

§ Constructing homotopy colimits

• Geometric Realisation:

Given $X: \Delta^{\text{op}} \rightarrow \text{Top}$ a simplicial space define its geometric realisation as

$$|X| := \text{coeq} \left(\coprod_{[n] \rightarrow [k]} X_k \times \Delta^n \rightrightarrows \coprod_n X_n \times \Delta^n \right)$$

Top map: $X([n] \rightarrow [k]): X_k \rightarrow X_n$
 Bottom map: $\Delta([n] \rightarrow [k]): \Delta^n \rightarrow \Delta^k$

$$\cong \coprod_n X_n \times \Delta^n / \begin{aligned} &(\partial_i x, t) \sim (x, d^i t) \\ &(s_i x, t) \sim (x, s^i t) \end{aligned}$$

$\Delta^n = \text{standard } n\text{-simplex}$

Q. Given objectwise weak equivalence $X \rightarrow Y$ when is $|X| \cong |Y|$?

A. When X, Y are Reedy cofibrant (as defined below)

Def: n^{th} Latching object of X :

$$L_n X := \bigcup_{i=1}^n s_i(X_{n-1})$$

$$\text{eg: } L_0 X = \phi,$$

$$L_1 X = X_0, \quad L_2 X = X_1 \bigcup_{X_0} X_1$$

We have a natural inclusion: $L_n X \rightarrow X_n$

We say that X is Reedy cofibrant if this map is a cofibration.

• We also have a natural map $|X| \rightarrow \text{colim}_{\Delta^{\text{op}}} X (\cong \text{coeq} (X_1 \xrightarrow[\partial_0]{\partial_1} X_0))$ which maps a point in $X_n \times \Delta^n$ to any of its vertices. Such a map is well-defined as we're taking the colimit over Δ^{op} .

• Homotopy colimits:

Def: Given a small diagram $\mathcal{D}: \mathcal{I} \rightarrow \text{Top}$ a simplicial replacement of \mathcal{D} is defined as:

$$\text{srep}(\mathcal{D}) := \coprod_{i_0 \in \mathcal{I}} \mathcal{D}(i_0) \xleftarrow{\quad} \coprod_{i_0 \leftarrow i_1} \mathcal{D}(i_1) \xleftarrow{\quad} \coprod_{i_0 \leftarrow i_1 \leftarrow i_2} \mathcal{D}(i_2) \cdots$$

$$\text{Define } \text{hocolim}_{\mathcal{I}} \mathcal{D} := |\text{srep}(\mathcal{D})|$$

• We have a natural map

$$\begin{aligned} \text{hocolim}_{\mathcal{I}} \mathcal{D} &\rightarrow \text{colim}_{\Delta^{\text{op}}} \text{srep} \mathcal{D} \\ &\cong \text{coeq} \left(\coprod_{i_1 \rightarrow i_0} \mathcal{D}(i_1 \rightarrow i_0) \rightarrow \coprod_{i_0} \mathcal{D}(i_0) \right) = \text{colim}_{\mathcal{I}} \mathcal{D} \end{aligned}$$

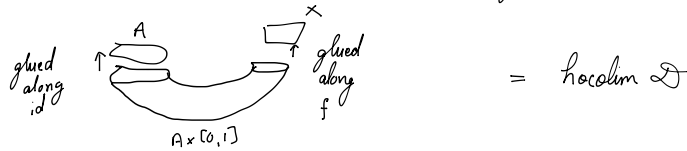
Th^m: $\text{srep}(\mathcal{D})$ is always Reedy cofibrant,

so if $\mathcal{D}, \mathcal{D}': \mathcal{I} \rightarrow \text{Top}$ are objectwise equivalent then so are $\text{hocolim}_{\mathcal{I}} \mathcal{D}, \text{hocolim}_{\mathcal{I}} \mathcal{D}'$.

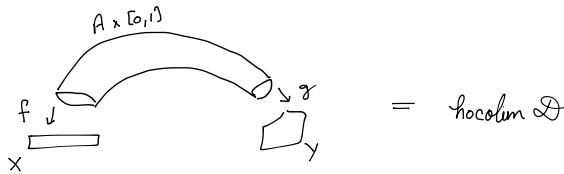
The above theorem is false if we replace Top with an arbitrary simplicially enriched model category. In that case, we further require $\mathcal{D}, \mathcal{D}'$ to be diagrams of cofibrant objects.

eg: $\mathcal{D} = X \xrightarrow{f} Y$ degenerate

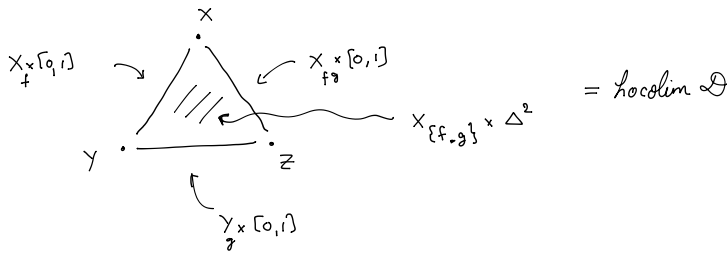
In this case the homotopy \mathcal{D} is the mapping cylinder



eg: $\mathcal{D} = A \xrightarrow{f} X$ $\text{prep}(\mathcal{D}) = A \cup X \cup Y$ $\leftarrow A_f \cup A_g$ $\leftarrow X_{\{f, g\}}$ all other simplices degenerate



eg: $\mathcal{D} = X \xrightarrow{f} Y \xrightarrow{g} Z$ $\text{prep}(\mathcal{D}) = X \cup Y \cup Z \leftarrow X_f \cup Y_g \leftarrow X_{\{f, g\}}$ + degenerate simplices



• alternative formula for homotopy:

given $\mathcal{D}: I \rightarrow \text{Top}$ we have

$$\text{homotopy}_{\mathcal{D}} \cong \text{coeq} \left(\coprod_{i \rightarrow j} \mathcal{D}(i) \times B((j \downarrow I)^{\text{op}}) \rightrightarrows \coprod_i \mathcal{D}(i) \times B((i \downarrow I)^{\text{op}}) \right) \quad \text{where } B \text{ denotes nerve}$$

• $j \downarrow I$ is the category of objects $\{ \begin{smallmatrix} j \\ i \downarrow \end{smallmatrix} \}$ and morphisms $\{ \begin{smallmatrix} j & \\ i & \rightarrow k \end{smallmatrix} \}$

• The nerve of $B((j \downarrow I)^{\text{op}})$ is the simplicial set

$$\coprod_{j \rightarrow i} \Delta^0 \rightrightarrows \coprod_{\begin{smallmatrix} j \\ i \rightarrow k \end{smallmatrix}} \Delta^1 \rightrightarrows \coprod_{\begin{smallmatrix} j \\ i \rightarrow l_1 \rightarrow l_2 \end{smallmatrix}} \Delta^2 \dots$$

the boundary maps are

$$\left(\begin{smallmatrix} j \\ i_0 \rightarrow i_1 \rightarrow \dots \rightarrow i_n \end{smallmatrix} \right) \begin{matrix} \xrightarrow{\partial_0} i_0 \rightarrow i_1 \rightarrow \dots \rightarrow i_{n-1} \\ \xrightarrow{\partial_1} i_0 \rightarrow i_1 \rightarrow \dots \rightarrow (i_{n-2} \rightarrow i_{n-1} \rightarrow i_n) \\ \vdots \\ \xrightarrow{\partial_n} i_1 \rightarrow i_2 \rightarrow \dots \rightarrow i_n \end{matrix}$$

this is where $B((\text{op})^{\text{op}})$ & B differ