CS738: Advanced Compiler Optimizations

Interprocedural Data Flow Analysis
Functional Approach

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Interprocedurally Valid Paths

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- Path $q \in \mathrm{path}_{G^*}(r_1, n)$ is in $\mathrm{IVP}(r_1, n)$

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- Not all paths in G^* are feasible
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- IVP(r_1, n): set of all interprocedurally valid paths from r_1 to n
- Path $q \in \text{path}_{G^*}(r_1, n)$ is in IVP(r_1, n)
  - iff sequence of all E^1 edges in q (denoted q_1)is *proper*

Proper sequence

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Proper sequence

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- let $q_1[i]$ be the first return edge in q_1. q_1 is proper if
  - $i > 1$; and
  - $q_1[i-1]$ is call edge corresponding to $q_1[i]$; and
  - q_1' obtained from deleting $q_1[i-1]$ and $q_1[i]$ from q_1 is proper

Interprocedurally Valid Complete Paths

- $\mathrm{IVP}_0(r_p, n)$ for procedure p and node $n \in N_p$

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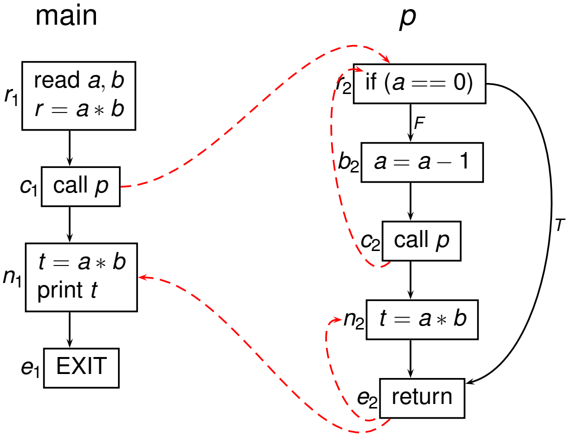
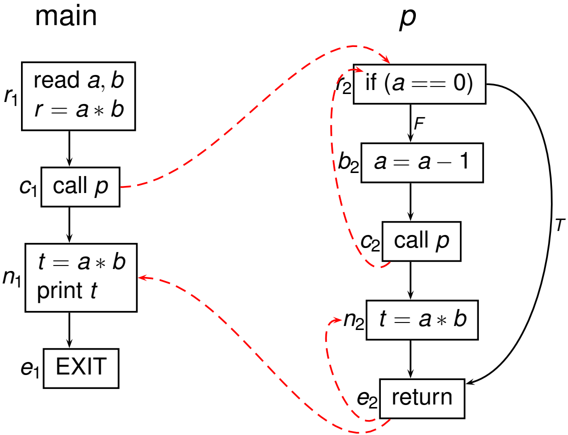
Interprocedurally Valid Complete Paths

- $\mathrm{IVP}_0(r_p, n)$ for procedure p and node $n \in N_p$
- set of all interprocedurally valid paths q in G^* from r_p to n s.t.
  - Each call edge has corresponding return edge in q restricted to E^1

IVPs

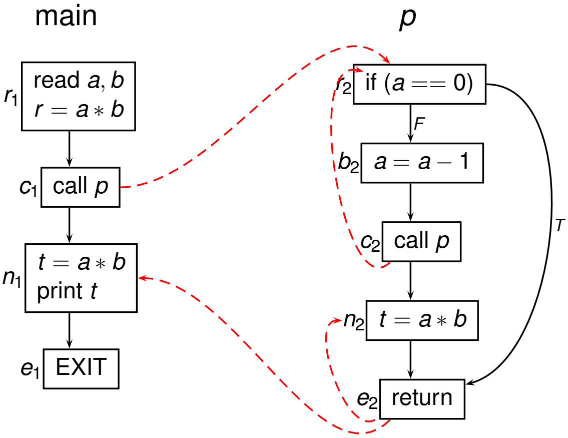

main
p
r_1
read a, b
$r = a * b$
c_1
call p
n_1
$t = a * b$
print t
e_1
EXIT
r_2
if $(a == 0)$
F
b_2
$a = a - 1$
c_2
call p
T
n_2
$t = a * b$
e_2
return

IVPs



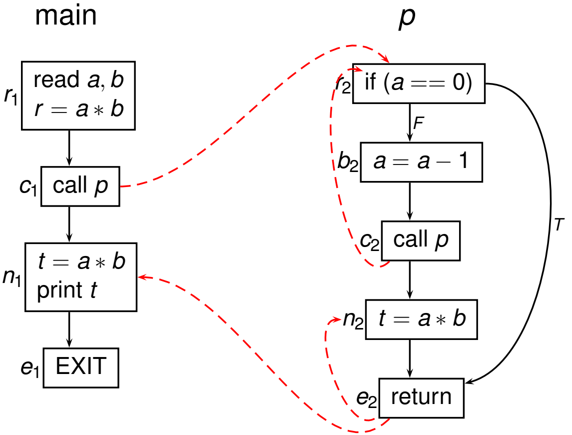
$$r_1 \to c_1 \to r_2 \to c_2 \to r_2 \to e_2 \to n_2 \to e_2 \to n_1 \to e_1$$

