

$$Q1) \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 0 & -1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$\left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 0 & 1 & 0 \\ 1 & 0 & -1 & 0 & 0 & -1 \end{array} \right] \xrightarrow[E_{3,1}(-1)]{E_{2,1}(-1)} \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & -1 & 1 & -1 \\ 0 & -1 & -2 & -1 & -2 & -2 \end{array} \right] \xrightarrow{E_{3,2}(1)} \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & -1 & 1 & -1 \\ 0 & 0 & 0 & 0 & -1 & -3 \end{array} \right]$$

System is inconsistent

$$Q2) A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 1 \\ 3 & -4 & 10 \end{bmatrix}$$

$$i) \left[\begin{array}{ccccccc} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 1 & 0 & 1 & 0 \\ 3 & -4 & 10 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{E_{3,1}(-3)} \left[\begin{array}{ccccccc} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 1 & 0 & 1 & 0 \\ 0 & -4 & 7 & -2 & -3 & 0 & 1 \end{array} \right]$$

$$E_{3,2}(2) \rightarrow \left[\begin{array}{ccccccc} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 9 & -4 & -1 & 2 & 1 \end{array} \right] \} A^{-1} \text{ does not exist}$$

ii) We can normally find the determinant of a matrix by $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$
Since A^{-1} does not exist, we can say that $\det(A) = 0$

Q3)

① The standard matrix for rotation around y axis by θ degrees:

$$\begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix} = A \quad \left. \vphantom{\begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}} \right\} \text{Put } \theta = \frac{\pi}{6} \Rightarrow A = \begin{bmatrix} \sqrt{3}/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & \sqrt{3}/2 \end{bmatrix}$$

② Find the standard matrix for projection onto $x - 2y = 0$

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \vec{N} = \langle 1, -2, 0 \rangle$$

$$a) e_1 - \text{proj}_{\vec{N}} e_1 = \langle 1, 0, 0 \rangle - \left(\frac{\langle 1, 0, 0 \rangle \cdot \langle 1, -2, 0 \rangle}{5} \cdot \langle 1, -2, 0 \rangle \right) = \left\langle \frac{4}{5}, \frac{2}{5}, 0 \right\rangle$$

$$b) e_2 - \text{proj}_N e_2 = \langle 0, 1, 0 \rangle - \left(\frac{\langle 0, 1, 0 \rangle \cdot \langle 1, -2, 0 \rangle}{5} \cdot \langle 1, -2, 0 \rangle \right) = \left\langle \frac{2}{5}, \frac{1}{5}, 0 \right\rangle$$

$$c) e_3 - \text{proj}_N e_3 = \langle 0, 0, 1 \rangle - \left(\frac{\langle 0, 0, 1 \rangle \cdot \langle 1, -2, 0 \rangle}{5} \cdot \langle 1, -2, 0 \rangle \right) = \langle 0, 0, 1 \rangle$$

To find the standard matrix, write the results from a, b, c together (vertically)

$$\text{St. Mat.} = A = \begin{bmatrix} 4/5 & 2/5 & 0 \\ 2/5 & 1/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

! To find the standard matrix for the whole operation, multiply

$$A_2 \cdot A_1$$

$$A_2 \cdot A_1 = \begin{bmatrix} 4/5 & 2/5 & 0 \\ 2/5 & 1/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \sqrt{3}/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & \sqrt{3}/2 \end{bmatrix} = \begin{bmatrix} 2\sqrt{3}/5 & 2/5 & 2/5 \\ \sqrt{3}/5 & 1/5 & 1/5 \\ -1/2 & 0 & \sqrt{3}/2 \end{bmatrix}$$

ii) let's assume we have the vector $u = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$$A \cdot \vec{u} = \begin{bmatrix} 2\sqrt{3}/5 \\ \sqrt{3}/5 \\ -1/2 \end{bmatrix} = \vec{u}' \Rightarrow |\vec{u}'| \neq |\vec{u}| = 1 \quad \left. \vphantom{\begin{matrix} A \cdot \vec{u} \\ \vec{u}' \end{matrix}} \right\} \begin{array}{l} \text{Norm of the} \\ \text{unit vector is} \\ \text{not preserved} \end{array}$$

Q4)

$$\begin{vmatrix} 1 & -1 & 4 & 2 \\ 0 & 2 & 1 & 1 \\ 0 & -2 & 2 & 0 \\ 0 & -3 & 0 & 0 \end{vmatrix} = 1 \cdot \begin{vmatrix} 2 & 1 & 1 \\ -2 & 2 & 0 \\ -3 & 0 & 0 \end{vmatrix} = (-1)^4 \cdot 1 \cdot \begin{vmatrix} -2 & 2 \\ -3 & 0 \end{vmatrix} = 6$$

$$\det(A^5) = [\det(A)]^5 = 6^5 = 7776$$

Q5) line 1 $\Rightarrow x = 1+t, y = 0+2t, z = -1+0t$ } Position vector $v_1 = \langle 1, 2, 0 \rangle$

line 2 $\Rightarrow x = 1-t, y = 0, z = -1+2t$ } Position vector $v_2 = \langle -1, 0, 2 \rangle$

Let the plane formed by these lines be : $ax+by+cz+d=0$

$\vec{N} = \langle a, b, c \rangle \Rightarrow$ Find the normal vector by $v_1 \times v_2$

$$v_1 \times v_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 0 \\ -1 & 0 & 2 \end{vmatrix} = \langle 4, -2, 2 \rangle = \vec{N}, 4x-2y+2z+d=0$$

A point on the line 1, $P_0 = (1, 0, -1)$ is on the plane

$4-2+d=0 \Rightarrow d=-2$ } The plane eq is : $4x-2y+2z-2=0$