

# GPIOEMLIB

## Detailed Description

General Purpose Input/Output (GPIO) API.

This module contains functions to control the GPIO peripheral of Silicon Labs 32-bit MCUs and SoCs. The GPIO peripheral is used for pin configuration and direct pin manipulation and sensing as well as routing for peripheral pin connections.

## Enumerations

```
enum    GPIO_Mode_TypeDef {
    gpioModeDisabled = _GPIO_P_MODEL_MODE0_DISABLED,
    gpioModeInput = _GPIO_P_MODEL_MODE0_INPUT,
    gpioModeInputPull = _GPIO_P_MODEL_MODE0_INPUTPULL,
    gpioModeInputPullFilter =
        _GPIO_P_MODEL_MODE0_INPUTPULLFILTER,
    gpioModePushPull = _GPIO_P_MODEL_MODE0_PUSHPULL,
    gpioModePushPullAlternate =
        _GPIO_P_MODEL_MODE0_PUSHPULLALT,
    gpioModeWiredOr = _GPIO_P_MODEL_MODE0_WIREDOR,
    gpioModeWiredOrPullDown =
        _GPIO_P_MODEL_MODE0_WIREDORPULLDOWN,
    gpioModeWiredAnd = _GPIO_P_MODEL_MODE0_WIREDAND,
    gpioModeWiredAndFilter =
        _GPIO_P_MODEL_MODE0_WIREDANDFILTER,
    gpioModeWiredAndPullUp =
        _GPIO_P_MODEL_MODE0_WIREDANDPULLUP,
    gpioModeWiredAndPullUpFilter =
        _GPIO_P_MODEL_MODE0_WIREDANDPULLUPFILTER,
    gpioModeWiredAndAlternate =
        _GPIO_P_MODEL_MODE0_WIREDANDALT,
    gpioModeWiredAndAlternateFilter =
        _GPIO_P_MODEL_MODE0_WIREDANDALTFILTER,
    gpioModeWiredAndAlternatePullUp =
        _GPIO_P_MODEL_MODE0_WIREDANDALTPULLUP,
```

```

    gpioModeWiredAndAlternatePullUpFilter =
    _GPIO_P_MODEL_MODE0_WIREDANDALTPULLUPFILTER
}

```

```
enum    GPIO_Port_TypeDef
```

## Functions

```
void    GPIO_DbgLocationSet (unsigned int
location)
```

Sets the pin location of the debug pins (Serial Wire interface).

```
__STATIC_INLINE void    GPIO_DbgSWDClkEnable (bool enable)
```

Enable/disable serial wire clock pin.

```
__STATIC_INLINE void    GPIO_DbgSWDIOEnable (bool enable)
```

Enable/disable serial wire data I/O pin.

```
__STATIC_INLINE void    GPIO_DbgSWOEnable (bool enable)
```

Enable/Disable serial wire output pin.

```
__STATIC_INLINE void    GPIO_EM4DisablePinWakeup (uint32_t
pinmask)
```

Disable GPIO pin wake-up from EM4.

```
void    GPIO_EM4EnablePinWakeup (uint32_t
pinmask, uint32_t polaritymask)
```

Enable GPIO pin wake-up from EM4. When the function exits, EM4 mode can be safely entered.

```
__STATIC_INLINE void    GPIO_EM4SetPinRetention (bool enable)
```

Enable GPIO pin retention of output enable, output value, pull enable, and pull direction in EM4.

```
void    GPIO_ExtIntConfig (GPIO_Port_TypeDef
port, unsigned int pin, unsigned int
intNo, bool risingEdge, bool
fallingEdge, bool enable)
```

Configure the GPIO external pin interrupt.

```
__STATIC_INLINE void    GPIO_InputSenseSet (uint32_t val,
uint32_t mask)
```

Enable/disable input sensing.

```
__STATIC_INLINE void    GPIO_IntClear (uint32_t flags)
```

Clear one or more pending GPIO interrupts.

