

Development tools and software support

Ege Üniversitesi Müh. Fakültesi

Bilgisayar Mühendisliği Bölümü

Gömülü ve Gerçek Zamanlı Sistemler

2013

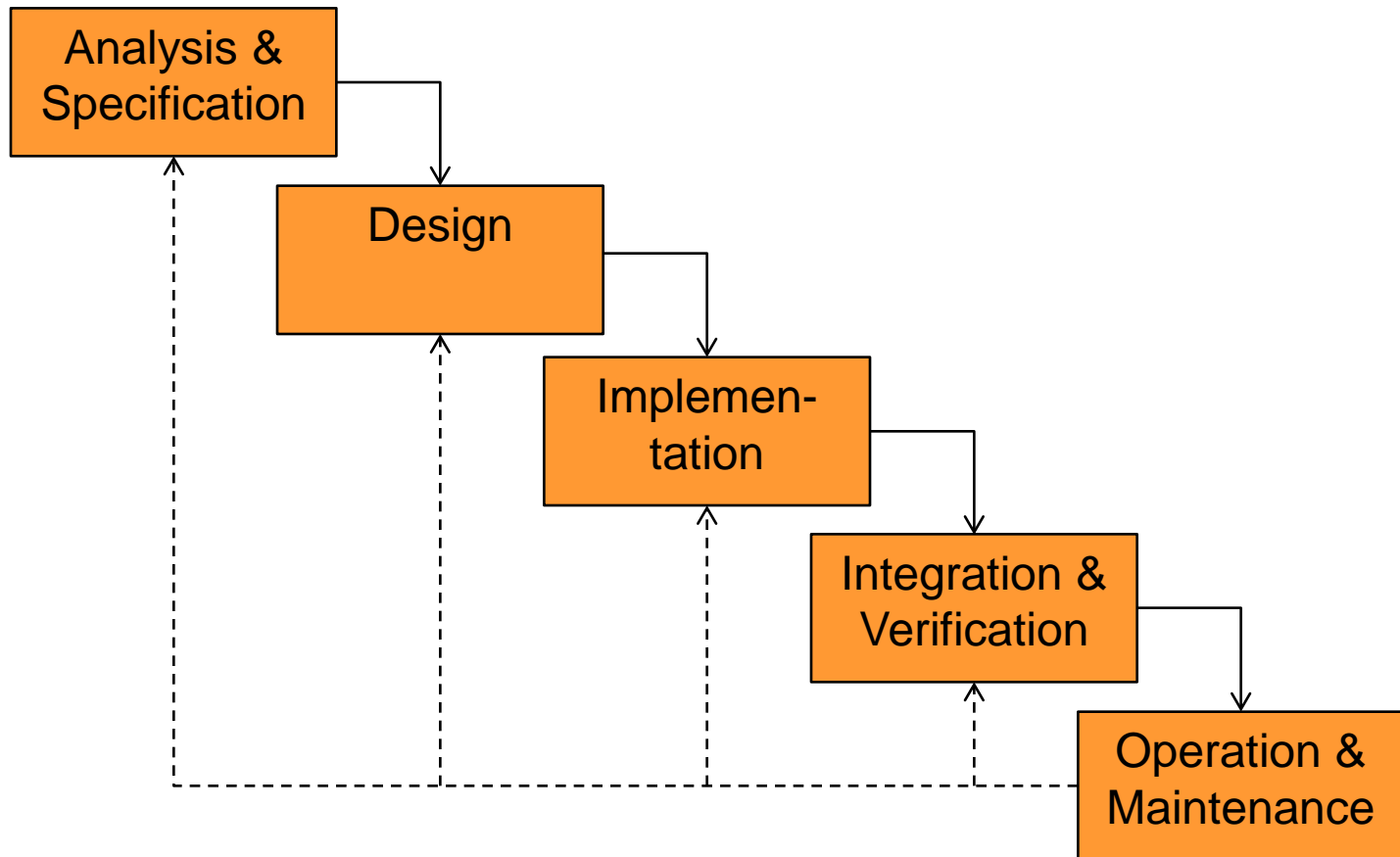
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Introduction

