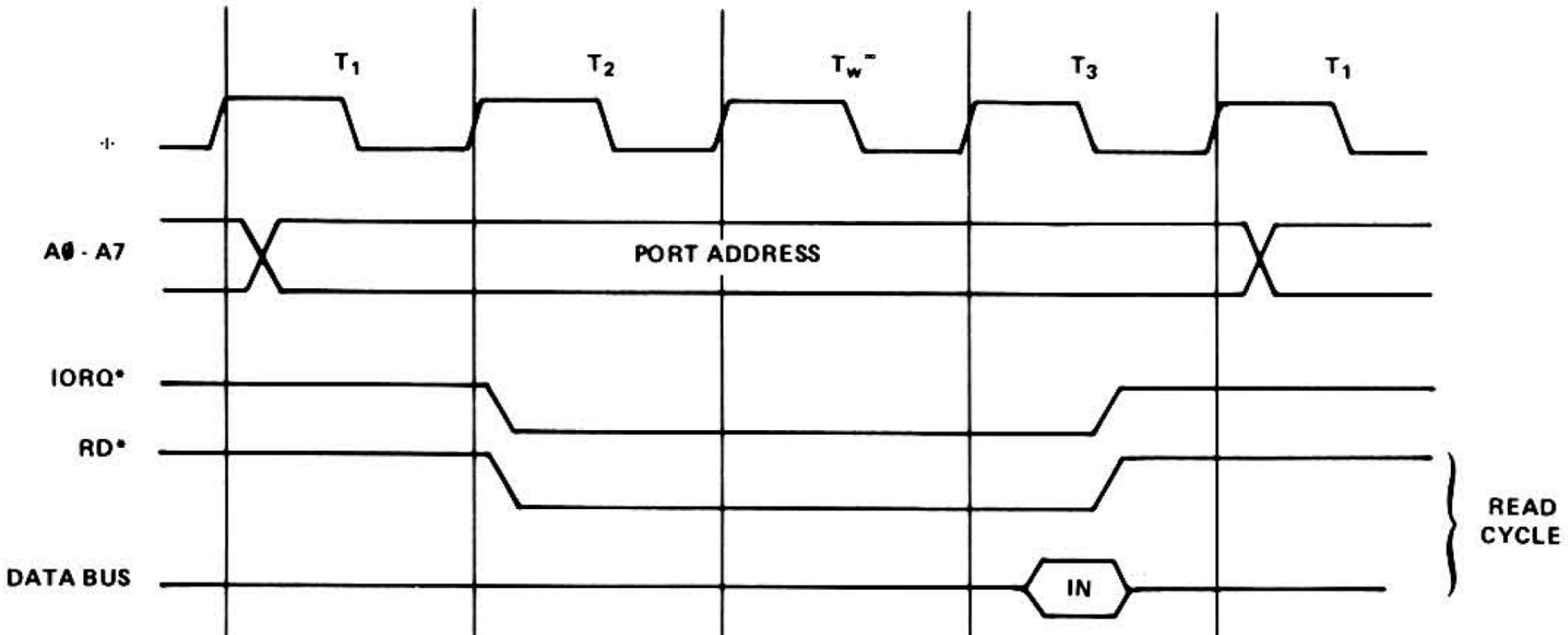
# I/O Bus Pins

Name	Description	Pins
D[0-7]	Data lines	1,3,...,15
A[0-7]	Address lines	17,19,...,31
RD*	Read in progress	33
WR*	Write in progress	35
IORQ*	I/O request	49
EXTIOSEL*	Assert for read operation	43
IOBUS_WAIT*	Force wait-states on Z80	41
IOBUS_INT*	Signal interrupt to Z80	39