__STATIC_INLINE void	<b>GPIO_IntConfig</b> (GPIO_Port_TypeDef port, unsigned int pin, bool risingEdge, bool fallingEdge, bool enable) Configure GPIO interrupt.
__STATIC_INLINE void	<b>GPIO_IntDisable</b> (uint32_t flags) Disable one or more GPIO interrupts.
__STATIC_INLINE void	<b>GPIO_IntEnable</b> (uint32_t flags) Enable one or more GPIO interrupts.
__STATIC_INLINE uint32_t	<b>GPIO_IntGet</b> (void) Get pending GPIO interrupts.
__STATIC_INLINE uint32_t	<b>GPIO_IntGetEnabled</b> (void) Get enabled and pending GPIO interrupt flags. Useful for handling more interrupt sources in the same interrupt handler.
__STATIC_INLINE void	<b>GPIO_IntSet</b> (uint32_t flags) Set one or more pending GPIO interrupts from SW.
__STATIC_INLINE void	<b>GPIO_Lock</b> (void) Locks the GPIO configuration.
__STATIC_INLINE unsigned int	<b>GPIO_PinInGet</b> (GPIO_Port_TypeDef port, unsigned int pin) Read the pad value for a single pin in a GPIO port.
GPIO_Mode_TypeDef	<b>GPIO_PinModeGet</b> (GPIO_Port_TypeDef port, unsigned int pin) Get the mode for a GPIO pin.
void	<b>GPIO_PinModeSet</b> (GPIO_Port_TypeDef port, unsigned int pin, GPIO_Mode_TypeDef mode, unsigned int out) Set the mode for a GPIO pin.
__STATIC_INLINE void	<b>GPIO_PinOutClear</b> (GPIO_Port_TypeDef port, unsigned int pin) Set a single pin in GPIO data out port register to 0.
__STATIC_INLINE unsigned int	<b>GPIO_PinOutGet</b> (GPIO_Port_TypeDef port, unsigned int pin) Get current setting for a pin in a GPIO port data out register.
__STATIC_INLINE void	<b>GPIO_PinOutSet</b> (GPIO_Port_TypeDef

	<code>port, unsigned int pin)</code> Set a single pin in GPIO data out register to 1.
<code>__STATIC_INLINE void</code>	<code>GPIO_PinOutToggle (GPIO_Port_TypeDef port, unsigned int pin)</code> Toggle a single pin in GPIO port data out register.
<code>__STATIC_INLINE uint32_t</code>	<code>GPIO_PortInGet (GPIO_Port_TypeDef port)</code> Read the pad values for GPIO port.
<code>__STATIC_INLINE void</code>	<code>GPIO_PortOutClear (GPIO_Port_TypeDef port, uint32_t pins)</code> Set bits in DOUT register for a port to 0.
<code>__STATIC_INLINE uint32_t</code>	<code>GPIO_PortOutGet (GPIO_Port_TypeDef port)</code> Get current setting for a GPIO port data out register.
<code>__STATIC_INLINE void</code>	<code>GPIO_PortOutSet (GPIO_Port_TypeDef port, uint32_t pins)</code> Set bits GPIO data out register to 1.
<code>__STATIC_INLINE void</code>	<code>GPIO_PortOutSetVal (GPIO_Port_TypeDef port, uint32_t val, uint32_t mask)</code> Set GPIO port data out register.
<code>__STATIC_INLINE void</code>	<code>GPIO_PortOutToggle (GPIO_Port_TypeDef port, uint32_t pins)</code> Toggle pins in GPIO port data out register.
<code>__STATIC_INLINE void</code>	<code>GPIO_SlewrateSet (GPIO_Port_TypeDef port, uint32_t slewrate, uint32_t slewrateAlt)</code> Set slewrate for pins on a GPIO port.
<code>__STATIC_INLINE void</code>	<code>GPIO_Unlock (void)</code> Unlocks the GPIO configuration.

## Enumeration Type Documentation

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enum `GPIO_Mode_TypeDef`

Pin mode. For more details on each mode, refer to the reference manual.

