# Applying Machine Learning to LTE/5G Performance Trend Analysis

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In Ericsson,

Motivation

- Many test cases are executed for testing software packages
- Evaluate the performance of an updated software package by visualizing the graph
- Algorithm that can reduce the workload of manual inspection

- Detect the state of the CPU utilization (degradation, improvement, or steady state)
- Detect whether there is any change in the test environment that affects the CPU utilization

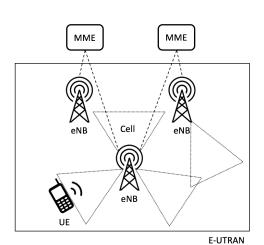


Figure: LTE architecture overview

Software release

Data sources

- Test case
   → an observation
   in the dataset
   Remark: There are

Remark: There are different types of test cases





Figure: Top: Several software packages are launched in the timeline, Bottom: The CPU utilization value in each software package

Data is collected on January 20, 2017 Three datasets: Software release A. B. and C.

- Sorted by software package version
- Filtered out test cases which are not executed properly
- Selected test case which has the lowest value of the CPU utilization to represent a performance of a specific software package

In total, each dataset contains 64, 241, and 144 test cases. respectively

## TotCpu%: CPU utilization

#### Predictor variables

- local events in EventsPerSec
  - RrcConnectionSetupComplete
  - Paging
  - X2HandoverRequest
- test environments
  - DuProdName: Product hardware name
  - Fdd/Tdd: Different standard of LTE 4G Technology
  - NumCells: Number of cells in the base station

## Method

- Markov switching model
- E-divisive method
- Tools

Markov switching model

$$y_t = X_t \beta_{S_t} + \phi_{1,S_t} y_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_{S_t}^2)$$

Assuming that  $S_t$  denote an unobservable state variable  $y_t$  is the observed value of time series at time t  $X_t$  is a design matrix containing the predictor variables of time series at time t

 $\beta_{S_t}$  are a column vector of the coefficients in state  $S_t$ , where  $S_t = 1, 2, ..., k$ 

 $\phi_{1,\mathcal{S}_t}$  is an autoregression coefficient at time t-1 in state  $\mathcal{S}_t$ 

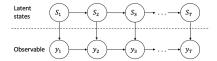


Figure: Model with additional dependencies at observation level



# Markov switching autoregressive model

$$y_t = X_t \beta_{S_t} + \phi_{1,S_t} y_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_{S_t}^2)$$

Assuming that  $S_t$  denote an unobservable state variable

A coefficient of a predictor variable can have either different values in different state,  $\beta_{S_t}$ , or a constant value in all state,  $\beta$ .

The variable whose coefficient can take on *different* values is said to have a **switching effect**.

The variable which has the *same* coefficient in all states is the variable that does not have a switching effect, or said to have a **non-switching effect**.

# E-divisive [James, 2016]

E-divisive method

- Non-parametric approach: more flexible as no assumption about the distribution is made
- Detects multiple change point locations based on a divisive hierarchical estimation algorithm
- Algorithm: Recursively partition a time series, and perform a permutation test to find the statistical significance of an estimated change point.
- Remark: Obtain a rough idea of the change point location

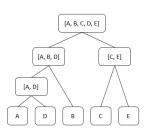


Figure: Divisive hierarchical clustering

- Markov switching model is performed using MSwM package [Sanchez-Espigares, 2014] Various extensions and modifications were made in the package For example,
  - → Make it more stable to use with categorical variables
  - $\rightarrow$  State prediction function
  - $\rightarrow$  Plots for visualizing the results
- E-divisive method is performed using ecp package [James, 2016]

#### Results and Discussion

- Markov switching model
  - Analysis I: Number of state
  - Analysis II: Number of switching coefficients
- E-divisive method
- Comparison between both methods
  - Simulated data
  - Real data
- State inference on the results from the Markov switching model

- Number of states. k
- Number of switching coefficients in the model

Based on the applied literature, the information criteria called the Bayesian Information Criterion (BIC) is used for model selection

$$BIC = -2\ln(L(\hat{\theta})) + m \cdot \ln(T)$$

where, m is the number of parameters and T is the number of observations BIC attempts to reduce an overfitting problem by penalizing on the number of parameters in the model

