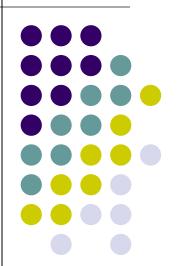
Algorithms

Chapter 6.1, 6.4, 6.5, 6.6



ROAD MAP



Transform And Conquer

- Instance simplification
- Representation change
- Problem reduction

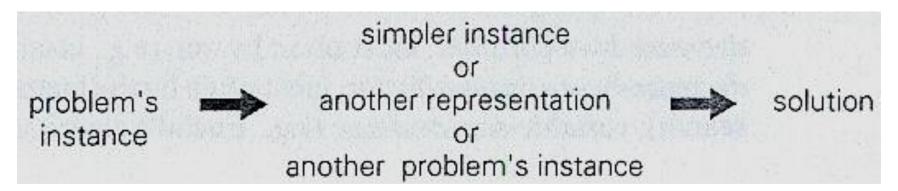
Transform And Conquer



- Transform and conquer technique is based on idea of <u>transformation</u>
- This method works in two stages
 - Transformation stage
 - The problem is modified to another problem
 - more amenable to solution
 - Conquering stage
 - It is solved

Transform And Conquer Strategy





- Instance simplification
 - Transformation to a simplier instance problem
- Representation change
 - Transformation to a different representation of <u>same</u> instance
- Problem reduction
 - Tranformation to an instance of a different problem for which an algorithm is already available

ROAD MAP



- Transform And Conquer
 - Instance simplification
 - Presorting
 - Element Uniqueness
 - Computing Mode
 - Searching
 - Representation change
 - Problem reduction

Presorting



- Presorting is an old idea in computer science
- Many questions about a list are easier to answer if the list is sorted
- Efficiency of sorting algorithms is important
 - The benefits of a sorted list should more than the time spend for sorting.
 - Otherwise, use unsorted list directly
- We will assume that lists are implemented as arrays

Sorting



- We discussed three elementary sorting algorithms
 - Selection sort
 - Buble sort
 - Insertion sort

These algorithms are *quadratic* in worst and average case

- Also discussed two advanced algorithms
 - Merge sort
 - Θ(nlogn) in worst and average case
 - Quick sort
 - Θ(nlogn) in average case
 - $\Theta(n^2)$ in worst case
- Are there faster algorithms?
 - There is no general <u>comparison-based</u> sorting algorithm can have better efficiency than <u>@(nlogn)</u>

Element Uniqueness



- Example 1 : Checking element uniqueness in an array
 - Brute force algorithm compare pairs of array's elements until either two equal elements were found or no pairs were left
 - Its worst case efficiency was $\Theta(n^2)$
 - Alternatively, what can we do?

Element Uniqueness



- Approach :
 - 1. sort the array
 - 2. check only its consecutive elements

If the array has equal elements, a pair of them must be next to each other





```
ALGORITHM PresortElementUniqueness (A[0..n-1])

//Solves the element uniqueness problem by sorting the array first

//Input: An array A[0..n-1] of orderable elements

//Output: Returns "true" if A has no equal elements, "false" otherwise

Sort the array A

for i \leftarrow 0 to n-2 do

if A[i] = A[i+1] return false

return true
```

What is the running time of the algorithm?

Element Uniqueness



Analysis:

$$T(n) = T_{sort}(n) + T_{scan}(n)$$

$$T(n) \in \Theta(n \log n) + \Theta(n)$$

$$T(n) = \Theta(n \log n)$$

More efficient than brute-force algorithm



Example 2 : Computing mode

A mode is value that occurs most often in a given list of numbers

For 5,1,5,7,6,5,7 the mode is 5

- In brute-force approach
 - Scan the list
 - Compute the frequencies of all distinct values
 - Find the value with largest frequency
- How to implement this idea?





Method:

- Store values already encountered, along with their frequencies in a separate list
- On each iteration, the ith element of original list is compared with values encountered
- If a matching value is found, its frequency is incremented
- Otherwise, current element is added to the list of distinct values seen so far with a frequency of 1

What about analysis?

