

Linear Hybrid Automata for Analyzing Hybrid Systems

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ECE Qualifying Exam Presentation, Spring 2010

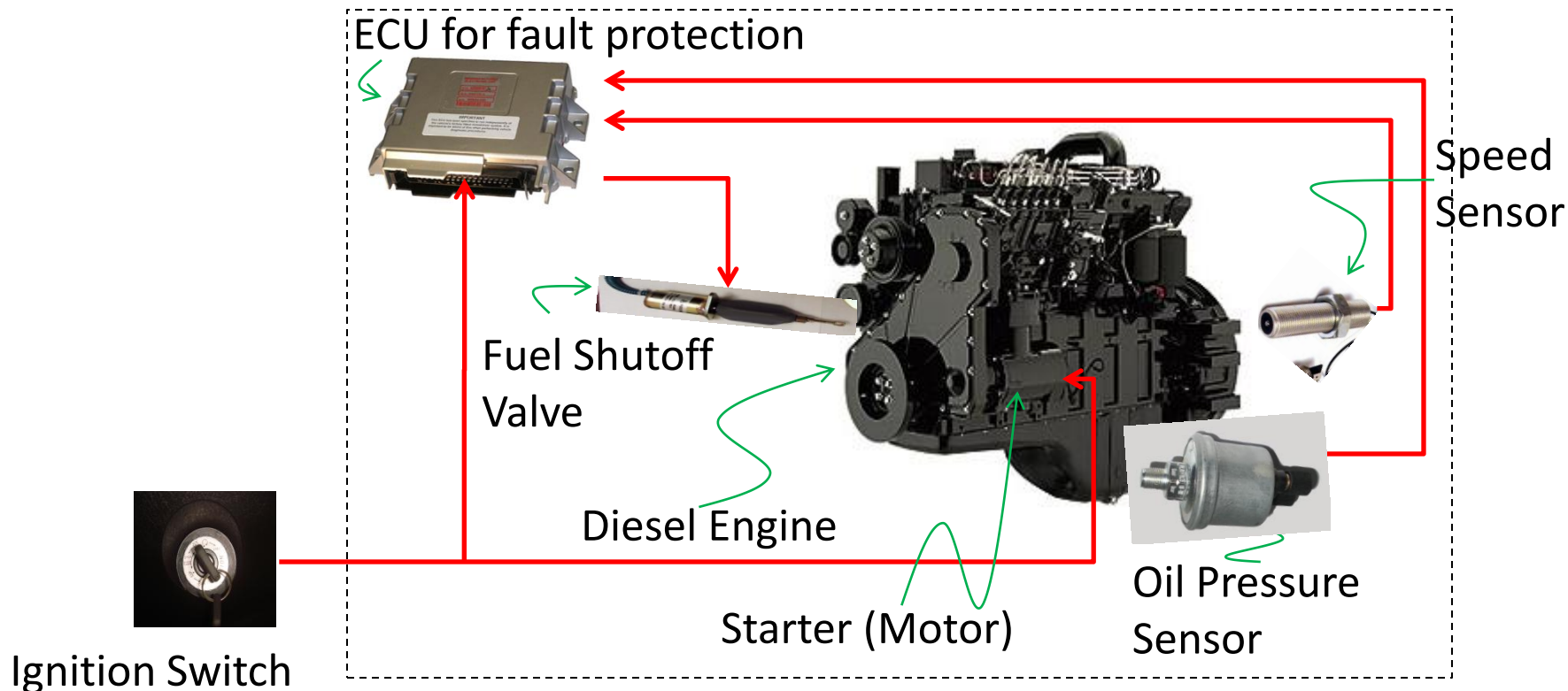
Apr 20, 2010

Outline

- **Hybrid systems**
 - Hybrid automata, linear hybrid automata
- **Checking Conformance to Specification**
 - Simulation relations, computing them
- **Checking Conformance Compositionally**
 - Assume-guarantee reasoning
- **Future Research Directions**
- **Summary**

A motivating example

- Verifying specifications “under all cases”



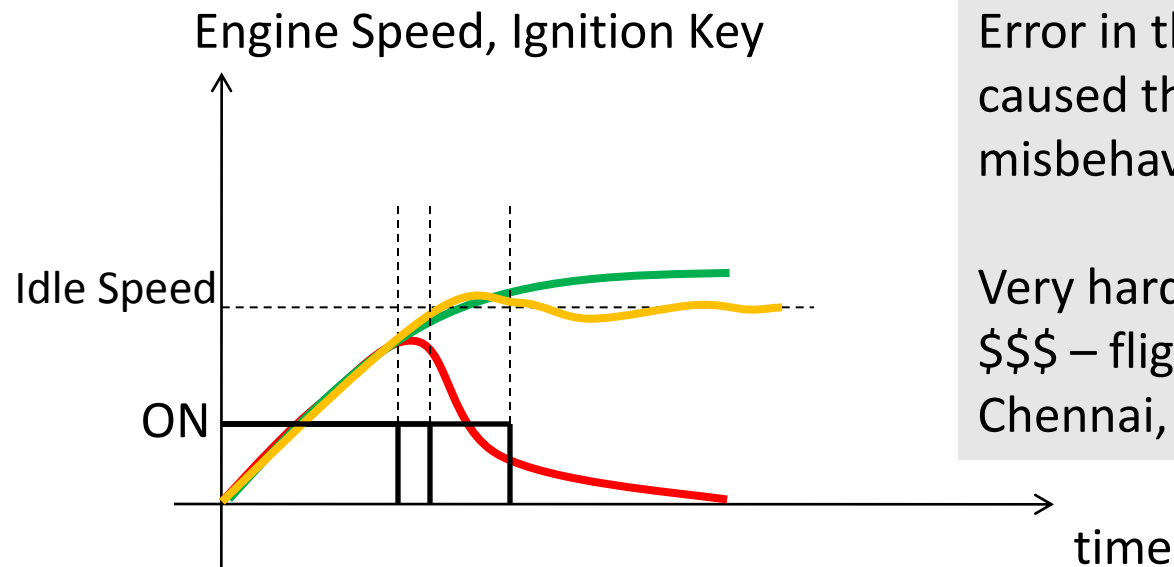
Specification: “If engine is running and oil pressure drops below x psi, the engine is shut off.”