Enumerator	
gpioModeDisabled	Input disabled. Pull-up if DOUT is set.
gpioModeInput	Input enabled. Filter if DOUT is set.
gpioModeInputPull	Input enabled. DOUT determines pull direction.
gpioModeInputPullFilter	Input enabled with filter. DOUT determines pull direction.
gpioModePushPull	Push-pull output.
gpioModePushPullAlternate	Push-pull using alternate control.
gpioModeWiredOr	Wired-or output.
gpioModeWiredOrPullDown	Wired-or output with pull-down.
gpioModeWiredAnd	Open-drain output.
gpioModeWiredAndFilter	Open-drain output with filter.
gpioModeWiredAndPullUp	Open-drain output with pull-up.
gpioModeWiredAndPullUpFilter	Open-drain output with filter and pull-up.
gpioModeWiredAndAlternate	Open-drain output using alternate control.

gpioModeWiredAndAlternateFilter	Open-drain output using alternate control with filter.
gpioModeWiredAndAlternatePullUp	Open-drain output using alternate control with pull-up.
gpioModeWiredAndAlternatePullUpFilter	Open-drain output using alternate control with filter and pull-up.

Definition at line 552 of file `em_gpio.h`.

enum `GPIO_Port_TypeDef`

GPIO ports IDs.

Definition at line 479 of file `em_gpio.h`.

# Function Documentation

void `GPIO_DbgLocationSet` ( unsigned int `location` )

Sets the pin location of the debug pins (Serial Wire interface).

## Note

Changing the pins used for debugging uncontrolled, may result in a lockout.

## Parameters

[in]	<code>location</code>	The debug pin location to use (0-3).
------	-----------------------	--------------------------------------

Definition at line 79 of file `em_gpio.c`.

Referenced by `DBG_SW0Enable()`.

---

```
__STATIC_INLINE void GPIO_DbgSWDClkEnable      ( bool enable )
```

Enable/disable serial wire clock pin.

### Note

Disabling SWDClk will disable the debug interface, which may result in a lockout if done early in startup (before debugger is able to halt core).

### Parameters

[in]	enable	<ul style="list-style-type: none"><li>false - disable serial wire clock.</li><li>true - enable serial wire clock (default after reset).</li></ul>
------	--------	---

Definition at line 623 of file `em_gpio.h`.

References `BUS_RegBitWrite()`.

---

```
__STATIC_INLINE void GPIO_DbgSWDIOEnable      ( bool enable )
```

Enable/disable serial wire data I/O pin.

### Note

Disabling SWDClk will disable the debug interface, which may result in a lockout if done early in startup (before debugger is able to halt core).

### Parameters

[in]	enable	<ul style="list-style-type: none"><li>false - disable serial wire data pin.</li><li>true - enable serial wire data pin (default after reset).</li></ul>
------	--------	---

Definition at line 648 of file `em_gpio.h`.

References [BUS\\_RegBitWrite\(\)](#).

---

```
__STATIC_INLINE void GPIO_DbgSW0Enable (bool enable )
```

Enable/Disable serial wire output pin.

### Note

Enabling this pin is not sufficient to fully enable serial wire output, which is also dependent on issues outside the GPIO module. Refer to [DBG\\_SW0Enable\(\)](#).

### Parameters

[in]	enable	<ul style="list-style-type: none"><li>• false - disable serial wire viewer pin (default after reset).</li><li>• true - enable serial wire viewer pin.</li></ul>
------	--------	---

Definition at line [676](#) of file [em\\_gpio.h](#).

References [BUS\\_RegBitWrite\(\)](#).

Referenced by [DBG\\_SW0Enable\(\)](#).

---

```
__STATIC_INLINE void GPIO_EM4DisablePinWakeup (uint32_t pinmask )
```

Disable GPIO pin wake-up from EM4.

### Parameters

[in]	pinmask	Bit mask containing the bitwise logic OR of which GPIO pin(s) to disable. Refer to Reference Manuals for pinmask to GPIO port/pin mapping.
------	---------	--

Definition at line [707](#) of file [em\\_gpio.h](#).

