INTRO TO DATA SCIENCE LECTURE 10: SUPPORT VECTOR MACHINES

LAST TIME:

- ENSEMBLE TECHNIQUES
- PROBLEMS IN CLASSIFICATION
- BAGGING, BOOSTING, RANDOM FORESTS

AGENDA

I. SUPPORT VECTOR MACHINES
II. NONLINEAR CLASSIFICATION
III. MAXIMUM MARGIN HYPERPLANES
IV. SLACK VARIABLES

EXERCISE:

V. SVM IN SCIKIT-LEARN

Q: What is a support vector machine?

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- A: A binary linear classifier whose decision boundary is *explicitly* constructed to minimize generalization error.

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recall:

binary classifier — solves two-class problem **linear classifier** — creates linear decision boundary (in 2d)

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The generalization error is equated with the geometric concept of **margin**, which is the region along the decision boundary that is free of data points.

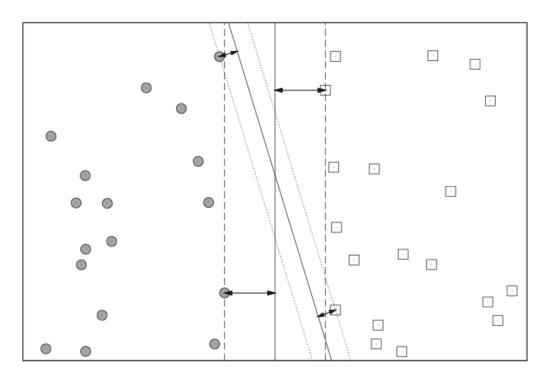


FIGURE 18-4. Two decision boundaries and their margins. Note that the vertical decision boundary has a wider margin than the other one. The arrows indicate the distance between the respective support vectors and the decision boundary.

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The goal of an SVM is to create the linear decision boundary with the largest margin. This is commonly called the **maximum margin hyperplane**.

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NOTE

A *hyperplane* is just a high-dimensional generalization of a line.

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A: Using a clever maneuver called the **kernel trick**.

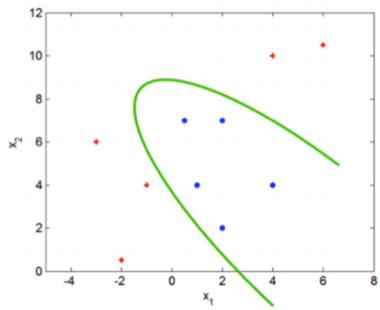
THE KERNEL TRICK

Nonlinear applications of SVM rely on an implicit (nonlinear) mapping Φ that sends vectors from the original feature space K into a higher-dimensional feature space K.

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Nonlinear classification in K is then obtained by creating a linear decision boundary in K.

Suppose we need a more complex classifier than a linear decision boundary allows.



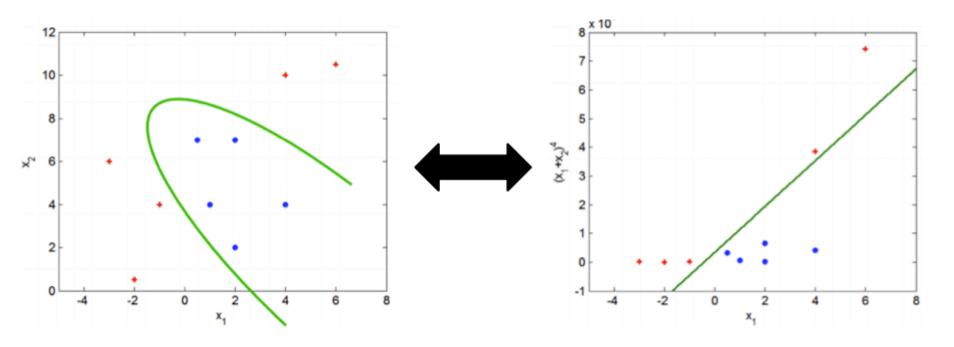
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This *linear* decision boundary will be mapped to a *nonlinear* decision boundary in the original feature space.



original feature space K

higher-dim feature space K'

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It will likely lead to more complexity (both modeling complexity and computational complexity) than we want.

