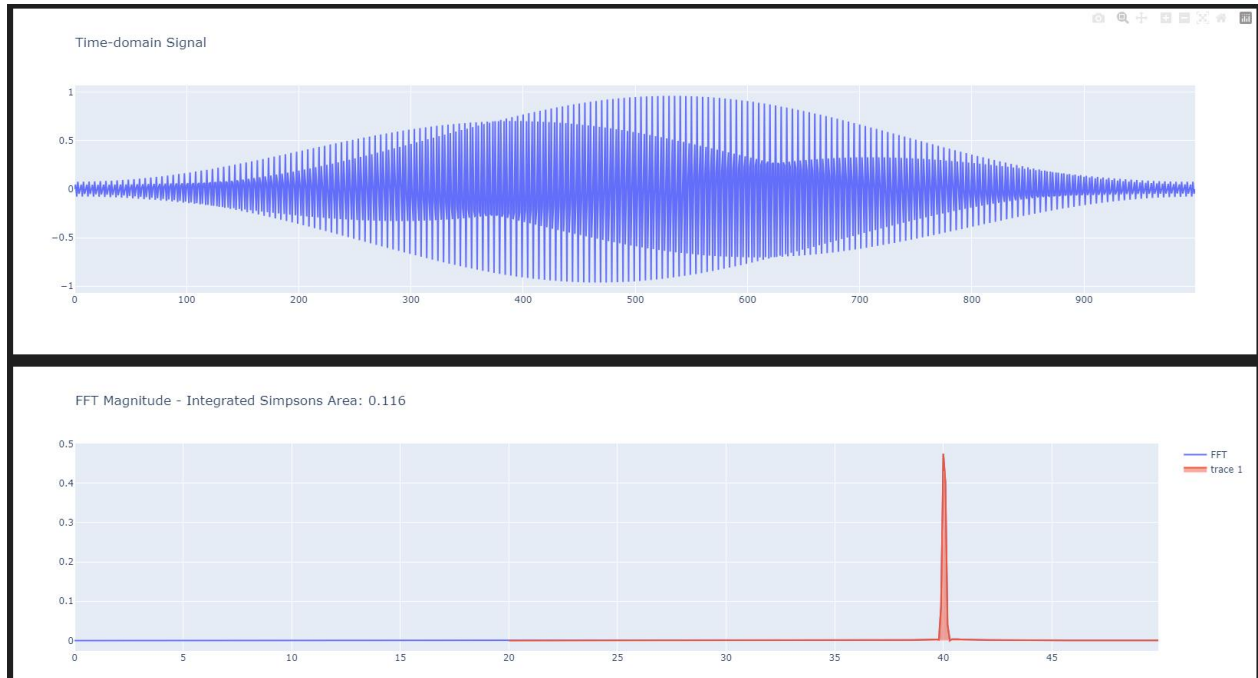
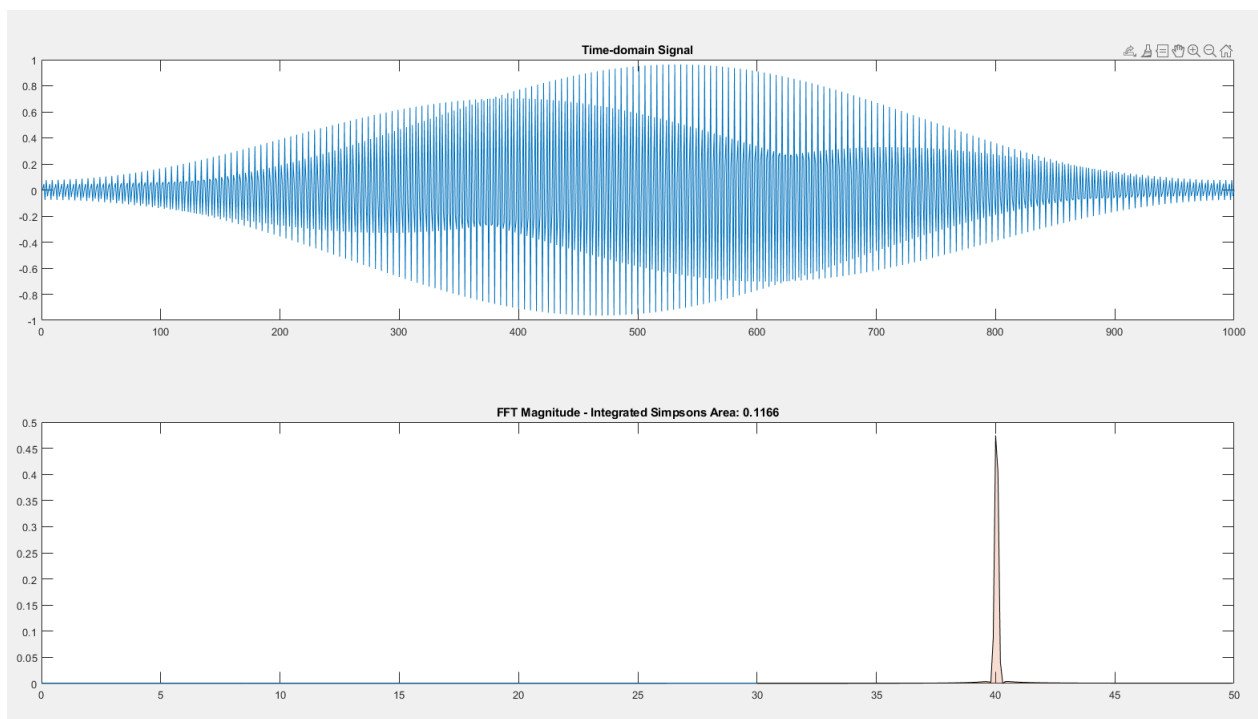