---



```
void GPIO_EM4EnablePinWakeup      ( uint32_t      pinmask,
                                   uint32_t      polaritymask
                                   )
```

Enable GPIO pin wake-up from EM4. When the function exits, EM4 mode can be safely entered.

## Note

It is assumed that the GPIO pin modes are set correctly. Valid modes are [gpioModeInput](#) and [gpioModeInputPull](#).

## Parameters

[in]	<code>pinmask</code>	A bitmask containing the bitwise logic OR of which GPIO pin(s) to enable. See Reference Manuals for a pinmask to the GPIO port/pin mapping.
[in]	<code>polaritymask</code>	A bitmask containing the bitwise logic OR of GPIO pin(s) wake-up polarity. See Reference Manuals for pinmask-to-GPIO port/pin mapping.

Definition at line `356` of file `em_gpio.c`.

References [GPIO\\_EM4SetPinRetention\(\)](#), and [GPIO\\_IntClear\(\)](#).

Referenced by [UTIL\\_shutdown\(\)](#).

```
__STATIC_INLINE void GPIO_EM4SetPinRetention      ( bool      enable )
```

Enable GPIO pin retention of output enable, output value, pull enable, and pull direction in EM4.

## Note

On series 0 devices EM4 gpio retention can either be turned on or off. On series 1 devices there are three EM4 GPIO retention modes available. These modes are "Disabled", "EM4EXIT" and "SWUNLATCH". Use the [EMU\\_EM4Init\(\)](#) to configure the GPIO retention mode on a series 1 device.

The behavior of this function depends on the configured GPIO retention mode. If the GPIO retention mode is configured to be "SWUNLATCH" then this function will not change

anything. If the retention mode is anything else then this function will set the GPIO retention mode to "EM4EXIT" when the enable argument is true, and "Disabled" when false.

## Parameters

[in]	enable	<ul style="list-style-type: none"><li>• true - enable EM4 pin retention.</li><li>• false - disable EM4 pin retention.</li></ul>
------	--------	---

Definition at line 760 of file `em_gpio.h`.

References [BUS\\_RegBitWrite\(\)](#).

Referenced by [GPIO\\_EM4EnablePinWakeup\(\)](#).

```
void GPIO_ExtIntConfig (GPIO_Port_TypeDef port,
                      unsigned int pin,
                      unsigned int intNo,
                      bool risingEdge,
                      bool fallingEdge,
                      bool enable
                      )
```

Configure the GPIO external pin interrupt.

It is recommended to disable interrupts before configuring the GPIO pin interrupt. See [GPIO\\_IntDisable\(\)](#) for more information.

The GPIO interrupt handler must be in place before enabling the interrupt.

Notice that any pending interrupt for the selected interrupt is cleared by this function.

## Note

On series 0 devices, the pin number parameter is not used. The pin number used on these devices is hardwired to the interrupt with the same number.

On series 1 devices, the pin number can be selected freely within a group. Interrupt numbers are divided into 4 groups (`intNo / 4`) and valid pin number within the interrupt groups are: 0: pins 0-3 (interrupt number 0-3) 1: pins 4-7 (interrupt number 4-7) 2: pins 8-11 (interrupt number 8-11) 3: pins 12-15 (interrupt number 12-15)

Parameters

[in]	port	The port to associate with the pin .
[in]	pin	The pin number on the port.
[in]	intNo	The interrupt number to trigger.
[in]	risingEdge	Set to true if the interrupt will be enabled on the rising edge. Otherwise, false.
[in]	fallingEdge	Set to true if the interrupt will be enabled on the falling edge. Otherwise, false.
[in]	enable	Set to true if the interrupt will be enabled after the configuration is complete. False to leave disabled. See <a href="#">GPIO_IntDisable()</a> and <a href="#">GPIO_IntEnable()</a> .

Definition at line 182 of file em\_gpio.c .

References [BUS\\_RegBitWrite\(\)](#) , [BUS\\_RegMaskedWrite\(\)](#) , and [GPIO\\_IntClear\(\)](#) .