What we observed: **Not always!**

Diagnosis

Starting logic in ECU:

“If ignition key pressed & engine speed > idle, engine started”

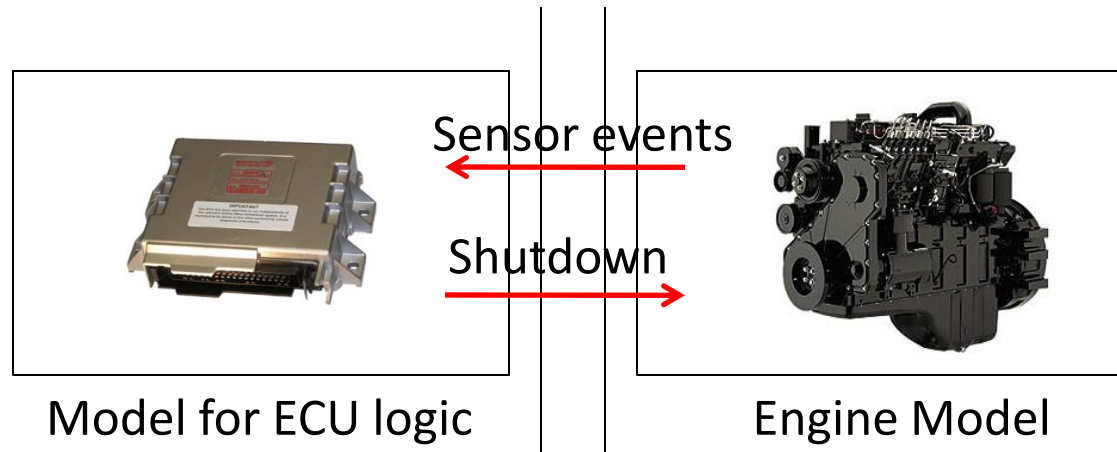


Error in the starting logic caused the stopping logic to misbehave.

Very hard to debug. > 2 months.
\$\$\$ – flights between Pune, Chennai, Bangalore; man-hours

If we had...

A way to model our (software & physical) system...



and...

A method and/or a tool to verify the specification never gets violated under ANY conditions ...

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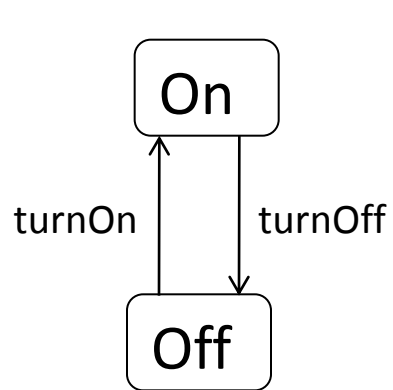
• Checking Conformance Compositionally

