progress of deep learning on graph

sources

- Third Representation Learning for Graphs Workshop (ReLiG 2017)
- https://github.com/thunlp/NRLPapers
- https://truyentran.github.io/repLearn.html
- http://geometricdeeplearning.com/

agenda

- Modeling Relational Data with GCN
- Motif-aware graph embeddings
- Graph Convolutional Matrix Completion
- Geometric deep learning: going beyond Euclidean data

Modeling Relational Data

with GCN

MODELING RELATIONAL DATA WITH GRAPH CONVOLUTIONAL NETWORKS

LINK PREDICTION AND ENTITY CLASSIFICATION ON KNOWLEDGE GRAPHS

M. Schlichtkrull*, T. N. Kipf*, P. Bloem, R. vd Berg, I. Titov, M. Welling, Model Relational Data with Graph Convolutional Networks, arXiv:1703.06103 (2 By the author of GCN

<u>link</u>

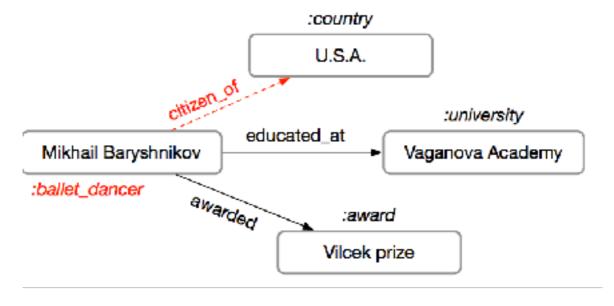
Contribution: consider relation and entity classification at the same time Pro: utilize mutual information between relation and entity

Concept

 Predicting missing information in knowledge bases is the main focus of statistical relational learning (SRL).

Motivation Example:

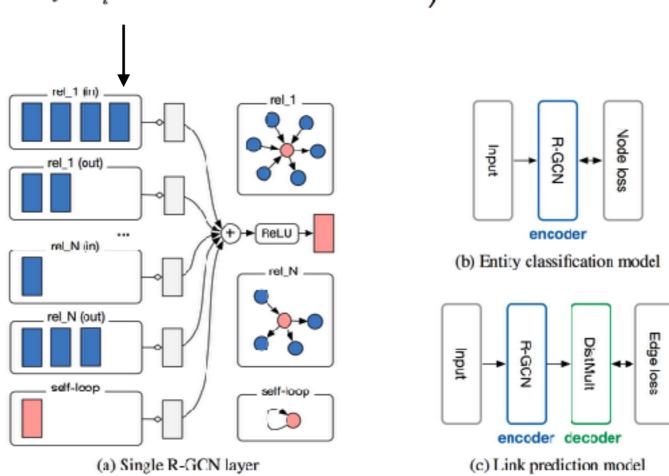
- Vilcek prize (an award honoring contributions of immigrants to the US society) implies having the US citizenship,
- graduating from the Vaganova Academy probably means that the entity is a ballet dancer.



Modeling Relational Data with GCN

traverse all types of relations and neighbors

$$h_i^{(l+1)} = \sigma \left(\sum_{r \in \mathcal{R}} \sum_{j \in \mathcal{N}_i^r} \frac{1}{c_{i,r}} W_r^{(l)} h_j^{(l)} + W_0^{(l)} h_i^{(l)} \right)$$



Modeling Relational Data with Graph Convolutional Networks

Methods for tasks:

DistMult
$$f(s, r, o) = e_s^T R_r e_o$$
 triple (s, r, o) (subject, relation, object)

Link prediction

$$\mathcal{L} = -\frac{1}{(1+\omega)|\hat{\mathcal{E}}|} \sum_{(s,r,o,y)\in\mathcal{T}} y \log \sigma \big(f(s,r,o)\big) + (1-y) \log \big(1 - \sigma \big(f(s,r,o)\big)\big)$$

- ω negative sample rate
- $|\hat{\mathcal{E}}|$ Edge number
- Entity classification

$$\mathcal{L} = -\sum_{i \in \mathcal{Y}} \sum_{k=1}^{K} t_{ik} \ln h_{ik}^{(L)}$$

categorical cross entropy

 t_{ik} denotes its respective ground truth label.