Referenced by [BOARD\\_alsEnableIRQ\(\)](#) , [BOARD\\_envSensEnableIRQ\(\)](#) , [BOARD\\_gasSensorEnableIRQ\(\)](#) , [BOARD\\_hallSensorEnableIRQ\(\)](#) , [BOARD\\_imuEnableIRQ\(\)](#) , [BOARD\\_pushButtonEnableIRQ\(\)](#) , and [GPIO\\_IntConfig\(\)](#) .

```
__STATIC_INLINE void GPIO_InputSenseSet      (uint32_t val,
                                              uint32_t mask
                                              )
```

Enable/disable input sensing.

Disabling input sensing if not used, can save some energy consumption.

Parameters

[in]	val	Bitwise logic OR of one or more of: <ul style="list-style-type: none"><li>GPIO_INSENSE_INT - interrupt input sensing.</li><li>GPIO_INSENSE_PRS - peripheral reflex system input sensing.</li></ul>
[in]	mask	Mask containing bitwise logic OR of bits similar as for val used to

indicate which input sense options to disable/enable.

Definition at line 806 of file `em_gpio.h`.

Referenced by `ezradio_hal_GpioInit()`.

```
__STATIC_INLINE void GPIO_IntClear          (uint32_t flags )
```

Clear one or more pending GPIO interrupts.

### Parameters

[in]	flags	Bitwise logic OR of GPIO interrupt sources to clear.
------	-------	--

Definition at line 823 of file `em_gpio.h`.

Referenced by `BOARD_alsClearIRQ()`, `BOARD_gasSensorClearIRQ()`, `BOARD_hallSensorClearIRQ()`, `BOARD_imuClearIRQ()`, `BOARD_picGetFwRevision()`, `BOARD_pushButton0ClearIRQ()`, `BOARD_pushButton1ClearIRQ()`, `GPIO_EM4EnablePinWakeup()`, `GPIO_ExtIntConfig()`, and `GPIOINT_CallbackRegister()`.

```
__STATIC_INLINE void          (GPIO_Port_TypeDef port,
GPIO_IntConfig               unsigned int pin,
                             bool risingEdge,
                             bool fallingEdge,
                             bool enable
                             )
```

Configure GPIO interrupt.

If reconfiguring a GPIO interrupt that is already enabled, it is generally recommended to disable it first, see `GPIO_Disable()`.

The actual GPIO interrupt handler must be in place before enabling the interrupt.

Notice that any pending interrupt for the selected pin is cleared by this function.

#### Deprecated:

Deprecated function. New code should use [GPIO\\_ExtIntConfig\(\)](#).

#### Note

A certain pin number can only be associated with one port; i.e., if GPIO interrupt 1 is assigned to port A/pin 1, then it is not possible to use pin 1 from any other ports for interrupts. Refer to the reference manual. On devices which implement GPIO\_EXTIPINSEL registers a more flexible approach is possible, refer to [GPIO\\_ExtIntConfig\(\)](#).

#### Parameters

[in]	<code>port</code>	The port to associate with <code>pin</code> .
[in]	<code>pin</code>	The pin number on the port ( == GPIO EXTI interrupt number).
[in]	<code>risingEdge</code>	Set to true if interrupts will be enabled on rising edge, otherwise false.
[in]	<code>fallingEdge</code>	Set to true if interrupts will be enabled on falling edge, otherwise false.
[in]	<code>enable</code>	Set to true if interrupt will be enabled after configuration completed, false to leave disabled. See <a href="#">GPIO_IntDisable()</a> and <a href="#">GPIO_IntEnable()</a> .

Definition at line `1296` of file `em_gpio.h`.

References [GPIO\\_ExtIntConfig\(\)](#).

Referenced by [BOARD\\_init\(\)](#), [BOARD\\_pushButtonEnableIRQ\(\)](#), and [ezradio\\_hal\\_GpioInit\(\)](#).