- Assume-guarantee reasoning

• Future Research Directions

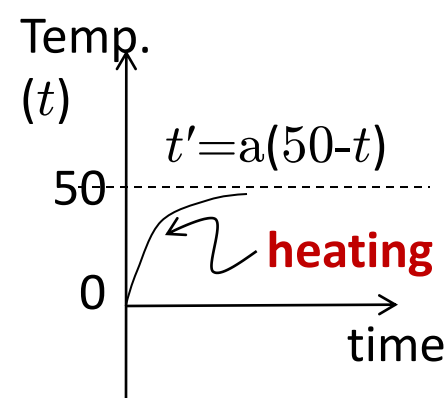
• Summary

Hybrid dynamics: a simple example

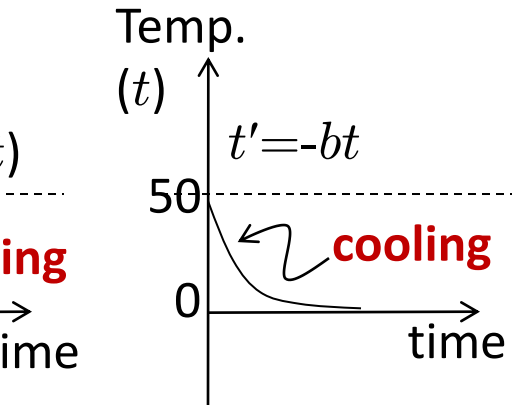


DISCRETE

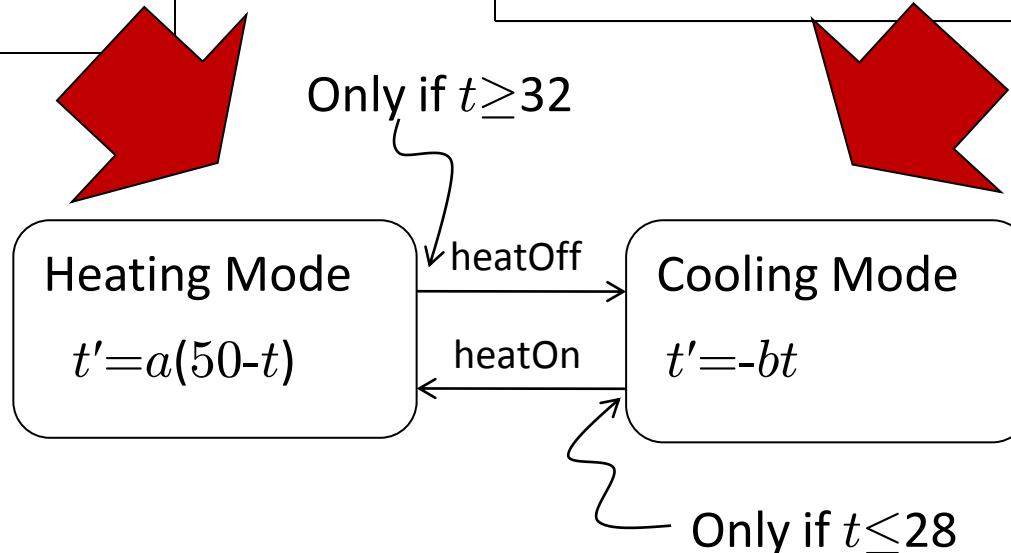
Thermostat



CONTINUOUS



Room Temperature

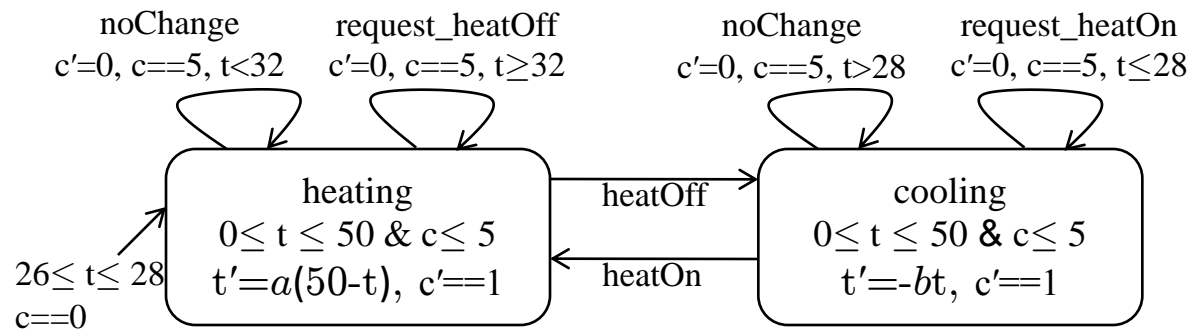


HYBRID

Hybrid automata (HA)

HA: tuple $(Loc, Var, Lab, Tran, Act, Inv, Init)$

Example:



Thermostat System

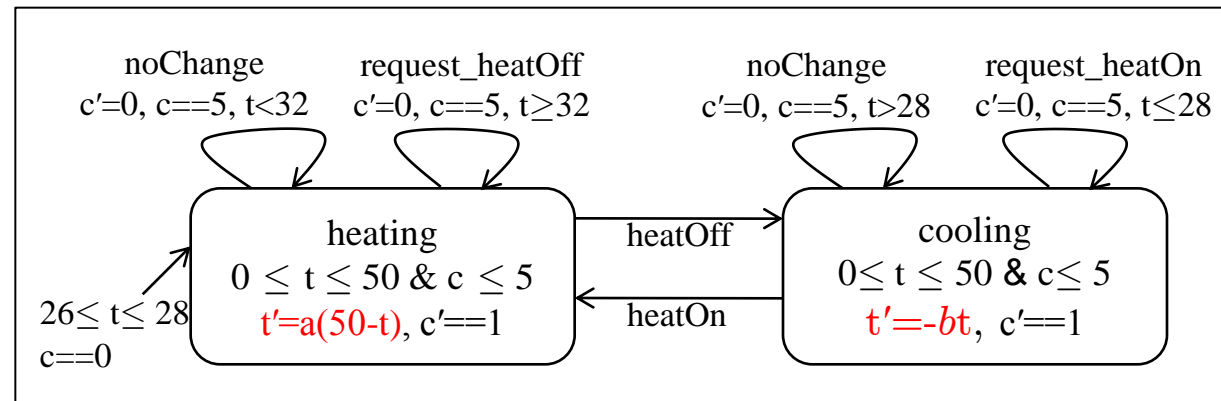
- Sample temperature every 5 sec.
- Set-point 30 deg, hysteresis ± 2 deg

Linear Hybrid automata (LHA)

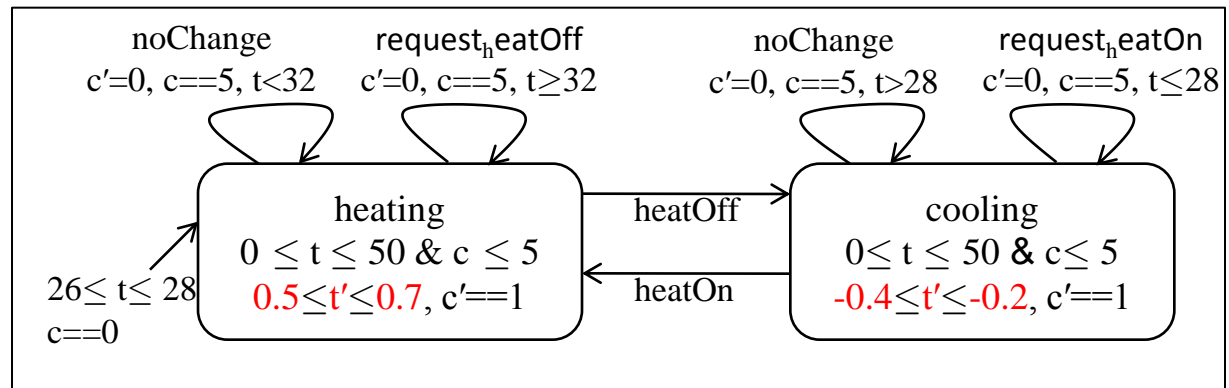
LHA: *Act*, *Inv*, *Init* and continuous part of *Tran* given by **linear** formulas $Ax \{ \leq \text{or} < \} b$

Example:

HA

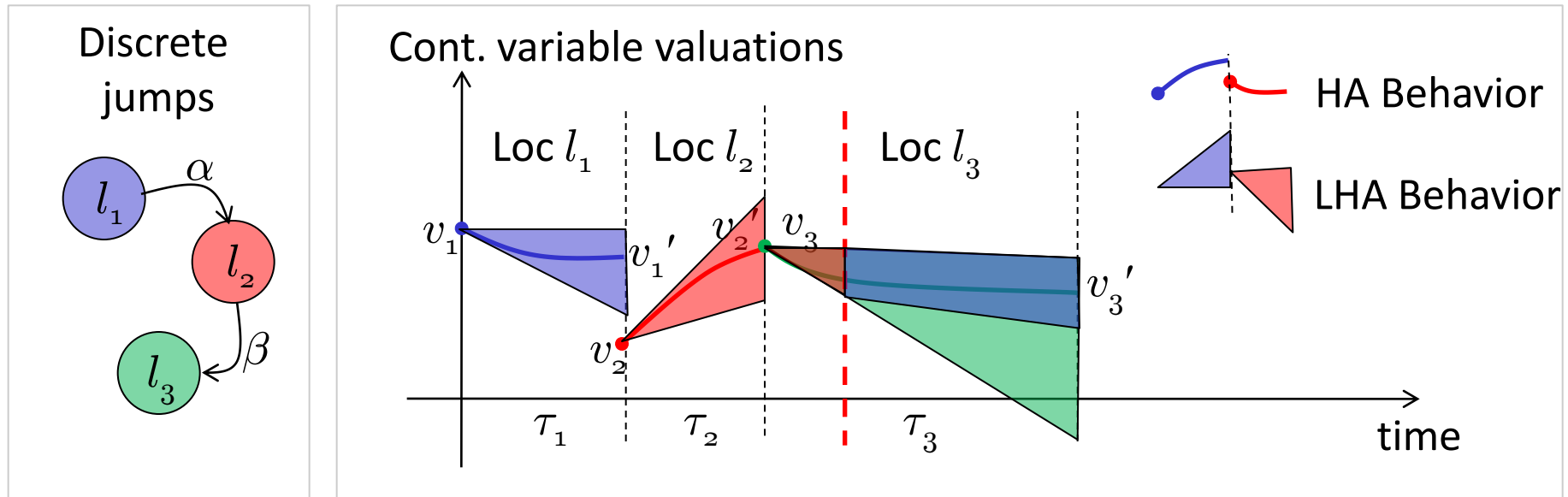


LHA



Behaviors of hybrid systems

- Continuous evolutions and discrete jumps



- LHA can approximate complex hybrid dynamics arbitrarily well. [Hen+98]

Timed transitions of LHA

LHA states are pairs (l, v) , where

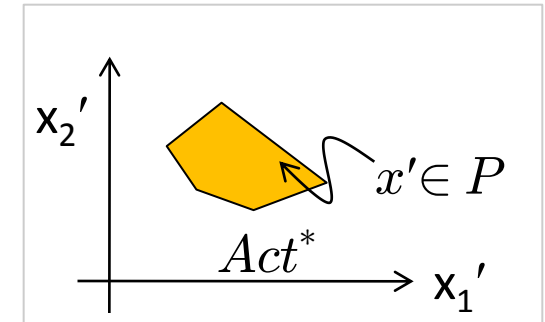
- $l \in Loc$ and
- v = instantaneous valuation of Var

Time evolution in a location is a polyhedral computation

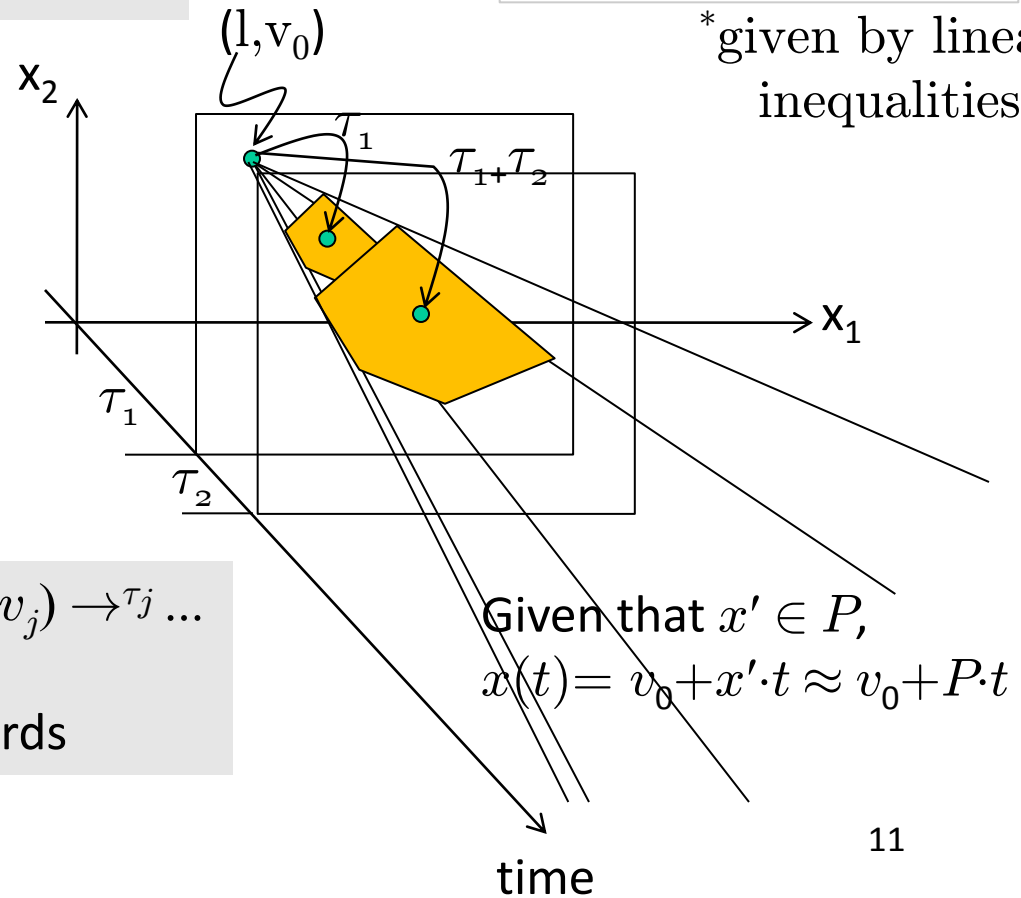
Timed trace: $(l_i, v_i) \xrightarrow{\tau_i} (l_i, v_i') \xrightarrow{\alpha} (l_j, v_j) \xrightarrow{\tau_j} \dots$