- C was introduced in 1972 by Dennis Richie
- Designed as programming language for UNIX
- Two important dialects:
 - K&R:
 - Kernighan & Richie style
 - Language launch
 - Obsolete
 - ANSI C:
 - Current and most significant dialect
- Characteristics
 - High level language
 - Abstract processor view
 - High availability
 - Close to hardware
 - Control and data structures

Development Process I

- Water fall model
 - A simple model



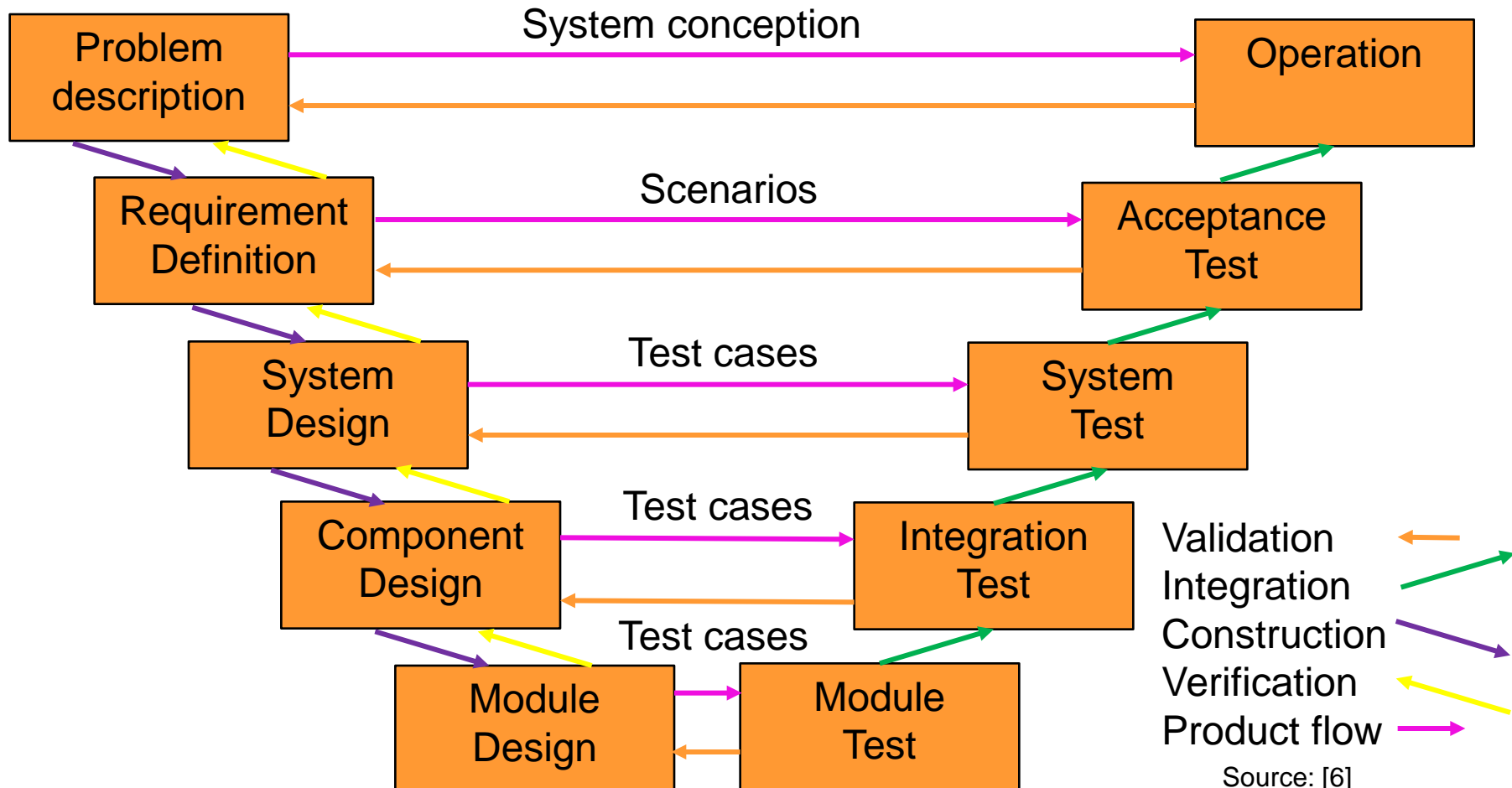
Development Process II