- Number of comparisons depends on the input.
 - In the best case: (all the elements are same)

$$C(n) \in \Theta(n)$$

In worst case: (all the elements are different)

$$C(n) = \sum_{i=1}^{n} (i-1) = 0 + 1 + \dots + (n-1)$$

$$C(n) = \frac{n(n-1)}{2}$$

$$C(n) \in \Theta(n^2)$$

What can we do as an alternative?



Approach :

1. Sort the input

Then all equal values will be adjacent to each other

2. Find the longest run of adjacent equal values in the sorted array

ALGORITHM PresortMode(A[0..n-1])

```
//Computes the mode of an array by sorting it first
//Input: An array A[0..n-1] of orderable elements
//Output: The array's mode
Sort the array A
                       //current run begins at position i
i \leftarrow 0
modefrequency ← 0 //highest frequency seen so far
while i \le n - 1 do
    runlength \leftarrow 1; runvalue \leftarrow A[i]
    while i+runlength \le n-1 and A[i+runlength] = runvalue
         runlength \leftarrow runlength + 1
    if runlength > modefrequency
        modefrequency ←runlength; modevalue ←runvalue
    i \leftarrow i + runlength
return modevalue
```





- Analysis:
 - Running time of algorithm depends on the time spent on sorting
 - remainder of the algorithm takes linear time (why ?)
 - So, with an $\Theta(n\log n)$ sort, worst case efficiency will be $\Theta(n\log n)$

Searching Problem



- Example 3 : Searching Problem
 - Searching for a given value v in a given array of n sortable items
 - Brute force solution is sequential search
 - needs n comparisons in worst case
 - If the array is sorted, we apply binary search
 - requires only $|\log_2 n| + 1$ comparisons in worst case

Searching Problem



- Assume the most efficient Θ(nlogn) sort is used
- Total running time in worst case and also average case will be

$$T(n) = T_{sort}(n) + T_{search}(n)$$
$$= \Theta(n \log n) + \Theta(\log n) = \Theta(n \log n)$$

- Worst than sequential search!...
- What if the search will be done several times?...

Presorting

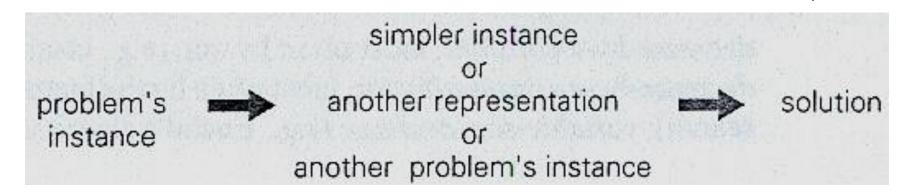


Discussion:

- Geometric algorithms dealing with sets of points use presorting in one way or another
 - Presorting is used in divide and conquer for closest pair problem and convex-hull problem
- Some problems for directed acyclic graphs can be solved more easily after topologically sorting the digraph
 - Finding the shortest and longest paths







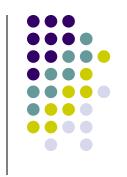
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ROAD MAP



- Transform And Conquer
 - Instance simplification
 - Representation change
 - Heaps and Heapsort
 - Horner's Rule and Binary Exponentiation
 - Problem Reduction

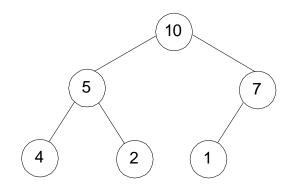
Heaps

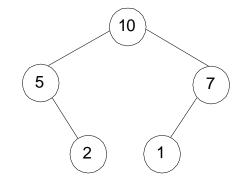


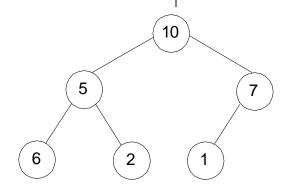
- Heap is an important data structure, suitable for implementing priority queues
- Priority queue is a multiset of items with an orderable charecteristics called an item's priority
 - find an item with highest priority
 - delete an item with highest priority
 - add a new item to multiset
- Heap is representation change over regular list
 - Provides efficient algorithms for basic operations
- Heap also serves an important sorting algorithm called heapsort