Timed word: $\tau_i \alpha \tau_j \dots$

Timed language: set of all timed words



*given by linear inequalities



Given that $x' \in P$,
 $x(t) = v_0 + x' \cdot t \approx v_0 + P \cdot t$

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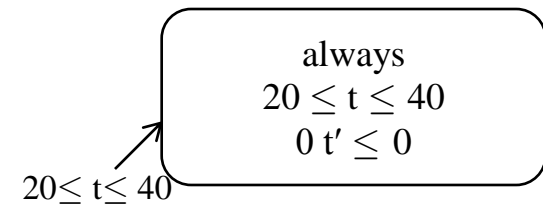
• Summary

Checking Conformance using LHA

In words

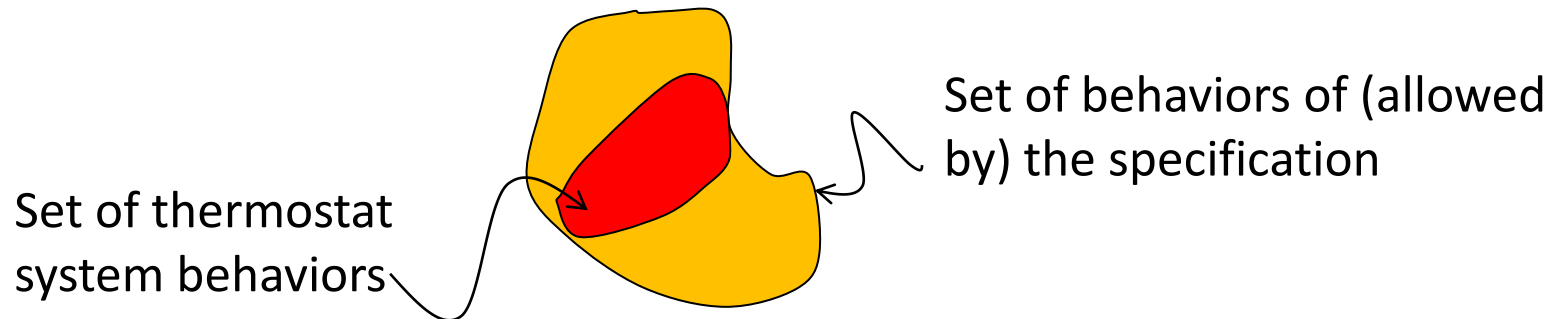
“Under any condition, the room temperature never goes below 20 C or above 40 C.”

Modeled as an LHA



Specifications

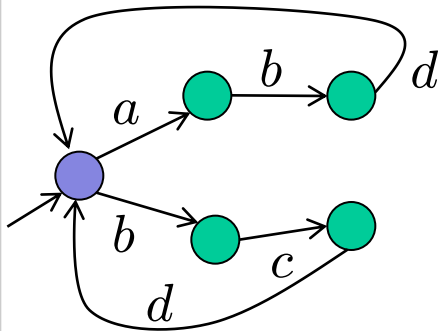
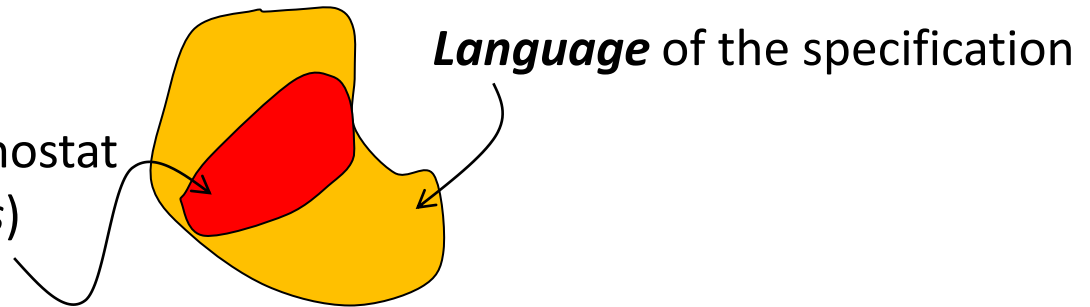
Verification problem (in abstract sense)



Checking Conformance – Transition systems

Verification problem

Language = Set of thermostat system behaviors (*words*)



In case of loops:
- words infinite,
e.g., $abdbcd\dots$
- language with
infinite words

Language inclusion

Brute force method

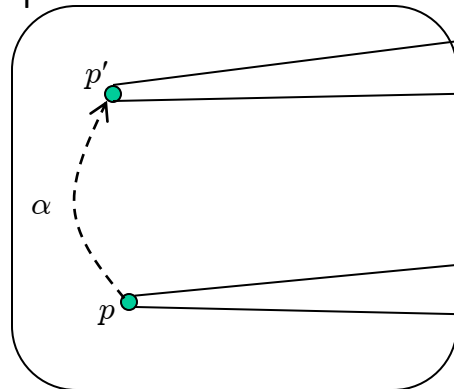
impossible for infinite words and/or languages

Simulation Relations – Transition systems

- **Local** condition to guarantee language inclusion
- A relation $\preceq \subseteq S_P \times S_Q$ is a **simulation relation** iff
 $\forall (p, q) \in \preceq$, also written as $p \preceq q$ and $\forall \alpha \in \text{set of labels } \Sigma$,
 if $p \xrightarrow{\alpha} p'$ then $\exists q' \in S_Q$ s.t. $q \xrightarrow{\alpha} q' \wedge p' \preceq q'$.