- Analysis & Specification
 - Problem analysis with constraints
 - Requirements Specification
- Design
 - System architecture
 - Hardware/Software Partitioning
- Implementation
 - Module realization
 - Subsystem (module) tests
- Integration & Verification
 - Module Composition
 - System tests
- Operation & Maintenance
 - System launch
 - Functional extension

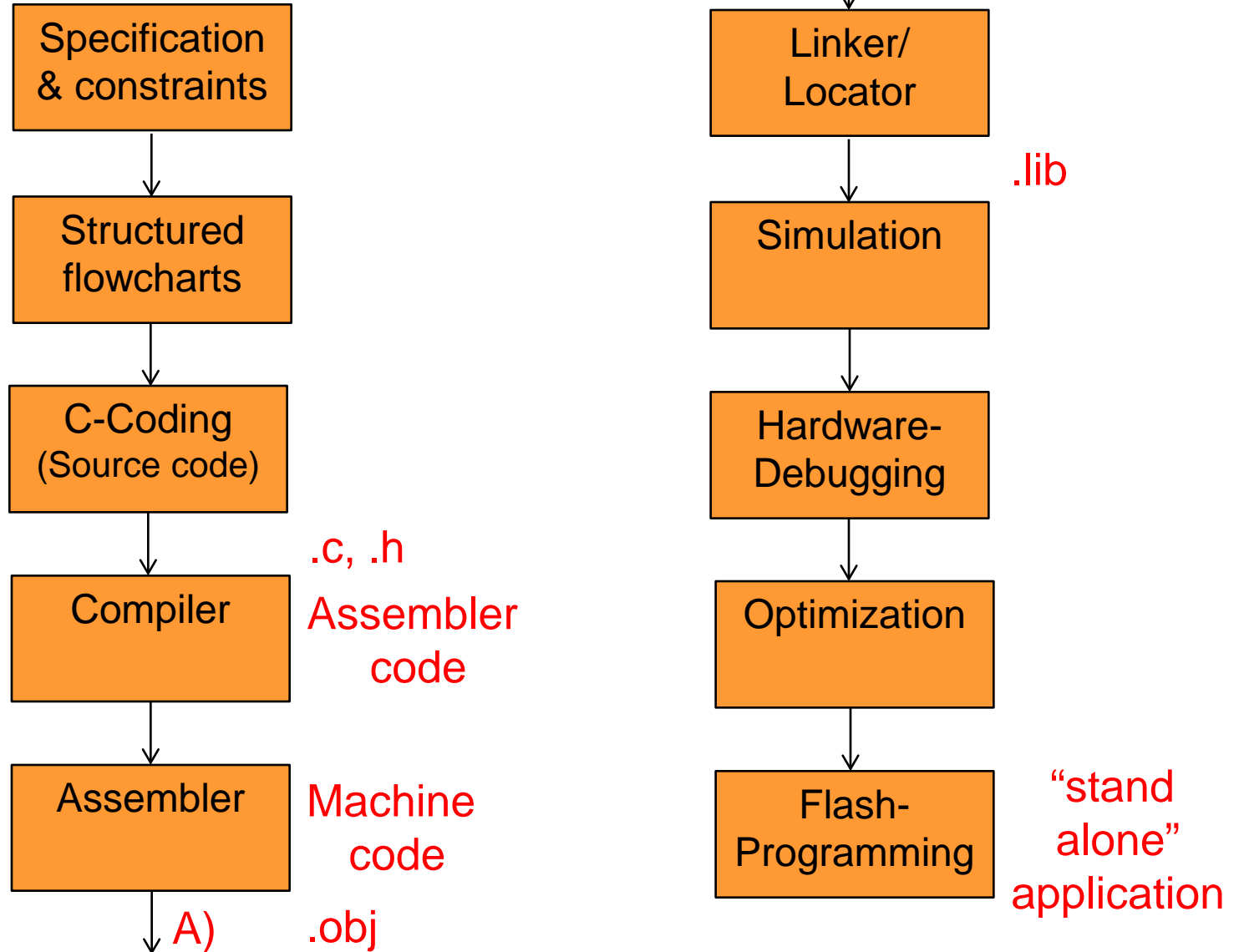
Main focus

Development Process III: V-Model

- V-Model: Approach model - in German “**V**orgehens-Modell”