---

```
__STATIC_INLINE void GPIO_IntDisable          ( uint32_t  flags )
```

Disable one or more GPIO interrupts.

#### Parameters

[in]	<code>flags</code>	GPIO interrupt sources to disable.
------	--------------------	------------------------------------

Definition at line `839` of file `em_gpio.h`.

Referenced by `BOARD_picGetFwRevision()`, and `DisableSi114xInterrupt()`.

---

```
__STATIC_INLINE void GPIO_IntEnable          ( uint32_t  flags )
```

Enable one or more GPIO interrupts.

### Note

Depending on the use, a pending interrupt may already be set prior to enabling the interrupt. To ignore a pending interrupt, consider using `GPIO_IntClear()` prior to enabling the interrupt.

### Parameters

[in]	flags	GPIO interrupt sources to enable.
------	-------	-----------------------------------

Definition at line `856` of file `em_gpio.h`.

Referenced by `BOARD_picGetFwRevision()`, and `EnableSi114xInterrupt()`.

---

```
__STATIC_INLINE uint32_t GPIO_IntGet          ( void      )
```

Get pending GPIO interrupts.

### Returns

GPIO interrupt sources pending.

Definition at line `868` of file `em_gpio.h`.

---

```
__STATIC_INLINE uint32_t GPIO_IntGetEnabled  ( void      )
```

Get enabled and pending GPIO interrupt flags. Useful for handling more interrupt sources in the same interrupt handler.

**Note**

Interrupt flags are not cleared by the use of this function.

**Returns**

Pending and enabled GPIO interrupt sources. The return value is the bitwise AND combination of

- the OR combination of enabled interrupt sources in GPIO\_IEN register and
- the OR combination of valid interrupt flags in GPIO\_IF register.

Definition at line 888 of file `em_gpio.h` .

Referenced by `GPIOINT_CallbackRegister()` .

```
__STATIC_INLINE void GPIO_IntSet          ( uint32_t flags )
```

Set one or more pending GPIO interrupts from SW.

**Parameters**

[in]	flags	GPIO interrupt sources to set to pending.
------	-------	---

Definition at line 907 of file `em_gpio.h` .

Referenced by `EnableSi114xInterrupt()` .

```
__STATIC_INLINE unsigned int GPIO_PinInGet ( GPIO_Port_TypeDef port, unsigned int pin )
```

Read the pad value for a single pin in a GPIO port.

**Parameters**

[in]	port	The GPIO port to access.
------	------	--------------------------

[in]	pin	The pin number to read.
------	-----	-------------------------

### Returns

The pin value, 0 or 1.

Definition at line 938 of file `em_gpio.h`.

References `BUS_RegBitRead()`.

Referenced by `ADC0_IRQHandler()`, `BSP_McuBoard_UsbVbusOcFlagGet()`, `EnableSi114xInterrupt()`, `ezradio_hal_NirqLevel()`, and `TOUCH_IsBusy()`.

```
GPIO_Mode_TypeDef GPIO_PinModeGet (GPIO_Port_TypeDef port,
                                   unsigned int      pin)
                                   )
```

Get the mode for a GPIO pin.

### Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin number in the port.

### Returns

The pin mode.

Definition at line 327 of file `em_gpio.c`.

```
void GPIO_PinModeSet (GPIO_Port_TypeDef port,
                     unsigned int      pin,
                     GPIO_Mode_TypeDef mode,
                     unsigned int      out)
                     )
```



Set the mode for a GPIO pin.

## Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin number in the port.
[in]	mode	The desired pin mode.
[in]	out	A value to set for the pin in the DOUT register. The DOUT setting is important for some input mode configurations to determine the pull-up/down direction.

Definition at line 278 of file `em_gpio.c`.

References `GPIO_PinOutClear()`, `GPIO_PinOutSet()`, and `gpioModeDisabled`.

