# MATRICES AND MATRIX OPERATIONS V

# EIGENVALUES AND EIGENVECTORS

# **Linear Systems of the Form**

$$Ax = \lambda x$$

Many applications of linear algebra are concerned with systems of n linear equations in n unknowns that are expressed in the form

$$Ax = \lambda x$$

where 1 is a scalar. Such systems are really homogeneous linear systems in disguise, since the given system can be written as

 $\lambda x - Ax = 0$  or, by inserting an identity matrix and factoring, as

$$(\lambda I - A)x = 0$$

# Example: Finding $(\lambda I - A)$

The linear system

$$x_1 + 3x_2 = \lambda x_1$$
$$4x_1 + 2x_2 = \lambda x_2$$

can be written in matrix form as

$$\begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \quad \text{and} \quad x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

This system can be written as

$$\lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

or

$$\lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

or

$$\begin{bmatrix} \lambda - 1 & -3 \\ -4 & \lambda - 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda I - A = \begin{bmatrix} \lambda - 1 & -3 \\ -4 & \lambda - 2 \end{bmatrix}$$

The primary problem of interest for linear systems of the form  $(\lambda I - A)x = 0$  is to determine those values of  $\lambda$  for which the system has a nontrivial solution; such a value of  $\lambda$  is called **characteristic** value or an **eigenvalue** of A. If  $\lambda$  is eigenvalue of A, then the nontrivial solution of  $(\lambda I - A)x = 0$  are called **eigenvectors** of A corresponding to  $\lambda$ .

### **Definition**

If A is  $n \times n$  matrix, then a nonzero vector x in  $\mathbb{R}^n$  is called an **eigenvector** of A if Ax is a scalar multiple of x; that is if

$$Ax = \lambda x$$

for some scalar  $\lambda$ . The scalar  $\lambda$  is called an **eigenvalue** of A, and x said to be an **eigenvector** of A corresponding to  $\lambda$ .

# **Example:** Eigenvector of a 2x2 Matrix

The vector  $x = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  is an eigenvector of

$$A = \begin{bmatrix} 3 & 0 \\ 8 & -1 \end{bmatrix}$$

corresponding to the eigenvalue  $\lambda = 3$ , since

$$Ax = \begin{bmatrix} 3 & 0 \\ 8 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 3x$$

To find the eigenvalues of  $n \times n$  matrix A, we rewrite

$$Ax = \lambda x$$
 as  $Ax = \lambda Ix$  or equivalently,

$$(\lambda I - A)x = 0$$

For  $\lambda$  to be an eigenvalue, there must be a nonzero solution of this equation.

Theorem Equation  $(\lambda I - A)x = 0$  has a nonzero solution if and only if

$$\det(\lambda I - A) = 0$$

This is called the <u>characteristic equation</u> of A; the scalars satisfying this equation are the eigenvalues of A.

Remark A nxn homogeneous system of linear equations has a unique solution (the trivial solution) if and only if its determinant is non-zero. If this determinant is non-zero an infinite number of solutions.

When expanded the determinant,  $\frac{\det(\lambda I - A) = 0}{\det(\lambda I - A)}$  is always a polynomial p in  $\lambda$ , called the characteristic polynomial of A:

If A is an  $n \times n$  matrix, then the characteristic polynomial of A has degree n and the coefficient of  $\frac{\lambda^n}{n}$  is 1; that is, the characteristic polynomial  $\frac{p(\lambda)}{p(\lambda)}$  of an  $\frac{1}{n \times n}$  matrix has the form

$$p(\lambda) = \det(\lambda I - A) = \lambda^n + c_1 \lambda^{n-1} + \dots + c_n$$

It follows from the <u>Fundamental Theorem of</u>
<u>Algebra</u> that the characteristic equation

$$\lambda^n + c_1 \lambda^{n-1} + \ldots + c_n = 0$$

has at most n distinct solutions, so an  $n \times n$  matrix has at most n distinct eigenvalues.

