

$(\mu/\mu, \lambda) - ES$ with Search Path in C++

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I. INTRODUCTION

The main goal of our work was to implement the algorithm $(\mu/\mu, \lambda) - ES$ with Search Path presented in the paper [1]. To test and compare our algorithm with other implementations, we used the COCO platform [2].

In the next section, we introduce the algorithm as it is written in the corresponding paper, then we explain how we implemented it and which results we obtained.

II. THE ALGORITHM

The algorithm we implemented is the following :

Algorithm 1 The $(\mu/\mu, \lambda) - ES$ with Search Path

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1: given  $n \in \mathbb{N}, \lambda \in \mathbb{N}, \mu \approx \lambda/4 \in \mathbb{N}, c_\sigma \approx \sqrt{\mu/(n+\mu)},$ 
    $d \approx 1 + \sqrt{\mu/n}, d_i \approx 3n$ 
2: initialize  $\mathbf{x} \in \mathbb{R}^n, \boldsymbol{\sigma} \in \mathbb{R}_+^n, \mathbf{s}_\sigma = \mathbf{0}$ 
3: while not happy do
4:   for  $k \in \{1, \dots, \lambda\}$  do
5:      $\mathbf{z}_k = \mathcal{N}(\mathbf{0}, \mathbf{I})$  iid for each  $k$ 
6:      $\mathbf{x}_k = \mathbf{x} + \boldsymbol{\sigma} \circ \mathbf{z}_k$ 
7:   end for
8:    $\mathcal{P} \leftarrow \text{sel\_}\mu\_best(\{\mathbf{x}_k, \mathbf{z}_k, f(\mathbf{x}_k) | 1 \leq k \leq \lambda\})$ 
   recombination and parent update
9:    $\mathbf{s}_\sigma \leftarrow (1 - c_\sigma)\mathbf{s}_\sigma + \sqrt{c_\sigma(2 - c_\sigma)} \frac{\sqrt{\mu}}{\mu} \sum_{\mathbf{z}_k \in \mathcal{P}} \mathbf{z}_k$ 
10:   $\boldsymbol{\sigma} \leftarrow \boldsymbol{\sigma} \circ \exp^{1/d_i} \left( \frac{\|\mathbf{s}_\sigma\|}{\mathbb{E}[\|\mathcal{N}(\mathbf{0}, \mathbf{I})\|]} - 1 \right) \times \exp^{c_\sigma/d} \left( \frac{\|\mathbf{s}_\sigma\|}{\mathbb{E}[\|\mathcal{N}(\mathbf{0}, \mathbf{I})\|]} - 1 \right)$ 
11:   $\mathbf{x} = \sum_{\mathbf{x}_k \in \mathcal{P}} \mathbf{x}_k$ 
12: end while
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In this algorithm, f is the function we want to minimize, \mathbf{x} its parameters, and n the dimension of \mathbf{x} . λ is the number of offsprings and μ is the number of parents. Therefore the selection function will select the μ best in the offspring population. The \mathbf{x}_k are the offsprings, \mathbf{s}_σ is the search path, \mathbf{z}_k are the mutation steps and $\boldsymbol{\sigma}$ the mutation vectors.

III. OUR IMPLEMENTATION

A. Implementation of the algorithm

We implemented this algorithm in C++, and in this section we present how we implemented it and which choices we made.

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1) Initialization

Regarding the initialization, the vector \mathbf{x} is initialized to the center of the domain and every element of the vector $\boldsymbol{\sigma}$ (`Sigma[]`) is initialized to one sixth of the domain range. This is the preferred initial condition because it keeps the solution as far as possible from the boundaries of the problem domain. Another option would be to randomly initialize the solution vector, but that could possibly bias the analysis as a random \mathbf{x} could be already too close to the optimum.

$$\mathbf{x}_k = \text{lowerbound} + \frac{\text{upperbound} - \text{lowerbound}}{2}$$

$$\sigma = \frac{\text{upperbound} - \text{lowerbound}}{6}$$

2) Stop criteria

In the while loop, two stop criteria can be found in our implementation. The first one is the budget, i.e. the number of iterations, and the second one is the 'happy' criterion : the programme will stop if there is no change between two iterations bigger than 10^{-9} .

3) Selecting the μ best individuals

In order to select the μ best individuals, the value of f is calculated for every \mathbf{x} in the population and stored in a vector called `fitness[]`. The population is then sorted against this vector, so that the μ best are positioned at the beginning of X_k . The first implementation relied on a sorting algorithm by insertion, which incurred in a long run time due to its high computational cost $O(n^2)$. Given the already long processing time necessary to run and benchmark the algorithm, it was important to optimize every part of the code and the naive insertion method was replaced by a Shellsort algorithm.

B. Tuning the hyperparameters

The performance of the algorithm relies on two hyperparameters, namely the budget multiplier and the size of the population λ . To fine tune these parameters, the algorithm was tested with different sets of values and analyzed on the COCO platform.

IV. ANALYSIS OF THE RESULTS

To analyse the results, we launched our algorithm on the COCO platform : [2]. The COCO (COMparing Continuous Optimizers) platform provides benchmarks for comparison between optimizing algorithm, and visualizing tools to plot the data.

V. CONCLUSION

VI. BIBLIOGRAPHY

REFERENCES

- [1] Hansen, N., D.V. Arnold and A. Auger (2015). Evolution Strategies. In Janusz Kacprzyk and Witold Pedrycz (Eds.): *Handbook of Computational Intelligence*, Springer, Chapter 44, pp.871-898
- [2] <https://github.com/numbbbo/coco>