# I/O Bus Write Cycle

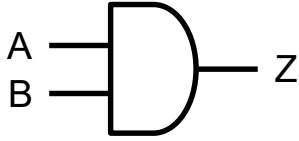


# I/O Bus Read Cycle



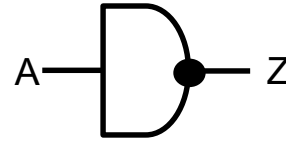
# Boolean Logic

## ***AND***



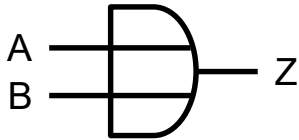
A	B	Z
0	0	0
0	1	0
1	0	0
1	1	1

## ***NOT***

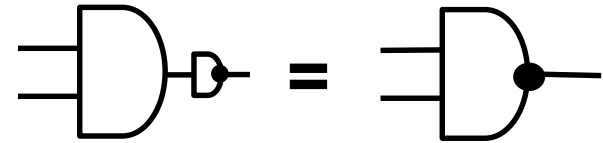


A	Z
0	1
1	0

## ***OR***

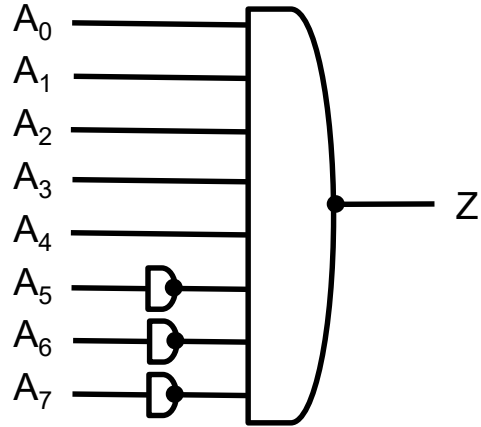


A	B	Z
0	0	0
0	1	1
1	0	1
1	1	1



## ***NAND***

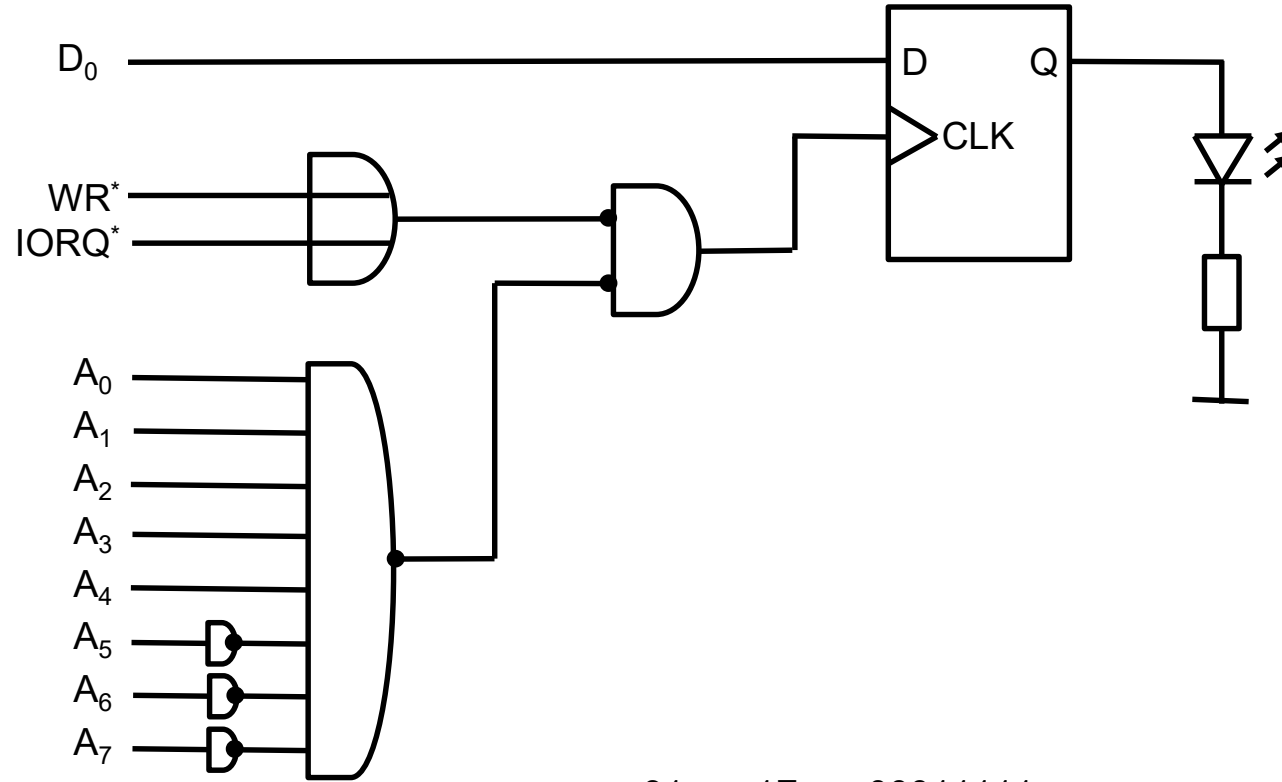
# Boolean Logic Example



**$Z = 0$  if and only if  $A_0 \dots A_4 = 1$  and  $A_5 \dots A_7 = 0$**

$$31_{10} = 1F_{16} = 00011111_2$$

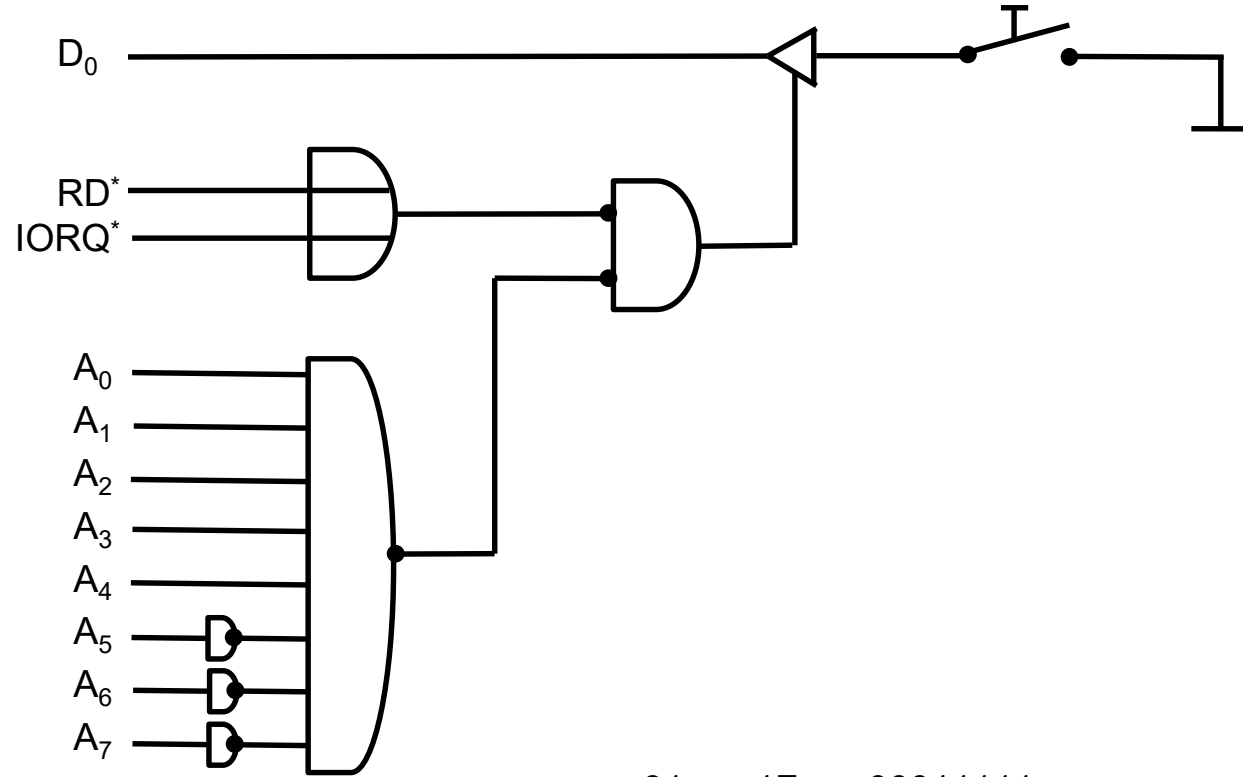
