Asgn. 4 Secret Device Driver

Approach

Before diving into coding our device driver, we looked over the device driver tutorial and the reading assigned in the assignment description. The tutorial showed us how to start up, update, and shutdown the hello device. After we had a basic understanding of how to interface with a device we began modifying the hello device driver until we had a working secret device driver.

Architecture

Our driver is expected to function very much like the hello driver. Since all drivers have the same list of functions, we simply had to copy the hello driver and change it's individual function behaviors. Obviously our driver had a lot more restrictions than the hello driver, as well as allowing the ability to write to the device.

Implementation

Development Environment:

Version of MINIX kernel is 3.1.8. It was installed as a VM via Virtual Box.

Files Modified:

All of the files in the hello driver directory were copied and modified to be of use for our secret device. Most of the files, including the Makefile, the .conf file, and the .d file simply involved us changing variable names to 'secret'. The header file was modified to only define our max secret length. Hello.c was greatly changed to assure behavior was exactly as described in the specifications. A few global variables as well as function prototypes were declared for use throughout the file. hello_open() and hello_transfer() were the two functions changed the most. Inside these functions we do multiple checks for things such as message type and message sender.

Problems Encountered

- 1. One of the road blocks we ran into is not being able to get the uid of the current user logged in. We tried using the *m_source field* of a message structure as the *endpoint_t* to the *getnucred* function, but that always set the real user id to 0.
- 2. When we were testing if a user that owns the device can write and read from a buffer and then another user can write to the buffer we were getting a permission error. The buffer was being emptied, but another user could not write to it.
- 3. Another problem encountered was still keeping the secret after the initial write fd had closed. Our initial approach involved just clearing the secret once our open counter had reached zero. So we had the problem of having the initial write increment the counter and decrement when done, which essentially just cause a write and immediate erase.

- 4. Writing a message whose size was larger than the size of the buffer was not resulting in an error. Instead, the maximum amount of characters that fit into the buffer were being written to it.
- 5. For error handling we weren't sure how to set the correct error. Whenever there was incorrect usage or permission errors we were setting error to the appropriate error code and then printing using perror(). This resulted in strange output that made no sense.

Solutions

- 1. The solution to getting the real uid of the user currently logged in was to use the IO_ENDPT field of the message structure in *secret_open()*.
- 2. The reason why we were getting a permission error when a new user was attempting to write to an empty buffer was because we forgot to reset the permissions of the device when the buffer was being emptied.
- 3. In order to make sure we didn't clear the secret after the initial write fd had closed, we had to make sure we only cleared the secrets after reads were performed. Therefore, since the initial fd was only performing a write we didn't bother checking the open count. The counter would still be set to zero after the write, but the secret would still remain this way.
- 4. When checking for the size of the message typed by the user we were using the bytes local variable in <code>secret_transfer()</code>. This variable was set to the the max size of the buffer when the message was longer than the size of the buffer. We fixed this by using <code>iov->iov size</code> instead to get the size of the message that the user typed in.
- 5. We realized that when handling errors, we just needed to return the appropriate error to the calling function, in this case driver_task(). The calling function would then appropriately handle the error that was returned from our function. We also noticed that driver_task() would print the error message in certain situations, but not others, so for those cases we output our own error messages.

Lessons Learned

In this assignment we learned how to interface with a device file through a device driver and how to make a character device file. In terms of writing a device driver, we learned that MINIX separates device driver independent software with device driver dependent software. This makes MINIX more modular because we only need to provide functions for our specific device through a driver structure. All devices are controlled by the driver_task() which calls the functions that we provided to the driver structure.

```
#ifndef __SECRET_H
#define __SECRET_H

/** The Hello, World! message. */
#define HELLO_MESSAGE "Hello, World!\n"
#define SECRET_SIZE 8192

#endif /* __SECRET_H */
```

Page 1/1

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```
1 #include <minix/drivers.h>
2 #include <minix/driver.h>
3 #include <sys/types.h>
4 #include <sys/ioctl.h>
5 #include <errno.h>
6 #include <stdio.h>
7 #include <stdlib.h>
8 #include <minix/ds.h>
9 #include "secret.h"
10
11 #define 0 RDWR 6
12 #define 0 WRONLY 2
13
14 char secret[SECRET SIZE];
15 uid t owner = -1;
16 struct ucred e:
17 int wr_counter = 0;
18
19 | /*
  * Function prototypes for the hello driver.
20
21
22 FORWARD PROTOTYPE( char * secret name,
                                              (void) );
                                              (struct driver *d, message *m) );
23 FORWARD PROTOTYPE( int secret open,
24 FORWARD PROTOTYPE( int secret ioctl,
                                              (struct driver *d, message *m) );
25 FORWARD PROTOTYPE( int secret close,
                                              (struct driver *d, message *m) );
26 FORWARD _PROTOTYPE( struct device * secret_prepare, (int device) );
27 FORWARD _PROTOTYPE( int secret_transfer, (int procnr, int opcode,
                                              u64 t position, iovec t *iov,
28
                                              unsigned nr_req) );
29
30 FORWARD PROTOTYPE( void secret geometry, (struct partition *entry) );
31
32 /* SEF functions and variables. */
33 FORWARD _PROTOTYPE( void sef_local_startup, (void) );
34 FORWARD _PROTOTYPE( int sef_cb_init, (int type, sef_init_info_t *info) );
FORWARD PROTOTYPE( int sef_cb_lu_state_save, (int) );
36 FORWARD PROTOTYPE( int lu state restore, (void) );
37
38 /* Entry points to the hello driver. */
39
  PRIVATE struct driver secret tab =
40
  {
      secret_name,
41
      secret open,
42
      secret close,
43
      secret_ioctl,
44
      secret_prepare,
45
```

Page 1/7

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85

86

89

90

} 87 88

return OK;

PRIVATE int secret_open(d, m)

struct driver *d;