Illustration of the heap's definition









a heap

not a heap

not a heap

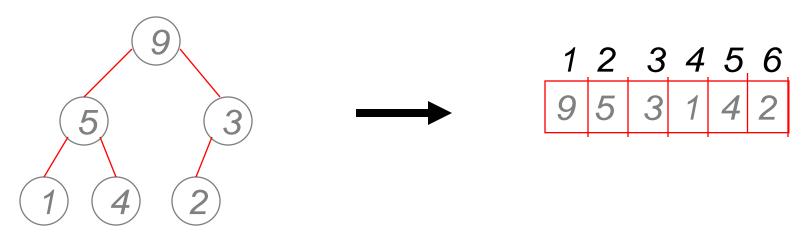
Some Important Properties of a Heap



- Given n, there exists a unique binary tree with n nodes that
 - is essentially complete, with $h = \lfloor \log_2 n \rfloor$
- The root contains the largest key
- The subtree rooted at any node of a heap is also a heap
- A heap can be represented as an array

Heap's Array Representation

Store heap's elements in an array (whose elements indexed, for convenience, 1 to *n*) in top-down left-to-right order. Example:



- Left child of node j is at 2j
- Right child of node j is at 2j+1
- Parent of node j is at \(\frac{j}{2}\)
- Parental nodes are represented in the first \(\frac{n}{2} \) locations

Heap Construction (bottom-up)

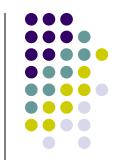


Step 0: Initialize the structure with keys in the order given

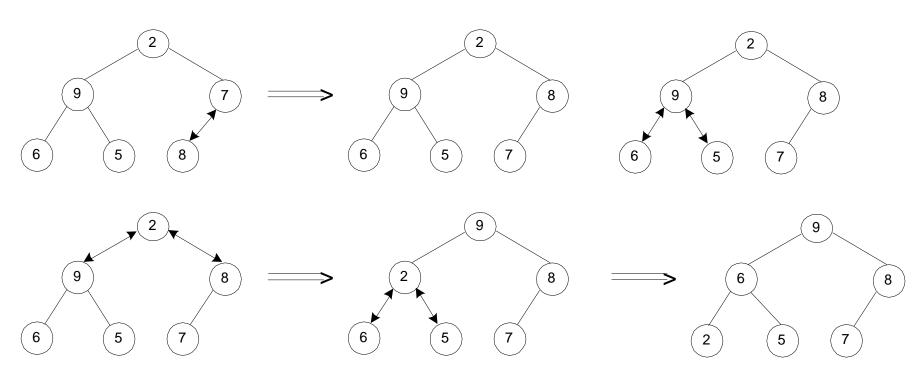
Step 1: Starting with the last (rightmost) parental node, fix the heap rooted at it, if it doesn't satisfy the heap condition: keep exchanging it with its largest child until the heap condition holds

