d1: Decision theory investigates decision problems: how an agent deals with choosing among actions. d2: Reinforcement learning is a type of unsupervised learning where an agent learns how to behave in an environment. d3: Information retrieval deals with representing information objects. g: agent action decision, theory, investigates, problems, how, an, agent, deals, with, choosing, among, actions, reinforcement, is, a, type, of, unsupervised, where, learns, to, behave, in, environment. Information, retrieval, representation, objects 11.03.05 n1 tf(t, d1) n2 tf(t,d2) n3 tf(t,d3) nq tf(t,q) N(t) idf(t,D) A3 B = tfidf(t,q,D) cos θ1 cos θ2 cos θ3 no of occurance of no.of ord in the n1/total no occurance n2/total no.of n3/total no.of ng/total document D LOG(4/N(t)) as $\cos \theta 1 = (A1 \cos \theta 2 = (A2 \cos \theta 3 = (A3$ occurance of of words in of word in no.of occurance of no.of words occurance of no.of words i.e. in d1 , d2 n=4, (d1, d2, d3 tfidf(t,d1,D) = tf(t,d1)*tfidf(t,d2,D) = tfidf(t,d3,D) = . B) / Words / text (t) word in d1 d1 d2 words in d2 word in d3 in d3 word in a and d3) and a) idf(t, D) tf(t,d2)* idf(t, D) tf(t,d3)* idf(t, D) tf(t,a)* idf(t, D) IA1I.IBI IA21.IB1 in a decision theory 2 0,15384615 0.04631230 1 0,07692308 0.60205999 investigates 1 0,07692308 0,60205999 0,04631230 problems 0,60205999 0.04631230 1 0.07692308 1 0,07692308 0,055556 0,30102999 0,023156154 0,01672388 how an 1 0.07692308 0.1111111 0.30102999 0.02315615 0,03344777 agent 1 0,07692308 0,12493873 0,00961067 0,00694104 0,06246936 deals 1 0,07692308 0,14285714 0,30102999 0,02315615 0,04300428 The cosine similarity measures the similarity between 0,14285714 0,0231561 two vectors based on the cosine of the angle between with 0,07692308 0,30102999 choosing 1 0,07692308 0,60205999 0,04631230 them. A higher cosine similarity score indicates a 0,60205999 0,04631230 higher degree of similarity between the vectors. among 1 0,07692308 0,02315615 0,15051499 1 0,07692308 0,30102999 actions In order of decresing cosine similarity ($\cos\theta 1 > \cos\theta 2$ reinforcement 0,60205999 0,03344777 0,60205999 0,03344777 > cos θ3) 4,38714785 0,62060725 0,03344777 0,60205999 0,03344777 type of 0.0555556 0,60205999 0.03344777 0.60205999 0.055556 0,03344777 unsupervised 0,055556 0,60205999 where 0,60205999 learn 0,1666667 0,60205999 0,10034333 0,60205999 0,03344777 0.0555556 behave 0,60205999 0,03344777 0.055556 0.0555556 0.602059993 0,03344777 0,60205999 0,03344777 Information 0,28571429 0,60205999 retrieval 0,14285714 0,60205999 representation 0,14285714 0,60205999 0,0860085 0.14285714 objects 0,602059991 0.086008 0,011429452 0,008574599 0,033649167 0,081481879 |A1| |A2| |A3|