Let's hang on to the logic of the previous example, namely:

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- remap the feature vectors x_i into a higher-dimensional space K'
- create a linear decision boundary in K'
- back out the nonlinear decision boundary in K from the result

some popular kernels:

el
$$k(\mathbf{x},\mathbf{x}')=\langle\mathbf{x},\mathbf{x}'
angle$$

polynomial kernel
$$k(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^\mathsf{T} \mathbf{x}' + 1)^d$$

Gaussian kernel
$$k(\mathbf{x}, \mathbf{x}') = \exp(-\gamma ||\mathbf{x} - \mathbf{x}'||^2)$$

1 1 1

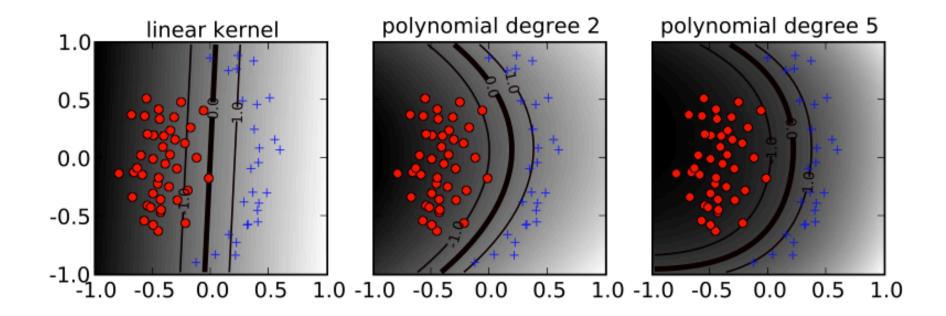
some popular kernels:

The **hyperparameters** d, γ affect the flexibility of the decision plane.

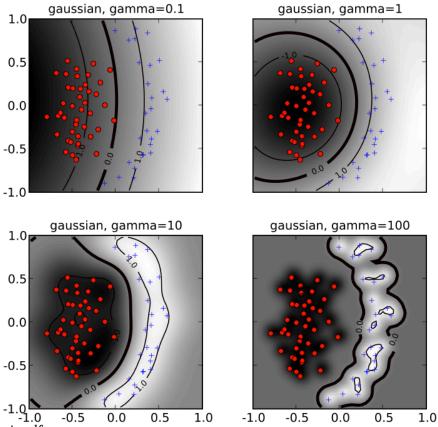
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NONLINEAR CLASSIFICATION — GAUSSIAN KERNEL



source: http://pyml.sourceforge.net/doc/howto.pdf

III. MAXIMUM MARGIN HYPERPLANES

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A: By the discriminant function,

$$f(\mathbf{x}) = \mathbf{w}^{\mathsf{T}} \mathbf{x} + b.$$

$$(OR f(x) = \beta_1 x_1 + \dots + \beta_n x_n + b)$$

such that w is the weight vector and b is the bias.

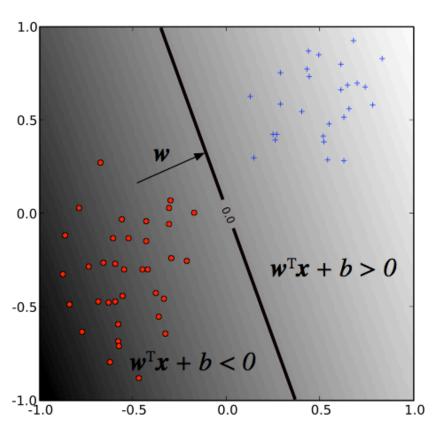
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such that w is the *weight vector* and b is the *bias*. The sign of f(x) determines the (binary) class label of a record x.