IVPs



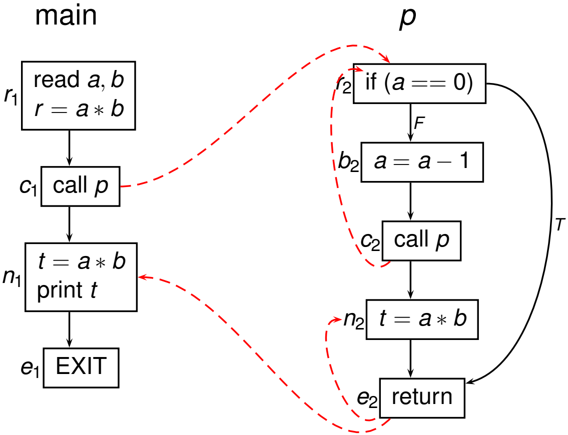
$$r_1 \to c_1 \to r_2 \to c_2 \to r_2 \to e_2 \to n_2 \to e_2 \to n_1 \to e_1$$
$$\in \mathrm{IVP}(r_1, e_1)$$

IVPs



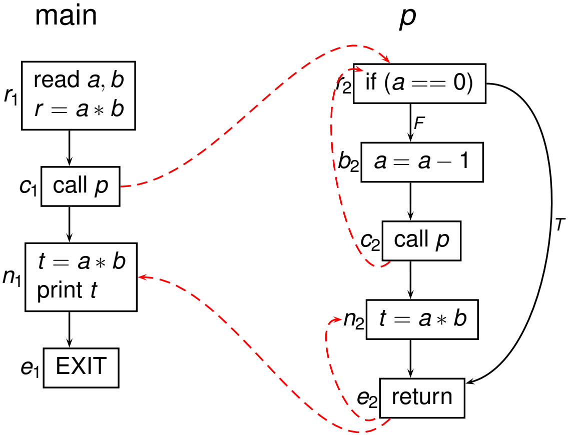
$$r_1 \rightarrow c_1 \rightarrow r_2 \rightarrow c_2 \rightarrow r_2 \rightarrow e_2 \rightarrow n_1 \rightarrow e_1$$

IVPs



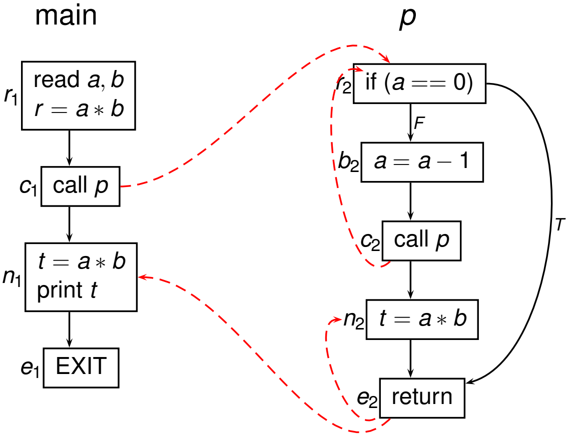
$$r_1 \to c_1 \to r_2 \to c_2 \to r_2 \to e_2 \to n_1 \to e_1 \notin \mathrm{IVP}(r_1, e_1)$$

IVPs



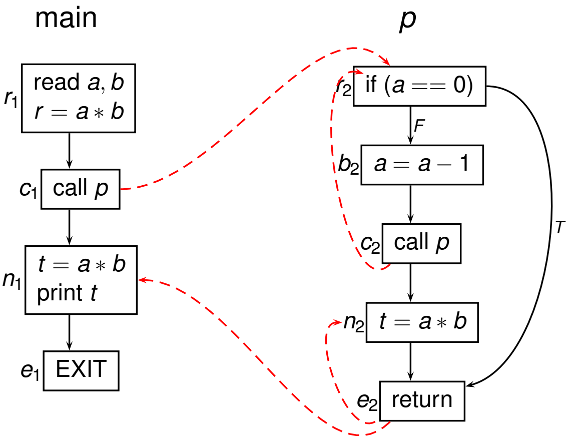
$$r_2 \rightarrow c_2 \rightarrow r_2 \rightarrow e_2 \rightarrow n_2$$

