


<div>CS738: Advanced Compiler Optimizations</div> <div>Data Flow Analysis</div> <div> <div>Amey Karkare</div> <div>karkare@cse.iitk.ac.in</div> <div>http://www.cse.iitk.ac.in/~karkare/cs738</div> <div>Department of CSE, IIT Kanpur</div> </div> <div>  </div>	<div>Agenda</div> <div> <ul style="list-style-type: none"> ▶ Static analysis and compile-time optimizations ▶ For the next few lectures ▶ <i>Intraprocedural</i> Data Flow Analysis <ul style="list-style-type: none"> ▶ Classical Examples ▶ Components </div>	<div>Data Flow Analysis</div> <div> <ul style="list-style-type: none"> ▶ Class of techniques to derive information about flow of data <ul style="list-style-type: none"> ▶ along program execution paths ▶ Used to answer questions such as: <ul style="list-style-type: none"> ▶ whether two identical expressions evaluate to same value <ul style="list-style-type: none"> ▶ used in common subexpression elimination ▶ whether the result of an assignment is used later <ul style="list-style-type: none"> ▶ used by dead code elimination </div>	<div>Data Flow Abstraction</div> <div> <ul style="list-style-type: none"> ▶ Basic Blocks (BB) <ul style="list-style-type: none"> ▶ sequence of 3-address code stmts ▶ single entry at the first statement ▶ single exit at the last statement ▶ Typically we use "maximal" basic block (maximal sequence of such instructions) </div>
<div>Assumptions</div> <div> <ul style="list-style-type: none"> ▶ Intraprocedural: Restricted to a single function ▶ Input in 3-address format ▶ Unless otherwise specified </div>	<div>3-address Code Format</div> <div> <ul style="list-style-type: none"> ▶ Assignments <pre> x = y op z x = op y x = y </pre> ▶ Jump/control transfer <pre> goto L if x relop y goto L </pre> ▶ Statements can have label(s) <pre> L: ... </pre> ▶ Arrays, Pointers and Functions to be added later when needed </div>	<div>Identifying Basic Blocks</div> <div> <ul style="list-style-type: none"> ▶ <i>Leader</i>: The first statement of a basic block <ul style="list-style-type: none"> ▶ The first instruction of the program (procedure) ▶ Target of a branch (conditional and unconditional goto) ▶ Instruction immediately following a branch </div>	<div>Special Basic Blocks</div> <div> <ul style="list-style-type: none"> ▶ Two special BBs are added to simplify the analysis <ul style="list-style-type: none"> ▶ empty (?) blocks! ▶ <i>Entry</i>: The first block to be executed for the procedure analyzed ▶ <i>Exit</i>: The last block to be executed </div>
<div>Data Flow Abstraction</div> <div> <ul style="list-style-type: none"> ▶ Control Flow Graph (CFG) ▶ A rooted directed graph $G = (N, E)$ ▶ N = set of BBs <ul style="list-style-type: none"> ▶ including <i>Entry</i>, <i>Exit</i> ▶ E = set of edges </div>	<div>CFG Edges</div> <div> <ul style="list-style-type: none"> ▶ Edge $B_1 \rightarrow B_2 \in E$ if control can transfer from B_1 to B_2 <ul style="list-style-type: none"> ▶ Fall through ▶ Through jump (goto) ▶ Edge from <i>Entry</i> to (all?) real first BB(s) ▶ Edge to <i>Exit</i> from all last BBs <ul style="list-style-type: none"> ▶ BBs containing return ▶ Last real BB </div>	<div>Data Flow Abstraction: Program Points</div> <div> <ul style="list-style-type: none"> ▶ Input state/Output state for BBs <ul style="list-style-type: none"> ▶ Program point before/after a bb ▶ Denoted $IN[B]$ and $OUT[B]$ ▶ For B_1 and B_2: <ul style="list-style-type: none"> ▶ if there is an edge from B_1 to B_2 in CFG, then the program point <i>after</i> the last stmt of B_1 <i>may be</i> followed immediately by the program point <i>before</i> the first stmt of B_2. </div>	<div>Data Flow Abstraction: Execution Paths</div> <div> <ul style="list-style-type: none"> ▶ An execution path is of the form $p_1, p_2, p_3, \dots, p_n$ <p>where $p_i \rightarrow p_{i+1}$ are adjacent program points in the CFG.</p> ▶ Infinite number of possible execution paths in practical programs. ▶ Paths having no finite upper bound on the length. ▶ Need to <i>summarize</i> the information at a program point with a finite set of facts. </div>
<div>Data Flow Abstraction: Control Flow Graph</div> <div> <ul style="list-style-type: none"> ▶ Graph representation of paths that program may exercise during execution ▶ Typically one graph per procedure ▶ Graphs for separate procedures have to be combined/connected for interprocedural analysis <ul style="list-style-type: none"> ▶ Later! ▶ Single procedure, single flow graph for now. </div>	<div>Data Flow Abstraction: Program Points</div> <div> <ul style="list-style-type: none"> ▶ Input state/Output state for Stmt <ul style="list-style-type: none"> ▶ Program point before/after a stmt ▶ Denoted $IN[s]$ and $OUT[s]$ ▶ Within a basic block: <ul style="list-style-type: none"> ▶ Program point after a stmt is same as the program point before the next stmt </div>	<div>Data Flow Schema</div> <div> <ul style="list-style-type: none"> ▶ Data flow values associated with each program point <ul style="list-style-type: none"> ▶ Summarize all possible states at that point ▶ <i>Domain</i>: set of all possible data flow values ▶ Different domains for different analyses/optimizations </div>	<div>Data Flow Problem</div> <div> <ul style="list-style-type: none"> ▶ Constraints on data flow values <ul style="list-style-type: none"> ▶ Transfer constraints ▶ Control flow constraints ▶ Aim: To find a solution to the constraints <ul style="list-style-type: none"> ▶ Multiple solutions possible ▶ Trivial solutions, . . . , Exact solutions ▶ We typically compute approximate solution <ul style="list-style-type: none"> ▶ Close to the exact solution (as close as possible!) ▶ Why not exact solution? </div>