 $\boldsymbol{h}_{ik}^{(L)}$ is the k-th entry of the network output

Motif-aware graph embeddings

Contribution: motif-based graph classification Pro: motif level information

Significant graph

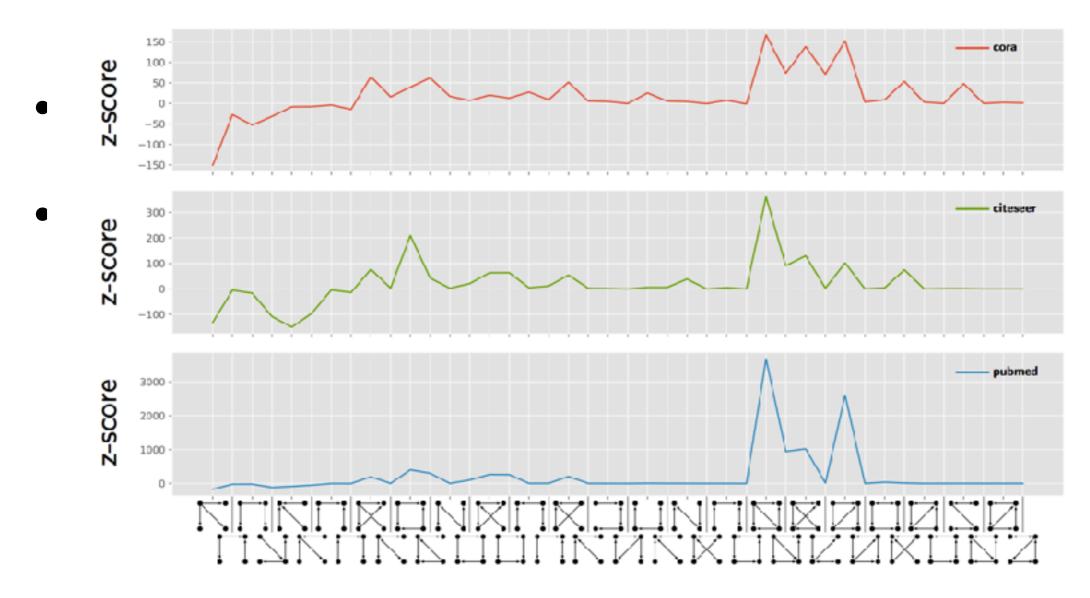
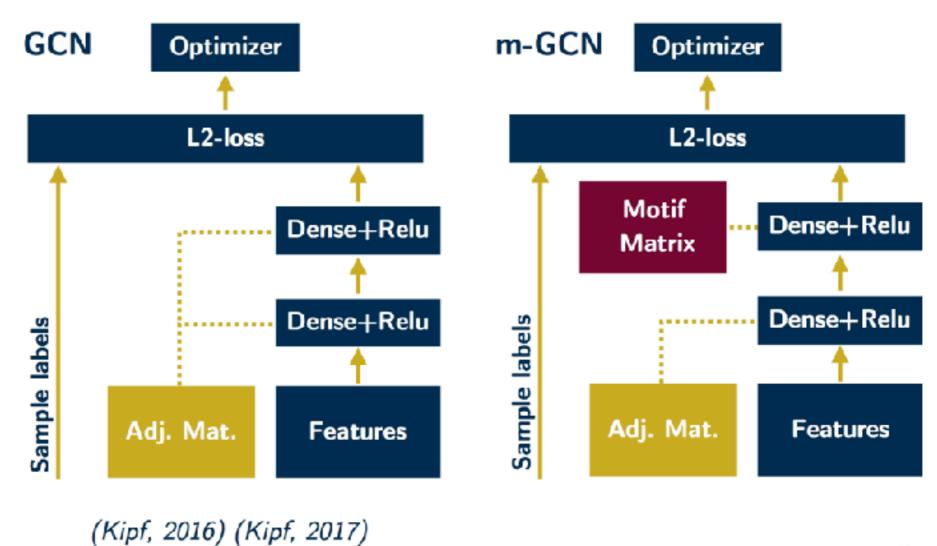