1a - python



1a - matlab



1b - python

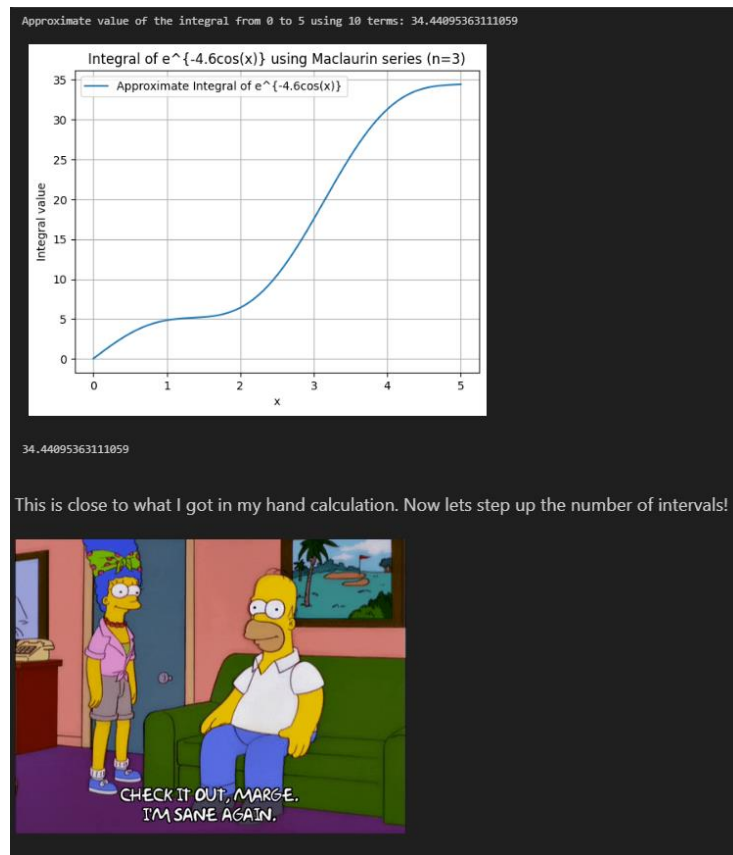


Figure 1: Maclaurin Series - checking validity of low N value hand calc