IVPs



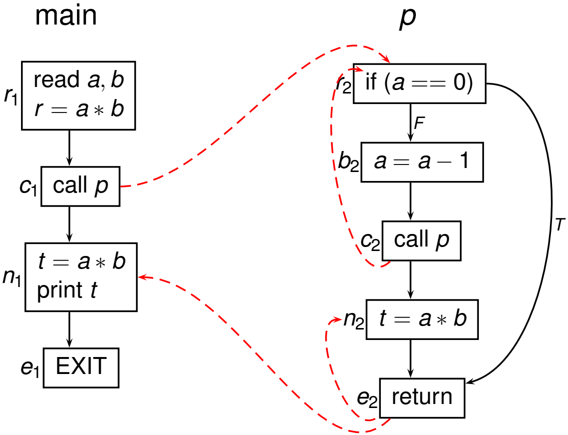
$$r_2 \rightarrow c_2 \rightarrow r_2 \rightarrow e_2 \rightarrow n_2 \in \mathrm{IVP}_0(r_2, n_2)$$

IVPs



$$r_2 \rightarrow c_2 \rightarrow r_2 \rightarrow c_2 \rightarrow e_2 \rightarrow n_2$$

IVPs



$$r_2 \to c_2 \to r_2 \to c_2 \to e_2 \to n_2 \notin \mathrm{IVP}_0(r_2, n_2)$$

Path Decomposition

$$
\begin{array}{rcl}
q & \in & \mathrm{IVP}(r_{\mathrm{main}}, n) \\
& \Leftrightarrow & \\
q & = & q_1 \parallel (c_1, r_{p_2}) \parallel q_2 \parallel \cdots \parallel (c_{j-1}, r_{p_j}) \parallel q_j \\
& & \text{where for each } i < j, q_i \in \mathrm{IVP}_0(r_{p_i}, c_i) and q_j \in \mathrm{IVP}_0(r_{p_j}, n)
\end{array}
$$

Functional Approach

- (L, F): a *distributive* data flow framework

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Functional Approach

- (L, F): a *distributive* data flow framework
- Procedure p, node $n \in N_p$
- $\phi_{(r_p,n)} \in F$ describes flow of data flow information from start of r_p to start of n
  - along paths in $\mathrm{IVP}_0(r_p, n)$

Functional Approach Constraints

$$
\begin{aligned}
\phi_{(r_p,r_p)} &\leq id_L \\
\phi_{(r_p,n)} &= \bigwedge_{(m,n)\in E_p} (h_{(m,n)} \circ \phi_{(r_p,m)}) \qquad \text{for } n \in N_p
\end{aligned}
$$

where

$$
h_{(m,n)} = \begin{cases} f_{(m,n)} & \text{if } (m,n) \in E_p^0, \\ & \quad f_{(m,n)} \in F \text{ associated flow function} \\ \phi_{(r_q,e_q)} & \text{if } (m,n) \in E_p^1 \text{ and } m \text{ calls procedure } q \end{cases}
$$

Information x at r_p translated to information $\phi_{(r_p,n)}(x)$ at n

Solving ϕ Constraints

- Round-robin iterative approximations to initial values

$$
\begin{array}{rcll}
\phi^0_{(r_p,r_p)} & \leq & id_L & \\
\phi^0_{(r_p,n)} & \leq & f_\Omega & \quad n \in N_p - \{r_p\}
\end{array}
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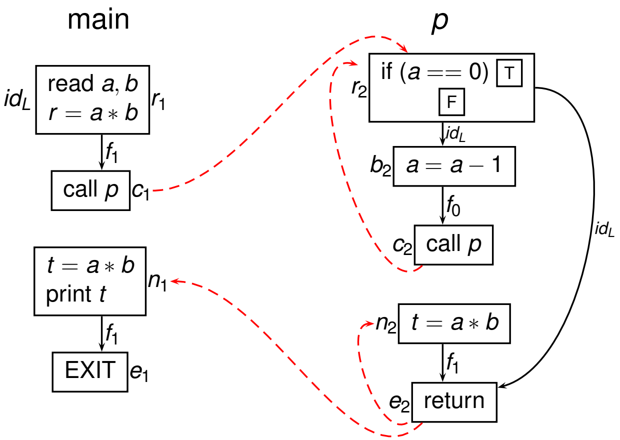
Solving ϕ Constraints

- Round-robin iterative approximations to initial values

$$\begin{array}{rcll} \phi^0_{(r_p, r_p)} & \leq & id_L & \\ \phi^0_{(r_p, n)} & \leq & f_\Omega & \quad n \in N_p - \{r_p\} \end{array}$$

