2020-2021 Fall Semester

Linear Algebra & Applications

Solutions for Homework # 4

(21)
(a) let
$$K = \begin{bmatrix} a \\ b \\ cd \end{bmatrix}$$
 and $K = v_1 \cdot c_1 + v_2 \cdot c_2 + v_3 \cdot c_3$

$$\begin{vmatrix} a - 2c_2 \\ 3c_1 \\ 2a - c_2 \\ + c_3 = d \end{vmatrix} = \begin{bmatrix} 4 - 2 & 0 \\ 3 & 0 & 3 \\ 1 & 0 & 4 \end{bmatrix} \cdot \begin{bmatrix} c_1 - a \\ c_2 - a \\ c_3 = d \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 0 & 0 & 0 \\ 3 & 0 & 3 & 0 \\ 2 & -1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ E_{1,1}(-4) \\ E_{2,1}(-2) \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} a \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} c_1 - a \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 0 & 0 \\ 2 & -1 & -2 \\ 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ E_{2,1}(-2) \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} a \\ -2 & -2 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ -2 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a \\ 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 0 & 0 \\ 1 & -2 & 0 \\ 0 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ -2 & 0 \\ 0 & -1 & -2 \\ 0 & -1 & 2 \end{bmatrix} \cdot \begin{bmatrix} a \\ -2 & 0 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} a \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} a \\ 0$$

Given vector span a subspace consisting of vector
$$K$$
, that $K = \begin{bmatrix} 2c \\ 3d \\ c \\ d \end{bmatrix}$; $c, d \in IR$

since there are an infinite amount of solutions, the vectors are linearly dependent

C) The dimension for R' is 4, therefore any linearly ind. 4 vectors form a books.

We already have 3 vectors which are linearly independent, but they can span R', it we can find a bouth vector "v which is not in the span, we can write the books for R' (add-minus theorem)

We found that subspace sponned of the given vectors consists of vectors such:

$$K = \begin{bmatrix} 2c \\ 5 \\ 6 \end{bmatrix}; \text{ b, c, d} \in \mathbb{R} \text{ therefore } V = \begin{bmatrix} \frac{1}{2} \\ \frac{3}{3} \end{bmatrix} \text{ is not in the spon}$$

$$\text{d} \text{ basis for } R \text{ is } = \left\{ (4,3,2,1), (-2,0,-1,0), (0,3,0,1), (1,2,3,4) \right\}$$

Q2)
$$\nabla \cos^2 x - \sin^2 x = \cos 2x \Rightarrow f_1 = \cos 2x$$
 and $f_2 = \cos 2x$ applying Wronskian:

 $\begin{vmatrix} \cos 2x & \cos 2x \\ \cos 2x \end{vmatrix} = \begin{vmatrix} \cos 2x & \cos 2x \\ -2\sin 2x & -2\sin 2x \end{vmatrix} = -2\sin 2x \cos 2x + 2\sin 2x \cos 2x = 0$

Since the wronskian is equal to 0, these vectors are linearly dependent.

Q3) Dimension of
$$R^3$$
 is 3, therefore basis for R^3 consist of 3 vectors (hoose $u_1, u_3, u_4 \Rightarrow$ Test for linear independence:

 $u_1. c_1 + u_3. c_3 + u_4. c_4 = 0$, find $c_1, c_3. c_4$

$$\begin{bmatrix} c_1 + c_3 & = 0 \\ -2c_1 & = 0 \end{bmatrix} \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 7 \end{bmatrix} \begin{bmatrix} c_1 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_3 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_1 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_3 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_4 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_1 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_1 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_3 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_4 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_3 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} c_4 & 0$$

Since our number of vectors is equal to the dimention of the plane, we can say u, us, u, form a bouts without testing for their span.

Base = {(1,-2,0), (1,0,-1), (0,0,7)}

Depress the remaining vector, uz, by the base vectors u.c. + uz. cz + uz. cz = uz , find cz, cz, cz

The dimension of the subspace spanned by these vectors is 4

24) If we remove a vector from a set of linearly independent vectors, the remaining ones will also be theatly independent. But since the remaining vectors are less than the dimersion, they won't be a basis for the space

Since those I vectors are the basis for the space any other vector can be expressed as a linear combination of the basis vectors. Therefore, if we add another vector to the set, but new set of vectors will be linearly dependent.

25) Let M be a subspace of R that is spanned by the given vectors. If we find a vector of such VEM, then our new set of vectors which additionally has vin, is a larger linearly independent set.

Q6) The vectors u and v, are the bouls for the uxv plane.

The vector resulting from projuxy w lies in the ux v plane therefore it can be expressed at a linear combination of the basis vectors u and v.

Therefore u, v and profuse w are not linearly independent

Q7) The basis for 2x2 matrices has 4 vectors. If we are given 5 2x2 matrices, only 4 of them can be linearly independent in total. So, in the worst case scenario, at least one of the live vectors is linearly dependent and therefore can be expressed as a linear combination of the remaining vectors.

The basis for 3x3 matrices consists of 9 vectors. If we are given 5 3x3 matrices, every one of them can be linearly independent. In such a case, the given matrices can not be expressed on a linear combination of the remaining ones.