CS738: Advanced Compiler Optimizations SSA Continued

Amey Karkare

karkare@cse.iitk.ac.in

http://www.cse.iitk.ac.in/~karkare/cs738 Department of CSE, IIT Kanpur



Agenda

- Properties of SSA
- ► SSA to Executable
- SSA for Optimizations

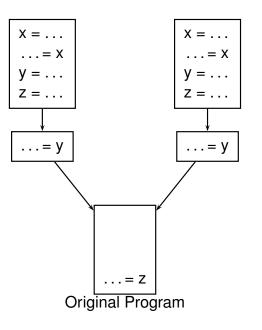
Complexity of Construction

- $ightharpoonup R = \max(N, E, A, M)$
- ► *N*: nodes, *E*: edges in flow graph
- ► A: number of assignments
- ► M: number of uses of variables
- ► Computation of DF: $O(R^2)$
- ► Computation of SSA: $O(R^3)$
- ► In practice, worst case is rare.
- ► Practical complexity: *O*(*R*)

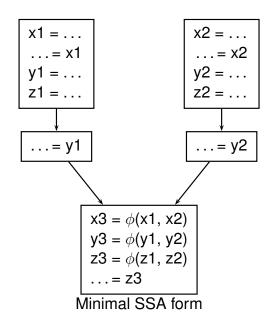
Linear Time Algorithm for ϕ -functions

- ▶ By Sreedhar and Gao, in POPL'95
- Uses a new data structure called DJ-graph
- Linear time is achieved by careful ordering of nodes in the DJ-graph
- ▶ DF for a node is computed only once an reused later if required.

Variants of SSA Form: Simple Example



Variants of SSA Form: Simple Example



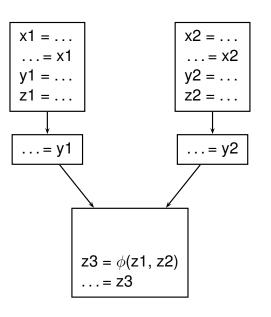
Variants of SSA Form

- \blacktriangleright Minimal SSA still contains extraneous ϕ -functions
 - ▶ Inserts some ϕ -functions where they are dead
 - ► Would like to avoid inserting them
- Pruned SSA
- Semi-Pruned SSA

Pruned SSA

- lacktriangle Only insert ϕ -functions where their value is live
- ▶ Inserts fewer ϕ -functions
- Costs more to do
- ► Requires global Live variable analysis

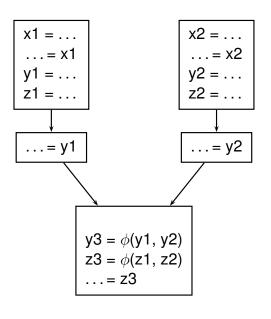
Variants of SSA Form: Pruned SSA Example



Semi-Pruned SSA Form

- ▶ Discard names used in only one block
- \blacktriangleright Total number of $\phi\text{-functions}$ between minimal and pruned SSA
- ► Needs only local Live information
- ▶ Non-locals can be computed without iteration or elimination

Variants of SSA Form: Semi-pruned SSA Example

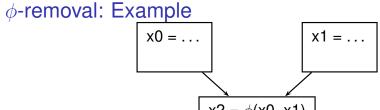


Computing Non-locals

```
foreach block B {
  defined = {}
  foreach instruction V = X op Y {
    if X not in defined
        non-locals = non-locals U {X}
    if Y not in defined
        non-locals = non-locals U {Y}
    defined = defined U {V}
  }
}
```

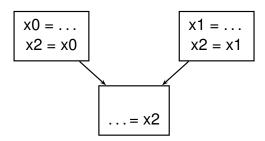
SSA to Executable

- ► At some point, we need executable code
 - ▶ Need to fix up the ϕ -function
- ► Basic idea
 - ▶ Insert copies in predecessors to mimic ϕ -function
 - Simple algorithm
 - ► Works in most cases, but not always
 - Adds lots of copies
 - ► Many of them will be optimized by later passes

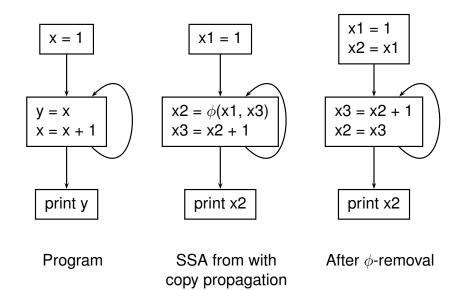


 $x2 = \phi(x0, x1)$... = x2

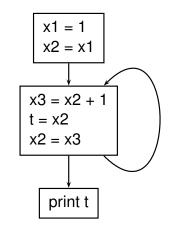
 $\bigvee \phi\text{-removal}$



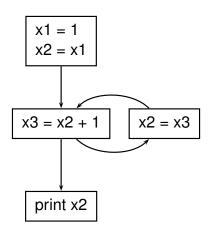
Lost Copy Problem



Lost Copy Problem: Solutions

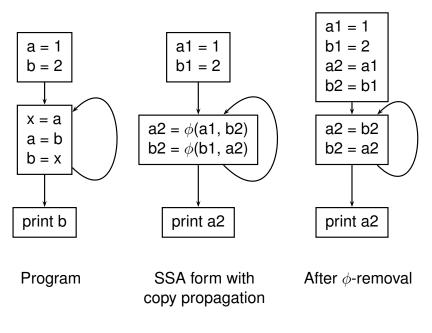


1. Use of Temporary



2. Critical Edge Split

Swap Problem



Swap Problem: Solution

- Fix requires compiler to detect and break dependency from output of one ϕ -function to input of another ϕ -function.
- ▶ May require temporary if cyclic dependency exists.

SSA Form for Optimizations

- SSA form can improve and/or speed up many analyses and optimizations
 - ► (Conditional) Constant propagation
 - ► Dead code elimination
 - Value numbering
 - ► PRE
 - ► Loop Invariant Code Motion
 - Strength Reduction