- Reach maximal fixed point

Example



main
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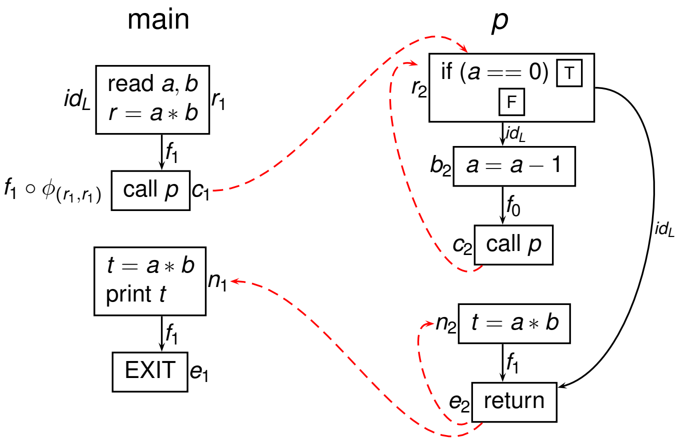
id_L
read a, b
$r = a * b$
r_1
f_1
call p
c_1
$t = a * b$
print t
n_1
f_1
EXIT
e_1
r_2
if $(a == 0)$
T
F
id_L
b_2
$a = a - 1$
f_0
c_2
call p
id_L
n_2
$t = a * b$
f_1
e_2
return

Example



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$r = a * b$
r_1
f_1
$f_1 \circ \phi_{(r_1,r_1)}$
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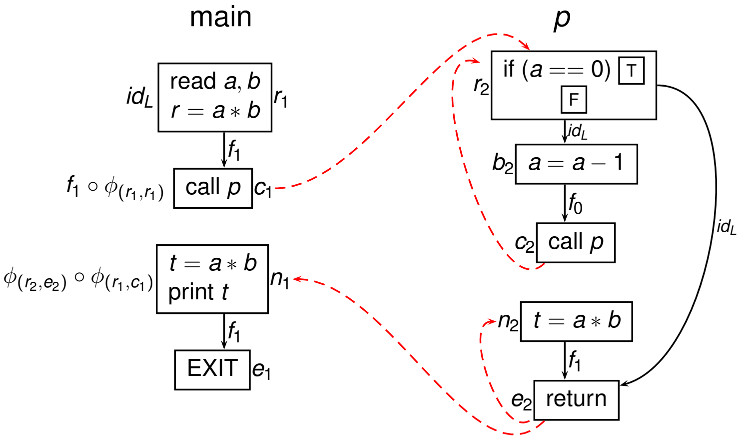

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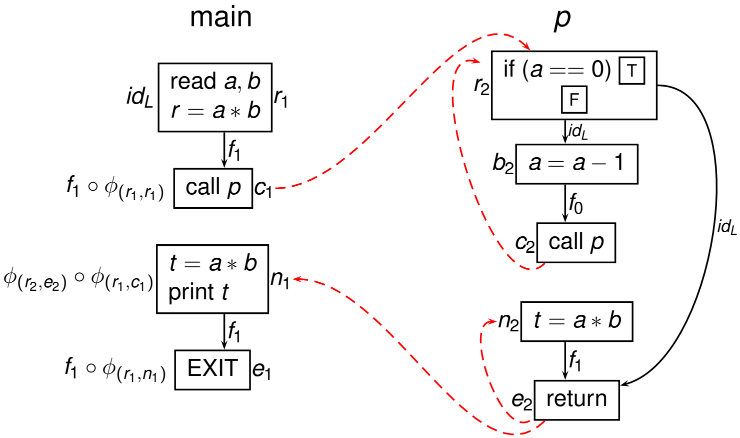

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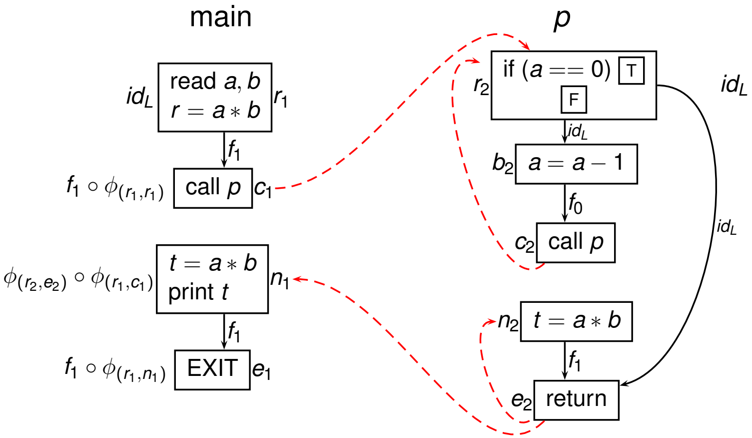

