Anqi Li

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EDUCATION

Peking University Sep 2023 - present
B.S. in Intelligent Science and Technology
Advisor: He Wang   GPA: 3.70/4.00

RESEARCH EXPERIENCE

Galbot Feb 2025 - present
Research Intern, Department of Large Models
Working on multimodal foundation models for embodied navigation.

RESEARCH INTERESTS

My long-term research goal is to build intelligent robotic systems that operate reliably in complex, human-centered environments. Currently, I focus on *embodied navigation* with vision-language-action (VLA) models, exploring how general intelligence enables robust and adaptive navigation behaviors. In the future, I hope to extend these ideas toward a more unified framework of human-centered robotic intelligence that seamlessly integrates perception, reasoning, and action.

PUBLICATIONS AND PREPRINTS

[1] **Anqi Li***, Zhiyong Wang*, Jiazhao Zhang*, Minghan Li, Yunpeng Qi, Zhibo Chen, Zhizheng Zhang†, He Wang†. *UrbanVLA: A Vision-Language-Action Model for Urban Micromobility.* **arXiv preprint arXiv:2510.23576**, 2025.

[2] Jiazhao Zhang*, **Anqi Li***, Yunpeng Qi*, Minghan Li*, Jiahang Liu, Shaoan Wang, Haoran Liu, Gengze Zhou, Yuze Wu, Xingxing Li, Yuxin Fan, Wenjun Li, Zhibo Chen, Fei Gao, Qi Wu, Zhizheng Zhang†, He Wang† *Embodied Navigation Foundation Model.* **arXiv preprint arXiv:2509.12129**, 2025.

[3] Shaoan Wang*, Jiazhao Zhang*, Minghan Li, Jiahang Liu, **Anqi Li**, Kui Wu, Fangwei Zhong, Junzhi Yu, Zhizheng Zhang, He Wang. *TrackVLA: Embodied Visual Tracking in the Wild.* **CoRL 2025**.