- Model with lower BIC value is preferable
- However, model output along with plot should also be taken into account as well

Analysis I: Number of states
Hypothesis: Markov switching model with *two* or *three* states

- Model with lower BIC value is preferable
- However, model output along with plot should also be taken into account as well
- Two-state model offered less details, and plots were unrealistic and difficult to make an interpretation
- Three-state model was chosen for further analysis as it provided more intepretable plots and better fit
- Remark: Higher number of states  $k \ge 4$  are more likely to give worse results and were not considered

Analysis II: Number of switching coefficients in the model Hypothesis: Test environments (DuProdName, Fdd/Tdd, and *Numcells*) is possible to have non-switching effects

- Recall: The variable whose coefficient is constant in all states are said to have a non-switching effect
- Attempt to reduce the number of parameters to be estimated in the model
- Algorithm used numerical optimization
  - → more estimated parameters will make the obtained result unstable
- Each dataset of the software release was tested with different models
- Three final models for each dataset were obtained

- Apply the E-divisive method to all three datasets of the software release A, B, and C
- Input: the value of the CPU utilization

- In the real data, the state of the CPU utilization is unknown
  - → Evaluation of the model can't be made

- In the real data, the state of the CPU utilization is unknown → Evaluation of the model can't be made
- Simulated two datasets (Dataset 1 and Dataset 2) with the ground truth about the state.

The real models for each state are

$$y_t = \begin{cases} 10 + 0.6X_{1,t} - 0.9X_{2,t} + 0.5y_{t-1} + \varepsilon_t^{(1)} & \text{Normal} \\ 2 + 0.8X_{1,t} + 0.2y_{t-1} + \varepsilon_t^{(2)} & \text{Bad} \\ -12 + 0.7X_{1,t} + 0.2X_{2,t} - 0.2y_{t-1} + \varepsilon_t^{(3)} & \text{Good} \end{cases}$$

 $y_t$  is assumed to be value of a CPU usage

$$X_{1,t} \sim U[50, 200]$$
  
 $X_{2,t} \sim U[0, 50]$   
 $\varepsilon_t^{(1)} \sim N(0, 1), \quad \varepsilon_t^{(2)} \sim N(2, 0.5), \quad \text{and} \quad \varepsilon_t^{(3)} \sim N(1, 1)$ 

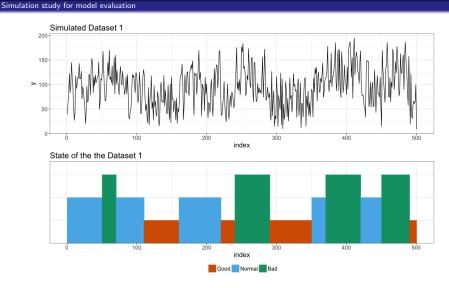


Figure: A simulated data of Dataset 1 and the period in the time series when observation is in each state.



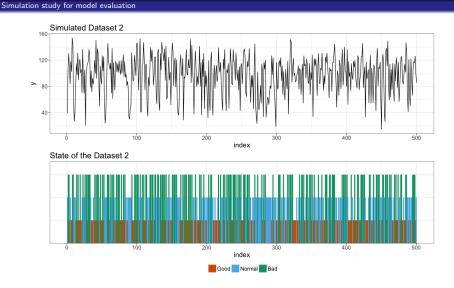


Figure: A simulated data of Dataset 2 and the period in the time series when observation is in each state.

Comparison between both methods

Apply the Markov switching model and the E-divisive method to the simulated Dataset 1 and Dataset 2

Comparison between both methods

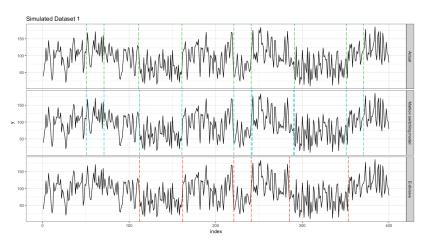


Figure: Top: Actual change point, Middle: Markov switching model, Bottom: E-divisive method