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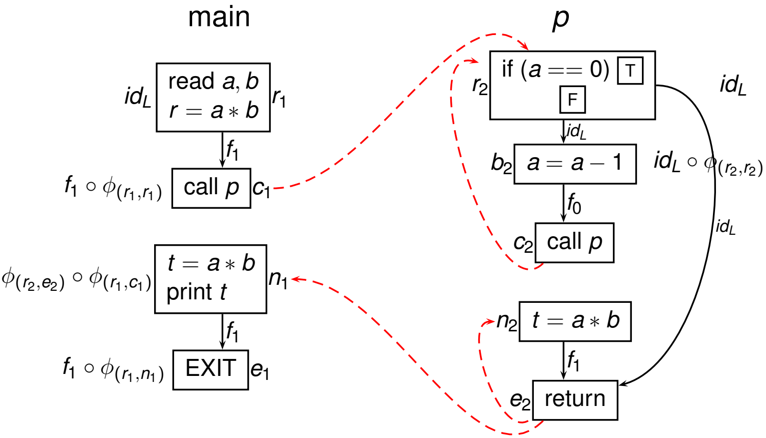

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r_1
f_1
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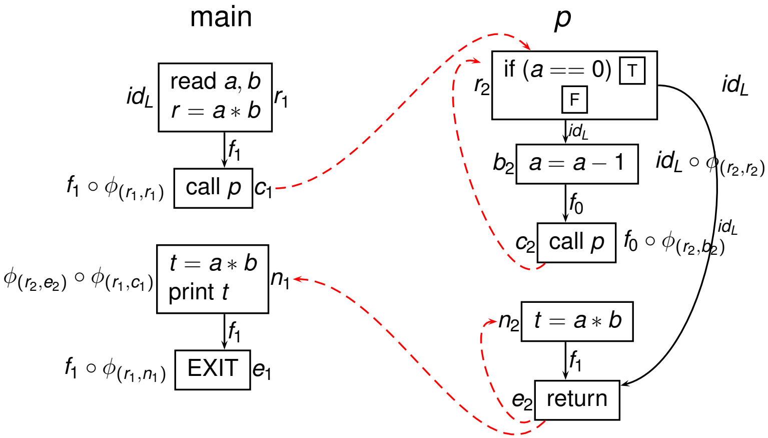
$f_1 \circ \phi_{(r_1,r_1)}$
c_1
$t = a * b$
print t
$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$
n_1
f_1
EXIT
$f_1 \circ \phi_{(r_1,n_1)}$
e_1
if $(a == 0)$
T
F
r_2
id_L
id_L
$a = a - 1$
b_2
$id_L \circ \phi_{(r_2,r_2)}$
f_0
call p
c_2
id_L
$t = a * b$
n_2
f_1
return
e_2

Example



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c_1
$t = a * b$
print t
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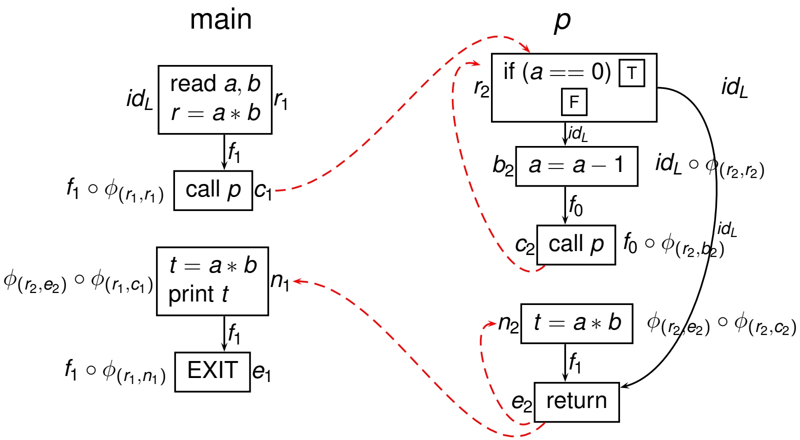
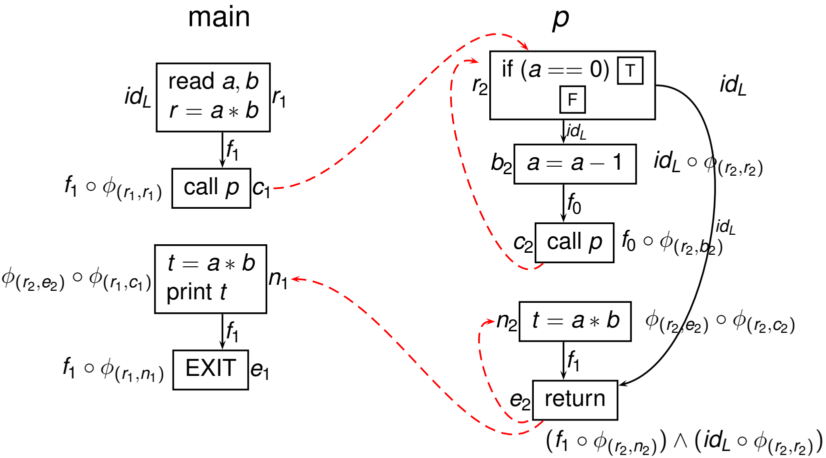
n_1
f_1
EXIT
$f_1 \circ \phi_{(r_1,n_1)}$
e_1
if $(a == 0)$
T
F
r_2
id_L
id_L
b_2
$a = a - 1$
$id_L \circ \phi_{(r_2,r_2)}$
f_0
c_2
call p
$f_0 \circ \phi_{(r_2,b_2)}$
id_L
n_2
$t = a * b$
f_1
e_2
return