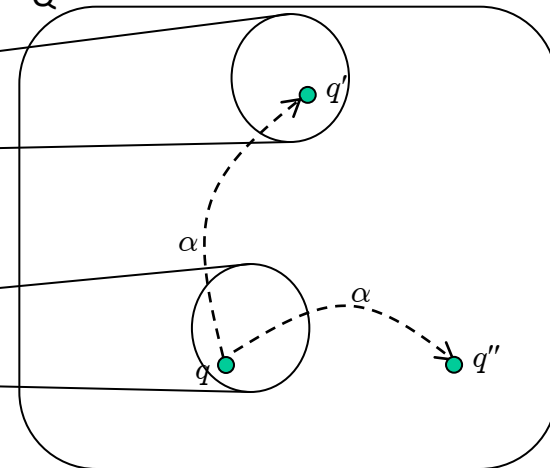
- **Pictorially:**

S_P : States of P



Transition system P

S_Q : States of Q

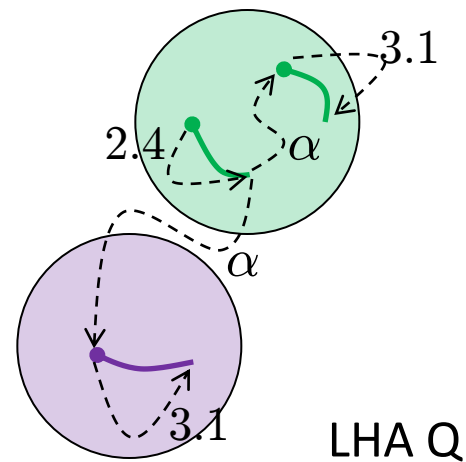
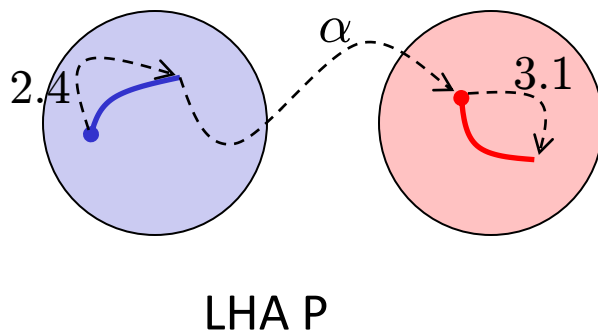


Transition system Q

Simulation Relations – LHA

- A relation $\preceq \subseteq S_P \times S_Q$ is a **simulation relation** iff
 $\forall (k,u) \preceq (l,v)$ and $\forall \alpha \in \text{set of labels } Lab \cup R^+$,
 if $(k,u) \xrightarrow{\alpha} (k',u')$ then $\exists (l',v') \in S_Q$ s.t. $(l,v) \xrightarrow{\alpha} (l',v') \wedge (k',u') \preceq (l',v')$.
- **States are pairs, transitions are timed or discrete**

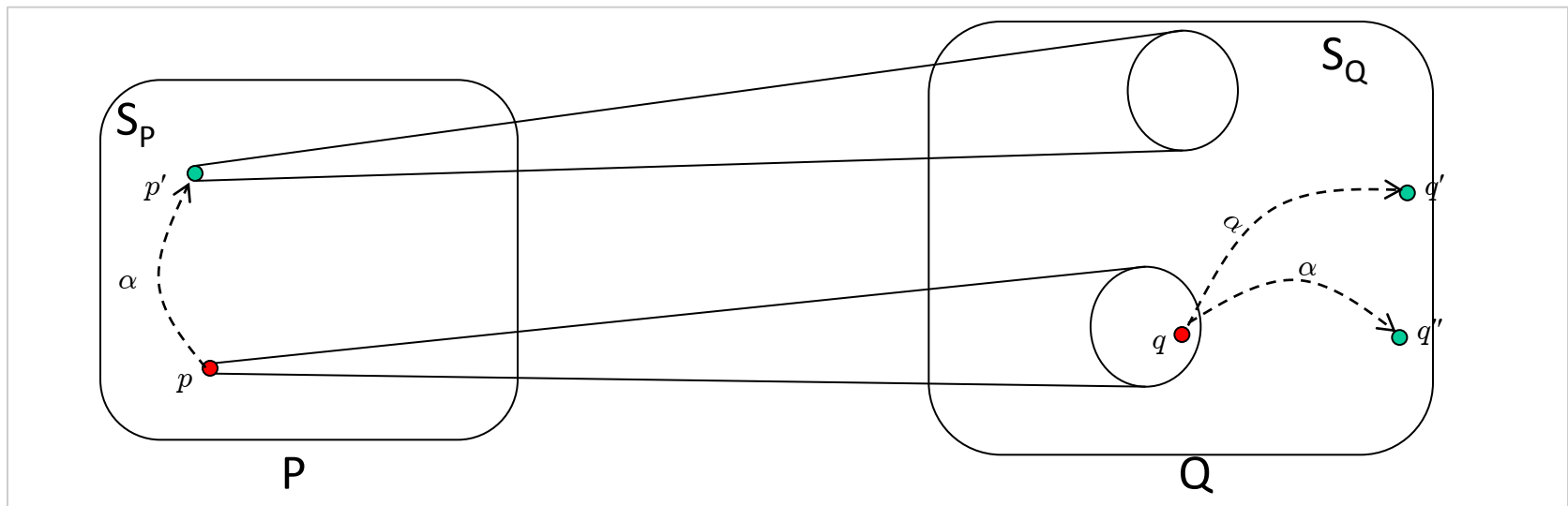
- **Pictorially:**



Computing simulation relations

Fixed-point algorithm: (Idea)

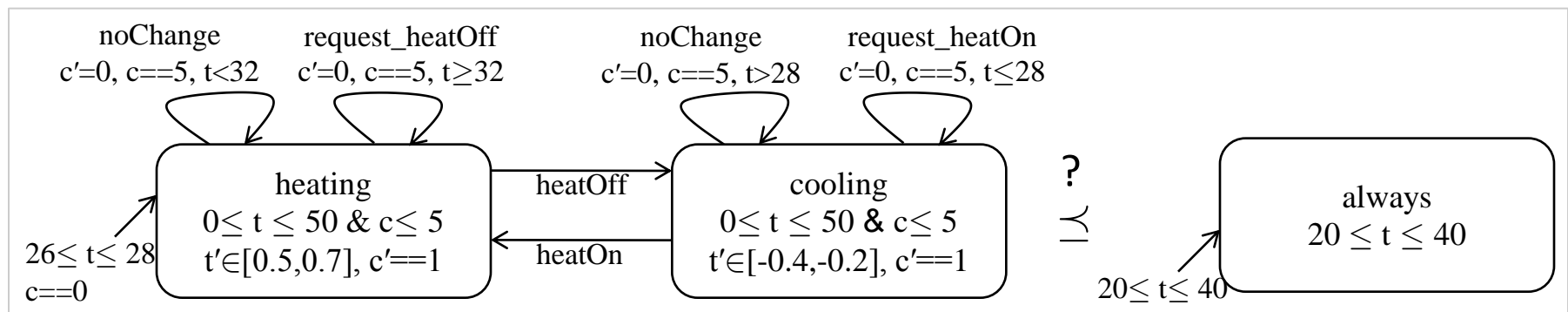
1. Starting with the first guess $\preceq_0 = S_P \times S_Q$
2. Refine the guess $\preceq_{i+1} := \preceq_i \setminus B_i$ by subtracting **bad** states
3. Stop when no more bad states are left (i.e. when a **fixed-point** is reached) i.e. $\preceq_{i+1} == \preceq_i$.