# 1 Bit Output



$$31_{10} = 1F_{16} = 00011111_2$$



# 1 BitInput



$$31_{10} = 1F_{16} = 00011111_2$$

# ATF16V8B

- Generic Array Logic (GAL)
- Ideal for prototyping and minimizing simple Boolean equations.
- Precursor of FPGAs.
- Can be erased and reprogrammed.
- Up to 16 Inputs.
- 8 I/O.
- Requires a programmer (e.g., TL866II)



**TL866II Plus**



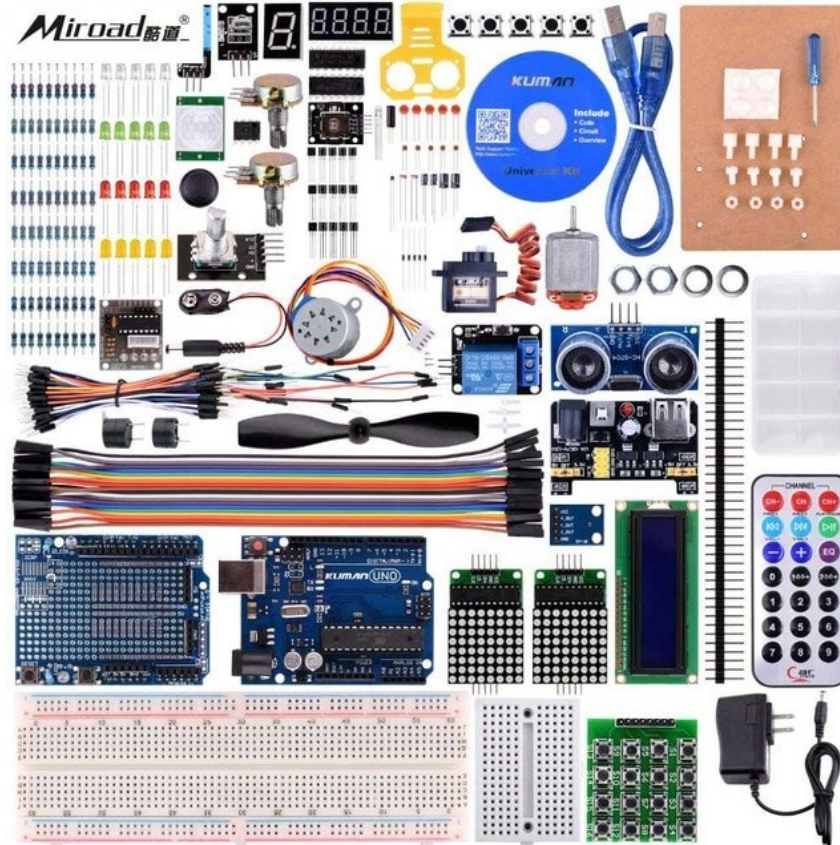
# GAL Pin Assignments

```
/* Inputs */  
Pin [2..9] = [A7..0];  
Pin 17 = !RD_N;  
Pin 18 = !WR_N;  
Pin 19 = !IORQ_N;  
  
/* Outputs */  
Pin 14 = EXTIO_SEL;  
Pin 13 = !ARDUINO_SEL_N;
```