Example



main
p
read a, b
r = a ∗ b
id_L
r_1
f_1
call p
f_1 ∘ φ_(r_1,r_1)
c_1
t = a ∗ b
print t
n_1
φ_(r_2,e_2) ∘ φ_(r_1,c_1)
f_1
EXIT
f_1 ∘ φ_(r_1,n_1)
e_1
if (a == 0)
T
F
r_2
id_L
id_L
b_2
a = a − 1
id_L ∘ φ_(r_2,r_2)
f_0
c_2
call p
f_0 ∘ φ_(r_2,b_2)
id_L
n_2
t = a ∗ b
φ_(r_2,e_2) ∘ φ_(r_2,c_2)
f_1
e_2
return

Example



main
p
read a, b
$r = a * b$
id_L
r_1
f_1
call p
c_1
$f_1 \circ \phi_{(r_1,r_1)}$
$t = a * b$
print t
n_1
$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$
f_1
EXIT
e_1
$f_1 \circ \phi_{(r_1,n_1)}$
if $(a == 0)$
T
F
r_2
id_L
id_L
b_2
$a = a - 1$
$id_L \circ \phi_{(r_2,r_2)}$
f_0
c_2
call p
$f_0 \circ \phi_{(r_2,b_2)}$
id_L
n_2
$t = a * b$
$\phi_{(r_2,e_2)} \circ \phi_{(r_2,c_2)}$
f_1
e_2
return
$(f_1 \circ \phi_{(r_2,n_2)}) \wedge (id_L \circ \phi_{(r_2,r_2)})$

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}

Iterative Solution

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Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id

Iterative Solution

Function	Constraint	Iteration #			
		Init	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_2,r_2)}$	id_L	id	id	id	id

Iterative Solution

Function	Constraint	Iteration #			
		Init	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_2,r_2)}$	id_L	id	id	id	id
$\phi_{(r_2,b_2)}$	$id_L \circ \phi_{(r_2,r_2)}$	f_Ω	id	id	id

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_2,r_2)}$	id_L	id	id	id	id
$\phi_{(r_2,b_2)}$	$id_L \circ \phi_{(r_2,r_2)}$	f_Ω	id	id	id
$\phi_{(r_2,c_2)}$	$f_0 \circ \phi_{(r_2,b_2)}$	f_Ω	f_0	f_0	f_0

Iterative Solution

		Iteration #			
Function	**Constraint**	**Init**	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_2,r_2)}$	id_L	id	id	id	id
$\phi_{(r_2,b_2)}$	$id_L \circ \phi_{(r_2,r_2)}$	f_Ω	id	id	id
$\phi_{(r_2,c_2)}$	$f_0 \circ \phi_{(r_2,b_2)}$	f_Ω	f_0	f_0	f_0
$\phi_{(r_2,n_2)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_2,c_2)}$	f_Ω	f_Ω	f_0	f_0

Iterative Solution

Function	Constraint	Iteration # Init	1^{st}	2^{nd}	3^{rd}
$\phi_{(r_1,r_1)}$	id_L	id	id	id	id
$\phi_{(r_1,c_1)}$	$f_1 \circ \phi_{(r_1,r_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_1,n_1)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_1,c_1)}$	f_Ω	f_Ω	f_1	f_1
$\phi_{(r_1,e_1)}$	$f_1 \circ \phi_{(r_1,n_1)}$	f_Ω	f_1	f_1	f_1
$\phi_{(r_2,r_2)}$	id_L	id	id	id	id
$\phi_{(r_2,b_2)}$	$id_L \circ \phi_{(r_2,r_2)}$	f_Ω	id	id	id
$\phi_{(r_2,c_2)}$	$f_0 \circ \phi_{(r_2,b_2)}$	f_Ω	f_0	f_0	f_0
$\phi_{(r_2,n_2)}$	$\phi_{(r_2,e_2)} \circ \phi_{(r_2,c_2)}$	f_Ω	f_Ω	f_0	f_0
$\phi_{(r_2,e_2)}$	$(f_1 \circ \phi_{(r_2,n_2)}) \wedge (id_L \circ \phi_{(r_2,r_2)})$	f_Ω	id	id	id

