

Apply machine learning to Performance trend analysis

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Overview

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- 3 Markov switching model
 - Markov switching autoregressive model
- 4 Model estimation
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- 5 What has been done?
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Objectives


- Detect the degradation, improvement or steady state in CPU utilization
- Detect whether there is some changes in test environment that have an impact on CPU utilization

Data preprocessing

One software product \Rightarrow many software packages

One software package \Rightarrow many different types of test cases

- Discard incomplete test case
- Multiple values separated by a tab character are stored together in column \Rightarrow split a tab-separated values to columns



ID	Variable1	Variable2
1	X	A=2 B=1 C=5
2	Y	A=4 B=2 C=8
3	Z	A=1 C=6
.	.	.
.	.	.
.	.	.

ID	Variable1	A	B	C
1	X	2	1	5
2	Y	4	2	8
3	Z	1	0	6
.
.
.

Figure: Data example

Markov switching model, [Hamilton, 1989]

- A technique uses for describing the evolution of the process at different period of time
- Model involves multiple structures that can characterize the time series behaviors in different states
- The switching mechanism between the states is assumed to be an unobserved Markov chain - a stochastic process which contains the probability of transition from one state to any other state

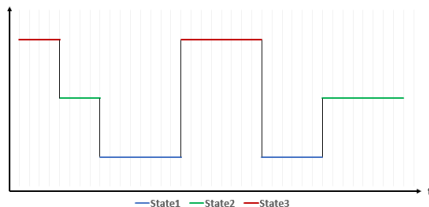


Figure: regime shift between states

Markov switching model, [Hamilton, 1989]

Assuming that S_t denote an unobservable state variable

$$y_t = X_t' \beta_{S_t} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_{S_t}^2)$$

y_t is the observed value of time series at time t

X_t are the predictor variables of time series at time t

β_{S_t} are the coefficients in state S_t , where $S_t = 1, 2, \dots, k$

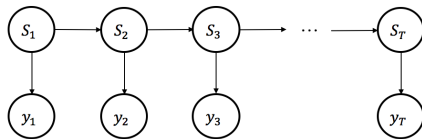


Figure: Model structure

Markov switching model

Given dataset,

$$y_t = X_t' \beta_{S_t} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_{S_t}^2)$$

- y_t is CPU utilization
- X_t are some components which have an impact on the CPU utilization and test environment
- Assume there are three states ($k = 3$): normal, good, bad

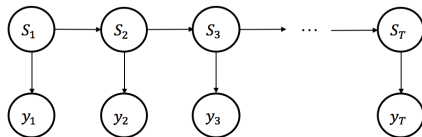


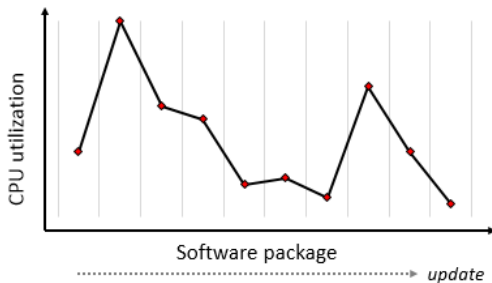
Figure: Model structure

Markov switching autoregressive model

Autoregressive model

$$y_t = c + \sum_{i=1}^p \phi_p y_{t-i} + \varepsilon_t$$

where c is constant, ϕ_p are parameters and ε_t is white noise



Markov switching autoregressive model

The observation are drawn from the first order autoregressive model, AR(1).

$$y_t = X_t' \beta_{S_t} + \phi_{1,S_t} y_{t-1} + \varepsilon_t$$

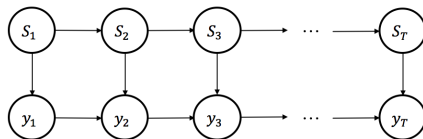


Figure: Model with additional dependencies at observation level

Model estimation

Model parameters

$$\theta = (\beta_{S_t}, \phi_{1,S_t}, \sigma_{S_t}^2, \pi_{S_t}, p_{ij})$$

where,

π_{S_t} is initial probabilities in state S_t

p_{ij} is transition probabilities, $p_{ij} = P(S_t = j | S_{t-1} = i) \quad 1 \leq i, j \leq k$

and S_t is non-observable variable

Model Likelihood

$$L(\theta; y_t) = f(y_t | \theta) = \sum_{t=1}^T \sum_{S_t=1}^k f(y_t | S_t; \theta) P(S_t)$$

E-M algorithm

- Expectation step: Calculate the expectation of S_t given the observation under the current estimated parameters
- Maximization step: Obtain new estimates of the parameters by maximizing likelihood
- Repeat until converged

What has been done?

Study and review source code in the R package in detail

- MSwM: An univariate autoregressive Markov switching model for linear and generalized model [Sanchez-Espigares, 2014]

What has been done?

Implement and modify code in the package

- Small typo in the code when computing residual variance
- Solve noninvertible Hessian using generalized inverse procedure [Gill, 2004]
- Extension for categorical predictor variables
- NAs coefficients

What has been done?

Results of fitting Markov switching autoregressive model

- Estimated parameters in each state
- For each observation,
 - ⇒ State assignment
 - ⇒ Probability assignment in each state
- Graphs show periods where the observation is in the specific state

Next step

- Model selection: Compare several models (e.g., number of states, number of parameters which have switching effects)
- State prediction: Find the most probable state for the new observation
- Making a state inference
- Fit model for other software products



James D Hamilton (1989)

A new approach to the economic analysis of nonstationary time series and the business cycle

Econometrica: Journal of the Econometric Society, pages 357-384.



Jeff Gill and Gary King (2004)

What to do when your hessian is not invertible: Alternatives to model respecification in nonlinear estimation

Sociological methods & research, 33(1):54-87.



Josep A. Sanchez-Espigares and Alberto Lopez-Moreno (2014)

MSwM: Fitting Markov Switching Models

CRAN R.