```
Page 2/7
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          secret_transfer,
  46
  47
          nop_cleanup,
          secret_geometry,
  48
          nop alarm,
  49
          nop cancel,
  50
          nop_select,
  51
          nop_ioctl,
  52
          do_nop,
  53
     };
  54
  55
     /** Represents the /dev/hello device. */
  56
     PRIVATE struct device secret device;
  57
  58
     /** State variable to count the number of times the device has been opened. *
  59
     PRIVATE int open_counter;
  60
  61
     PRIVATE char * secret_name(void)
  62
  63
          printf("secret_name()\n");
  64
          return "hello";
  65
     }
  66
  67
     PRIVATE int secret_ioctl(d, m)
  68
          struct driver *d;
  69
          message *m;
  70
  71
     {
          uid t grantee;
  72
  73
          if (m->REQUEST == SSGRANT)
  74
          {
  75
             sys_safecopyfrom(m->IO_ENDPT, (vir_bytes)m->IO_GRANT,
  76
            0, (vir bytes)&grantee, sizeof(grantee), D);
  77
             owner = grantee;
  78
          }
  79
          else
  80
          {
  81
             printf("invalid ioctl request\n");
  82
             return ENOTTY;
  83
          }
  84
```

```
91
        message *m;
   {
92
        getnucred(m->IO ENDPT, &e);
93
94
        /*printf("secret open(). Called %d time(s).\n", ++open counter);*/
95
        if (m->COUNT == 0 RDWR)
96
97
           printf("Can't open device with read write access\n");
98
           return EACCES;
99
        }
100
        else if (m->COUNT & W BIT)
101
102
           if (e.uid != owner && owner != -1)
103
             return EACCES:
104
           if (strlen(secret) != 0)
105
           {
106
              /*printf("cannot create /dev/Secret: No space left on device\n");*/
107
              return ENOSPC;
108
           }
109
110
        ++open_counter;
111
112
        if (owner == -1)
113
           owner = e.uid;
114
115
        return OK;
   }
116
117
   PRIVATE int secret close(d, m)
118
119
        struct driver *d;
120
        message *m;
121 | {
        /*printf("secret close()\n");*/
122
        return OK;
123
124 | }
125
126 PRIVATE struct device * secret_prepare(dev)
127
        int dev;
   {
128
        secret device.dv base.lo = 0;
129
        secret device.dv base.hi = 0;
130
131
        secret device.dv size.lo = SECRET SIZE;
        secret device.dv size.hi = 0;
132
133
        return &secret device;
134 | }
135
```

```
136
   PRIVATE int secret_transfer(proc_nr, opcode, position, iov, nr req)
137
        int proc_nr;
        int opcode;
138
        u64 t position;
139
        iovec t *iov;
140
        unsigned nr_req;
141
142
        int bytes, ret;
143
144
        /*printf("secret_transfer()\n");*/
145
146
        bytes = SECRET_SIZE - position.lo < iov->iov_size ?
147
                 SECRET SIZE - position.lo : iov->iov size;
148
149
        if (bytes <= 0)</pre>
150
        {
151
            return OK;
152
153
        switch (opcode)
154
155
            case DEV_GATHER_S:
156
                 if (owner == -1 || owner == e.uid)
157
                 {
158
                    open counter--;
159
                    ret = sys_safecopyto(proc_nr, iov->iov_addr, 0,
160
                                       (vir_bytes) (secret + position.lo),
161
                                        bytes, D);
162
                    iov->iov_size -= bytes;
163
                    if (open counter == 0)
164
                    {
165
                       memset(secret, 0, strlen(secret));
166
                       owner = -1;
167
                    }
168
                 }
169
                 else
170
171
                 {
172
                    --open_counter;
                    ret = EACCES;
173
174
                 break;
175
            case DEV_SCATTER_S:
176
                 --open counter;
177
178
                 if (iov->iov_size > SECRET_SIZE)
179
                 {
                     printf("Input too big\n");
180
```

}

break;

default:

return ret;

entry->heads

entry->sectors

/* Save the state. */

return OK;

u32 t value;

return OK;

/*

181

182

183

184

185 186

187

188

189

190

191

192 193 | } 194

195

196

198

199

200 201

204

205

206 207

208 209 | } 210

211

212

213 214

215

216

217 218 219

220 221

222 223 224

225

202 | } 203

{ 197

}

* Register init callbacks. Use the same function for all event types

if (do_announce_driver) {

270