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for each procedure p

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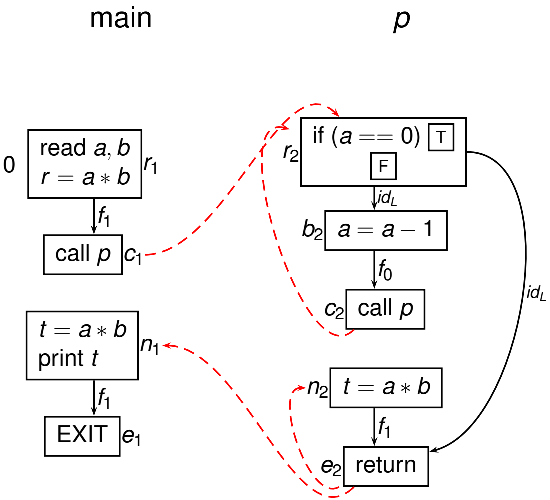
- Iterative algorithm for solution, maximal fixed point solution

Example



Functions
$\phi_{(r_1,r_1)} = id_L$
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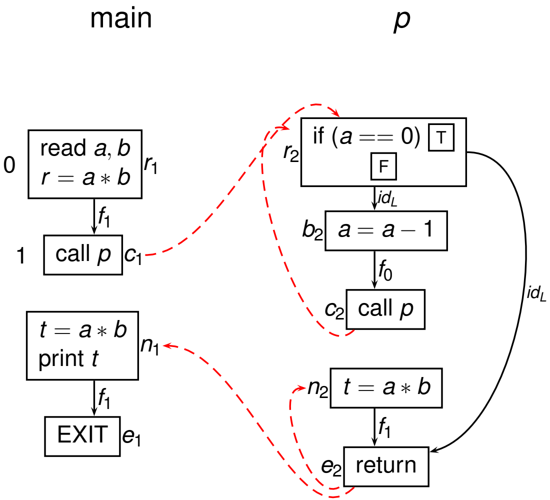

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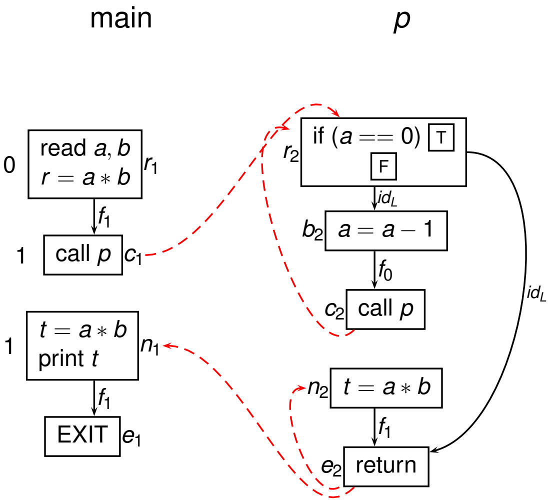

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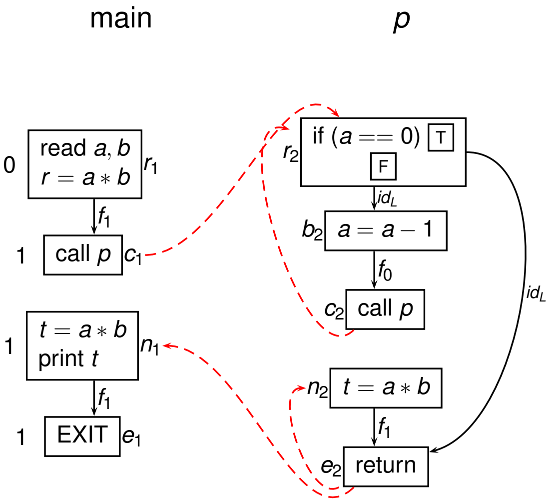

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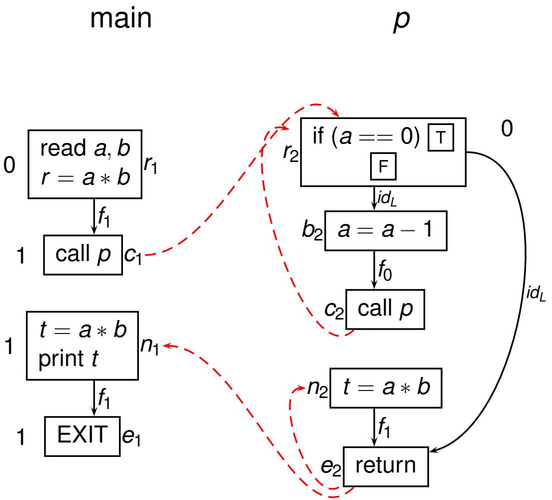

