



SOS Design Document

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Contents

| | |
|----------------------------|---|
| Project Introduction | 2 |
| High Level Design..... | 3 |
| Layered Architecture | 3 |
| Modules Each Layer | 4 |
| Low Level..... | 5 |
| Application Layer | 5 |
| SOS Layer | 8 |
| SOS APIs | 8 |

List of Figures

| | |
|-------------------------------------|---|
| Figure 1 Layered Architecture | 3 |
| Figure 2 Sequence Diagram | 5 |
| Figure 3 Class Diagram..... | 6 |
| Figure 4 sos_sequence diagram | 7 |

List of Tables

| | |
|-----------------------------------|----|
| Table 1 sos_init API | 8 |
| Table 2 sos_deinit API | 9 |
| Table 3 sos_create_task API | 10 |
| Table 4 sos_delete_task API | 11 |
| Table 5 sos_modify_task API | 12 |
| Table 6 sos_run API..... | 13 |
| Table 7 sos_disable API..... | 14 |
| Table 8 sos_enable API | 14 |

Project Introduction

The SOS(Small operating System) is simulate the basic role of OS Scheduler to handle multiple task and synchronize them.

In this documentation will discuss the layered architecture of the system, Modules APIs and their flowchart and

High Level Design

Layered Architecture

APPLICATION LAYER: In this layer the application or system will be implemented here, this layer that will be between User events and other layers.

Utilities LAYER: that have standard types will use with all entire system and bit manipulation functions

OS LAYER: this layer will apply multi-tasking behavior to the system

ECU LAYER: this layer has all hardware driver outside **MCU**.

MCA LAYER: this layer has all peripheral drivers that are inside **MCU**.

