

Howework 5

Lingyu Zhou

2024.4.10

2.

1.

$$\begin{aligned}\bar{y}(x) &= \mathbb{E}[y] \\ &= \mathbb{E}[f(x) + \epsilon] \\ &= \mathbb{E}[f(x)] + \mathbb{E}[\epsilon] \\ &= f(x), \text{ since } f \text{ is deterministic}\end{aligned}$$

2.

It measures the expected error of the expected classifier and the actual value given data x . It should be 0 when $\bar{h}_k(x)$ is the ideal expected classifier for data point x .

3.

$$\begin{aligned}\text{EPE}_k(x) &= \mathbb{E}_{D,(x,y)}[(y - h_k(x))^2] \\ &= \mathbb{E}_{D,(x,y)}[(y - \bar{y}(x) + \bar{y}(x) - h_k(x))^2] \\ &= \mathbb{E}_{D,(x,y)}[(y - \bar{y}(x))^2 + 2(y - \bar{y}(x))(\bar{y}(x) - h_k(x)) + (\bar{y}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_D[\mathbb{E}_{(x,y)}[2(y - \bar{y}(x))(\bar{y}(x) - h_k(x))]] + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_D[2(\bar{y}(x) - h_k(x))\mathbb{E}_{(x,y)}[(y - \bar{y}(x))]] + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_D[2(\bar{y}(x) - h_k(x))(\mathbb{E}_{(x,y)}[y] - \bar{y}(x)) + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - h_k(x))^2] \\ &:= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_D[2(\bar{y}(x) - h_k(x))(\mathbb{E}[y|x] - \bar{y}(x)) + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - \bar{h}(x) + \bar{h}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{D,(x,y)}[(\bar{y}(x) - \bar{h}(x))^2 + 2(\bar{y}(x) - \bar{h}(x))(\bar{h}(x) - h_k(x)) + (\bar{h}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{(x,y)}[(\bar{y}(x) - \bar{h}(x))^2] + \mathbb{E}_{D,(x,y)}[2(\bar{y}(x) - \bar{h}(x))(\bar{h}(x) - h_k(x)) + \mathbb{E}_{D,(x,y)}[(\bar{h}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{(x,y)}[(\bar{y}(x) - \bar{h}(x))^2] + \mathbb{E}_{(x,y)}[\mathbb{E}_D[2(\bar{y}(x) - \bar{h}(x))(\bar{h}(x) - h_k(x))]] + \mathbb{E}_{D,(x,y)}[(\bar{h}(x) - h_k(x))^2] \\ &:= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{(x,y)}[(\bar{y}(x) - \bar{h}(x))^2] + \mathbb{E}_{(x,y)}[\mathbb{E}_D[2(\bar{y}(x) - \bar{h}(x))(\bar{h}(x) - \bar{h}(x))]] + \mathbb{E}_{D,(x,y)}[(\bar{h}(x) - h_k(x))^2] \\ &= \mathbb{E}_{(x,y)}[(y - \bar{y}(x))^2] + \mathbb{E}_{(x,y)}[(\bar{y}(x) - \bar{h}(x))^2] + \mathbb{E}_{D,(x,y)}[(\bar{h}(x) - h_k(x))^2] \\ &= \underbrace{\mathbb{E}_{D,(x,y)}[(y(x) - \bar{y}(x))^2]}_{\text{noise}} + \underbrace{\mathbb{E}_{D,(x,y)}[(\bar{y}(x) - \bar{h}(x))^2]}_{\text{bias}} + \underbrace{\mathbb{E}_{D,(x,y)}[(\bar{h}(x) - h_k(x))^2]}_{\text{variance}}\end{aligned}$$

4.

$$\begin{aligned}\mathbb{E}_{D,(x,y)}[(\bar{y}(x) - y(x))^2] &= \mathbb{E}_{D,(x,y)}[(\mathbb{E}[f(x) + \epsilon] - f(x) - \epsilon)^2] \\ &= \mathbb{E}_{D,(x,y)}[(f(x) + 0 - f(x) - \epsilon)^2] \\ &= \mathbb{E}_{D,(x,y)}[\epsilon^2] \\ &= \text{VAR}(\epsilon) - \mathbb{E}[\epsilon]^2 \\ &= \sigma^2\end{aligned}$$

