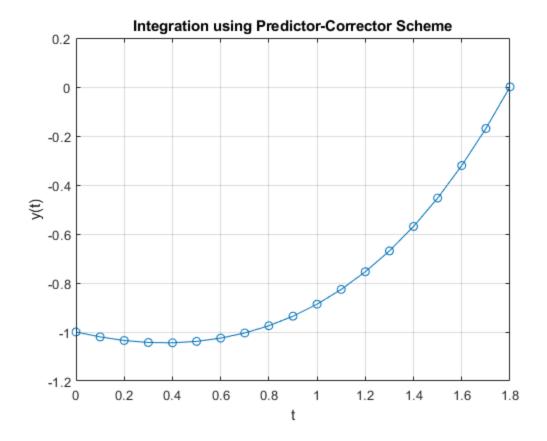
```
function predictor_corrector_integration()
% Compute average of TUID
TUID = [9,1,5,1,8,7,2,8,9];
alpha = mean(TUID);
fprintf('my TUID average: %.2f\n', alpha);
% Given data
t_values = 0.0:0.1:1.8;
f_{values} = [1.00, 0.84, 0.78, 0.73, 0.68, 0.65, 0.61, 0.58, 0.55, 0.53, 0.50, 0.50]
 0.48, 0.45, 0.43, 0.41, 0.39, 0.37, 0.35, 0.33];
h = 0.1;
y = -1; % Initial value
% Predictor-Corrector Scheme
for j = 1:length(t values)-1
    t = t_values(j);
    % Predictor
    y_star = y(end) + h * dydt(t, y(end), f_values(j), alpha);
    % Corrector
    y_{next} = y(end) + (h/2) * (dydt(t, y(end), f_values(j), alpha) + dydt(t+h, y_{next})
 y_star, f_values(j+1), alpha));
    y = [y, y_next];
end
% Plotting
figure;
plot(t_values, y, '-o');
xlabel('t');
ylabel('y(t)');
title('Integration using Predictor-Corrector Scheme');
grid on;
% Estimate the minimum value of y
[min_value, index] = min(y);
t_min = t_values(index);
fprintf('The minimum value of y is approximately %.4f at t = %.1f\n',
min_value, t_min);
    function dy = dydt(t, y, f_t, alpha)
        dy = y / (y * cos(t / 3) + alpha * f_t) + t;
    end
end
my TUID average: 5.56
The minimum value of y is approximately -1.0441 at t = 0.4
```



Published with MATLAB® R2023a