Design flow I




Design flow II

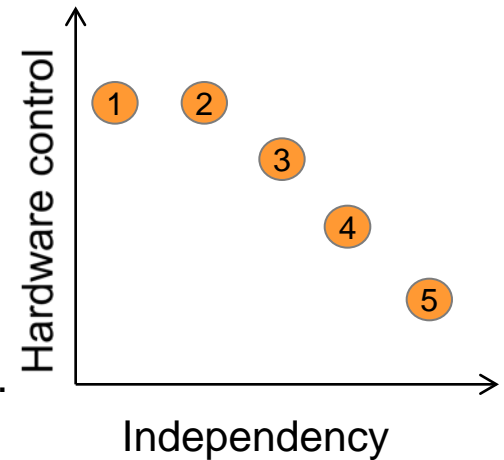
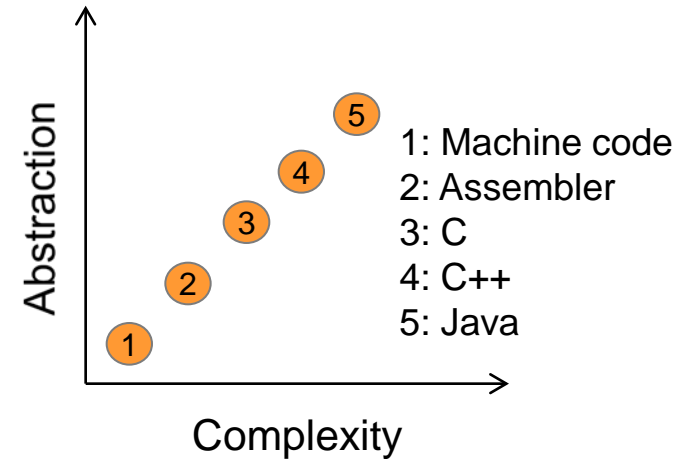
- Compiler
 - Translation of high level instructions to Assembler or Machine code
 - Machine code (Native code): sequence of CPU instructions (binary data)
- Assembler
 - Mnemonics: 1:1 representation of machine code
- Linker/Locator
 - Module binding and attaching physical address
- Optimization
 - Optimizing tool for speed or area
- Simulator
 - Source code testing on host PC
- Debugging
 - Source code testing on target
 - Levels: source level, machine code

Design flow III

- IDE – Integrated Development Environment
 - Complete development frame including translation and test tools
- Files:
 - Source code: .c:
 - Function implementation
 - Definition global variables
 - Header files: .h
 - Declarations: functions, data types
 - .obj: object file
 - .lib: library file

C versus Assembler

- C
 - Pros
 - Higher abstraction
 - Portable
 - Better readable
 - Early syntax check
 - Cons
 - Less performance than Assembler
- Assembler
 - Pros
 - Closer hardware control
 - Commonly faster and less resources
 - Cons
 - More prone to errors. Extensive testing required.
-  Focus: C language + StellarisWare®



Embedded C

- C language is general purpose
 - Developing programs for data processing or embedded systems
 - Embedded software often must have immediate hardware access to internal peripherals
- For the different requirements of the applications
 - An add on or a reduction of the general C language is necessary
 - This is called “Embedded C”
- This has consequences to the main advantage of a high level language: the Portability
- Microcontroller-specific categories:
 - Memory: program and data memory
 - Peripherals: Inputs/Outputs, timers etc.
 - Interrupts: sources, priority