Referenced by `ADC0_IRQHandler()`, `BOARD_envSensEnable()`, `BOARD_flashDeepPowerDown()`, `BOARD_gasSensorEnable()`, `BOARD_hallSensorEnable()`, `BOARD_init()`, `BSP_BccPinsEnable()`, `BSP_BusControlModeSet()`, `BSP_EbiInit()`, `BSP_initBoard()`, `BSP_McuBoard_DeInit()`, `BSP_McuBoard_Init()`, `BSP_McuBoard_UsbVbusPowerEnable()`, `CAPLESENSE_setupGPIO()`, `CMU_ClkOutPinConfig()`, `DBG_SW0Enable()`, `ezradio_hal_GpioInit()`, `gpioInit()`, `I2CSPM_Init()`, `ICM20648_spiInit()`, `initGpio()`, `KSZ8851SNL_SPI_Init()`, `MIC_deInit()`, `MIC_init()`, `MICROSD_Deinit()`, `MICROSD_Init()`, `MSDD_Init()`, `RETARGET_SerialEnableFlowControl()`, `RETARGET_SerialInit()`, `sl_efp_init()`, `SPI_TFT_Init()`, `TFT_DirectGPIOConfig()`, and `UTIL_shutdown()`.

```
__STATIC_INLINE void GPIO_PinOutClear (GPIO_Port_TypeDef port,
                                       unsigned int      pin
                                       )
```

Set a single pin in GPIO data out port register to 0.

## Note

In order for the setting to take effect on the output pad, the pin must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

## Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin to set.

Definition at line 986 of file `em_gpio.h`.

References `BUS_RegMaskedClear()`.

Referenced by `BOARD_envSensEnable()`, `BOARD_flashDeepPowerDown()`, `BOARD_gasSensorEnable()`, `BOARD_gasSensorWake()`, `BOARD_hallSensorEnable()`, `BOARD_imuEnable()`, `BOARD_ledSet()`, `BOARD_micEnable()`, `BOARD_picGetFwRevision()`, `BOARD_rgblEdEnable()`, `BOARD_rgblEdPowerEnable()`, `BSP_McuBoard_UsbStatusLedEnable()`, `CAPT_enable()`, `ezradio_hal_ClearNsel()`, `ezradio_hal_DeassertShutdown()`, `GPIO_PinModeSet()`, `I2CSPM_Init()`, `KSZ8851SNL_SPI_SetChipSelect()`, `sl_efp_enter_em2()`, and `SPI_TFT_WriteRegister()`.

```
__STATIC_INLINE unsigned int      (GPIO_Port_TypeDef port,  
GPIO_PinOutGet                  unsigned int      pin  
                                )
```

Get current setting for a pin in a GPIO port data out register.

## Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin to get setting for.

## Returns

The DOUT setting for the requested pin, 0 or 1.

Definition at line 1011 of file `em_gpio.h`.

References [BUS\\_RegBitRead\(\)](#) .

```
__STATIC_INLINE void GPIO_PinOutSet (GPIO_Port_TypeDef port,
                                     unsigned int pin
                                     )
```

Set a single pin in GPIO data out register to 1.

## Note

In order for the setting to take effect on the output pad, the pin must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

## Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin to set.

Definition at line 1033 of file `em_gpio.h` .

References [BUS\\_RegMaskedSet\(\)](#) .

Referenced by [BOARD\\_envSensEnable\(\)](#) , [BOARD\\_flashDeepPowerDown\(\)](#) , [BOARD\\_gasSensorEnable\(\)](#) , [BOARD\\_gasSensorWake\(\)](#) , [BOARD\\_hallSensorEnable\(\)](#) , [BOARD\\_imuEnable\(\)](#) , [BOARD\\_ledSet\(\)](#) , [BOARD\\_micEnable\(\)](#) , [BOARD\\_picGetFwRevision\(\)](#) , [BOARD\\_rgbledEnable\(\)](#) , [BOARD\\_rgbledPowerEnable\(\)](#) , [BSP\\_McuBoard\\_UsbStatusLedEnable\(\)](#) , [CAPT\\_enable\(\)](#) , [ezradio\\_hal\\_AssertShutdown\(\)](#) , [ezradio\\_hal\\_SetNsel\(\)](#) , [GPIO\\_PinModeSet\(\)](#) , [I2CSPM\\_Init\(\)](#) , [initEbiCommon\(\)](#) , [KSZ8851SNL\\_SPI\\_SetChipSelect\(\)](#) , [sl\\_efp\\_enter\\_em0\(\)](#) , and [SPI\\_TFT\\_WriteRegister\(\)](#) .

```
__STATIC_INLINE void GPIO_PinOutToggle (GPIO_Port_TypeDef port,
                                       unsigned int pin
                                       )
```

Toggle a single pin in GPIO port data out register.