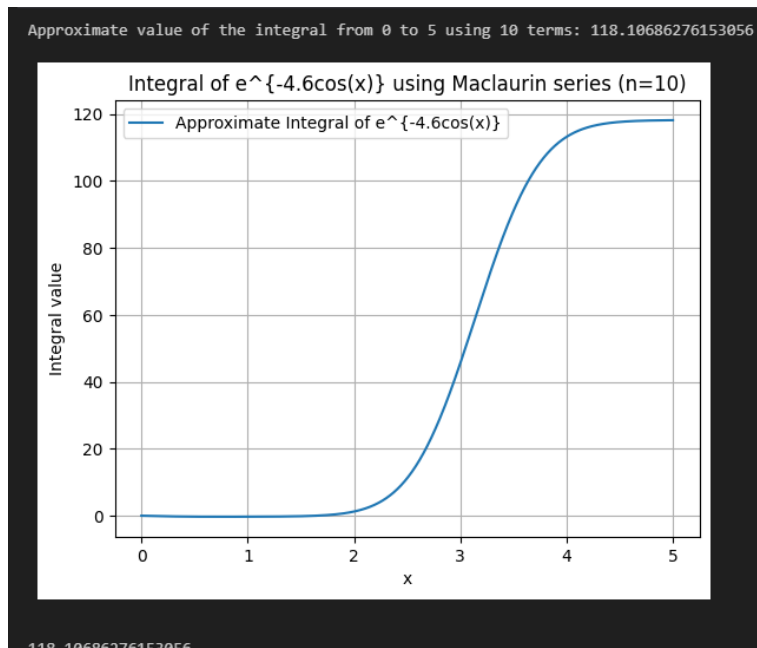
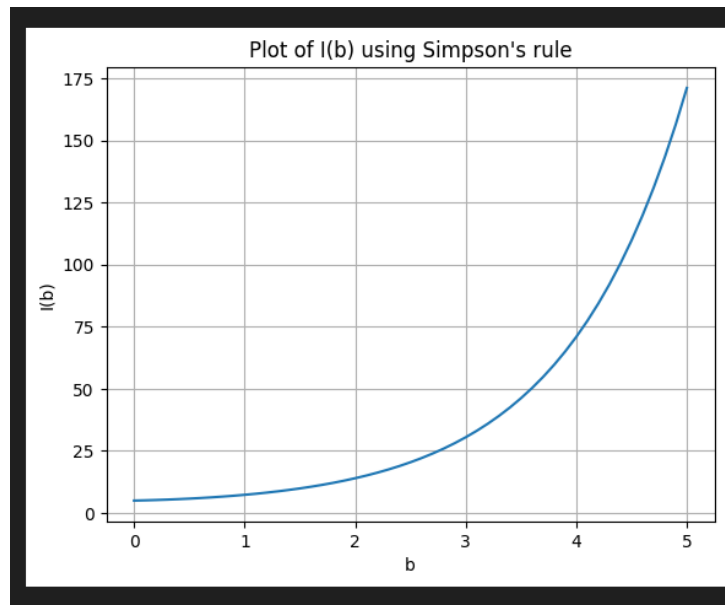
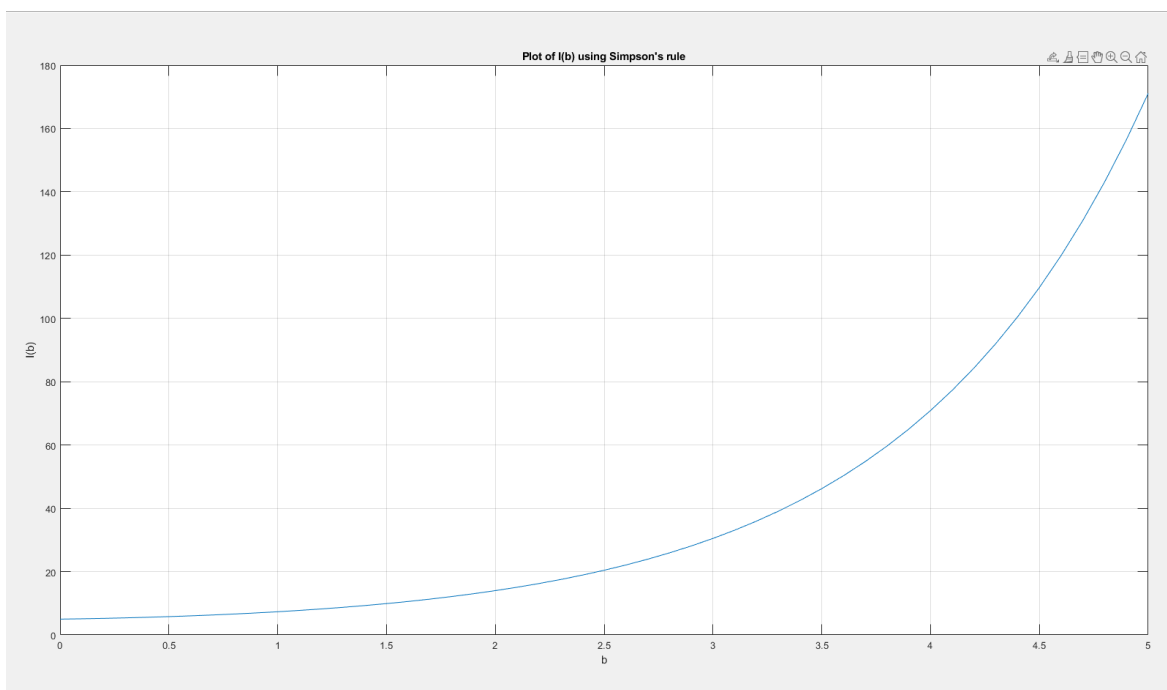