Data Flow Constraints: Transfer Constraints

- Transfer functions
 - relationship between the data flow values before and after a stmt
- forward functions: Compute facts *after* a statement s from the facts available *before* s .
 - General form:

$$OUT[s] = f_s(IN[s])$$
- backward functions: Compute facts *before* a statement s from the facts available *after* s .
 - General form:

$$IN[s] = f_s(OUT[s])$$
- f_s depends on the statement and the analysis

Data Flow Constraints: Control Flow Constraints

- Relationship between the data flow values of two points that are related by program execution semantics
- For a basic block having n statements:

$$IN[s_{i+1}] = OUT[s_i], i = 1, 2, \dots, n-1$$
- $IN[s_1], OUT[s_n]$ to come later

Data Flow Equations

- Typical Equation

$$OUT[s] = IN[s] - kill[s] \cup gen[s]$$
- $gen(s)$: information generated
- $kill(s)$: information killed
- Example:


```
a = b*c // generates expression b * c
c = 5   // kills expression b*c
d = b*c // is b*c redundant here?
```

Example Data Flow Analysis

- Reaching Definitions Analysis
- Definition of a variable x : $x = \dots \text{something} \dots$
- Could be more complex (e.g. through pointers, references, implicit)

Data Flow Constraints: Notations

- PRED(B): Set of predecessor BBs of block B in CFG
- SUCC(B): Set of successor BBs of block B in CFG
- $f \circ g$: Composition of functions f and g
- \oplus : An abstract operator denoting some way of combining facts present in a set.