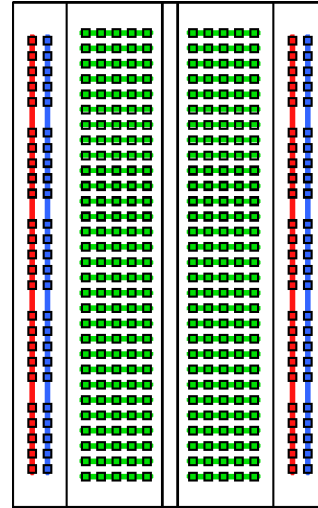
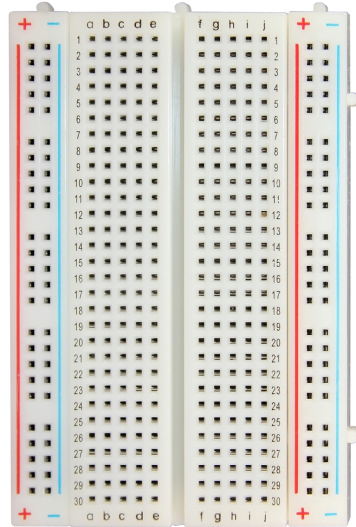
# GAL Boolean Equations

```
/* Equations */  
io_bus_sel = IORQ_N & (RD_N # WR_N);  
  
/* Arduino is selected at port 31 */  
arduino_sel = !A7 & !A6 & !A5 & A4 &  
              A3 & A2 & A1 & A0 & io_bus_sel;  
ARDUINO_SEL_N = arduino_sel;  
  
/* EXTIO_SEL_N allows the TRS-80 to read */  
EXTIO_SEL = arduino_sel & RD_N;
```

# Arduino Starter Kit



# Breadboards



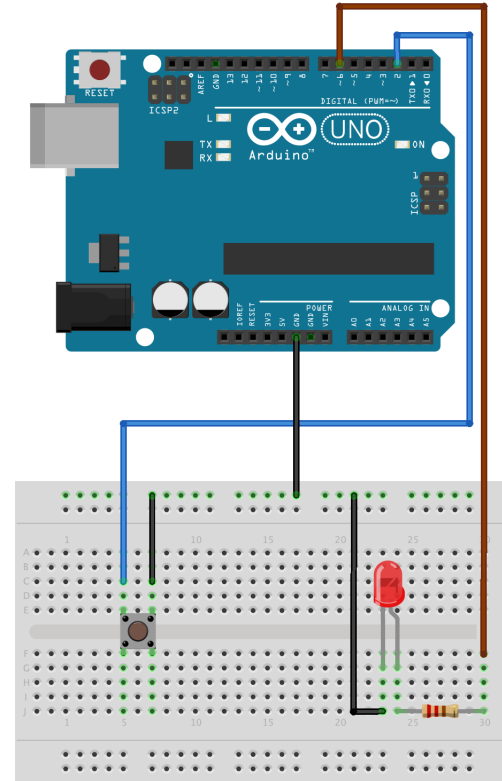
- Breadboards are used for fast prototyping.
- Allows to build an electronic circuit without soldering.
- Pins are connected as shown in the schematic on the right.

# General Purpose Input/Output (GPIO)

- Generic pin with no pre-defined purpose.
- Can be configured either as input or output.
- Programmable interface:
  - Read state of a binary device (e.g., push button).
  - Control on/off state of a binary output device (e.g., LED)
- Arduino Uno:
  - 14 digital GPIO pins.

# “Hello World” Arduino

- First circuit that makes use of the Arduino.
- Push button is connected to GPIO pin 2.
- LED is connected to GPIO pin 6.
- Both LED and the push button are also connected to ground to form a complete circuit with their respective GPIO pins.
- Pushing the button will not turn on the LED.
- Arduino needs to be programmed to implement desired behavior.