# **Example:** Eigen values and Eigenvectors

Find the eigenvalues and corresponding eigenvectors of the matrix

$$A = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$$

The characteristic equation of A is

$$\det(\lambda I - A) = \begin{vmatrix} \lambda & 0 \\ 0 & \lambda \end{vmatrix} - \begin{vmatrix} 1 & 3 \\ 4 & 2 \end{vmatrix} = \begin{vmatrix} \lambda - 1 & -3 \\ -4 & \lambda - 2 \end{vmatrix} = 0$$

or

$$\lambda^2 - 3\lambda - 10 = 0$$

The factored form of this equation is

$$(\lambda + 2)(\lambda - 5) = 0$$
, so the eigenvalues

of A are 
$$\lambda = -2, \lambda = 5$$
.

By definition,

$$x = \begin{vmatrix} x_1 \\ x_2 \end{vmatrix}$$

is an eigenvector of A if and only if  $\mathbf{x}$  is a nontrivial solution of  $(\lambda I - A)x = 0$ ; that is,

$$\begin{bmatrix} \lambda - 1 & -3 \\ -4 & \lambda - 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

If  $\lambda = -2$ , then

$$\begin{bmatrix} -3 & -3 \\ -4 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Solving this system yields  $x_1 = -x_2$   $x_2 = t$  so the eigenvectors corresponding to  $\lambda = -2$  are the nonzero solutions of the form

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

If  $\lambda = 5$ , then

$$\begin{bmatrix} 4 & -3 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Solving this system yields  $x_1 = \frac{3}{4}t, x_2 = t$  so the eigenvectors corresponding to  $\lambda = 5$  are the nonzero solutions of the form

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{3}{4}t \\ t \end{bmatrix} = t \begin{bmatrix} \frac{3}{4} \\ 1 \end{bmatrix}$$

### EIGEN VALUES AND EIGENVECTORS IN MATLAB

 $>> A=[1\ 3;\ 4\ 2]$ 

 $\mathbf{A} =$ 

1 3

4 2

>> [v,d]=eig(A)

 $\mathbf{v} =$ 

-0.7071 -0.6000

0.7071 -0.8000

 $\mathbf{d} =$ 

**-2 0** 

0 5

>> vv=[-1 1]

 $\mathbf{v}\mathbf{v} = -1 \quad \mathbf{1}$ 

>> vv=vv'

 $\mathbf{v}\mathbf{v} =$ 

-1

1

>> nor=norm(vv)

nor =

1.4142

>> vv=vv/nor

vv =

-0.7071

0.7071

>> vv'\*vv

ans =

1.0000

# **Example:** Eigen values and Eigenvectors

Find the eigenvalues and corresponding eigenvectors of the matrix

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 2 & 1 \\ 1 & \lambda - 2 \end{vmatrix} = 0$$

or

$$(\lambda - 2)^2 - 1 = 0$$

The roots of this equation  $\lambda = 3, \lambda = 1$ .

# Consider the first Eigen value

$$\lambda = 3$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Both rows of this matrix equation reduce to

$$x_1 = -x_2$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

# Consider the second Eigen value

$$\lambda = 1$$

$$\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Similar process leads to  $x_1 = x_2$ 

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

For t=1 the corresponding eigenvector is

$$\mathbf{A} =$$

### $\mathbf{v} =$

$$\mathbf{d} =$$

# **Example:** Eigen values of a 3x3 Matrix

Find the eigenvalues of

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & -17 & 8 \end{bmatrix}$$

The characteristic polynomial of A is

$$\det(\lambda I - A) = \det\begin{bmatrix} \lambda & -1 & 0 \\ 0 & \lambda & -1 \\ -4 & 17 & \lambda - 8 \end{bmatrix} = \lambda^3 - 8\lambda^2 + 17\lambda - 4$$

The Eigenvalues of A must therefore satisfy the cubic equation

$$\lambda^3 - 8\lambda^2 + 17\lambda - 4 = 0$$

$$(\lambda - 4)(\lambda^2 - 4\lambda + 1) = 0$$

$$\lambda = 4, \lambda = 2 + \sqrt{3}, \lambda = 2 - \sqrt{3}$$

$$\begin{bmatrix} 4 & -1 & 0 \\ 0 & 4 & -1 \\ -4 & 17 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -1 & 0 \\ 0 & 4 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$4x_1 - x_2 = 0$$
$$4x_2 - x_3 = 0$$

