

Q1)  $\hat{a}, \hat{b}$  are unit vectors in  $\mathbb{R}^3$

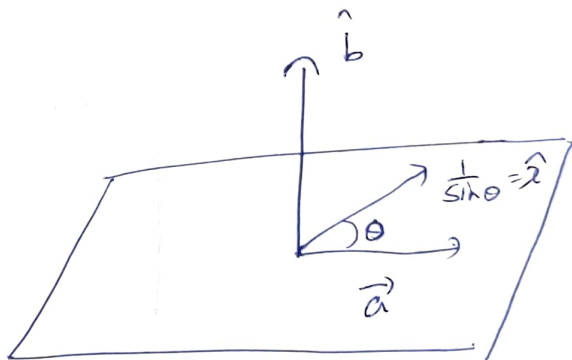
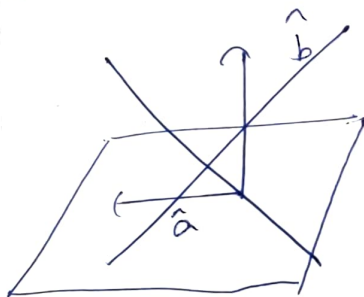
From the definition of cross product

$\hat{a} \times \hat{x}$  (if  $\hat{x}$  is not parallel to  $\hat{a}$ )  
is a vector which ~~was~~ is perpendicular to the  
plane containing  $\hat{a}$ , and  $\hat{x}$ .

$\therefore$  If a solution exists then  $\hat{a}$  and  $\hat{b}$  are perpendicular  
and if  $\hat{b}$  is not perpendicular to  $\hat{a}$  no solution  
exists.

Case

$$\hat{a} \cdot \hat{b} = 0$$



For different values of  $\theta$  (which are ~~not~~ integral multiples  
of  $\pi$ ) we get different ~~values~~ solutions.

$$|\hat{a}| |\hat{x}| (\sin \theta) = |\hat{b}| \quad \therefore \quad |\hat{x}| = \frac{1}{\sin \theta}$$

Q2)

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

claim  $A^n = \begin{bmatrix} \cos n\theta & -\sin n\theta \\ \sin n\theta & \cos n\theta \end{bmatrix}$

Proof  $n=1$  it is true, say it is true for  $n=k$

Then  $A^{k+1} = A^k A = \begin{bmatrix} \cos k\theta & -\sin k\theta \\ \sin k\theta & \cos k\theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

$$= \begin{bmatrix} \cos(k+1)\theta & -\sin(k+1)\theta \\ \sin(k+1)\theta & \cos(k+1)\theta \end{bmatrix}$$

we are done by induction.

as  $|P|=1$  let  $x_1 = \cos \alpha$ ,  $x_2 = \sin \alpha$ .

Suppose  $(A^{n_1})P = (A^{n_2})P$  for  $n_1, n_2 \in \mathbb{N}$ ,  $n_1 \neq n_2$

Then  $\begin{bmatrix} \cos n_1\theta & -\sin n_1\theta \\ \sin n_1\theta & \cos n_1\theta \end{bmatrix} \begin{bmatrix} \cos \alpha \\ \sin \alpha \end{bmatrix} = \begin{bmatrix} \cos(n_1\theta + \alpha) \\ \sin(n_1\theta + \alpha) \end{bmatrix}$

$$\therefore A^{n_1}P = A^{n_2}P \Leftrightarrow$$

$$n_1\theta + \alpha = n_2\theta + \alpha + 2n_3\pi$$

$$n_3 \in \mathbb{Z}$$

$$\therefore \theta = \frac{2n_3\pi}{(n_1 - n_2)}$$

$\therefore \theta$  is a rational multiple of  $\pi$ .

$\therefore$  If  $\theta$  is not a rational multiple of  $\pi$  then  
 all  $\Lambda^n \theta$  are distinct and the set  
 is infinite. If  $\theta$  is a rational multiple of  
 $\pi$ ,  $\exists n \in \mathbb{N}$  such that  $n\theta = 2k\pi$  for  
 some  $k \in \mathbb{Z}$ .