Fig. 6 - Z-scores for motifs of size-4 in Citation networks

Motif-aware graph embeddings

Motif laplacian for graph convolutional networks



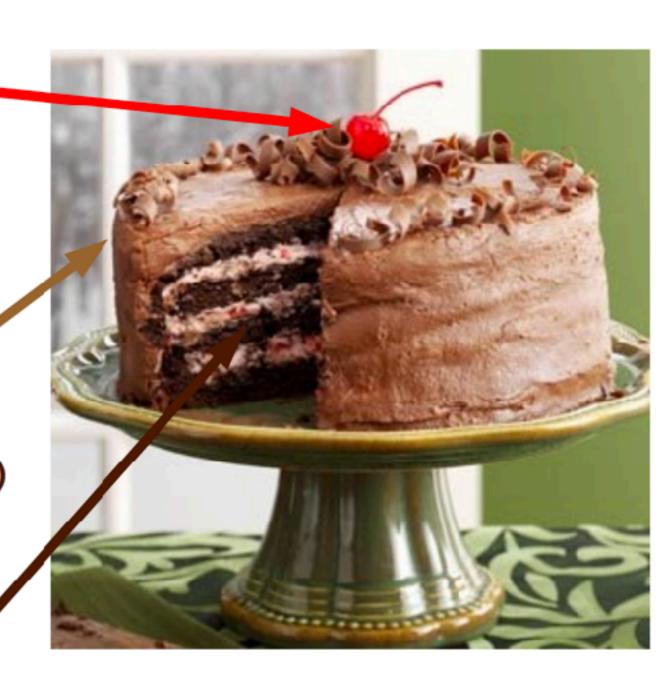
p. 14

Motif co-occurance matrix: select significant motifs, count if nodes exist in the same motif



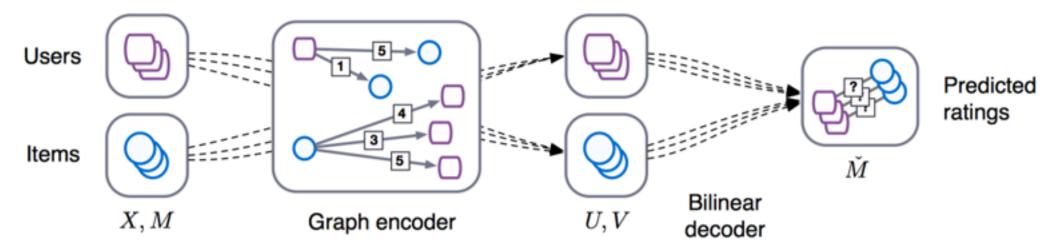
How Much Information Does the Machine Need to Predict?

- "Pure" Reinforcement Learning (cherry)
 - The machine predicts a scalar reward given once in a while.
 - A few bits for some samples
- Supervised Learning (icing)
 - The machine predicts a category or a few numbers for each input
 - Predicting human-supplied data
 - **▶** 10→10,000 bits per sample
- Unsupervised/Predictive Learning (cake)
 - The machine predicts any part of its input for any observed part.
 - Predicts future frames in videos
 - Millions of bits per sample



Graph Convolutional Matrix Completion

Contribution: unsupervised graph completion Pro: alleviate the pain of requiring mass data



of 1) a graph encoder model Z = f(X, A), which take as input an $N \times D$ feature matrix X and a graph adjacency matrix A, and produce an $N \times E$ node embedding matrix $Z = [z_1^T, \ldots, z_N^T]^T$, and 2) a pairwise decoder model $\check{A} = g(Z)$, which takes pairs of node embeddings (z_i, z_j) and predicts respective entries \check{A}_{ij} in the adjacency matrix. Note that N denotes the number of nodes, D the number of input features, and E the embedding size.