Eigenvectors of A corresponding to  $\lambda = 4$ 

$$x = t \begin{bmatrix} -1/16 \\ -1/4 \\ -1 \end{bmatrix}$$

# **Example:**

$$A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$$

The characteristic equation of matrix A is

$$\lambda^3 - 5\lambda^2 + 8\lambda - 4 = 0$$

Or in factored form,

$$(\lambda - 1)(\lambda - 2)^2 = 0$$

Thus the eigenvalues of A are  $\lambda_1 = 1$  and  $\lambda_{2,3} = 2$ By definition,

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

is an eigenvector of A corresponding to  $\frac{\lambda}{\lambda}$  if and only if **x** is a nontrivial solution of  $(\lambda I - A)x = 0$  that is, of

$$\begin{bmatrix} \lambda & 0 & 2 \\ -1 & \lambda - 2 & -1 \\ -1 & 0 & \lambda - 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

If 
$$\lambda = 1$$

$$\begin{bmatrix} 1 & 0 & 2 \\ -1 & -1 & -1 \\ -1 & 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Solving this system yields (verify)

$$x_1 = -2s, x_2 = s, x_3 = s$$

Thus the eigenvectors of A corresponding to  $\lambda = 1$  are the nonzero vectors of the form

$$\begin{bmatrix} -2s \\ s \\ s \end{bmatrix} = s \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

If 
$$\lambda = 2$$

$$\begin{bmatrix} 2 & 0 & 2 \\ -1 & 0 & -1 \\ -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Solving this system using Gaussian elimination yields (verify)

$$x_1 = -s, x_2 = t, x_3 = s$$

Thus the eigenvectors of A corresponding to  $\lambda = 2$  are the nonzero vectors of the form

$$x = \begin{bmatrix} -s \\ t \\ s \end{bmatrix}$$

$$x = \begin{bmatrix} -s \\ t \\ s \end{bmatrix} = \begin{bmatrix} -s \\ 0 \\ s \end{bmatrix} + \begin{bmatrix} 0 \\ t \\ 0 \end{bmatrix} = s \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Since

 $\begin{bmatrix} -1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  are **orthogonal**, these vectors

form a basis for the eigenspace corresponding to  $\lambda = 2$ .

A=[0 0 -2;1 2 1;1 0 3]

A =

0 0 -2

1 2 1

1 0 3

>> [v,d]=eig(A)

 $\mathbf{v} =$ 

0 -0.8165 0.7071 UNIT VECTORS

1.0000 0.4082 0

0 0.4082 -0.7071

d =

2 0 0

0 1 0

0 0 2

>>

# **Example:** Eigenvalues of an Upper Triangular Matrix

Find the eigenvalues of the upper triangular matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ 0 & a_{22} & a_{23} & a_{24} \\ 0 & 0 & a_{33} & a_{34} \\ 0 & 0 & 0 & a_{44} \end{bmatrix}$$

$$\det(\lambda I - A) = \det\begin{bmatrix} \lambda - a_{11} & -a_{12} & -a_{13} & -a_{14} \\ 0 & \lambda - a_{22} & -a_{23} & -a_{24} \\ 0 & 0 & \lambda - a_{33} & -a_{34} \\ 0 & 0 & 0 & \lambda - a_{44} \end{bmatrix}$$
$$= (\lambda - a_{11})(\lambda - a_{22})(\lambda - a_{33})(\lambda - a_{44})$$

Thus, the characteristic equation is

$$(\lambda - a_{11})(\lambda - a_{22})(\lambda - a_{33})(\lambda - a_{44}) = 0$$

and the eigenvalues are

$$\lambda_1 = a_{11}, \lambda_2 = a_{22}, \lambda_3 = a_{33}, \lambda_4 = a_{44}$$

which are precisely the diagonal entries of A.

**Theorem:** If A is an  $n \times n$  triangular matrix (upper triangular, lower triangular, or diagonal), then the eigenvalues of A are the entries on the main diagonal of A.

# **Example:** Eigenvalues of a Lower Triangular Matrix By inspection, the eigenvalues of the lower triangular

matrix

$$A = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ -1 & \frac{2}{3} & 0 \\ 5 & -8 & -\frac{1}{4} \end{bmatrix}$$

are 
$$\lambda = \frac{1}{2}, \lambda = \frac{2}{3}, \lambda = -\frac{1}{4}$$
.