Step 2: Repeat Step 1 for the preceding parental node

Example of Heap Construction



Construct a heap for the list 2, 9, 7, 6, 5, 8





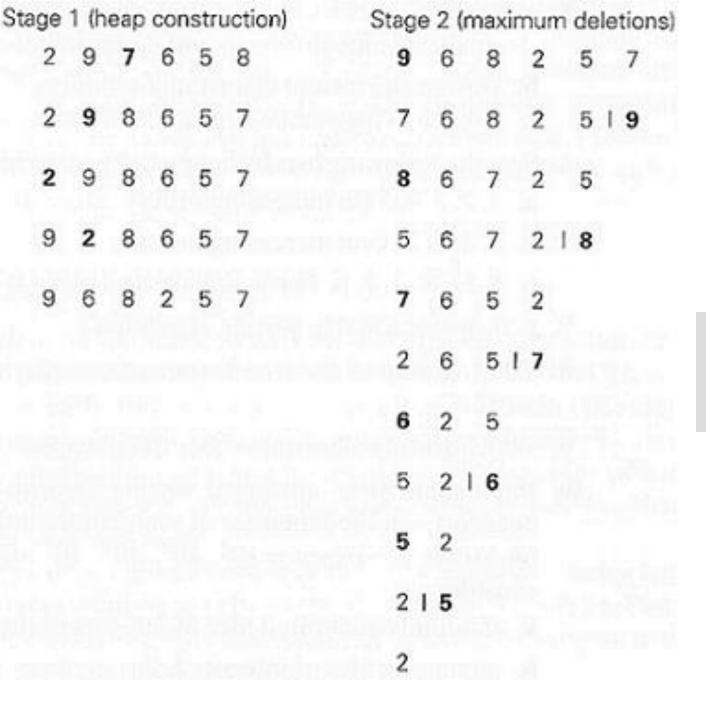


```
Algorithm HeapBottomUp(H[1..n])
//Constructs a heap from the elements of a given array
// by the bottom-up algorithm
//Input: An array H[1..n] of orderable items
//Output: A heap H[1..n]
for i \leftarrow \lfloor n/2 \rfloor downto 1 do
    k \leftarrow i; \quad v \leftarrow H[k]
     heap \leftarrow \mathbf{false}
     while not heap and 2*k \le n do
            j \leftarrow 2 * k
            if j < n //there are two children
                if H[j] < H[j+1] \quad j \leftarrow j+1
            if v > H[j]
                   heap \leftarrow \mathbf{true}
            else H[k] \leftarrow H[j]; \quad k \leftarrow j
      H[k] \leftarrow v
```

Heapsort



- Heapsort is an interesting two-stage algorithm
 - Stage 1 → heap construction
 - Construct a heap for a given array
 - Stage 2 → maximum deletions
 - Apply the root-deletion operation n-1 times to the remaining heap
 - As a result the array's elements are eliminated in decreasing order
 - Since under the array implementation, an element being deleted is placed last, the resulting array will be exactly the original array sorted in ascending order





Sorting array 2, 9, 7, 6, 5, 8 by heapsort

Heapsort



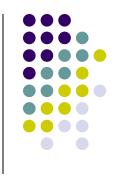
- Analysis:
 - We know that heap construction stage is O(n)
 - Stage 1
 - What about stage 2 ?

$$C(n) \le 2\lfloor \log_2(n-1)\rfloor + 2\lfloor \log_2(n-2)\rfloor + \dots + 2\lfloor \log_2 1\rfloor \le 2\sum_{i=1}^{n-1} \log_2 i$$

$$\le 2\sum_{i=1}^{n-1} \log_2(n-1) = 2(n-1)\log_2(n-1) \le 2n\log_2 n.$$

• For both stages O(n) + O(nlogn) = O(nlogn)

Heapsort



- Discussion :
 - Average case efficiency is also θ (nlogn)
 - such as mergesort
 - Heapsort does not require an extra storage
 - Timing experiments on random files show that heapsort runs more slowly than quicksort but it is competitive with mergesort

ROAD MAP



- Transform And Conquer
 - Instance simplification
 - Representation change
 - Heaps and Heapsort
 - Horner's Rule and Binary Exponentiation
 - Problem Reduction

Horner's Rule



Problem Definition:

Compute the value of a polynomial

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

at a given point x

- Polynomials constitute the most important class of functions
 - They posses a wealth of good properties
 - Can be used for approximating other types of functions
- Manipulating polynomials efficiently is an important problem

Horner's Rule



- Horner's rule provides elegant method for evaluating a polynomial
- It is a good example of representation change technique since it is based on representing P(x) by a formula

$$p(x) = (...(a_n x + a_{n-1})x + ...)x + a_0$$



• Example:

For example, for the polynomial

$$p(x) = 2x^4 - x^3 + 3x^2 + x - 5$$
 we get

$$p(x) = 2x^{4} - x^{3} + 3x^{2} + x - 5$$

$$= x(2x^{3} - x^{2} + 3x + 1) - 5$$

$$= x(x(2x^{2} - x + 3) + 1) - 5$$

$$= x(x(x(2x - 1) + 3) + 1) - 5$$



- The pen-and-pencil calculation can be conveniently organized with a two row table
 - First row contains the polynomial's coefficients listed from the highest a_n to the lowest a₀
 - Second row is filled from left to right as follows (except its first entry which is a_n)
 - Next entry is computed as the x's value times the last entry in the second row plus the next coefficient from first row
 - Final entry is the value being sought