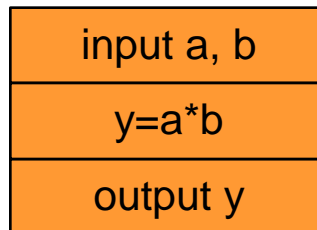
Design elements

- Pseudo code
- Flowchart
- Structured flowcharts (Nassi Shneiderman diagrams)

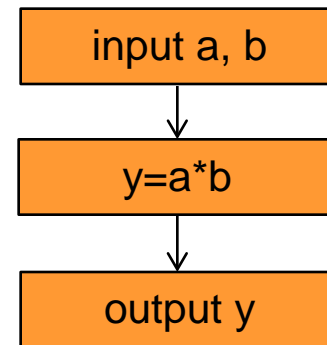
Pseudo
code

$y=a*b$

Structured
flowchart



Flowchart



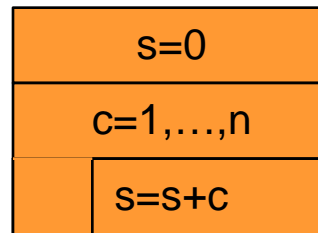
Source: [3]

Design elements: loops

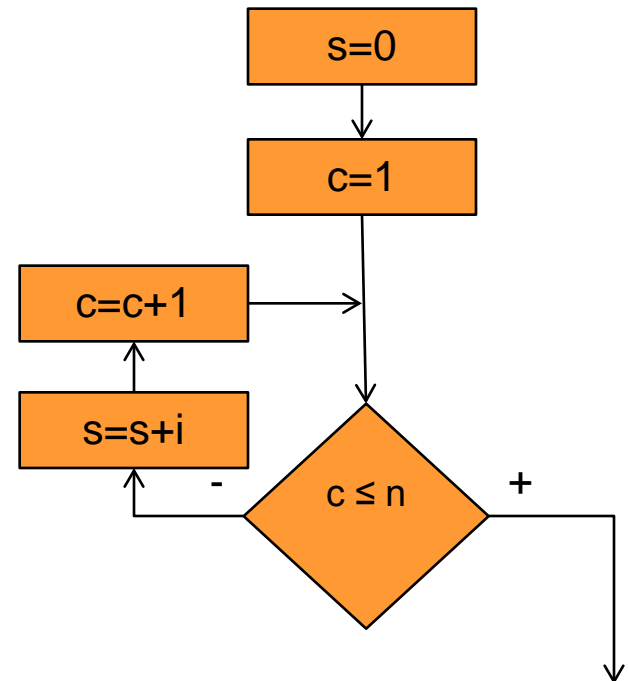
Pseudo code

```
s=0
for c=1,...,n
  s=s+c
end
```

Structured flowchart



Flowchart



+ : true
- : false

Source: [3]