PHAVer

- **P**olyhedral **H**ybrid **A**utomaton **V**erifier [Fre08]
 - Can compute simulation relations for LHA using the fixed-point algorithm
- For thermostat example, we ask:

`is_sim(thermostat, spec)?`



PHAVer: No.

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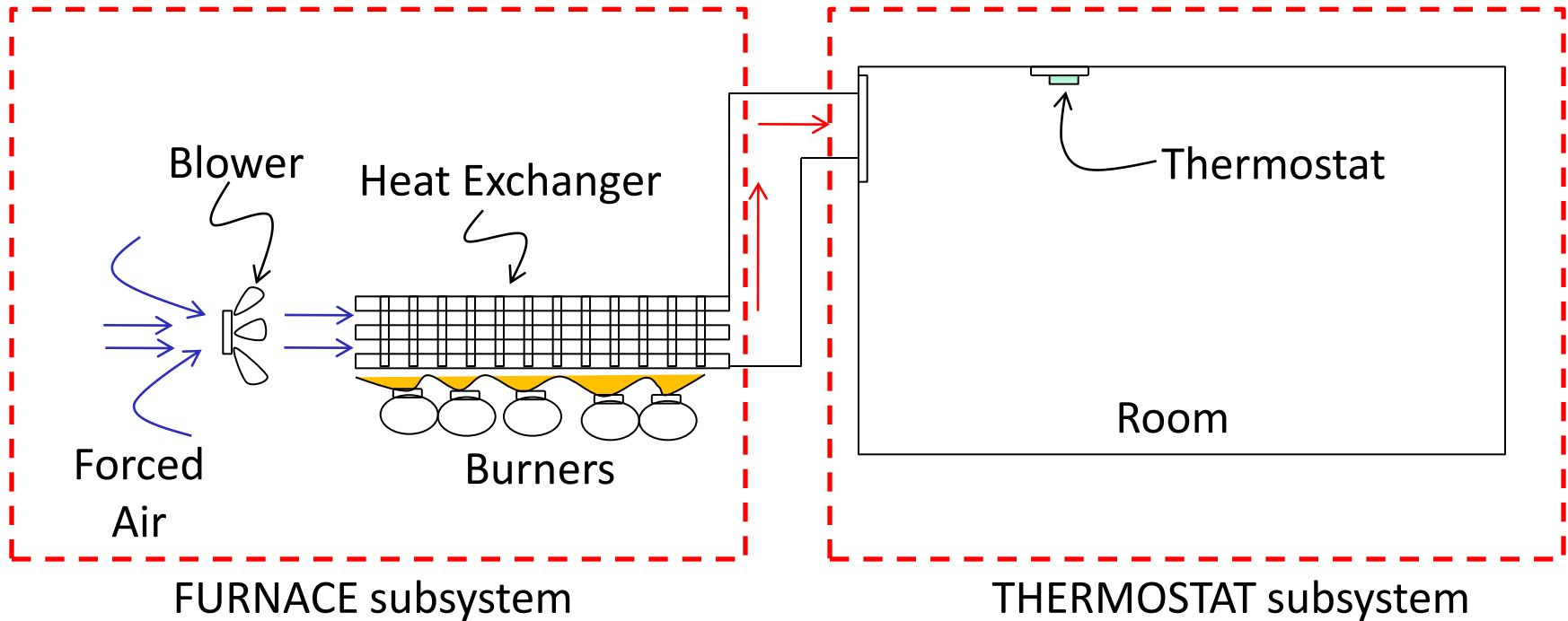
• Summary

Modular modeling and reasoning

- **Parallel composition** ($'||'$) **operation:**
 - Events with matching labels are synchronous.
 - Continuous variables are disjoint.
 - $Sys = Subsys_1 || Subsys_2 || \dots$
- **Often:** Modeling and analysis of such a Sys too expensive.
- **Need:** Ability to deduce whether $Sys \preceq Q$ without having to construct Sys explicitly.