# **Complex Eigenvalues**

It is possible for the characteristic equation of a matrix with real entries to have complex solutions. In fact, because the eigenvalues of an  $n \times n$  matrix are the roots of a polynomial of precise degree n, every  $n \times n$  matrix has exactly n eigenvalues if we count them as we count the roots of a polynomial (meaning that they may be repeated, and may occur in complex conjugate pairs).

# **Example: Complex eigenvalues**

$$A = \begin{bmatrix} -2 & -1 \\ 5 & 2 \end{bmatrix}$$

The characteristic polynomial of the given matrix is

$$\det(\lambda I - A) = \det\begin{bmatrix} \lambda + 2 & 1 \\ -5 & \lambda - 2 \end{bmatrix} = \lambda^2 + 1$$

So the characteristic equation is  $\lambda^2 + 1 = 0$ , the solutions of which are the imaginary numbers

$$\lambda = i, \lambda = -i$$

Thus we are forced to consider complex eigenvalues, even for real matrices.

# Eigenvalues and Eigenvectors of the power of A

Once the eigenvalues and eigenvectors of a matrix A are found, it is simple matter to find the eigenvalues and eigenvectors of any positive integer power of A; for example, if  $\frac{1}{2}$  is an eigenvalue of  $\frac{1}{2}$  and  $\frac{1}{2}$  is a corresponding eigenvector, then

$$A^2x = A(Ax) = A(\lambda x) = \lambda(\lambda x) = \lambda^2 x$$

which shows that  $\frac{\lambda^2}{\lambda}$  is an eigenvalue of  $\frac{A^2}{\lambda}$  and that  $\frac{x}{\lambda}$  is a corresponding eigenvector.

Theorem: If k is a positive integer,  $\frac{\lambda}{l}$  is an eigenvalue of a matrix  $\frac{A}{l}$ , and x is corresponding eigenvector, then  $\frac{\lambda^{k}}{l}$  is an eigenvalue of  $\frac{A^{k}}{l}$  and x is a corresponding eigenvector.

# **Example:**

We showed that the eigenvalues of

$$A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$$

are  $\lambda = 2$  and  $\lambda = 1$ .

 $\lambda = 2^5 = 32$  and  $\lambda = 1^5 = 1$  are eigenvalues of A<sup>5</sup>.

$$A^5 = \begin{bmatrix} -30 & 0 & -62 \\ 31 & 32 & 31 \\ 31 & 0 & 63 \end{bmatrix}$$

>> A=[0 0 -2; 1 2 1; 1 0 3]

$$A =$$

$$A5 =$$

>>

We also showed that

 $\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  are eigenvectors of A

corresponding to eigenvalue  $\lambda = 2$ . They are also eigenvectors of A<sup>5</sup>. Similarly, the eigenvector

 $\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$ 

of A corresponding to the eigenvalue  $\lambda = 1$  is also an eigenvector of  $A^5$ .

Theorem: A square matrix A is invertible if and only if

$$\lambda = 0$$

# is not an eigenvalue of A.

Assume that A is an  $n \times n$  matrix and observe first that  $\lambda = 0$  is a solution of the characteristic equation

$$\lambda^n + c_1 \lambda^{n-1} + \ldots + c_n = 0$$

if and only if the constant term  $\frac{c_n}{c_n}$  is zero. Thus it suffices to prove that A is invertible if and only if  $\frac{c_n \neq 0}{c_n \neq 0}$ . But

$$\det(\lambda I - A) = \lambda^n + c_1 \lambda^{n-1} + \dots + c_n$$

Or, on setting  $\lambda = 0$ ,

$$\det(-A) = c_n \quad \text{or} \quad (-1)^n \det(A) = c_n$$

It follows from the last equation that  $\frac{\det(A)=0}{c_n=0}$  if and only if  $\frac{c_n=0}{c_n\neq 0}$ , and this in turn implies that A is invertible if and only if  $\frac{c_n\neq 0}{c_n\neq 0}$ .

# **Example:**

We showed that the eigenvalues of

$$A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$$

are 
$$\lambda_1 = 1$$
 and  $\lambda_{2,3} = 2$ 

The matrix A is invertible since it has eigenvalues  $\lambda = 2$  and  $\lambda = 1$  neither of which is zero.

$$>> A=[0\ 0\ -2;\ 1\ 2\ 1;\ 1\ 0\ 3]$$

$$A =$$

# **Eigenvalues Relationships**

If A is a square n-by-n matrix with <u>real</u> or <u>complex</u> entries and if  $\lambda_i$ , i = 1...n are the (complex and distinct) <u>eigenvalues</u> of A, then

$$trace(A) = \sum_{i=1}^{n} \lambda_i$$
.