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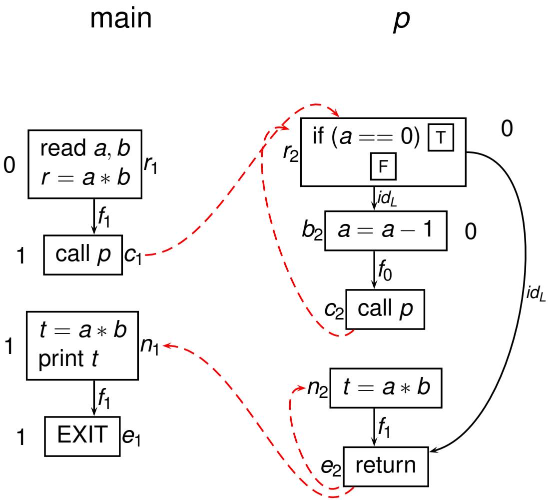

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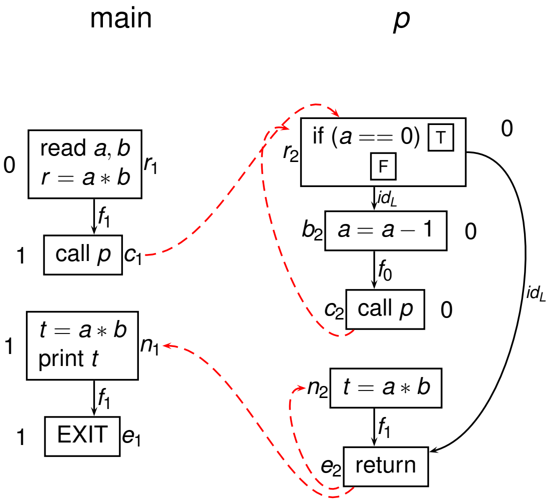

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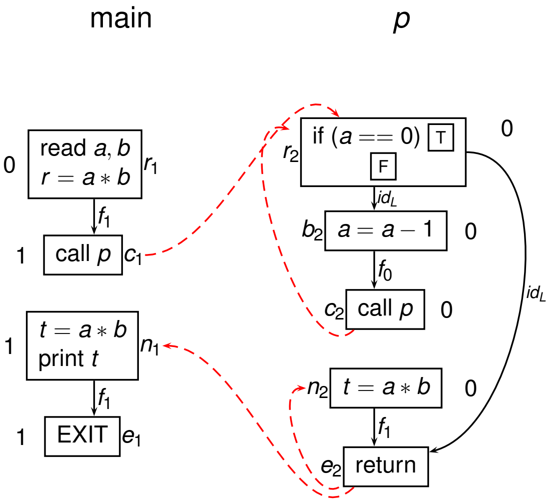

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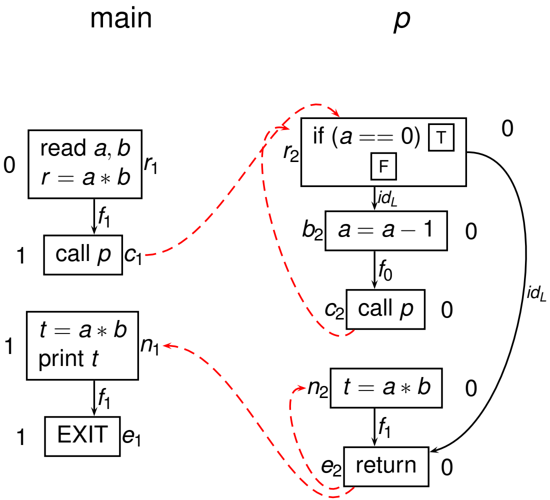

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Interprocedural MOP

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\Psi_n &= \bigwedge \{ f_q : q \in \mathrm{IVP}(r_{\mathrm{main}}, n) \} \in F \qquad \forall n \in N^* \\
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y_n is the *meet-over-all-paths solution* (MOP).

IVP_0 Lemma

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Proof: By induction (**Exercise/Reading Assignment**)

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Then

$$\Psi_n = \mathcal{X}_n$$

Proof: IVP_0 Lemma and Path decomposition

MOP

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Then

$$\Psi_n = \mathcal{X}_n$$

Proof: IVP_0 Lemma and Path decomposition

$$y_n = \Psi_n(\mathit{BoundaryInfo}) = \mathcal{X}_n(\mathit{BoundaryInfo})$$

MOP vs MFP

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- Is it possible to avoid explicit function compositions and meets?