Example

- $\text{sys} = \text{thermostat} \mid \mid \text{furnace}$



- Burners heats unevenly, n monitoring sensors

Assume-guarantee (AG) reasoning

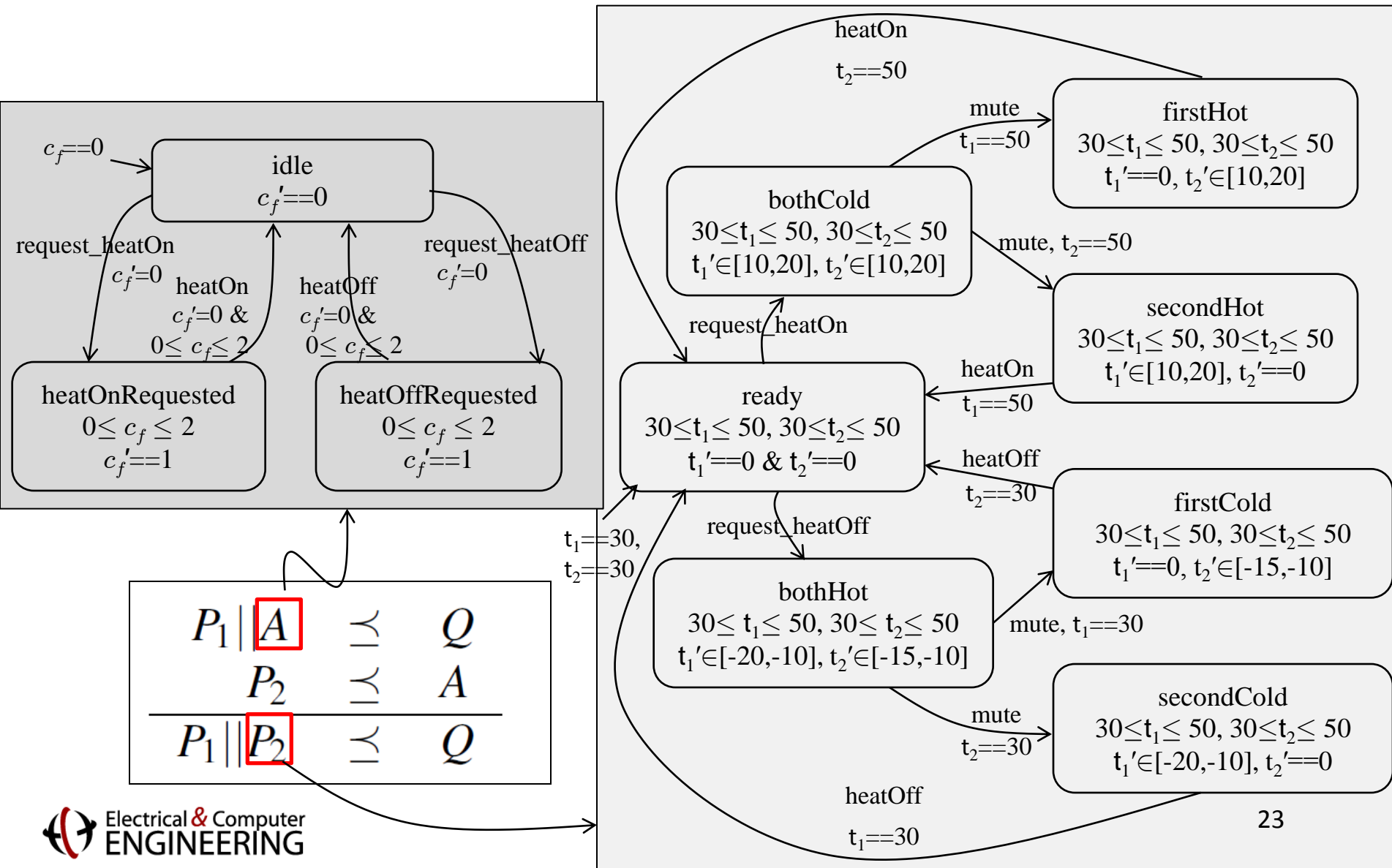
- **Non-circular reasoning** [Fre04]

$$\frac{\begin{array}{c} P_1 || A \preceq Q \\ P_2 \preceq A \end{array}}{P_1 || P_2 \preceq Q}$$

- **Main Idea:** Complex task deduced from simpler subtasks
- **Profitable** if A is simpler than P_2 , i.e.

$$P_1 || A \text{ simpler than } P_1 || P_2$$

Example (Furnace vs Assumption)



Experimental results

Comparison: Computation time AG/non-AG

#sensors in the furnace model	Non-AG Method $P_1 P_2 \preceq Q$		AG Method $P_1 A \preceq \text{and } Q P_2 \preceq A$	
	# State variables	Time (s)	# State variables	Time (s)
1	4	2.10	4 and 2	1.10
2	5	121.45	4 and 3	2.85
3	6	∞^*	4 and 4	23.51
4	7	∞^*	4 and 5	272.67

Legend: P_1 : Thermostat, P_2 : Furnace, A : Furnace Assumption, Q : Specification

Experimental results

- Simulation relation computation expensive
- Heuristic: Look at only reachable states

#sensors in the furnace model	Non-AG Method $P_1 P_2 \preceq Q$			AG Method $P_1 A \preceq Q \text{ and } P_2 \preceq A$		
	# State variables	Time (s)		# State variables	Time (s)	
		Full	Reach		Full	Reach
1	4	2.10	0.10	4 and 2	1.10	0.20
2	5	121.45	0.40	4 and 3	2.85	0.30
3	6	∞^*	1.40	4 and 4	23.51	2.80
4	7	∞^*	23.71	4 and 5	272.67	96.02

Legend: P_1 : Thermostat, P_2 : Furnace, A : Furnace Assumption, Q : Specification

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Future Research Directions – I

- Explicit simulation relation computation using fixed-point approach is **expensive**.

$$\preceq_{n+1} := \preceq_n \setminus B_n \text{ i.e. set difference } \preceq_n \cap \neg B_n$$

- **Alternative to explore:**
 - Developing necessary and sufficient conditions for existence of simulation relations
 - Ex.: Approximate simulation for transition systems with observations in metric spaces [GirardPappas03]

Future Research Directions – II

- For AG, significant **human effort** is needed in coming up with good assumptions A .

$$\frac{\begin{array}{ccc} P_1 || A & \preceq & Q \\ P_2 & \preceq & A \end{array}}{P_1 || P_2 \preceq Q}$$

- **Alternatives to explore:**
 - (Semi-)automating the assumption generation process by doing it iteratively
 - Ex.: Parameter synthesis for LHA [FrehseJhaKrogh08]

Summary

- ✓ **Simulation relations for conformance check**
- ✓ **AG for compositional reasoning**

- **Explicitly generating simulation relations computationally expensive**
 - Opportunity for further research
- **Assumption generation needs human effort**
 - Opportunity for further research

References

- [Hen+98] Algorithmic Analysis of Nonlinear Hybrid Systems**, Thomas Henzinger, Pei-Hsin Ho, Howard Wong-Toi
- [Fre08] PHAVer: Algorithmic Verification of Hybrid Systems Past HyTech**, Goran Frehse
- [Fre04] Assume-guarantee Reasoning of Hybrid Systems with Discrete Interaction using Simulation Relations**, Goran Frehse

Linear Hybrid Automata (LHA) for Analyzing Hybrid Systems (HS)

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