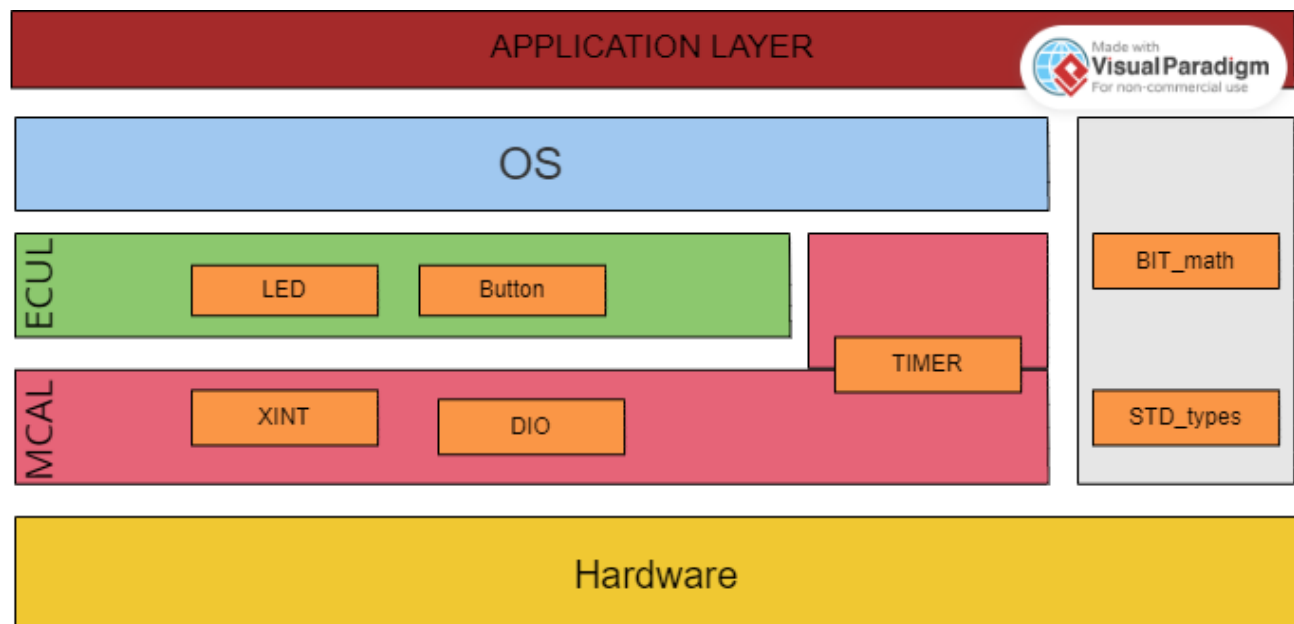


Figure 1 Layered Architecture

Modules Each Layer

1. APP Layer
 - I.APPLICATION Module
2. OS Layer
 - I.SOS Module is providing APIs to handle multiple tasks
3. Utilities Layer
 - I.BIT_math Module provides bit manipulation.
 - II.STD_types Module provides standard types
4. ECU Layer
 - I.Button Module provides APIs to control all buttons.
 - II.LED Module provides APIs to control LEDs.
5. MCA LAYER
 - I.Timer Module provides APIs to all timers in MCU.
 - II.DIO Module provides APIs to use GPIO and handle External interrupts.

