Zacharias Aram

Zacharias.Aram@ruhr-uni-bochum.de • +49 176 55780914 • Linkedin • Website

SKILLS AND INTERESTS

Programming: Python, SQL, PowerShell, C/C++, Html, SPS, Robot Programming (Universal Robots)

Software: Jupyter Notebook, PyCharm, Microsoft 365, SSMS, Inventor, SolidWorks, Plant Simulation, Matlab

Languages: Fluent in German, Aramaic, and English

Personal Interests: Weightlifting, Traveling, and spending Time with Family and Friends

PROFESSIONAL EXPERIENCE

LIS - Logistische Informationssysteme

IT – Project Consultant

- Utilizing Python, SQL, and Microsoft Office to optimize workflows and resolve technical challenges
- Serve as a liaison between IT development and clients to successfully implement IT solutions and manage projects efficiently
- Advise on the implementation and use of IT systems with a focus on process improvement, automation, and technological efficiency
- Conduct requirements analyses and implement customized IT solutions to optimize logistical processes and introduce Warehouse Management Systems

Comma Soft AG Bonn, Germany February 2024 – August 2024

Working Student: IT Consultant

- Programming and fine-tuning of Microsoft DSC to provide customized configuration management solutions and optimize IT infrastructure
- Utilizing Microsoft 365 and Azure for the development and implementation of Digital Workplace solutions
- Contributing to the conception and realization of innovative cloud solutions
- Applying a wide range of tools and technologies in the area of cloud infrastructure and IT security to deliver comprehensive customer solutions

Ruhr-Universität Bochum | Lehrstuhl für Produktionssysteme

Student Assistant

- Supported and advised on the digital transformation of international companies
- Created self-learning modules on Industry 4.0, maturity models, value creation processes, and digital business models
- Presented the self-learning modules in an international project consortium
- Conducted workshops

Cademy GmbH

Bachelor's Internship: Project Management

Independently developed a mobile collaborative robot system for the automotive industry

Cademy GmbH Ennepetal, Germany Technical Intern

- Trained in the following areas: Controllino PLC (industrialized Arduino), AGVs, collaborative robots, design, and additive manufacturing
- Assisted in research for agent-free manufacturing for the Fraunhofer Institute
- Assisted in quality control preparations and procedures
- Programmed Siemens LOGO control units

Greven, Germany September 2024 – Present

> Bochum, Germany July 2022 - April 2023

> > Ennepetal, Germany

March 2021 - July 2021

August 2021 – March 2022

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EDUCATION

Ruhr-Universität Bochum

Bochum, Germany April 2022 – August 2024

Master of Science

• Major, GPA: Mechanical Engineering, 3.7

• Master's Thesis: Artificial Intelligence and Computer Vision for Automated Recognition of Assembly Steps in the Context of Assistance Systems

Selangor, Malaysia

Universiti Putra Malaysia

March 2023 – July 2023

Ruhr-Universität Bochum

Bochum, Germany

Bachelor of Science

Semester Abroad

• Major, GPA: Mechanical Engineering, 2.2

• **Bachelor's Thesis:** Development of a Mobile Collaborative Robot System for Foaming Processes in the Automotive Industry

September 2017 – March 2022

Istanbul Teknik Üniversitesi

Istanbul, Turkey October 2020 – March 2021

Semester Abroad

Städtisches Gymnasium Ahlen

Ahlen, Germany August 2011 – July 2017

A-level

PROJECTS

Ruhr-Universität Bochum | Lehrstuhl für Produktionssysteme

Master's Thesis

Bochum, Germany October 2022 – August 2024

- Development and implementation of an innovative AI-based system for detecting assembly steps in manual assembly using advanced computer vision techniques
- Analysis and modeling of human movements and activities using AI algorithms to improve human-machine interaction
- Contribution to the optimization and efficiency enhancement of worker assistance systems through the use of artificial intelligence and machine learning

Cademy GmbH

Ennepetal, Germany August 2021 – March 2022

Bachelor's Thesis

- Independent development and conception of a mobile, collaborative robot system to increase efficiency in the foaming process of the automotive industry
- Development of an autonomous system for precise detection of tool positions and their openings to increase production flexibility and reduce manual interventions
- Successful construction and testing of a functional prototype that can be used in real industrial environments

VOLUNTEERING

Volkshochschule Ahlen

Ahlen, Germany

Volunteer

October 2022 - March 2023

• Trainer for students

Ingenieure ohne Grenzen e.V.

Candidate

Bochum, Germany November 2019 – February 2020

• Developed a brick press for disadvantaged groups in Africa