The product of the eigenvalues of a square matrix is equal to the determinant of that matrix.

$$det(A) = \prod_{i=1}^{n} \lambda_{i}$$
>> A=[0 0 -2;1 2 1;1 0 3]
A =

0 0 -2
1 2 1
1 0 3
>> det(A)
ans = 4
>> eig(A)
ans =

2
1
2
>> trace(A)
ans = 5

# **Example:**

$$A = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$$

The characteristic equation of A is

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -3 \\ -4 & \lambda - 2 \end{vmatrix} = 0$$

or

$$\lambda^2 - 3\lambda - 10 = 0$$

The factored form of this equation is

$$(\lambda + 2)(\lambda - 5) = 0$$
, so the eigenvalues

$$\lambda = -2, \lambda = 5$$

# **Example:**

$$A = \left[ \begin{array}{cc} 3 & 6 \\ 1 & 4 \end{array} \right].$$

Let's find both of the eigenvalues of the matrix

$$A - \lambda I = \begin{bmatrix} 3 - \lambda & 6 \\ 1 & 4 - \lambda \end{bmatrix}$$
$$\det(A - \lambda I) = (3 - \lambda)(4 - \lambda) - 6$$
$$= \lambda^2 - 7\lambda + 6$$
$$= (\lambda - 6)(\lambda - 1)$$

Therefore,  $\lambda = 6$  or  $\lambda = 1$ . We now know our eigenvalues.

Product of eigenvalues 
$$= \det(A)$$
  
 $6*1 = 12-6$   
 $6 = 6$ 

# **Example**

For

$$A = \left[ \begin{array}{cc} 2 & 6 \\ 2 & -2 \end{array} \right],$$

Product of eigenvalues = 
$$det(A)$$
  
 $4*(-4) = -4-12$   
 $-16 = -16$ 

$$\begin{vmatrix} 2-\lambda & 6\\ 2 & -2-\lambda \end{vmatrix} = (2-\lambda)(-2-\lambda) - 12 = 0$$

$$(\lambda^2 - 16) = 0 \quad \lambda_{1,2} = \pm 4 \qquad \lambda_1 \lambda_2 = -16$$

$$Trace(A) = 0 = \sum_{i=1}^{2} \lambda_i = 4 - 4 = 0$$

# **Example**

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 9 \\ 6 & 8 & 3 & 4 \\ 9 & 8 & 2 & 4 \end{bmatrix}$$

# >> [V,D]=eig(A)

```
V =
0.2499  0.3566  0.4375  0.0725
0.6496  0.5444  -0.3859  -0.1563
0.5016  -0.4121  0.6595  -0.7518
0.5137  -0.6377  -0.4741  0.6365
```

```
D =
 20.4460 0
                  0
    0 -6.5683
                  0
          0 -0.5759
    0
    0
          0
                0 0.6982
>> trace(D)
ans = 14.0000
>> TRACE(A)
ans = 14
>> det(A)
ans = 54
```

# Square root of a matrix

A matrix B is said to be a square root of A if the matrix product  $B \cdot B$  is equal to  $A^{[1]}$ .

### [edit] Computation by diagonalization

The square root of a  $\underline{\text{diagonal matrix}} D$  is formed by taking the square root of all the entries on the diagonal. This suggests the following methods for general matrices:

An  $n \times n$  matrix A is <u>diagonalizable</u> if there is a matrix V such that  $D = V^{-1}AV$  is a <u>diagonal matrix</u>. This happens if and only if A has n <u>eigenvectors</u> which constitute a basis for  $\mathbb{C}^n$ ; in this case, V can be chosen to be the matrix with the n eigenvectors as columns.

Now,  $A = VDV^{-1}$ , and hence the square root of A is

$$A^{1/2} = VD^{1/2}V^{-1}$$
.

This approach works only for <u>diagonalizable matrices</u>. For non-diagonalizable matrices one can calculate the <u>Jordan normal form</u> followed by a series expansion, similar to the approach described in <u>logarithm of a matrix</u>.