MAXIMUM MARGIN HYPERPLANES

As we said before, SVM solves for the decision boundary that minimizes generalization error, or equivalently, that has the maximum margin.

Q: Why are these the same thing?

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- Q: Why are these the same thing?
- A: Because using the mmh as the decision boundary minimizes the probability that a small perturbation in the position of a point produces a classification error.

Intuitively, the wider the margin, the clearer

hetween classes

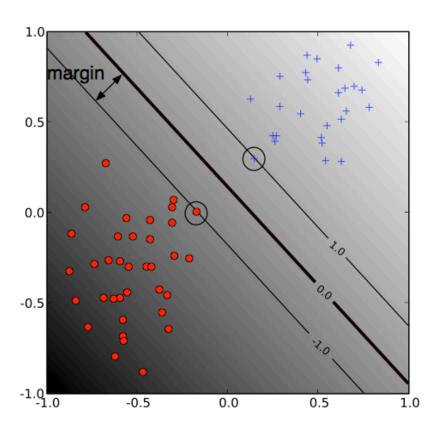
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The other points (far from the decision boundary) don't affect the construction of the mmh at all!

MAXIMUM MARGIN HYPERPLANES

All of the decision boundaries we've seen so far have split the data perfectly; eg, the data are **linearly separable**, and therefore the training error is 0.

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The optimization problem that this SVM solves is:

$$egin{array}{ll} \min & & rac{1}{2} ||\mathbf{w}||^2 \ & \mathbf{w} \cdot \mathbf{x}_i - b \geq 1 & ext{for } \mathbf{x}_i ext{ of the first class} \ & & \mathbf{w} \cdot \mathbf{x}_i - b \leq -1 & ext{for } \mathbf{x}_i ext{ of the second.} \end{array}$$

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The optimization problem that this SVM solves is:

```
minimize \frac{1}{2}||\mathbf{w}||^2 subject to: y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 i = 1, \dots, n.
```

IV. SLACK VARABLES

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Recall that in building the hard margin classifier, we assumed that our data was **linearly separable** (eg, that we could perfectly classify each record with a linear decision boundary).

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This can be done using by introducing slack variables.

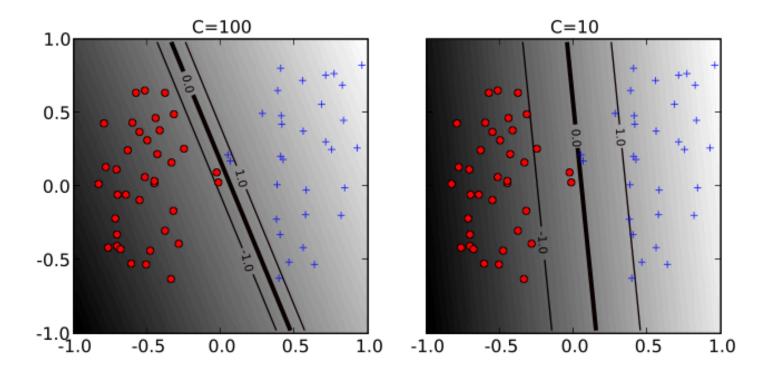
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The resulting **soft margin classifier** is given by:

minimize
$$\frac{1}{2}||\mathbf{w}||^2 + C\sum_{i=1}^n \xi_i$$

subject to: $y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 - \xi_i, \quad \xi_i \ge 0.$



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 subject to: $y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 - \xi_i, \quad \xi_i \ge 0.$

How do we compute this? Quadratic programming optimization technique There is a unique W which gives the best separation SVMs (and **kernel methods** in general) are versatile, powerful, and popular techniques that can produce accurate results for a wide array of classification problems.

The main disadvantage of SVMs is the lack of intuition they produce. These models are truly black boxes!

Advantages:

Represent non-linear representations

Disadvantages:

Difficult to train —

Difficult to choose hyperparameter Long training times

EX: SVM IN SCIKIT-LEARN