Low Level Application Layer

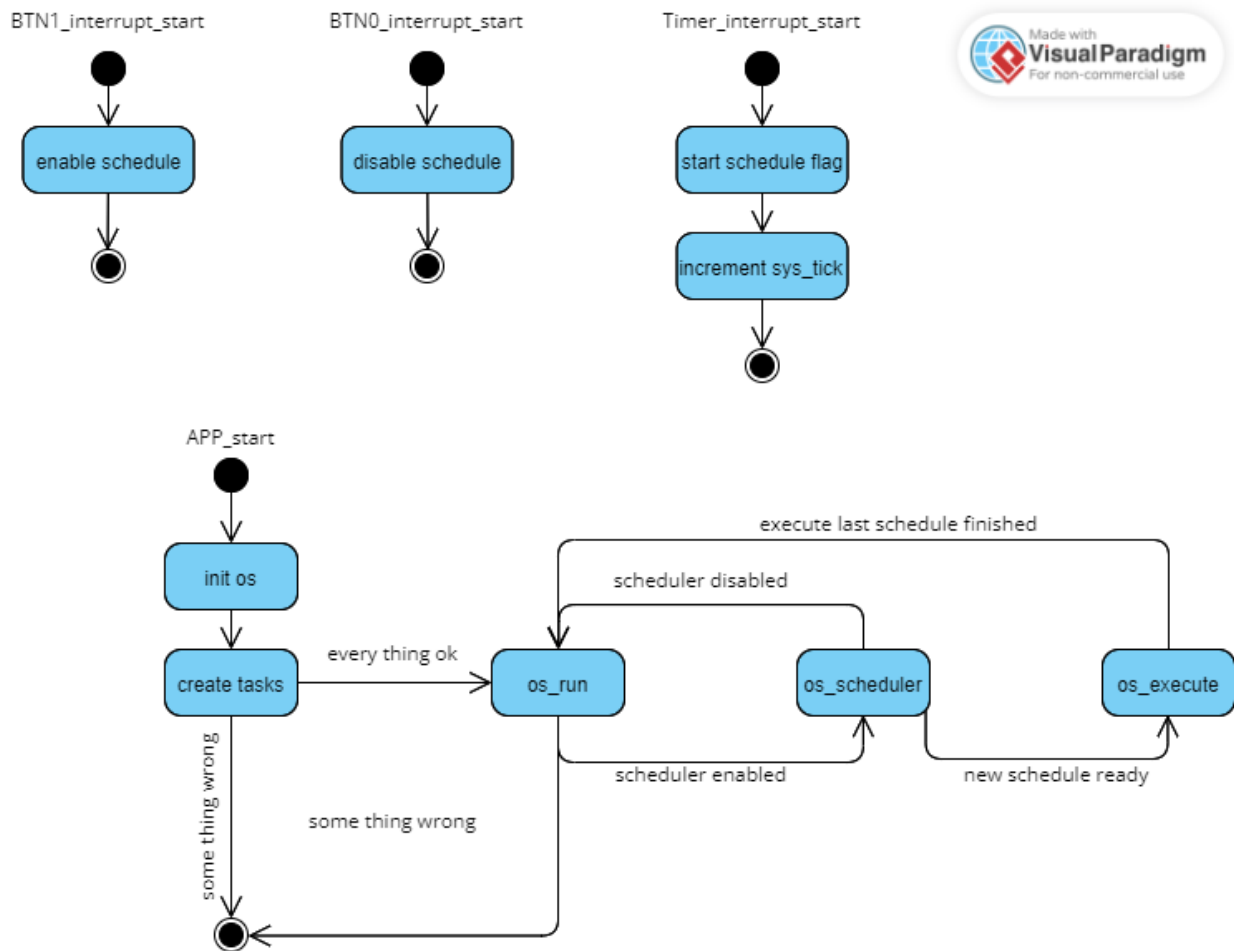


Figure 2 Sequence Diagram

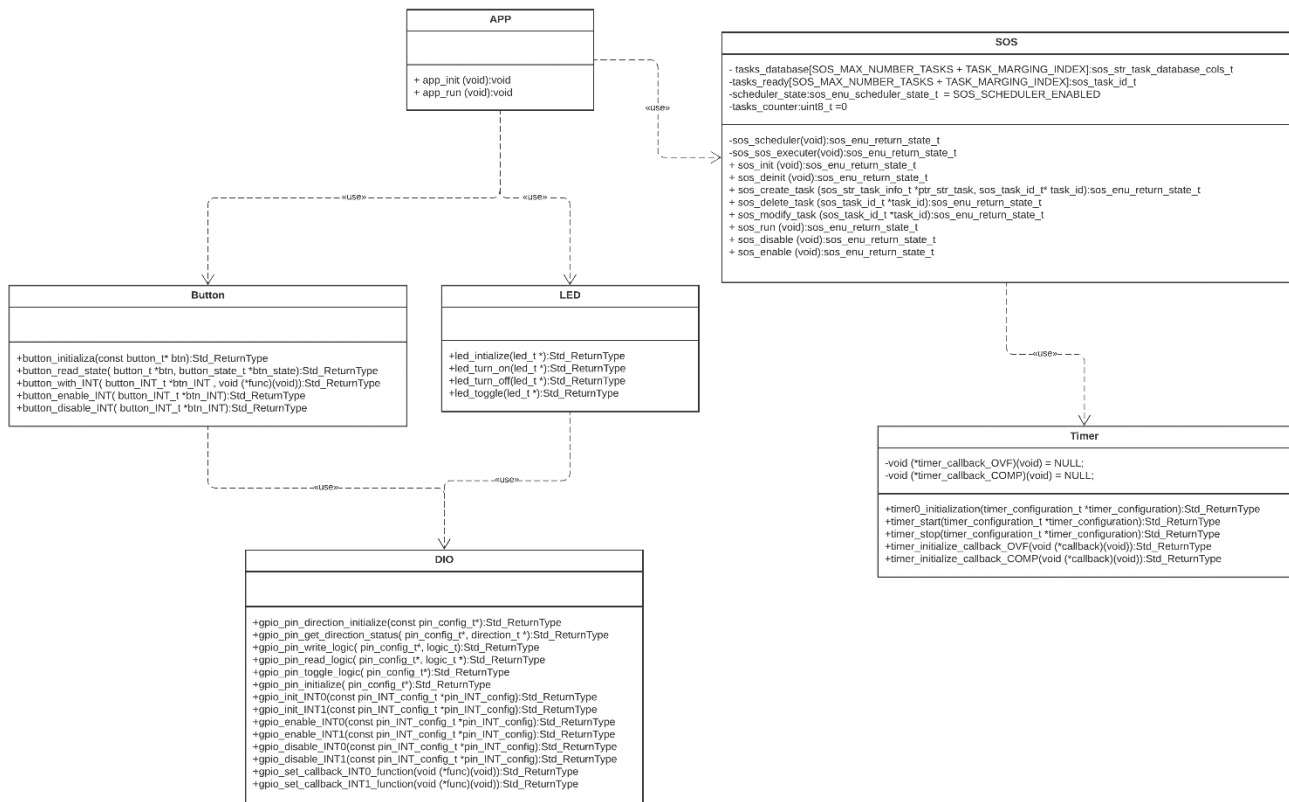


Figure 3 Class Diagram

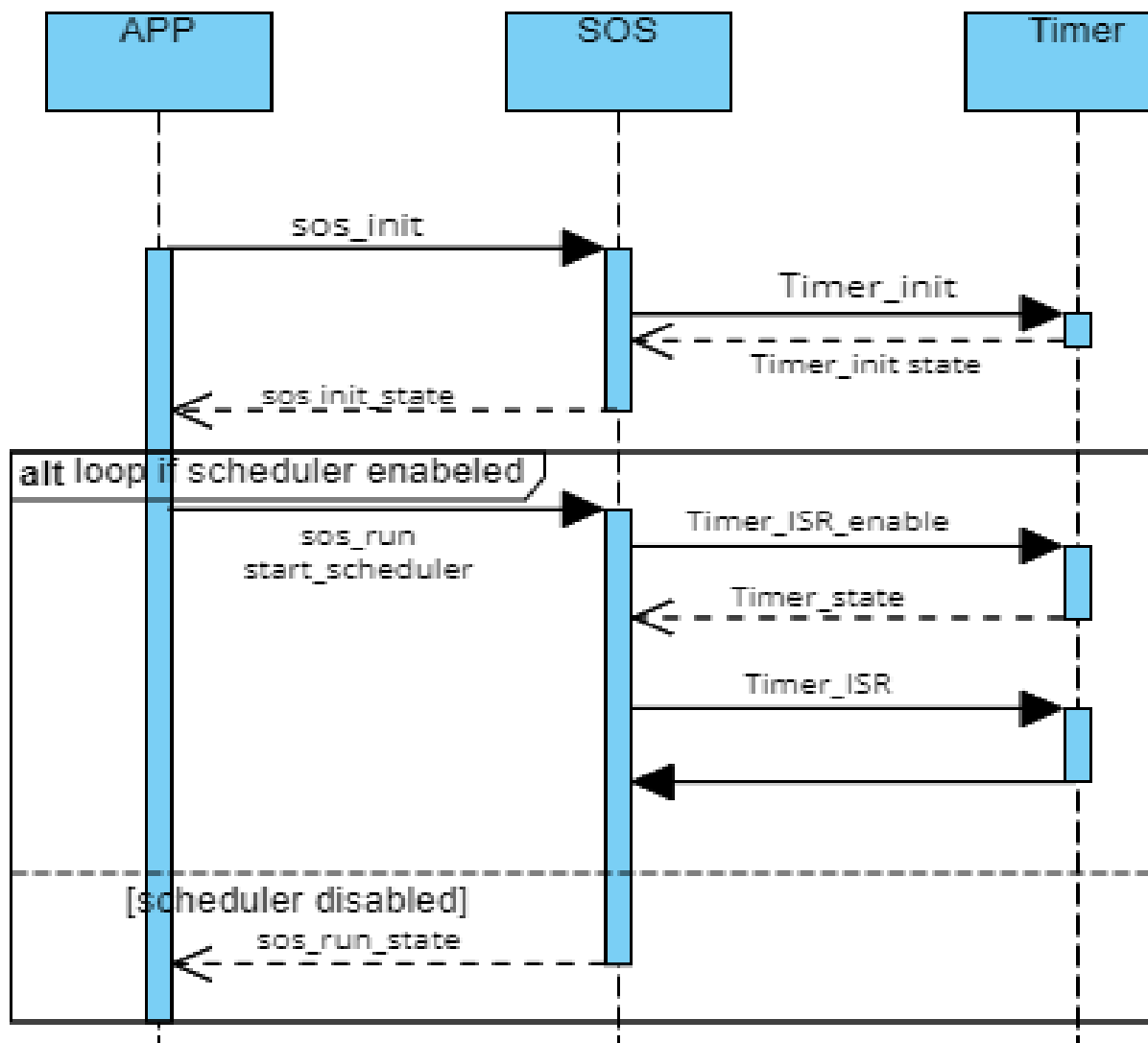


Figure 4 sos_sequence diagram

SOS Layer

SOS APIs

Table 1 *sos_init* API

| | |
|---------------------|--|
| API name | sos_init |
| Description | This API initialize the SOS |
| Syntax | <code>sos_enu_return_state_t sos_init (void)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | None |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | <code>SOS_E_NOT_OK</code> : there is something wrong but couldn't defined it <code>SOS_EXCEED_NUMBER_OF_TASKS</code> : the max number of tasks exceeded |