EXAMPLE 1 Evaluate
$$p(x) = 2x^4 - x^3 + 3x^2 + x - 5$$
 at $x = 3$.

coefficients	2	-1	3	1	-5
x = 3	2	$3 \cdot 2 + (-1) = 5$	$3 \cdot 5 + 3 = 18$	$3 \cdot 18 + 1 = 55$	$3 \cdot 55 + (-5) = 160$

$$P(3) = 160$$

 $3.2+(-1) \rightarrow 2x-1$ at $x=3$
 $3.5+3 = 18 \rightarrow x(2x-1)+3$ at $x=3$
 $3.18+1 = 55 \rightarrow x(x(2x-1)+3)+1$ at $x=3$
 $3.55+(-5) = 160 \rightarrow x(x(x(2x-1)+3)+1)-5 = p(x)$





```
ALGORITHM Horner(P[0..n], x)

//Evaluates a polynomial at a given point by Horner's rule

//Input: An array P[0..n] of coefficients of a polynomial of degree n

// (stored from the lowest to the highest) and a number x

//Output: The value of the polynomial at x

p \leftarrow P[n]

for i \leftarrow n - 1 downto 0 do

p \leftarrow x * p + P[i]

return p
```



- Analysis:
 - Number of multiplications and number of additions

$$M(n) = A(n) = \sum_{i=0}^{n-1} 1 = n$$

So how efficient is Horner's rule?



- Analysis:
 - Consider only the first term of a polynomial of degree n: a_nxⁿ
 - Just computing this term with brute force approach requires n multiplications
 - Horner's rule computes n-1 other terms in addition to this and still uses the same number of multiplications
 - So it is an optimal algorithm for polynomial evaluation



Discussion:

- Horner's rule also has some useful by-products
- The intermediate numbers generated by the algorithm in the process of evaluating P(x) at some point x₀ turn out to be the coefficient to the quotient of the division of P(x) by x-x₀
 - While the final result, in addition to being P(x₀) is equal to the remainder of this division of

$$P(x) = P'(x) (x-x_0) + P(x_0)$$

$$2x^4 - x^3 + 3x^2 + x - 5 by x-3$$

$$2x^3 + 5x^2 + 18x + 55 and 160$$

- This division algorithm is known as synthetic division
 - It is more convenient than long division

Exponentiation



- Problem Definition :
 - Compute *a*ⁿ
 - Computing aⁿ in an essential operation in primality-testing and encryption methods
 - The brute-force algorithm takes linear time
 - Designing other algorithms for computing aⁿ is important
 - For example, based on the representation change idea

Binary Exponentiation



- We will consider two algorithms for computing aⁿ
- Both of them exploit the binary representation of exponent n
 - One of them processed this processes this binary string left to right
 - The second does it right to left

Binary Exponentiation



Let

$$\mathbf{n} = \mathbf{b}_{\mathbf{I}} \dots \mathbf{b}_{\mathbf{i}} \dots \mathbf{b}_{\mathbf{0}}$$

be the string representation of a positive integer *n* in binary system

The value of n can be computed as the value of polynomial at x = 2

$$P(x) = b_I x^I + ... + b_i x^i + ... + b_0$$

If n = 13 its binary representation is 1101 and $13 = 1.2^3 + 1.2^2 + 0.2^1 + 1.2^0$





• If we compute the value of P(x) with Horner's rule

$$a^n = a^{p(2)} = a^{b_I 2^I + \dots + b_i 2^i + \dots + b_0}$$

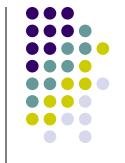
Horner's rule for the binary polynomial $p(2)$	Implications for $a^n = a^{p(2)}$	
$p \leftarrow 1$ //the leading digit is always 1 for $n \ge 1$	$a^p \leftarrow a^1$	
for $i \leftarrow I - 1$ downto 0 do	for $i \leftarrow I - 1$ downto 0 do	
$p \leftarrow 2p + b_i$	$a^p \leftarrow a^{2p+b_i}$	

$$a^{2p+b_i} = a^{2p} \cdot a^{b_i} = (a^p)^2 \cdot a^{b_i} = \begin{cases} (a^p)^2 & \text{if } b_i = 0\\ (a^p)^2 \cdot a & \text{if } b_i = 1 \end{cases}$$