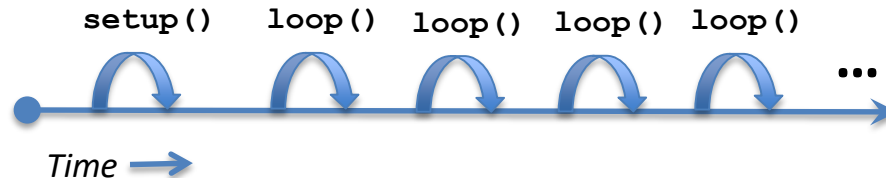




# Arduino Sketches

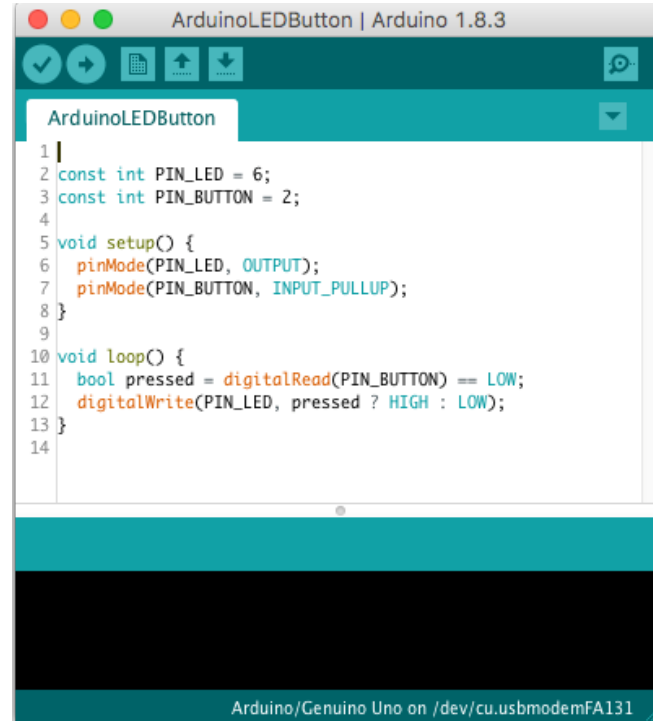
- Programs for the Arduino are called **Sketches**.
- Sketches can be written in C/C++.
- No operating system!
- Only one thread of execution.
- Support for common POSIX functions (e.g., `malloc()`, `strlen()`, etc)
- IDE automatically includes common header files.
- Popular IDEs:
  - Arduino IDE.
  - Atom with PlatformIO.

```
// Basic template for  
// a sketch  
  
void setup() {  
    // ...  
}  
  
void loop() {  
    // ...  
}
```



# Arduino IDE

- Download free Arduino IDE:  
<https://www.arduino.cc/en/Main/Software>
- Configuration:
  - *Tools > Board > Arduino/Genuino Uno*
  - *Tools > Programmer > AVR ISP*
  - *Tools > Port > /dev/XXX*
- Note: the Arduino needs to be connected to the laptop in order for it to show up under *Tools > Port*.



# Sketch for Button/LED Circuit

```
const int LED_PIN = 6;
const int BUTTON_PIN = 2;

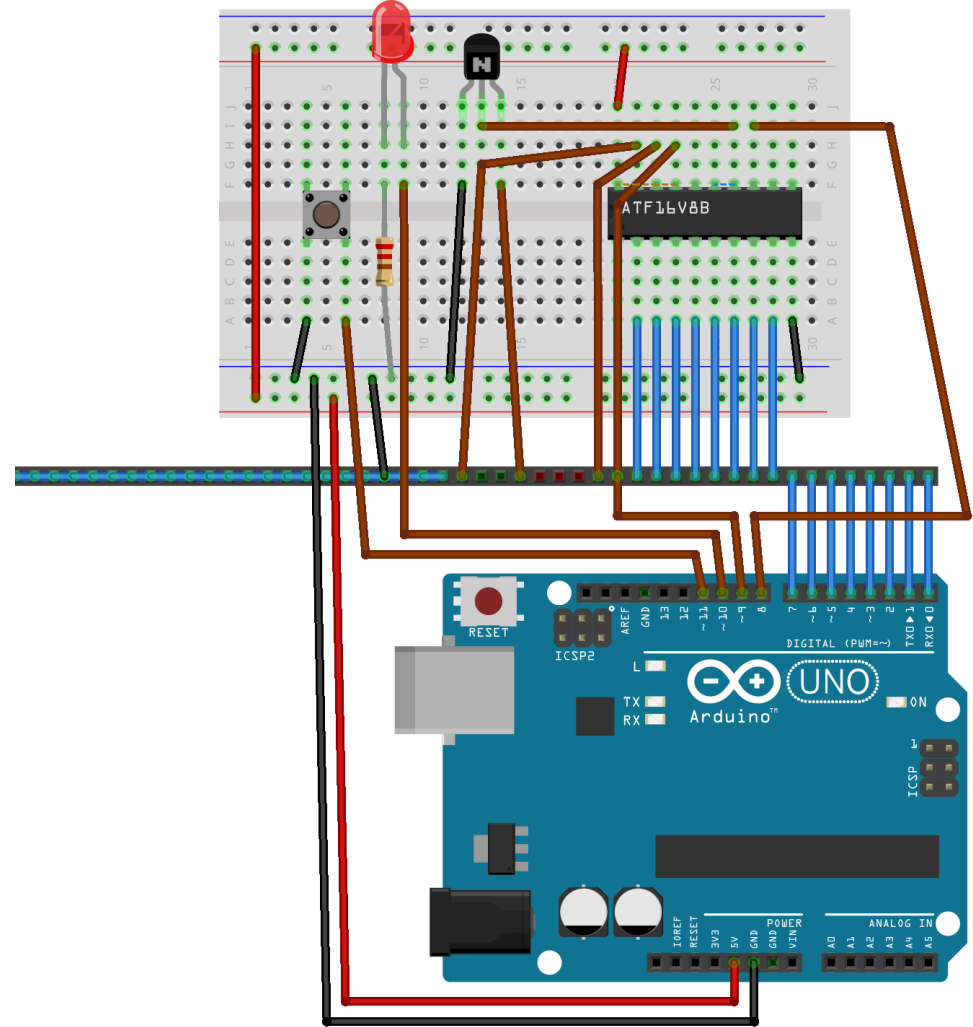
void setup() {
  pinMode(LED_PIN, OUTPUT);
  pinMode(BUTTON_PIN, INPUT_PULLUP);
}

void loop() {
  bool pressed = digitalRead(BUTTON_PIN) == LOW;
  digitalWrite(LED_PIN, pressed ? HIGH : LOW);
}
```