## Note

In order for the setting to take effect on the output pad, the pin must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

## Parameters

[in]	port	The GPIO port to access.
[in]	pin	The pin to toggle.

Definition at line 1060 of file `em_gpio.h`.

---

```
__STATIC_INLINE uint32_t GPIO_PortInGet (GPIO_Port_TypeDef port)
```

Read the pad values for GPIO port.

## Parameters

[in]	port	The GPIO port to access.
------	------	--------------------------

Definition at line 1080 of file `em_gpio.h`.

Referenced by `BOARD_pushButtonGetState()`.

---

```
__STATIC_INLINE void GPIO_PortOutClear (GPIO_Port_TypeDef port,
                                         uint32_t pins)
)
```

Set bits in DOUT register for a port to 0.

## Note

In order for the setting to take effect on the output pad, the pin must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

Parameters

[in]	port	The GPIO port to access.
[in]	pins	Bit mask for bits to clear in DOUT register.

Definition at line 1102 of file em\_gpio.h .

References [BUS\\_RegMaskedClear\(\)](#) .

```
__STATIC_INLINE uint32_t GPIO_PortOutGet (GPIO_Port_TypeDef port )
```

Get current setting for a GPIO port data out register.

Parameters

[in]	port	The GPIO port to access.
------	------	--------------------------

Returns

The data out setting for the requested port.

Definition at line 1124 of file em\_gpio.h .

```
__STATIC_INLINE void GPIO_PortOutSet (GPIO_Port_TypeDef port,
                                     uint32_t pins
                                     )
```

Set bits GPIO data out register to 1.

Note

In order for the setting to take effect on the respective output pads, the pins must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

Parameters

[in]	port	The GPIO port to access.
------	------	--------------------------

[in]	pins	Bit mask for bits to set to 1 in DOUT register.
------	------	---

Definition at line 1146 of file em\_gpio.h .

References [BUS\\_RegMaskedSet\(\)](#) .

```

__STATIC_INLINE void GPIO_PortOutSetVal (GPIO_Port_TypeDef port,
                                         uint32_t val,
                                         uint32_t mask
                                         )

```

Set GPIO port data out register.

**Note**

In order for the setting to take effect on the respective output pads, the pins must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

**Parameters**

[in]	port	The GPIO port to access.
[in]	val	Value to write to port data out register.
[in]	mask	Mask indicating which bits to modify.

Definition at line 1176 of file em\_gpio.h .

```

__STATIC_INLINE void GPIO_PortOutToggle (GPIO_Port_TypeDef port,
                                         uint32_t pins
                                         )

```

Toggle pins in GPIO port data out register.

**Note**

In order for the setting to take effect on the output pad, the pin must have been configured properly. If not, it will take effect whenever the pin has been properly configured.

Parameters

[in]	port	The GPIO port to access.
[in]	pins	Bit mask with pins to toggle.

Definition at line 1200 of file em\_gpio.h .

---

```
__STATIC_INLINE void      (GPIO_Port_TypeDef port,
GPIO_Slewrateset         uint32_t slewrateset,
                          uint32_t slewratesetAlt
                          )
```

Set slewrateset for pins on a GPIO port.

Parameters

[in]	port	The GPIO port to configure.
[in]	slewrateset	The slewrateset to configure for pins on this GPIO port.
[in]	slewratesetAlt	The slewrateset to configure for pins using alternate modes on this GPIO port.

Definition at line 1224 of file em\_gpio.h .

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