Figure 2: increasing N to compare to Simpson Rule



1b – matlab



1c – python

Method 1

```
>
# Define the function to be integrated
def f(x):
    return 1 / (2 - np.sqrt(x))

# Integrate the function from 0 to 5
integral_value, _ = quad(f, 0, 5)

# Generate x values for plotting
x = np.linspace(0, 5, 1000)
y = f(x)

[ ]

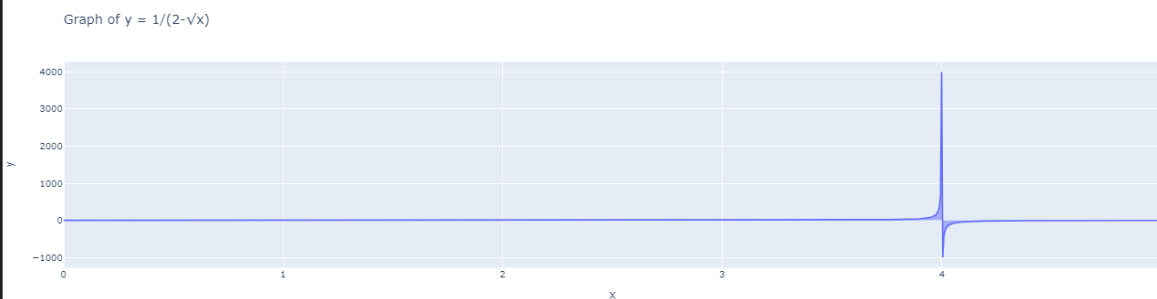
... C:\Users\Aaron\AppData\Local\Temp\ipykernel_19532\3069320982.py:6: IntegrationWarning: The integral is probably divergent, or slowly convergent.
      integral_value, _ = quad(f, 0, 5)
```

what my computer really means....