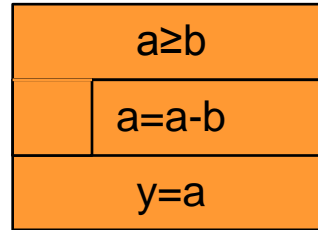
Design elements: loops

Pseudo code

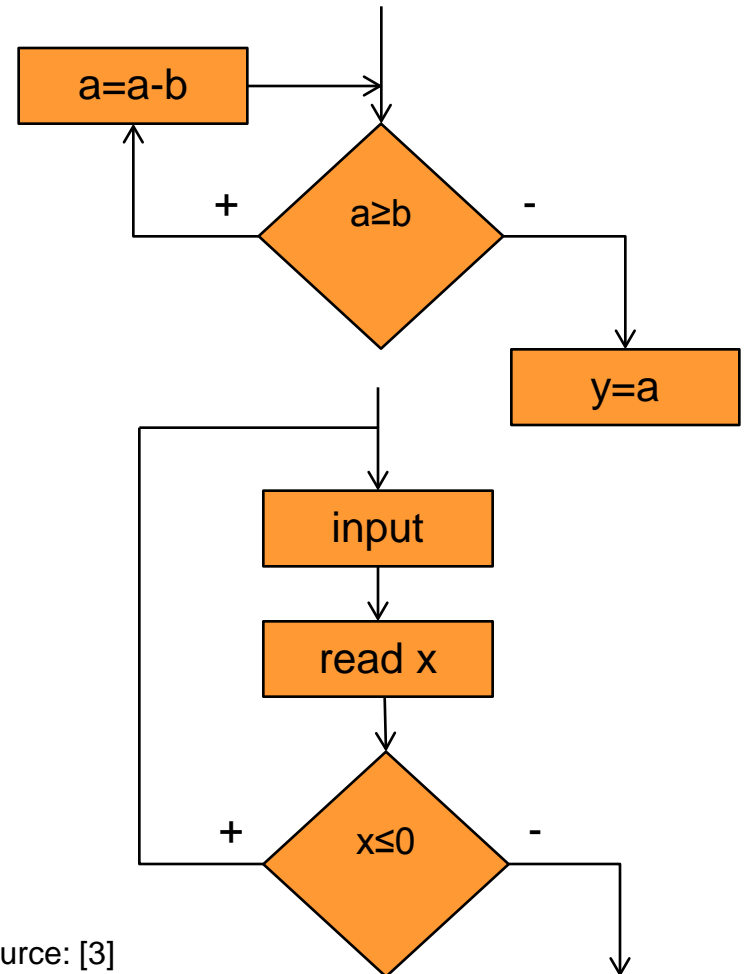
Example: $y \bmod b$

```
while  $a \geq b$   
   $a = a - b$   
end  
 $y = a$ 
```

Structured flowchart

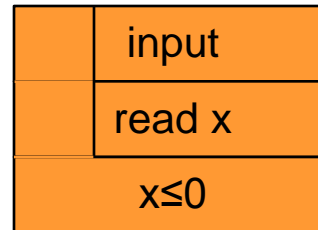


Flowchart



Example: input $x > 0$

```
do  
  input  
  read x  
while  $x \leq 0$ 
```



Alternative: repeat...until

Source: [3]

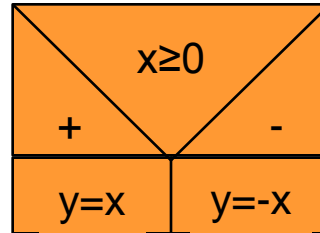
Design elements: conditions

Pseudo code

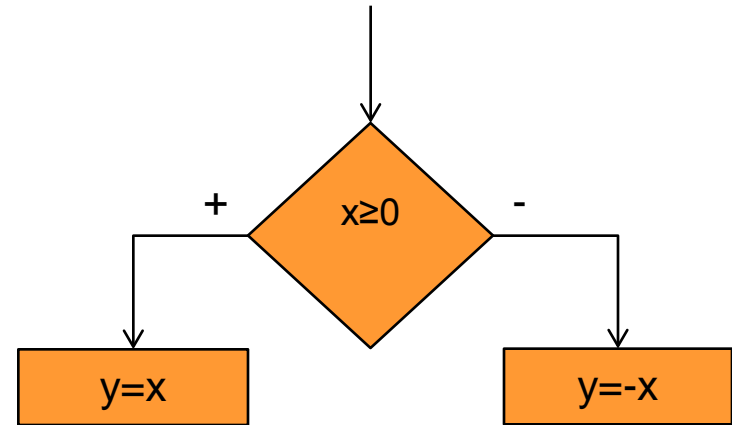
Example: $y = x$, if $x \geq 0$
 $-x$, otherwise

```
if  $x \geq 0$ 
   $y = x$ 
else
   $y = -x$ 
end
```