Data Flow Constraints: Basic Blocks

- Forward**
 - For B consisting of s_1, s_2, \dots, s_n

$$f_B = f_{s_1} \circ \dots \circ f_{s_n}$$

$$OUT[B] = f_B(IN[B])$$
 - Control flow constraints

$$IN[B] = \bigoplus_{P \in \text{PRED}(B)} OUT[P]$$
- Backward**

$$f_B = f_{s_1} \circ f_{s_2} \circ \dots \circ f_{s_n}$$

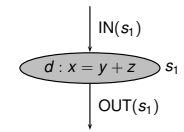
$$IN[B] = f_B(OUT[B])$$

$$OUT[B] = \bigoplus_{S \in \text{SUCC}(B)} IN[S]$$

Reaching Definitions Analysis

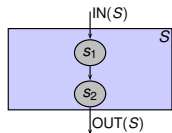
- A definition d reaches a point p if
 - there is a path from the point *immediately following* d to p
 - d is not "killed" along that path
 - "Kill" means redefinition of the left hand side (x in the earlier example)

RD Analysis of a Structured Program



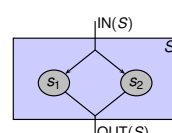
- $$OUT(s_1) = IN(s_1) - KILL(s_1) \cup GEN(s_1)$$
- $$GEN(s_1) = \{d\}$$
- $$KILL(s_1) = D_x - \{d\}, \text{ where } D_x: \text{ set of all definitions of } x$$
- $$KILL(s_1) = D_x? \text{ will also work here but may not work in general}$$

RD Analysis of a Structured Program



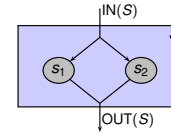
- $$GEN(S) = GEN(s_1) - KILL(s_2) \cup GEN(s_2)$$
- $$KILL(S) = KILL(s_1) - GEN(s_2) \cup KILL(s_2)$$
- $$IN(s_1) = IN(S)$$
- $$IN(s_2) = OUT(s_1)$$
- $$OUT(S) = OUT(s_2)$$

RD Analysis of a Structured Program



- $$GEN(S) = GEN(s_1) \cup GEN(s_2)$$
- $$KILL(S) = KILL(s_1) \cap KILL(s_2)$$
- $$IN(s_1) = IN(s_2) = IN(S)$$
- $$OUT(S) = OUT(s_1) \cup OUT(s_2)$$

RD Analysis is Approximate



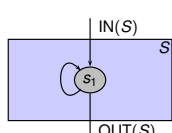
- Thus,
 - true $GEN(S) \subseteq \text{analysis } GEN(S)$
 - true $KILL(S) \supseteq \text{analysis } KILL(S)$
- More definitions computed to be reaching than actually do!
- Later we shall see that this is **SAFE** approximation
 - prevents optimizations
 - but NO wrong optimization

RD at BB level

- A definition d can reach the start of a block from any of its predecessor
 - if it reaches the end of some predecessor

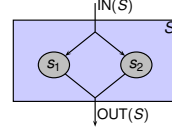
$$IN(B) = \bigcup_{P \in \text{PRED}(B)} OUT(P)$$
- A definition d reaches the end of a block if
 - either it is generated in the block
 - or it reaches block and not killed
$$OUT(B) = IN(B) - KILL(B) \cup GEN(B)$$

RD Analysis of a Structured Program



- $$GEN(S) = GEN(s_1)$$
- $$KILL(S) = KILL(s_1)$$
- $$OUT(S) = OUT(s_1)$$
- $$IN(s_1) = IN(S) \cup GEN(s_1)$$

RD Analysis is Approximate



- Assumption: All paths are feasible.
- Example:


```
if (true) s1;
else      s2;
```

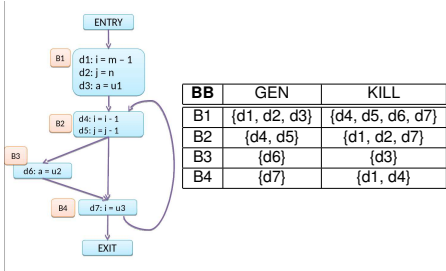
Fact	Computed	Actual
$GEN(S)$	$GEN(s_1) \cup GEN(s_2)$	$\supseteq GEN(s_1)$
$KILL(S)$	$KILL(s_1) \cap KILL(s_2)$	$\subseteq KILL(s_1)$