good thing Gaussian Quadrature is robust

$$\int_a^b f(x) dx \approx \sum_{i=1}^n w_i \cdot f(x_i)$$

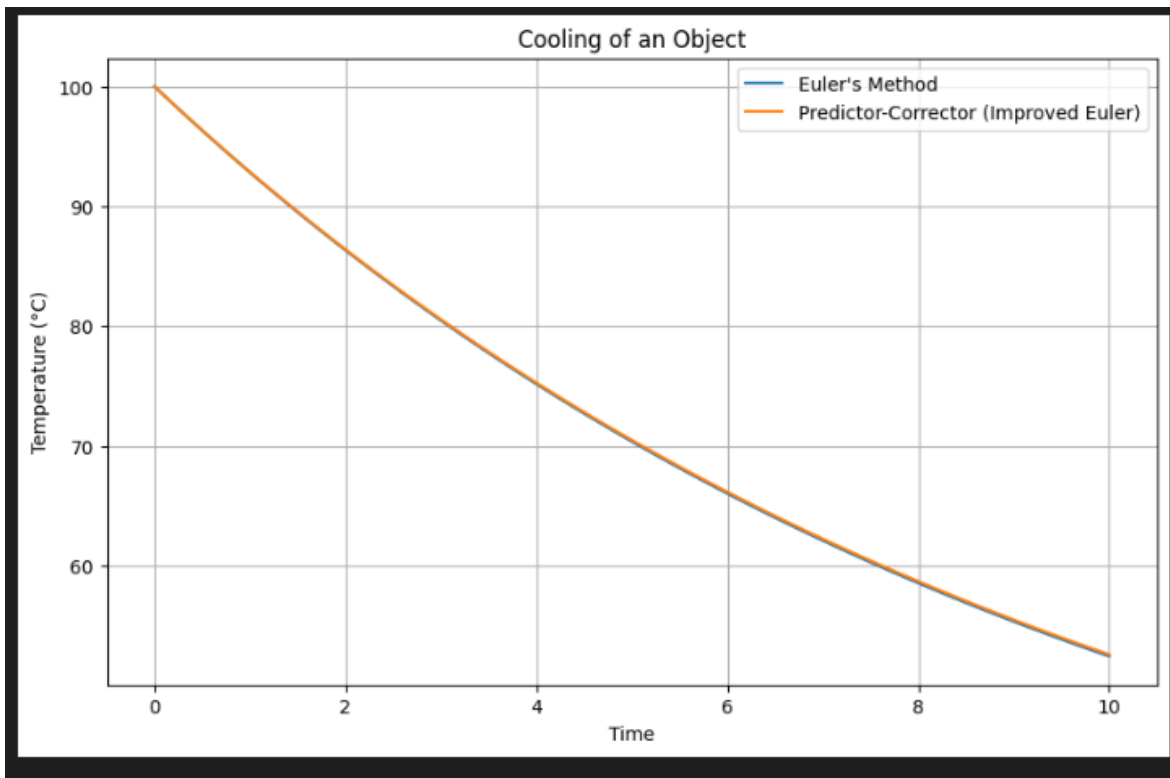