- This sketch assumes the wiring as shown on the “Hello World” for Arduino slide.
- GPIO pins can be configured either as input (**INPUT\_PULLUP**) or output (**OUTPUT**) via **pinMode()**
- **digitalRead()** can return either **HIGH** or **LOW**. For a pin configured as **INPUT\_PULLUP** it will return **LOW** when the button is pressed. It will also activate an internal pull-up resistor on that pin.
- The value of **HIGH** or **LOW** can be set for an output pin via **digitalWrite()**
- This sketch will constantly update the LED with each call to **loop()**

# Fritzing

- Design tool fritzing.org allows simple schematics.
- Uses ATF16V8B, transistor, LED, resistor, button.
- Button: pseudo input.
- LED: pseudo output.



# Main Polling Loop

```
#define PIN8 (1 << 0)
#define PIN9 (1 << 1)

void setup() {
    setup_app();
    pinMode(8, INPUT);
    pinMode(9, INPUT);
    // Configure pins
    // 0-7 as input
    DDRD = 0;
    noInterrupts();
}
```

```
void loop() {
    // Wait for ARDUINO_SEL_N to go low
    while (PINB & PIN8) ;
    if (PINB & PIN9) {
        // Read from I/O bus
        z80_out(PIND);
    } else {
        // Write to I/O bus
        DDRD = 0xff;
        PORTD = z80_in();
    }
    // Wait for ARDUINO_SEL_N to go high
    while (!(PINB & PIN8)) ;
    DDRD = 0;
}
```

# Examples

## ***Blinking LED***

```
10 OUT 236,16
20 OUT 31,0
30 FOR X=1TO1000:NEXT
40 OUT 31,1
50 FOR X=1TO1000:NEXT
60 GOTO 20
```

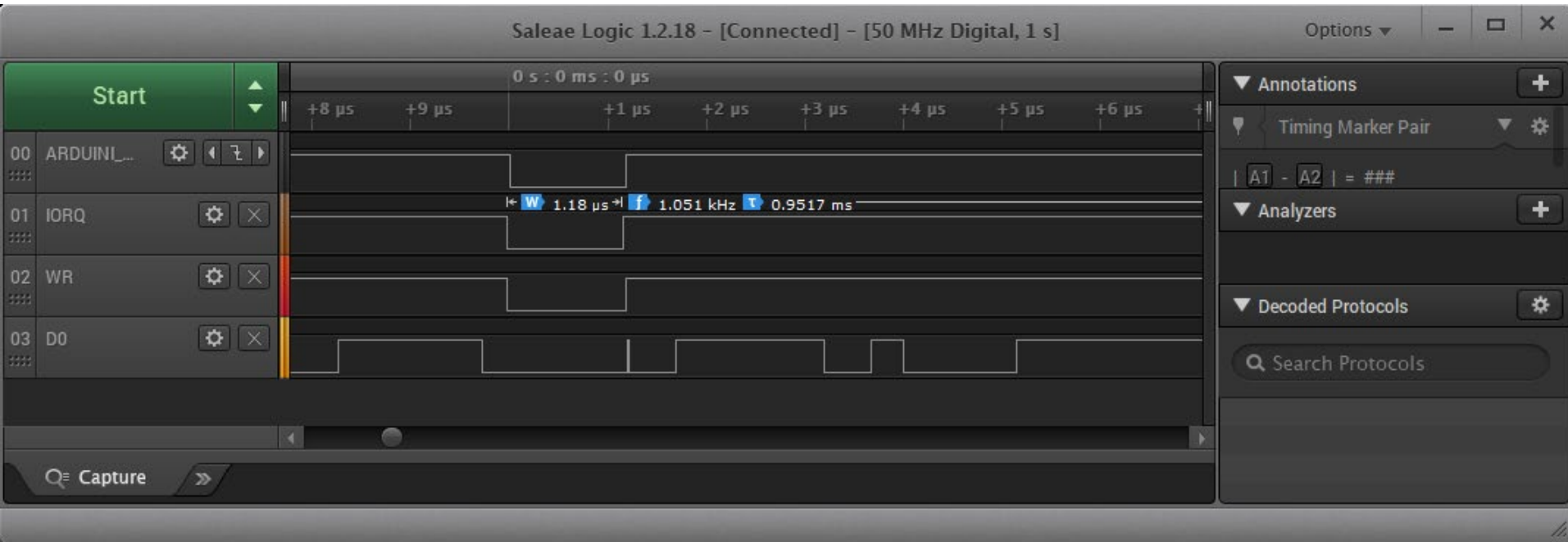
## ***Pushing Button turns off LED***

```
10 OUT 236,16
20 OUT 31,ABS(INP(31)-1)
30 GOTO 20
```