Binary Exponentiation



- After initializing the accumulator's value to a,
 - the bit string representing the exponent is always square the last value of accumulator
 - if the current binary digit is 1, also multiply it by a
- These observations lead to left-to-right exponentiation method of computing an



Left-to-right binary exponentiation

```
ALGORITHM
                 LeftRightBinaryExponentiation(a, b(n))
    //Computes an by the left-to-right binary exponentiation algorithm
    //Input: A number a and a list b(n) of binary digits b_1, \ldots, b_0
             in the binary expansion of a positive integer n
    //Output: The value of a^n
    product \leftarrow a
    for i \leftarrow I - 1 downto 0 do
         product \leftarrow product * product
         if b_i = 1 product \leftarrow product *a
    return product
```





- Example :
 - Compute a¹³ by left-right binary exponentiation
 - Here $n = 13 = (1101)_2$
 - So

binary digits of n	1	1	0	1
product accumulator	a	$a^2 \cdot a = a^3$	$(a^3)^2 = a^6$	$(a^6)^2 \cdot a = a^{13}$

Left-to-right binary exponentiation



Analysis:

Total number of multiplications M(n)

$$(b-1) \le M(n) \le 2(b-1)$$

- b is the length of bit string representing exponent n
- b-1 = logn

So efficiency is $\Theta(logn)$

Left-to-right binary exponentiation



- Discussion :
 - This algorithm is better efficiency class than bruteforce exponentiation
 - requires n-1 multiplications





Definition:

- Right-to-left binary exponentiation uses same binary polynomial p(2) yielding value of n
- But it does not apply Horner's rule
 - Exploits it differently

$$a^n = a^{b_1 2^I + \dots + b_i 2^i + \dots + b_0} = a^{b_1 2^I} \cdot \dots \cdot a^{b_i 2^i} \cdot \dots \cdot a^{b_0}$$





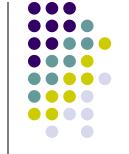
Thus aⁿ can be computed as the product of terms

$$a^{b_i 2^i} = \begin{cases} a^{2^i} & \text{if } b_i = 1\\ 1 & \text{if } b_i = 0 \end{cases}$$

- The product of consecutive terms a²ⁱ, skipping those for which the binary digit bi is zero
- We can compute a²ⁱ by simply squaring the same term we computed for the previous value of i since

$$a^{2i} = (a^{2^{i-1}})^2$$

We compute powers of a right to left (smallest to largest)



Right-to-left binary exponentiation

```
ALGORITHM RightLeftBinaryExponentiation(a, b(n))
    //Computes a^n by the right-to-left binary exponentiation algorithm
    //Input: A number a and a list b(n) of binary digits b_1, \ldots, b_0
             in the binary expansion of a nonnegative integer n
    //Output: The value of an
    term \leftarrow a //initializes a^{2^i}
    if b_0 = 1 product \leftarrow a
    else product \leftarrow 1
    for i \leftarrow 1 to I do
        term \leftarrow term * term
        if b_i = 1 product \leftarrow product * term
```

return product





Example :

- Compute a¹³ by right-toleft binary exponentiation
 - Here n = 13 = 1101
 - So

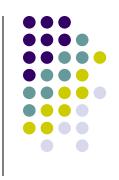
1	1.1	0	1	binary digits of n
a^8	a^4	a^2	а	terms a ²ⁱ
$a^5 \cdot a^8 = a^{13}$	$a \cdot a^4 = a^5$		а	product accumulator

Right-to-left binary exponentiation



- Analysis:
 - Efficiency is logaritmic
 - Same as left-to-right binary multiplications