$$\therefore (\Lambda^{x+n})p = (\Lambda^x)(\Lambda^n)p = (\Lambda^x)p$$

$$\Lambda^n = Id \quad (\text{As } \Lambda^n = Id_n)$$

$\therefore$  The set is finite

$$\{p, \Lambda p, \Lambda^2 p, \dots, \Lambda^{n-1} p\}$$

Q3)

$$\begin{bmatrix} x & y & z \end{bmatrix} \begin{bmatrix} a_1 & b_1 & c_1 \\ b_1 & a_2 & b_2 \\ c_1 & b_2 & a_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$= a_1 x^2 + a_2 y^2 + a_3 z^2 + 2b_1 xy + 2b_2 yz + 2c_1 xz$$

$$\therefore a_1 = 1, a_2 = 1, a_3 = -1, b_1 = \frac{7}{2}, b_2 = -\frac{3}{2}, c_1 = 3$$

And A is unique if it is symmetric.  
If not then it is not symmetric.

$$\begin{bmatrix} x & y & z \end{bmatrix} B \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ also gives the same expression.}$$

$$\text{where } B = \begin{bmatrix} 1 & 7 & 6 \\ 0 & 1 & -3 \\ 0 & 0 & -1 \end{bmatrix}$$

94)

$$A (\text{Adj}(A)) = (\det(A)) \text{Id}.$$

$$\therefore \text{If } \det A \neq 0 \quad \text{then} \quad A \underbrace{(\det(A))^{-1} \text{Adj}(A)}_{A^{-1}} = \text{Id}$$

2)  ~~$AB = \text{Id}$~~   $\therefore A$  is invertible

$$\text{2) } \det A = 0$$

Then  $A$  cannot be invertible by contradiction

$$\Rightarrow \det(A \ B) = \det(I)$$

$$\Rightarrow 0 = 1 \Rightarrow \text{contradiction}$$

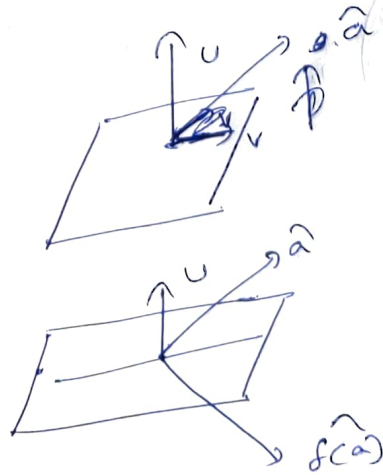
$A = I - U U^T$  is not invertible

$$\Rightarrow A U = U - U(U^T U) = 0 \quad U \neq 0$$

$$(A^{-1} A) U = U = 0 = A^{-1} (A U) = 0 \Rightarrow \text{contradiction}$$

$$f(u) = -u$$

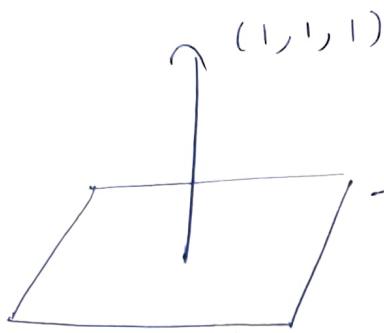
$$f(v) = v$$



$$\hat{a} = \hat{b} + \hat{c}$$

$\downarrow$                        $\downarrow$   
 $\perp$  to  $u$             $\perp$  to  $u$

$$f(a) = -\hat{b} + \hat{c}$$



plane

$P: (x + y + z = 0)$

take some vector

$\hat{a}_1 = (1, -1, 0)$  on  $P$

now let  $\hat{b}_1 = (1, 1, x)$  on  $P$

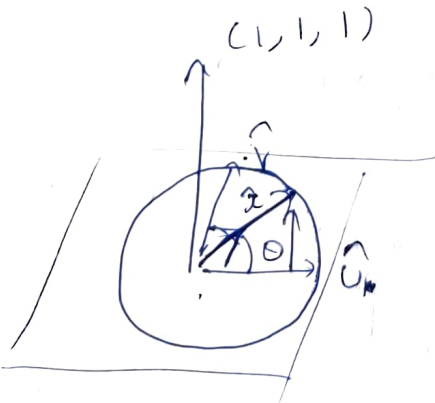
then  $1 + 1 + x = 0 \therefore x = -2$

clearly  $\hat{a}_1 \cdot \hat{b}_1 = 0$

By normalizing  $\hat{u}_1 = (\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}, 0)$

$\hat{v} = (\frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{-2}{\sqrt{6}})$

are such vectors



$\hat{x} = \hat{u}_1 \cos \theta + \hat{v} \sin \theta$

for  $\theta$  gives a parametrization