## ***Read Button State***

```
10 OUT 236,16
20 IF INP(31) = 1 THEN PRINT "BUTTON PRESSED"
30 GOTO 20
```

# Logic Analyzer



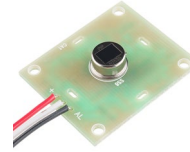
# Sensors



Humidity Sensor  
HIH-4030



Atmospheric Sensor  
BME280



Passive Infrared  
Motion Sensor



Ultrasonic Sensor  
HC-SR04



Soil Moisture



Sound Detector



Accelerometer, Gyroscope  
Temperature – MPU6050



Photocell



Reed Switch  
TMP36



# Actuators/Displays



Gear motor  
with Wheel Set



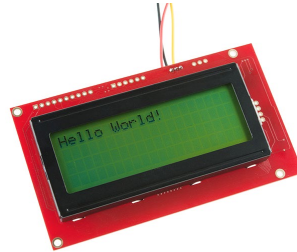
Solenoid



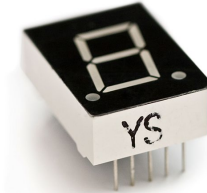
Water Valve



Relay



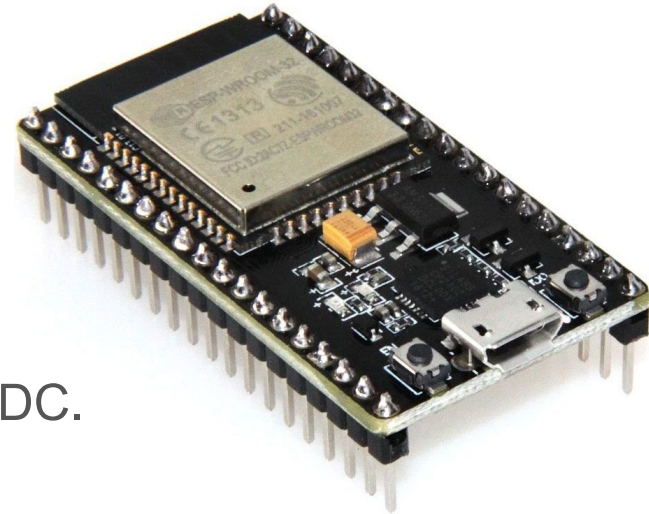
Liquid Crystal Display (LCD)