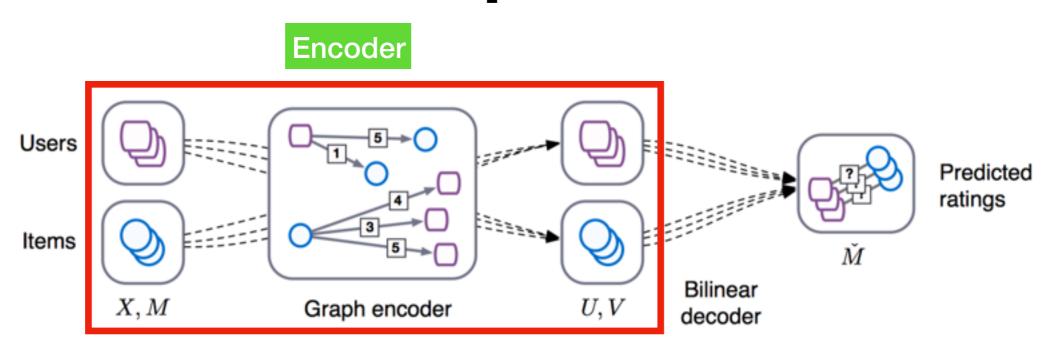
Variational Graph Auto-Encoders, https://arxiv.org/pdf/1611.07308.pdf

Encoder Decoder
$$\mathcal{L} = \mathbb{E}_{q(\mathbf{Z}|\mathbf{X},\mathbf{A})} \left[\log p\left(\mathbf{A} \mid \mathbf{Z}\right) \right] - \mathrm{KL} \left[q(\mathbf{Z} \mid \mathbf{X},\mathbf{A}) \mid\mid p(\mathbf{Z}) \right]$$

Non-probabilistic graph auto-encoder (GAE) model For a non-probabilistic variant of the VGAE model, we calculate embeddings \mathbf{Z} and the reconstructed adjacency matrix $\hat{\mathbf{A}}$ as follows:

$$\hat{\mathbf{A}} = \sigma(\mathbf{Z}\mathbf{Z}^{\mathsf{T}}), \text{ with } \mathbf{Z} = GCN(\mathbf{X}, \mathbf{A}).$$
 (4)

Graph Convolutional Matrix Completion



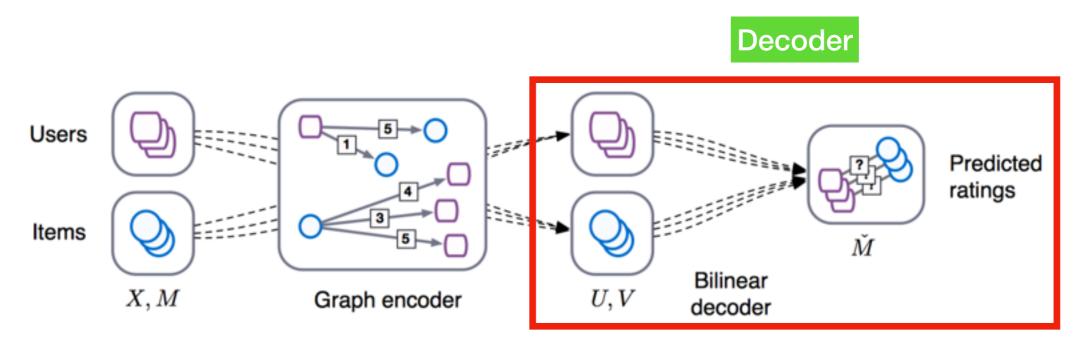
- Encoder
 - from items j to users i $\mu_{j \to i,r} = \frac{1}{c_{ij}} W_r x_j$

$$\mu_{j \to i, r} = \frac{1}{c_{ij}} W_r x_j$$

 c_{ij} is a normalization constant

$$h_i = \sigma \left[\operatorname{accum} \left(\sum_{j \in \mathcal{N}_{i,1}} \mu_{j \to i,1}, \dots, \sum_{j \in \mathcal{N}_{i,R}} \mu_{j \to i,R} \right) \right]$$

Graph Convolutional Matrix Completion



- Decoder
 - probability distribution over possible rating levels

$$\check{M}_{ij} = g(u_i, v_j) = \mathbb{E}_{p(\check{M}_{ij} = r)}[r] = \sum_{r \in R} r \ p(\check{M}_{ij} = r)$$

• The predicted rating is computed as $p(\check{M}_{ij} = r) = \frac{e^{u_i^T Q_r v_j}}{\sum_{s \in R} e^{u_i^T V_s v_j}}$