Structured flowchart

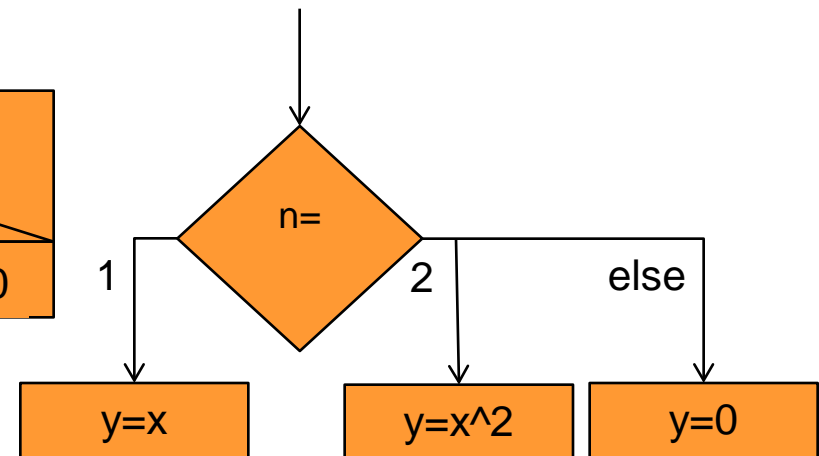
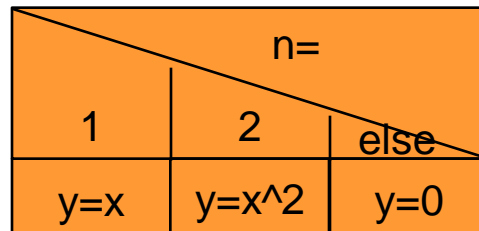


Flowchart



Example: $y = x$, if $n = 1$
 x^2 , if $n = 2$,
 0, otherwise

```
switch n=
  case 1:  $y = x$ 
  case 2:  $y = x^2$ 
  else    $y = 0$ 
```



Alternative:
if...else

Source: [3]

Pre-processor

- C uses an upstream pre-processor
- Characteristics
 - C independent
 - Starting with #
 - Instruction ends without semicolon
 - Erases comments
- simple macros
 - #include <name.h> (header file)
 - Default path for name.h
 - #define
 - Example: #define GPIO_PORTG_DATA_BITS_R ((volatile unsigned long *) 0x40026000)
 - #pragma
 - Pragma directives control the Compiler for implementation specific operations.

Data types

- Integer
 - Char: ASCII, 8 bits
 - Short: 8 bits
 - Int: 16 bits
 - Long: 32 bits
 - Note: compiler/architecture specific identifiers
- Floating point types
 - Float: 32 bits
 - Double: 64 bits
 - Long double: 80 bits
- Arrays:
 - Example: `int adc_val = {1,2,3,4,5};`

Operations

Operator	Description	Example
+, -, *, /, %	addition, subtraction multiplication, division, Modulo	int y=a+b;
+, -	Sign	int y=-a;
++, --	increment, decrement	int y=a++;
&,	bitwise and, or	int y= a & 0x01;
~	bit negation	int y=~a;
^	bit exclusive or	int y=a^0x01;
<<, >>	bit shift left, right	int y=a<<4;
&&,	logic or, and	int y= a 0x01;
!	logic not	int y=(!(a==b))
==, !=	equal, not equal	if (y==0)
<, >, <=, >=	comparison	if (y<0)
=, +=, &=, ...		int y+=5;
*, &	pointer, address	int y=*a;

Instructions

Instructions	Description	Example
<pre>if (cond) instr else instr</pre>	conditional statements	<pre>if (a==0) y=0; else y=1;</pre>
<pre>switch (n) { case cond1: instr1; case cond2: instr2; default: instr3; }</pre>	switch statements multiway branches	<pre>switch (n) { case 1: y=x; case 2: y=x^2; default: y=0; }</pre>
<pre>for (init; cond; incr) instr.</pre>	number of iteration is known	<pre>for (i=0;i<5;i++) {y=y+1;}</pre>
<pre>while (cond) instr</pre>	pre-test loop	<pre>while (a>0) y++;</pre>
<pre>do intr while (cond)</pre>	post-test loop	<pre>do y++; while (a<0)</pre>
<pre>{instr1; instr2; instr3; ...}</pre>	block	<pre>{a++; b--;}</pre>