Binary Exponentiation



- Discussion:
 - Both binary exponentiation algorithm discussed reduce somewhat by their reliance on availability of the explicit binary expansion of exponent n

ROAD MAP



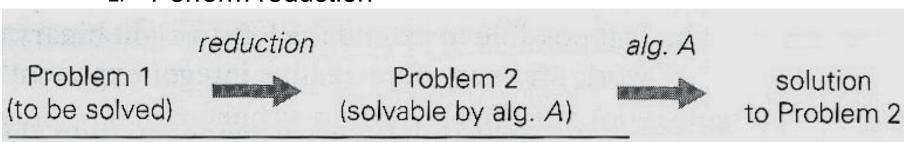
- Transform And Conquer
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 - Representation change
 - Problem Reduction
 - Computing The Least Common Multiple
 - Counting Paths in A Graph

Problem Reduction



Definition:

- Problem reduction is to reduce a problem you need to solve to another problem that you know how to solve
 - 1. Find a problem to reduce onto
 - 2. Perform reduction



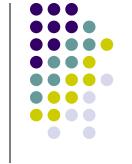
 The reduction worth if the reduction operations and algorithm A takes less time than solving the original problem directly

Least Common Multiple



Definition :

- Computing the least common multiple of two integers m and n is denoted lcm(m,n)
- *lcm* is defined as the smallest integer that is divisible by both *m* and *n*
 - lcm (24, 60) = 120
 - lcm(11,5) = 55
- It is an important notion in arithmetic and algebra



Computing the Least Common Multiple

Approach :

Given the prime factorizations of m and n, lcm (m,n) can be computed as the product of all the common prime factors of m and n times the product of m's prime factors that are not in n times n's prime factors that are not in m

$$24 = 2 . 2 . 2 . 3$$

 $60 = 2 . 2 . 3 . 5$
 $1cm(24, 60) = (2 . 2 . 3) . 2 . 5 = 120$



Computing the Least Common Multiple

 As a computational procedure, this algorithm has the same drawbacks as middle-school algorithm for computing greatest-commondivisor

How can we design a more efficient algorithm by using problem reduction?





- Product of lcm(m,n) and gcd(m,n) includes every factor of m and n exactly once
- So,

$$lcm(m,n) = \frac{m.n}{\gcd(m,n)}$$

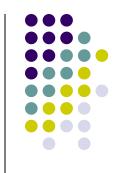
- This formula reduces lcm calculation to gcd calculation
- gcd(m,n) can be computed with Euclid's algorithm efficiently

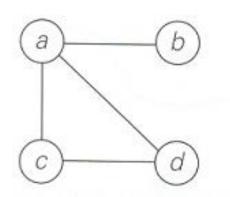
Counting Paths in a Graph



- Definition:
 - Counting different paths between two vertices in a graph
 - It is easy to prove that number of different paths of length k>0 from the ith vertex to the ith vertex of a graph equals the (i,j) th element of A^k where A is the adjacency matrix of the graph

Counting Paths in a Graph





$$A = \begin{bmatrix} a & b & c & d \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ c & 1 & 0 & 0 & 1 \\ d & 1 & 0 & 1 & 0 \end{bmatrix}$$

$$A^{2} = \begin{bmatrix} a & b & c & d \\ 3 & 0 & 1 & 1 \\ b & 0 & 1 & 1 & 1 \\ c & 1 & 1 & 2 & 1 \\ d & 1 & 1 & 1 & 2 \end{bmatrix}$$

a graph

its adjacency matrix A

its square A²

Elements of A and A² indicate the number of paths of lengths 1 and 2

Counting Paths in a Graph



- So, the problem can be solved with an algorithm for computing an appropriate power of its adjacency matrix
- Problem is reduced to matrix exponentiation
 - How to calculate A^k

Problem Reduction



- Discussion:
 - Plays a central role in theoretical computer science
 - where it is used to classify problems according to their complexity
 - The practical difficulty is finding a problem to which the problem at hand should be reduced
 - If we want our efforts to be of practical value, we need our reduction-based algorithm to be more efficient than solving the original problem directly