Value of I from 0 to 5: 4.07499

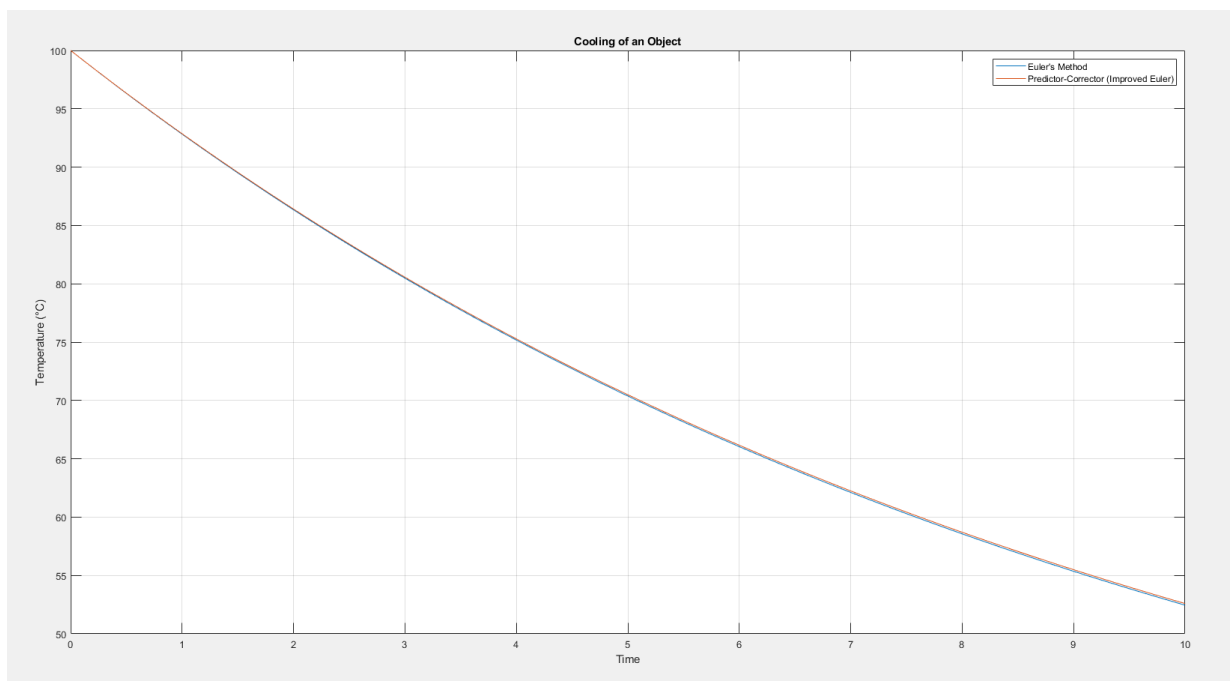
1c – matlab

Output - Value of I from 0 to 5: 4.07500

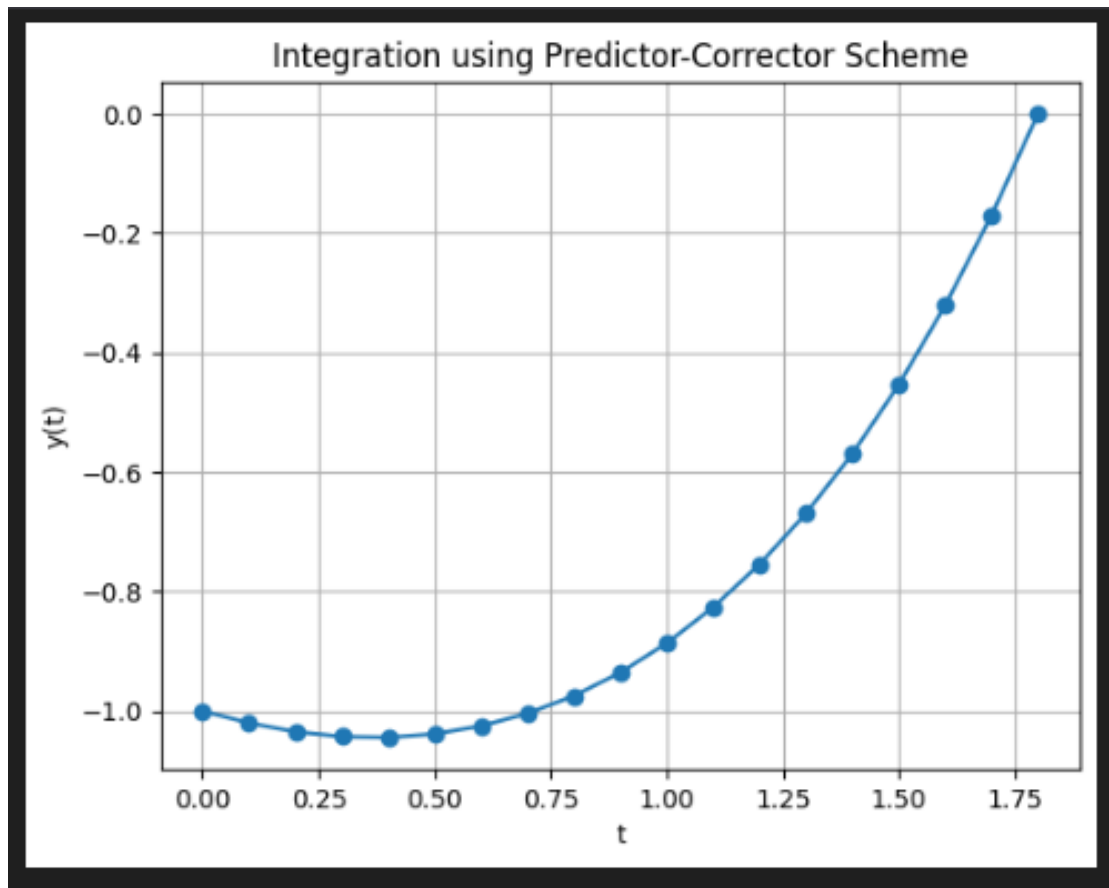