```
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226
        */
       sef_setcb_init_fresh(sef_cb_init);
227
       sef setcb init lu(sef cb init);
228
       sef setcb init restart(sef cb init);
229
230
231
        * Register live update callbacks.
232
233
        */
       /* - Agree to update immediately when LU is requested in a valid state. *
234
       sef_setcb_lu_prepare(sef_cb_lu_prepare_always_ready);
235
       /* - Support live update starting from any standard state. */
236
       sef setcb lu state isvalid(sef cb lu state isvalid standard);
237
       /* - Register a custom routine to save the state. */
238
       sef setcb lu state save(sef cb lu state save);
239
240
       /* Let SEF perform startup. */
241
       sef_startup();
242
243 | }
244
245 PRIVATE int sef cb init(int type, sef init info t *info)
246
   /* Initialize the hello driver. */
247
       int do announce driver = TRUE;
248
249
       open_counter = 0;
250
       switch(type) {
251
            case SEF INIT FRESH:
252
                printf("Refresed\n");
253
254
            break:
255
            case SEF INIT LU:
256
                /* Restore the state. */
257
                lu state restore();
258
                do announce_driver = FALSE;
259
260
                printf("Hey, I'm a new version!\n");
261
            break:
262
263
264
            case SEF INIT RESTART:
                printf("Hey, I've just been restarted!\n");
265
266
            break:
       }
267
268
269
       /* Announce we are up when necessary. */
```

Page 6/7

```
driver_announce();
271
        }
272
273
        /* Initialization completed successfully. */
274
        return OK;
275
276 | }
277
278 PUBLIC int main(int argc, char **argv)
279
   {
        /*
280
         * Perform initialization.
281
         */
282
        sef local startup();
283
284
        /*
285
         * Run the main loop.
286
287
        driver_task(&secret_tab, DRIVER_STD);
288
        return OK;
289
290 }
291
```

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <sys/types.h>
4 #include <sys/ioctl.h>
5 #include <fcntl.h>
6 #include <unistd.h>
7 #include <string.h>
8
9 int main(int argc, char *argv[])
10 | {
     int fd, res;
11
     char *msg = "hello\n";
12
     uid t uid;
13
14
     fd = open("/dev/Secret", 0 WRONLY);
15
     printf("Opening... fd=%d\n", fd);
16
     res = write(fd, msg, strlen(msg));
17
     printf("Writing... res = %d\n", res);
18
19
     /*try grant*/
20
21
     if (argc > 1 && 0 != (uid=atoi(argv[1]))) {
         if (res = ioctl(fd, SSGRANT, &uid))
22
            perror("ioctl");
23
         printf("Trying to change owner to %d ... res=%d\n", uid, res);
24
25
      return 0;
26
27 | }
28
```

```
Page 1/1
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  1 #include <stdio.h>
  2 #include <stdlib.h>
  3 #include <sys/types.h>
  4 #include <sys/ioctl.h>
  5 #include <fcntl.h>
```

```
6 #include <unistd.h>
7 #include <string.h>
8
9 int main(int argc, char *argv[])
10 | {
      int fd, res;
11
      char *msg = "hello";
12
      uid t uid;
13
14
      fd = open("/dev/Secret", 0_RDWR);
15
      printf("Opening... fd=%d\n", fd);
16
      res = write(fd, msg, strlen(msg));
17
      printf("Writing... res = %d\n", res);
18
19
      return 0;
20
21 | }
```

22

```
make: stopped in /usr/src/drivers/secrets
# make up
Refresed
# cat /dev/Secret
# echo "The Americans are coming" > /dev/Secret
# echo "Secret 2" > /dev/Secret
cannot create /dev/Secret: No space left on device
# cat /dev/Secret
The Americans are coming
# cat /dev/Secret
 echo "My secret" > /dev/Secret
 su heri
 cat /dev/Secret
cat: /dev/Secret: Permission denied
 cat > /dev/Secret
cannot create /dev/Secret: Permission denied
 exit
# cat /dev/Secret
My secret
# su heri
 echo "This is all mine" > /dev/Secret
S exit
 cat /dev/Secret
cat: /dev/Secret: Permission denied
# su heri
S cat /dev/Secret
This is all mine
 exit
```

```
minix3 [Running]
# ./a.out 13
Opening... fd=3
Writing... res = 6
Trying to change owner to 13 ... res=0
# cat /dev/Secret
cat: /dev/Secret: Permission denied
# su heri
$ cat /dev/Secret
hello
$ exit
```

```
minix3 [Running]
# cc test_rdwrt.c
# ./a.out
Can't open device with read write access
Opening... fd=-1
Writing... res = -1
```