Solving RD Constraints

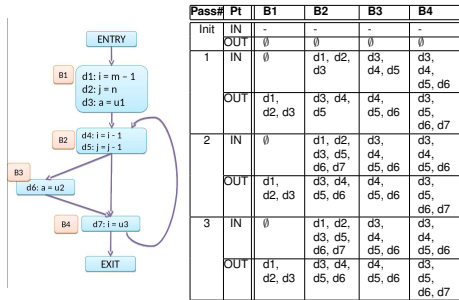
- KILL & GEN known for each BB.
- A program with N BBs has $2N$ equations with $2N$ unknowns.
 - Solution is possible.
 - Iterative approach (on the next slide).

```
for each block B {
    OUT(B) = {};
}
OUT(Entry) = {}; // note this for later discussion
change = true;
while (change) {
    change = false;
    for each block B other than Entry {
        IN(B) = union_{P in PRED(B)} OUT(P);
        oldOut = OUT(B);
        OUT(B) = IN(B) - KILL(B) union GEN(B);
        if (OUT(B) != oldOut) then {
            change = true;
        }
    }
}
```

Reaching Definitions: Example



Reaching Definitions: Application



Reaching Definitions: Application

Constant Folding

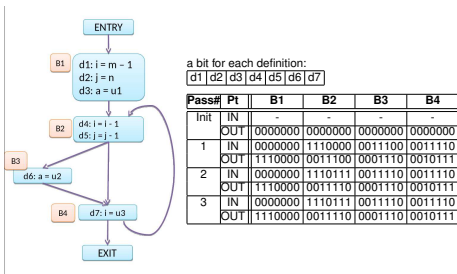
```

while changes occur {
  forall the stmts S of the program {
    foreach operand B of S {
      if there is a unique definition of B
        that reaches S and is a constant C {
        replace B by C in S;
        if all operands of S are constant {
          replace rhs by eval(rhs);
          mark definition as constant;
        }
      }
    }
  }
}
    
```

Reaching Definitions: Application

- Recall the approximation in reaching definition analysis
 - true $GEN(S) \subseteq$ analysis $GEN(S)$
 - true $KILL(S) \supseteq$ analysis $KILL(S)$
- Can it cause the application to infer
 - an expression as a constant when it has different values for different executions?
 - an expression as not a constant when it is a constant for all executions?
- Safety? Profitability?

Reaching Definitions: Bitvectors



Reaching Definitions: Bitvectors

- Set-theoretic definitions:

$$IN(B) = \bigcup_{P \in \text{PRED}(B)} OUT(P)$$

$$OUT(B) = IN(B) - KILL(B) \cup GEN(B)$$

- Bitvector definitions:

$$IN(B) = \bigvee_{P \in \text{PRED}(B)} OUT(P)$$

$$OUT(B) = IN(B) \wedge \neg KILL(B) \vee GEN(B)$$

- Bitwise \vee, \wedge, \neg operators

Reaching Definitions: Summary

- $GEN(B) = \{d_x \mid d_x \text{ in } B \text{ defines variable } x \text{ and is not followed by another definition of } x \text{ in } B\}$
- $KILL(B) = \{d_x \mid B \text{ contains some definition of } x\}$
- $IN(B) = \bigcup_{P \in \text{PRED}(B)} OUT(P)$
- $OUT(B) = IN(B) - KILL(B) \cup GEN(B)$
- meet (\wedge) operator: The operator to combine information coming along different predecessors is \cup
- What about the *Entry* block?

Reaching Definitions: Summary

- Entry block has to be initialized specially:

$$OUT(Entry) = \text{EntryInfo}$$

$$\text{EntryInfo} = \emptyset$$

- A better entry info could be:

$$\text{EntryInfo} = \{x = \text{undefined} \mid x \text{ is a variable}\}$$

- Why?