

Anqi Li

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EDUCATION

Peking University Sep 2023 - present
B.S. student in Intelligent Science and Technology
Research Advisor: [He Wang](#); GPA: 3.70/4

RESEARCH EXPERIENCE

Galbot Feb 2025 - present
Research Intern, Dept. of Large Models

RESEARCH INTEREST

My long-term goal is to develop intelligent robotic systems that operate reliably in complex human-centered environments. Currently, I focus on *embodied navigation* using vision-language-action (VLA) models, exploring how general intelligence enable robust navigation behaviors. In the future, I hope to extend these ideas toward broader human-centered robotic intelligence, integrating perception, reasoning, and action in a unified manner.

PUBLICATIONS AND PREPRINTS

[1] **Anqi Li***, Zhiyong Wang*, Jiazhao Zhang*, Minghan Li, Yunpeng Qi, Zhibo Chen, Zhizheng Zhang†, He Wang†. *UrbanVLA: A Vision-Language-Action Model for Urban Micromobility*. [arXiv preprint](#), 2025.

[2] Jiazhao Zhang*, **Anqi Li***, Yunpeng Qi*, Minghan Li*, Jiahang Liu, Shaoan Wang, Haoran Liu, Gengze Zhou, Yuze Wu, Xingxing Li, Yuxin Fan, Wenjun Li, Zhibo Chen, Fei Gao, Qi Wu, Zhizheng Zhang†, He Wang† *Embodied Navigation Foundation Model*. [arXiv preprint](#), 2025.

[3] Shaoan Wang*, Jiazhao Zhang*, Minghan Li, Jiahang Liu, **Anqi Li**, Kui Wu, Fangwei Zhong, Junzhi Yu, Zhizheng Zhang, He Wang. *TrackVLA: Embodied Visual Tracking in the Wild*. [CoRL 2025](#).