Example: Disassembly

- Basic instructions
 - For ...
 - If ... else ...

```
Disassembly (main) 33
25      for (i=0;i<100;i++)
      main, main:
0x00000298: 4811 LDR      R1, %C&CON1
0x0000029A: 2000 MOV      R0, #0x0
0x0000029C: 6008 STR      R0, [R1]
0x0000029E: 4813 LDR      R0, %C&CON1
0x000002A0: 6800 LDR      R0, [R0]
0x000002A2: 2864 CMP      R0, #0x64
0x000002A4: D215 BCS      %C&DW&L&main%2%E
27      k=i*i;
      $C$DW$L$main$2$B, $C$L1:
0x000002A6: 4811 LDR      R0, %C&CON1
0x000002A8: 6801 LDR      R1, [R0]
0x000002AA: 4810 LDR      R0, %C&CON1
0x000002AC: 6800 LDR      R0, [R0]
0x000002AE: 4348 MUL      R0, R1
0x000002B0: 490F LDR      R1, %C&CON2
0x000002B2: 6008 STR      R0, [R1]
28      y[i]=k;
0x000002B4: 480D LDR      R0, %C&CON1
0x000002B6: 6801 LDR      R1, [R0]
0x000002B8: 480D LDR      R0, %C&CON2
0x000002BA: 4A0E LDR      R2, %C&CON3
0x000002BC: 6800 LDR      R0, [R0]
0x000002BE: F8420021 STR.W R0, [R2, R1, LSL #2]
25      for (i=0;i<100;i++)
0x000002C2: 490A LDR      R1, %C&CON1
0x000002C4: 6808 LDR      R0, [R1]
0x000002C6: 1C40 ADD      R0, R0, #0x1
0x000002C8: 6008 STR      R0, [R1]
0x000002CA: 4808 LDR      R0, %C&CON1
0x000002CC: 6800 LDR      R0, [R0]
0x000002CE: 2864 CMP      R0, #0x64
0x000002D0: D3E9 BCC      %C&L1
31      if (i==99)
      $C$L2, $C$DW$L$main$2$E:
0x000002D2: 4808 LDR      R0, %C&CON1
0x000002D4: 6800 LDR      R0, [R0]
0x000002D6: 2863 CMP      R0, #0x63
0x000002D8: D103 BNE      %C&L3
32      k=100;
0x000002DA: 4905 LDR      R1, %C&CON2
0x000002DC: 2064 MOV      R0, #0x64
0x000002DE: 6008 STR      R0, [R1]
0x000002E0: E002 B        %C&L4
34      k=0;
      $C$L3:
0x000002E2: 4903 LDR      R1, %C&CON2
0x000002E4: 2000 MOV      R0, #0x0
0x000002E6: 6008 STR      R0, [R1]
36      }
      $C$L4:
```

Functions

- function
 - “Stand alone” block
 - Called by other blocks
 - Getting parameters (void: no parameter (obsolete))
 - Deliver max. one result (void: no result)
- master function: **main()**
 - Output
 - Void main(): no return
 - Int main(): integer value back (via return)
 - Input
 - Main (int argc): argc – number input parameter plus one
 - Main (int argc, char *argv[]): argv – pointer array of parameter

C Program Frame

```
/* Simple C Frame
```

```
    Project:
```

```
    Description
```

```
    Date:
```

```
    Revision:
```

```
    ...
```

```
*/
```

```
#include <xxx.h>
```

```
int main (int argc, char* argv[] ) {
```

```
    instructions;
```

```
    {} // blocks
```

```
    return 0;
```

```
}
```

Data Storage

- Variables characteristics
 - Local variables
 - Automatic variable generation by block entrance and deletion after leaving
 - Local: stack
 - Example:

```
void func() {  
    int localvar = 10;}
```
 - Local: register
 - Example:

```
void func() {  
    register int localvar = 10;}
```
 - Static and global variables
 - Static: defined inside a block, the value is conserved
 - Global: definition and initialisation outside functions
 - Extern: indicates that the global variable is still defined in a other file
 - Const: constant value, cannot be changed
 - Volatile: prevents optimisation

Questions and Exercises

1. Explain the terms Compiler, Assembler, Linker.
2. Design a water fall model.
3. Design a V model.
4. Draw a structured flowchart for an arithmetic mean with $n=5$.
5. Explain the design flow for the arithmetic mean.