Comparison between both methods

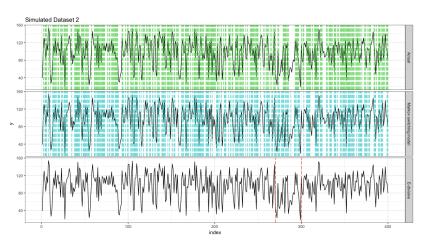


Figure: Top: Actual change point, Middle: Markov switching model, Bottom: E-divisive method



- Both methods detect changes at the same location
  - $\rightarrow$  high probability to be an actual change
- Both methods detect changes close to one another but not at the exact location
  - $\rightarrow$  lower chance to be a false alarm
- The response variable value fluctuates but the average value does not change drastically
  - → E-divisive method will not be able to identify the state change

#### Real data: Software release A

E-divisive cannot detect any changes in the time series data

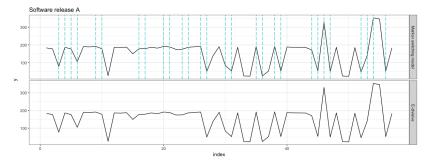


Figure: Top: Results from the Markov switching model, Bottom: The change point locations from the E-divisive

#### Real data: Software release B

 E-divisive method detects change-points at 130, 135, 153, and 170

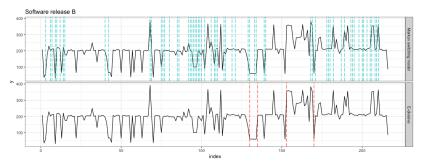


Figure: Top: Results from the Markov switching model, Bottom: The change point locations from the E-divisive

#### Real data: Software release C

• E-divisive method detects change-point at 9, 77, 82, and 105

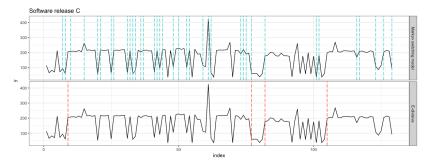


Figure: Top: Results from the Markov switching model, Bottom: The change point locations from the E-divisive

State inference

Software release A



## Software release A

• State 1: Degradation

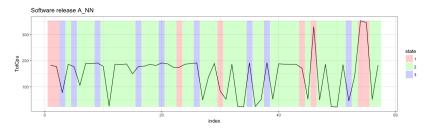


Figure: The CPU utilization showing the periods where the observation is in the specific state.

#### Software release B

State inference

• State 1: Degradation

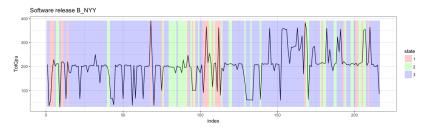


Figure: The CPU utilization showing the periods where the observation is in the specific state.

### Software release C

State inference

• State 1: Degradation

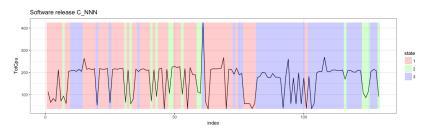


Figure: The CPU utilization showing the periods where the observation is in the specific state.

- Software release A: Fdd/Tdd and NumCells
- Software release B: DuProdName and NumCells
- Software release C: **DuProdName**

- Markov switching model is able to identify any changes between states rather well, despite some false alarms and missed detections
- E-divisive method is less powerful as it can detect fewer changes and failed to detect many changes
  - ightarrow the method only take into account the value of the CPU utilization
- Both methods could be used together to confirm the state change

Require more extensive data

- Consider on the other performance metrics (e.g.,memory usage and latency)
- Apply the Markov switching model to each QA Capacity test case type (i.e., one model for one type of test case)
- Normalize feature set by introducing weight parameters
- Use semi-supervised learning algorithm if some test cases are labeled with state
  - $\rightarrow$  combining clustering-based and classification-based methods



James D Hamilton (1989)

A new approach to the economic analysis of nonstationary time series and the business cycle  $\,$ 

Econometrica: Journal of the Econometric Society, pages 357-384.



Josep A. Sanchez-Espigares and Alberto Lopez-Moreno (2014) MSwM: Fitting Markov Switching Models CRAN R.



Nicholas A. James and David S. Matteson (2016)

ecp: Nonparametric Multiple Change Point Analysis of Multivariate Data *CRAN R*.