7 Segment Display

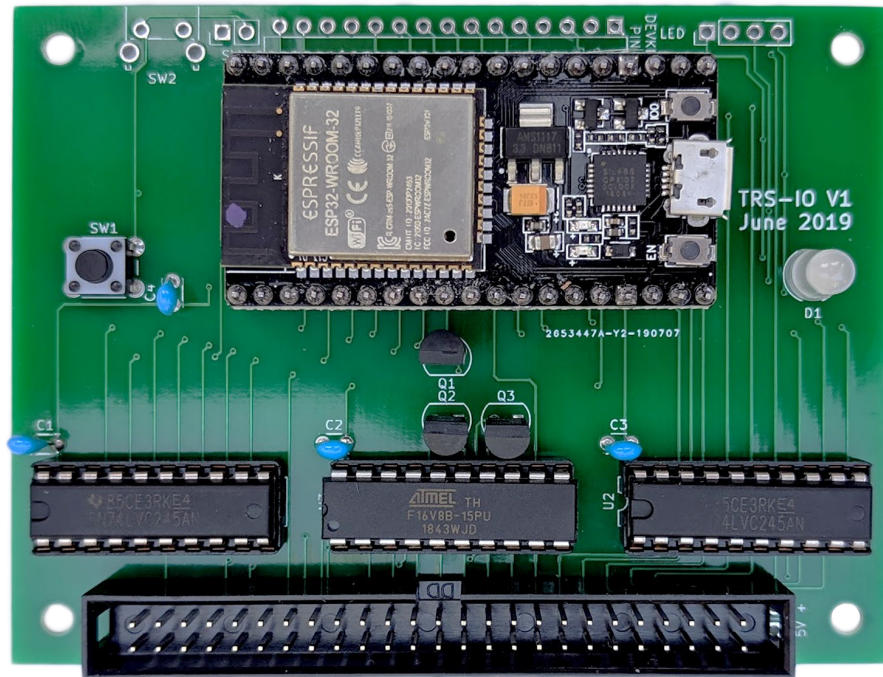
# ESP8266-32

- Low-cost microcontroller including WiFi and Bluetooth.
- Produced by Shanghai-based Chinese manufacturer, Espressif Systems.
- CPU: dual core 32bit RISC Tensilica Xtensa LX6 @ 240 MHz.
- FreeRTOS
- Flash memory: 4MB
- SRAM: 520 kB
- WiFi:
  - IEEE 802.11 b/g/n
  - WEP or WPA/WPA2 authentication, or open networks.
- Interface: 16 GPIO pins, SPI, I2C, UART, 10bit ADC.
- Price point: \$11

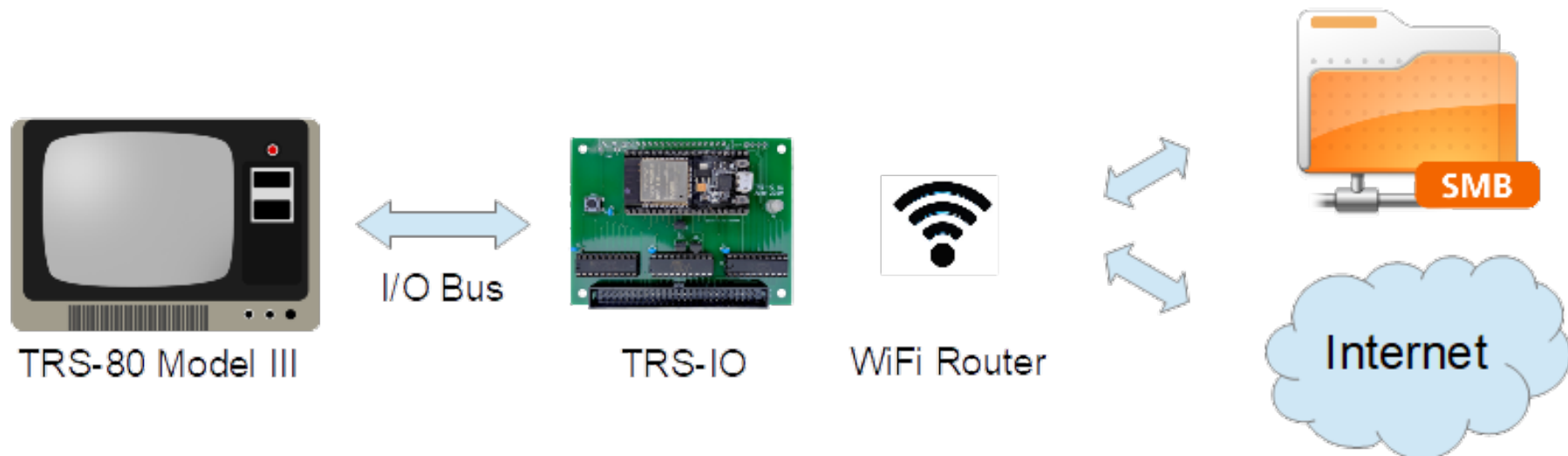


# Introducing TRS-IO

- Same components as the RetroStoreCard (backward compatible).
- Only differences :
  - A0-A3 are routed to the ESP
  - GAL scans for port 31 and ports 0xC0-0xCF
- Features:
  - RetroStore access
  - trs-nic (Berkeley Socket API)
  - trs-fs (POSIX file access API)
  - FreHD
  - OTA



# TRSIO



# All Good Things...

- Summary:
  - Old computers were great for learning.
  - Today's devices are tinker resistant.
  - Arduino to the rescue!
  - Connect an Arduino to the TRS-80's I/O Bus.
- Outlook:
  - TRSIO: Connecting the TRS-80 to the World!
  - Display at Tandy Assembly's Exhibition.
- Complete source and slides freely available at:  
<https://github.com/apuder /TRS-80-Arduino>

Contact: [arno@retrostore.org](mailto:arno@retrostore.org)