2a – python



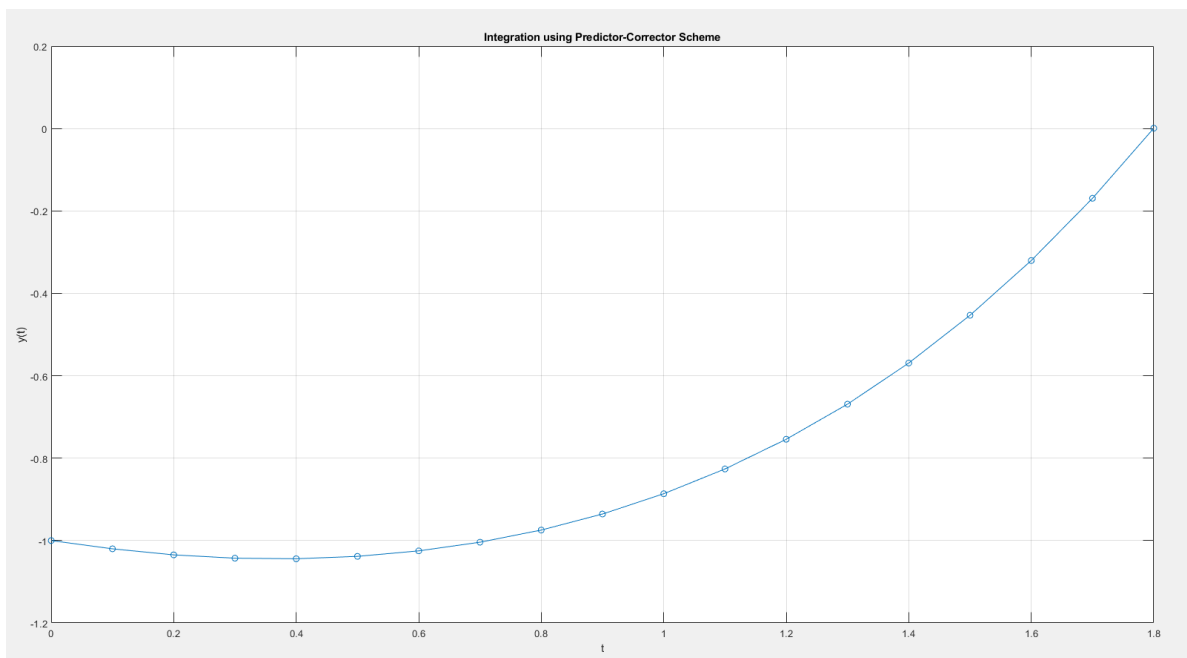
2a – matlab



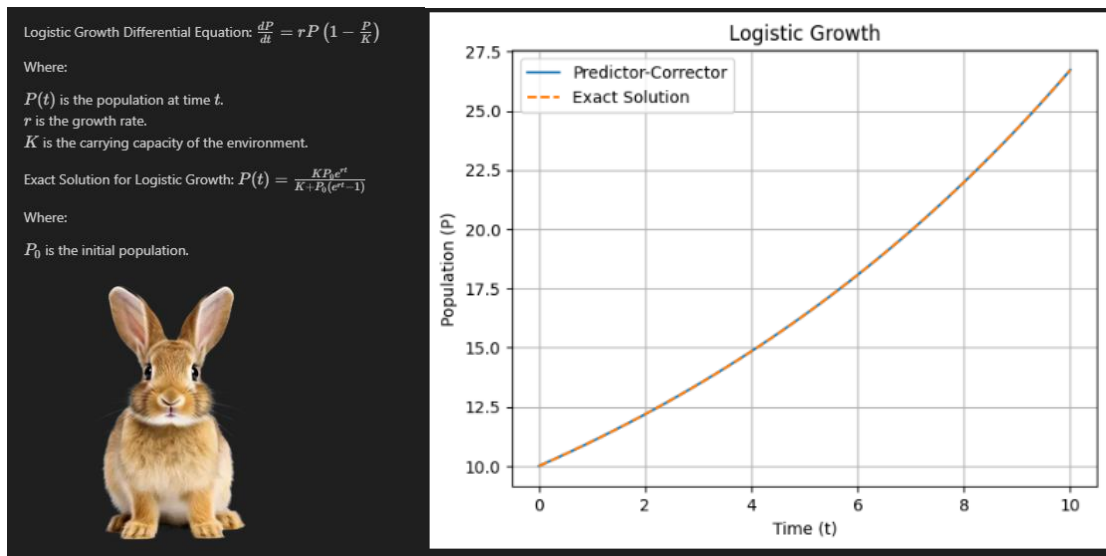
2b – python



