```
#define _XTAL_FREQ 20000000
#define Baud_rate 9600
// DEFINING LCD PINS
#define RS RB0
#define EN RB1
#define D4 RB2
#define D5 RB3
#define D6 RB4
#define D7 RB5
#include <xc.h>
#include "LCD16.h"// HEADER FILE TO USE LCD
void Initialize_UART(void)
  /**Setting I/O pins for UART*/
  TRISC6 = 0; // TX Pin set as output
  TRISC7 = 1; // RX Pin set as input
  SPBRG = ((_XTAL_FREQ/16)/Baud_rate) - 1;
  BRGH = 1; // for high baud_rate
  SYNC = 0; // Asynchronous
  SPEN = 1; // Enable serial port pins
```

```
TXEN = 1; // enable transmission
  CREN = 1; // enable reception
  TX9 = 0; // 8-bit reception selected
  RX9 = 0; // 8-bit reception mode selected
}
char UART_get_char()
{
if (PIR1bits.RCIF==1){ // IF DATA IS AVAILABLE
  if(OERR)
    CREN = 0;
    CREN = 1;
  }
  return RCREG; //receive the value and send it to main function
  }}
void delay(){
                      //DELAY FUNCTION
  for (int i=0;i<700;i++){
    for (int z=0;z<1000;z++){}
  }
```

```
}}
void lcdhome(void){ //LCD FUNCTION FOR STATUS DISPLAY
  Lcd_Clear();
    Lcd_Set_Cursor(1,1);
  Lcd_Print_String("L1 L2 L3 L4 L5");
  if (RD0==0){
    Lcd_Set_Cursor(2,1);
    Lcd_Print_String("OFF");
  }
  else if(RD0==1)
  {
    Lcd_Set_Cursor(2,1);
    Lcd_Print_String("ON ");
  }
  if (RD1==0){
    Lcd_Set_Cursor(2,4);
    Lcd_Print_String("OFF");
  }
  else if(RD1==1)
  {
    Lcd_Set_Cursor(2,4);
    Lcd_Print_String("ON ");
  }
  if (RD2==0){
    Lcd_Set_Cursor(2,7);
    Lcd_Print_String("OFF");
  }
```

```
else if(RD2==1)
{
  Lcd_Set_Cursor(2,7);
  Lcd_Print_String("ON ");
}
if (RD3==0){
  Lcd_Set_Cursor(2,10);
  Lcd_Print_String("OFF");
}
else if(RD3==1)
{
  Lcd_Set_Cursor(2,10);
  Lcd_Print_String("ON ");
if (RD4==0){
  Lcd_Set_Cursor(2,13);
  Lcd_Print_String("OFF");
}
else if(RD4==1)
{
  Lcd_Set_Cursor(2,13);
  Lcd_Print_String("ON ");
}
delay();
Lcd_Set_Cursor(1,1);
Lcd_Print_String("L6 L7 L8 L9 L10");
```

```
if (RD5==0){
  Lcd_Set_Cursor(2,1);
  Lcd_Print_String("OFF");
}
else if(RD5==1)
{
  Lcd_Set_Cursor(2,1);
  Lcd_Print_String("ON ");
}
  if (RD6==0){
  Lcd_Set_Cursor(2,4);
  Lcd_Print_String("OFF");
}
else if(RD6==1)
{
  Lcd_Set_Cursor(2,4);
  Lcd_Print_String("ON ");
}
 if (RD7==0){
  Lcd_Set_Cursor(2,7);
  Lcd_Print_String("OFF");
}
else if(RD7==1)
{
  Lcd_Set_Cursor(2,7);
  Lcd_Print_String("ON ");
```

```
}
    if (RC1==0){
    Lcd_Set_Cursor(2,10);
    Lcd_Print_String("OFF");
  }
  else if(RC1==1)
  {
    Lcd_Set_Cursor(2,10);
    Lcd_Print_String("ON ");
  }
    if (RC2==0){
    Lcd_Set_Cursor(2,13);
    Lcd_Print_String("OFF");
  }
  else if(RC2==1)
  {
    Lcd_Set_Cursor(2,13);
    Lcd_Print_String("ON ");
  }
  delay();
  return;
int main()
```

```
TRISB = 0x00; // INITIALIZING PORT B AS OUTPUT PORT
  TRISC=0x00; // INITIALIZING PORT C AS OUTPUT PORT
   RC1=0;//INITIALIZING PIN AS OUTPUT
 RC2=0;
  Lcd_Start();
    Lcd_Clear();
    Lcd_Set_Cursor(1,1);
     Lcd_Print_String("HOME AUTOMATION");
    int get_value;
    TRISD=0x00;// INITIALIZING PORT D AS OUTPUT PORT
    PORTD=0x00;
  Initialize_UART(); //Initialize UART module
  while(1) //Infinite loop
  {
    lcdhome();
   get_value= UART_get_char();
     /** COMPAIRING VALUE RECIEVED FROM SERIAL WITH OUR DESIRED INPUT AND THEN
CHANGING STATUS OF
      RESPECTIVE */
    if (get_value == '1')
    {
```

```
RD0=!RD0; //TOGGLING ON/OFF ACCORDING TO INPUT
  lcdhome();//CALLING FUNCTION TO DISPLAY CHANGE IN STATUS ON LCD
 }
else if (get_value == '2')
 {
  RD1=!RD1;
  lcdhome();
 }
 else if (get_value == '3')
 {
  RD2=!RD2;
  lcdhome();
 else if (get_value == '4')
  RD3=!RD3;
  lcdhome();
 else if (get_value == '5')
 {
  RD4=!RD4;
  lcdhome();
 }
 else if (get_value == '6')
 {
  RD5=!RD5;
  lcdhome();
```

```
}
    else if (get_value == '7')
     RD6=!RD6;
     lcdhome();
    }
    else if (get_value == '8')
    {
     RD7=!RD7;
     lcdhome();
    }
    else if (get_value == '9')
    {
     RC1=!RC1;
     lcdhome();
    else if (get_value == '0')
     RC2=!RC2;
     lcdhome();
    }
  }
}
```