$$\begin{aligned}
\mathbb{E}_{D,(x,y)}[(h(x) - \bar{h}(x))^2] &= \mathbb{E} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) + \epsilon_l - \mathbb{E} \left[\frac{1}{k} \sum_{l=1}^k f(x_l) + \epsilon_l \right] \right)^2 \right] \\
&= \mathbb{E} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) + \epsilon_l - \frac{1}{k} \sum_{l=1}^k \mathbb{E}[f(x_l) + \epsilon_l] \right)^2 \right] \\
&= \mathbb{E} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) + \epsilon_l - f(x_l) \right)^2 \right] \\
&= \mathbb{E} \left[\left(\frac{1}{k} \sum_{l=1}^k \epsilon_l \right)^2 \right] \\
&= \frac{1}{k^2} \mathbb{E} \left[\left(\sum_{l=1}^k \epsilon_l \right)^2 \right] \\
&= \frac{1}{k^2} \mathbb{E} \left[\left(\left(\sum_{l=1}^k \epsilon_l^2 \right) + \epsilon_1 \epsilon_2 + \dots + \epsilon_{k-1} \epsilon_k \right)^2 \right] \\
&= \frac{1}{k^2} \mathbb{E} \left[\left(\mathbb{E} \left(\sum_{l=1}^k \epsilon_l^2 \right) + \mathbb{E}[\epsilon_1 \epsilon_2 + \dots + \epsilon_{k-1} \epsilon_k] \right)^2 \right] \\
&= \frac{1}{k^2} \mathbb{E} \left[\left(\mathbb{E} \left(\sum_{l=1}^k \epsilon_l^2 \right) + \mathbb{E}[\epsilon_1] \mathbb{E}[\epsilon_2] + \dots + \mathbb{E}[\epsilon_{k-1}] \mathbb{E}[\epsilon_k] \right)^2 \right], \epsilon \text{ independent with each other} \\
&= \frac{1}{k^2} \mathbb{E} \left[\sum_{l=1}^k \mathbb{E}[\epsilon_l^2] \right] \\
&= \frac{1}{k^2} \left[\sum_{l=1}^k \text{VAR}(\epsilon) - \mathbb{E}[\epsilon]^2 \right] \\
&= \frac{1}{k^2} [k\sigma^2] \\
&= \frac{\sigma^2}{k}
\end{aligned}$$

$$\begin{aligned}
\mathbb{E}_{D,(x,y)}[(\bar{h}(x) - \bar{y}(x))^2] &= \mathbb{E}_{D,(x,y)} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) - \mathbb{E}[f(x) + \epsilon] \right)^2 \right] \\
&= \mathbb{E}_{D,(x,y)} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) - \mathbb{E}[f(x)] + \mathbb{E}[\epsilon] \right)^2 \right] \\
&= \mathbb{E}_{D,(x,y)} \left[\left(\frac{1}{k} \sum_{l=1}^k f(x_l) - f(x) \right)^2 \right] \\
&= \left(\frac{1}{k} \sum_{l=1}^k f(x_l) - f(x) \right)^2, \text{ since } f(\cdot) \text{ is deterministic}
\end{aligned}$$

Therefore:

$$\text{EPE}_k(x) = \sigma^2 + \frac{\sigma^2}{k} + \left(\frac{1}{k} \sum_{l=1}^k f(x_l) - f(x) \right)^2 = \sigma^2 + \frac{\sigma^2}{k} + \left(\frac{f(x_1) + \dots + f(x_k)}{k} - f(x) \right)^2$$

3.

	Overfitting	Underfitting
increase the regularization	yes	no
decrease the regularization	no	yes
use less features	yes	no
use more features	no	yes
use a more complex model	no	yes
use a less complex model	yes	no

4.

In this question for simplicity, write 2-norm " $\|\cdot\|_2$ " as " $\|\cdot\|$ ", \tilde{w} as w , \tilde{x} as x , keep \tilde{w}

1.

Since $\|a - b\| < \|a\| + \|b\|$ and $\|a - b\| \geq 0$, $\|a - b\|^2 < \|a\|^2 + 2\|a\| \cdot \|b\| + \|b\|^2$.

Therefore $\|w(D) - \tilde{w}\|^2 < \|w(D)\|^2 + 2\|w(D)\| \cdot \|\tilde{w}\| + \|\tilde{w}\|^2$.

Given $\|w(D)\| \leq B$, it follows $\|w(D)\|^2 \leq B^2$; also since $\tilde{w} = \mathbb{E}(w(D))$ and $\tilde{w} \leq \max_D(w(D)) \leq B$, combined we have $\|w(D) - \tilde{w}\|^2 \leq B^2 + 2B \cdot B + B^2 = 4B^2$

2.

$$\begin{aligned}
 h_D(x) - \tilde{h}(x) &= w(D)^\top x - \mathbb{E}_D[h_D(x)] \\
 &= w(D)^\top x - \mathbb{E}_D[w(D)^\top x] \\
 &= w(D)^\top x - \mathbb{E}_D[w(D)]^\top x, \text{ since } x \text{ not depend on } D \\
 &= w(D)^\top x - \tilde{w}(D)^\top x \\
 &= (w(D) - \tilde{w}(D))^\top x
 \end{aligned}$$

Taking square and expectation on both sides gives:

$$\begin{aligned}
 \mathbb{E}[(h_D(x) - \tilde{h}(x))]^2 &= \mathbb{E}[(w(D) - \tilde{w}(D))^\top x]^2 \\
 &\leq \mathbb{E}[(w(D) - \tilde{w}(D))^\top (w(D) - \tilde{w}(D)) x^\top x], \text{ given} \\
 &= \mathbb{E}[\|w(D) - \tilde{w}(D)\|^2 \cdot \|x\|^2] \\
 &= \mathbb{E}[\|w(D) - \tilde{w}(D)\|^2], \text{ given} \\
 &\leq 4B^2, \text{ by 1.}
 \end{aligned}$$