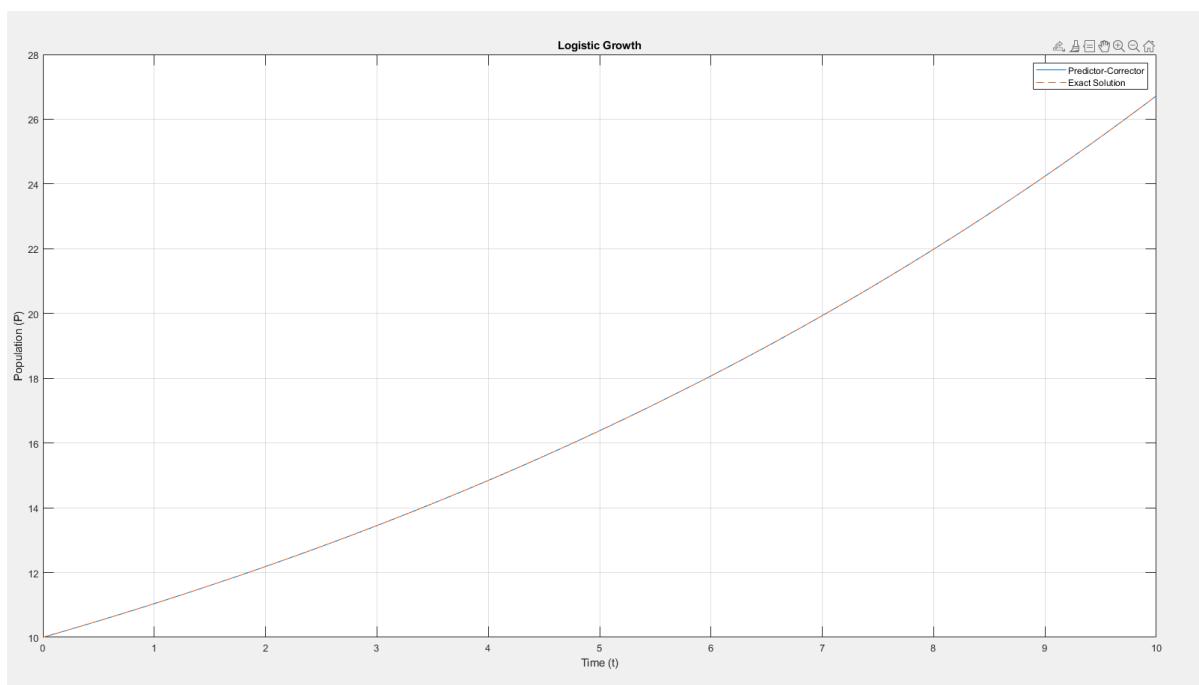
2b – matlab



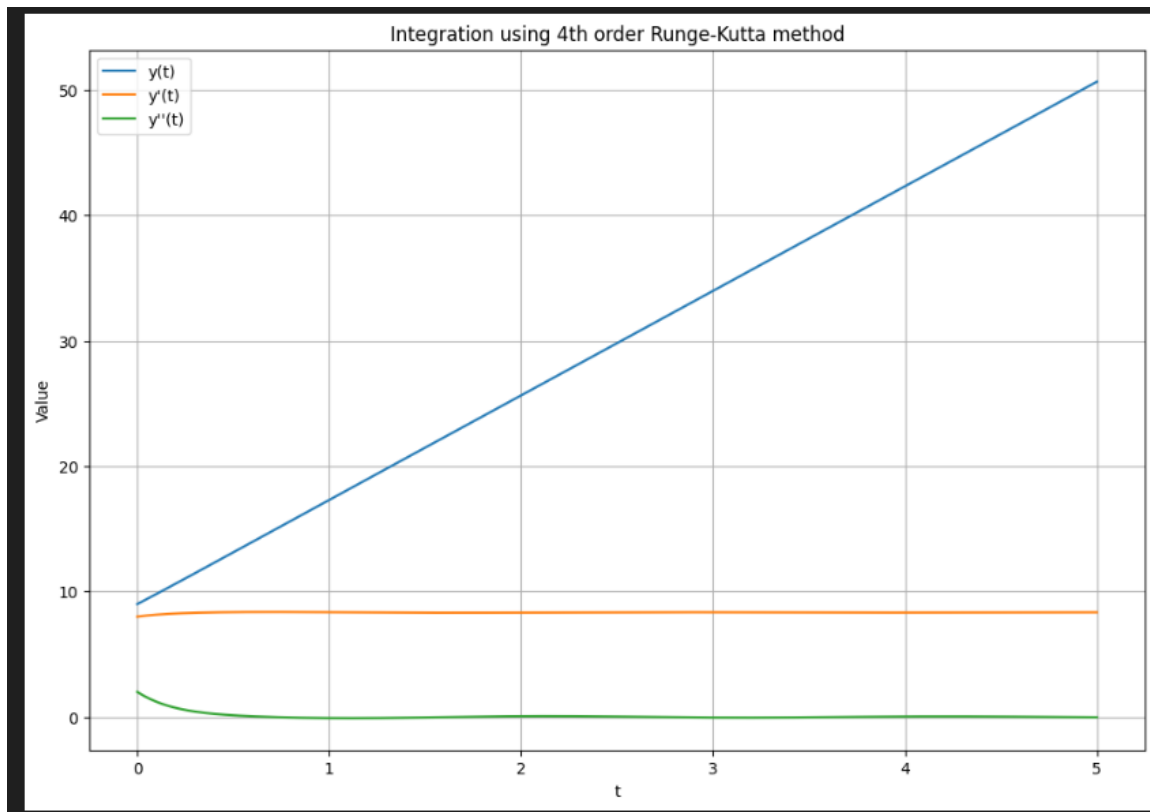
3a – python



3a – matlab



3b – python



3b – python