Table 2 *sos_deinit* API

| | |
|---------------------|--|
| API name | sos_deinit |
| Description | This API deinitialize the SOS |
| Syntax | <code>sos_enumeration_state_t sos_deinit (void)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | None |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | <code>SOS_E_NOT_OK</code> : there is something wrong but couldn't defined it |

Table 3 *sos_create_task* API

| | |
|---------------------|---|
| API name | sos_create_task |
| Description | This API to create task and add it to sos database |
| Syntax | <code>sos_enu_return_state_t sos_create_task(sos_str_task_info_t *ptr_str_task, sos_task_id_t* task_id)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | *ptr_str_task: address of struct has all task info |
| Parameters (out) | * task_id: address of variable to return id of created task |
| Parameters (in&out) | None |
| Return | <p><code>SOS_E_NOT_OK</code>: there is something wrong but couldn't defined it</p> <p><code>SOS_NULL_PTR</code>: null pointer used</p> <p><code>SOS_PRIORITY_NOT_ALLOW</code>: priority not allow to use</p> <p><code>SOS_TIME_LIMIT_NOT</code>: periodicity isn't allowed</p> <p><code>SOS_EXCEED_NUMBER_OF_TASKS</code>: the max number of tasks exceeded</p> |

Table 4 *sos_delete_task* API

| | |
|---------------------|---|
| API name | sos_delete_task |
| Description | This API to create task from sos database |
| Syntax | <code>sos_enu_return_state_t sos_delete_task(sos_task_id_t *task_id)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | * <code>task_id</code> : address of variable to return id of created task |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | <code>SOS_E_NOT_OK</code> : there is something wrong but couldn't defined it <code>SOS_NULL_PTR</code> : null pointer used <code>SOS_TASK_NOT_FOUND</code> : there isn't task in database by provided task_id |

Table 5 *sos_modify_task* API

| | |
|---------------------|---|
| API name | sos_modify_task |
| Description | This API to modify task is sos database |
| Syntax | <code>sos_enu_return_state_t sos_modify_task(sos_task_id_t *task_id, sos_str_task_info_t *ptr_str_task);</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | * <code>task_id</code> : address of variable to return id of created task * <code>ptr_str_task</code> : address of struct has all task info |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | <code>SOS_E_NOT_OK</code> : there is something wrong but couldn't defined it <code>SOS_NULL_PTR</code> : null pointer used <code>SOS_TASK_NOT_FOUND</code> : there isn't task in database by provided task_id <code>SOS_PRIORITY_NOT_ALLOW</code> : priority not allow to use <code>SOS_TIME_LIMIT_NOT</code> : periodicity isn't allowed <code>SOS_EXCEED_NUMBER_OF_TASKS</code> : the max number of tasks exceeded |

Table 6 *sos_run* API

| | |
|---------------------|--|
| API name | sos_run |
| Description | This API to run sos scheduler and executer |
| Syntax | <code>void sos_run(void)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | None |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | None |

Table 7 *sos_disable* API

| | |
|---------------------|-------------------------------------|
| API name | sos_disable |
| Description | This API to disable scheduler |
| Syntax | <code>void sos_disable(void)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | None |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | None |

Table 8 *sos_enable* API

| | |
|---------------------|------------------------------------|
| API name | sos_enable |
| Description | This API to enable scheduler |
| Syntax | <code>void sos_enable(void)</code> |
| Sync/Async | Sync |
| Reentrancy | Reentrant |
| Parameters (in) | None |
| Parameters (out) | None |
| Parameters (in&out) | None |
| Return | None |