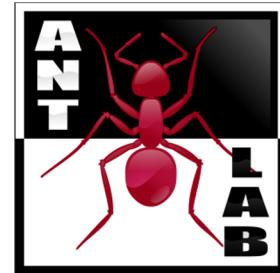




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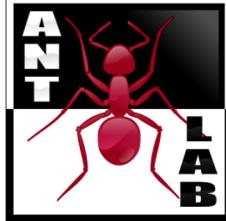
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TinyOS SIMulator

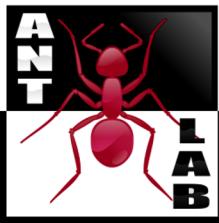
Simulate a Wireless Sensor Network
with TOSSIM





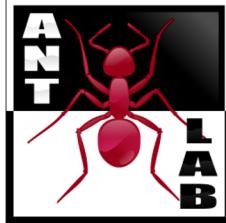
Motivations

- WSN require large scale deployment
- Located in inaccessible places
- Apps are deployed only once during network lifetime
- Little room to re-deploy on errors



System evaluation

- Check correctness of application behavior
- Sensors are hard to debug!
 - "... prepare to a painful experience"
[Tinyos authors' own words]



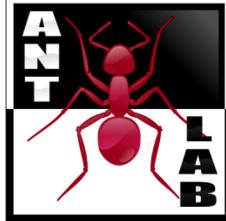
Simulation Pros and Cons

□ Advantages

- Study system in controlled environment
- Observe interactions difficult to capture live
- Helps in design improvement
- Cost effective alternative

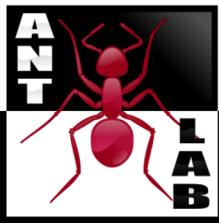
□ Disadvantages

- May not represent accurate real-world results
- Depends on modeling assumptions



General concepts

- TOSSIM is a discrete event simulator
- It uses the same code that you use to program the sensors
- There are two programming interfaces supported: Python and C++



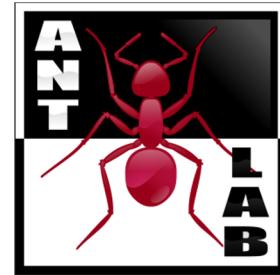
Key requirements

- Scalability
 - Large deployments (10^3 motes)
- Completeness
 - Cover as many interactions as possible
 - Simulate complete applications
- Fidelity
 - Capture real-world interactions
 - Reveal unexpected behavior
- Bridging
 - Between algorithm and implementation



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Exercise

Temperature and humidity sensor

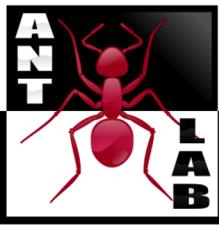


Fake temp/hum sensor

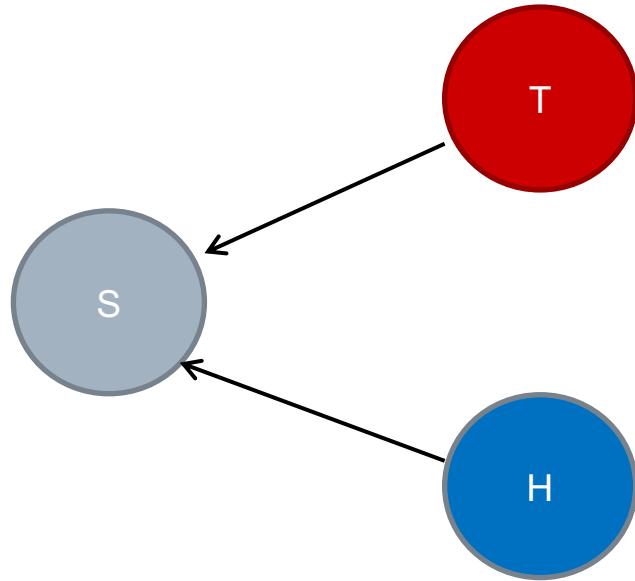
- Starting from the example in:
IOT-examples/TinyOS/Supporting\ Files/TempHumSensor

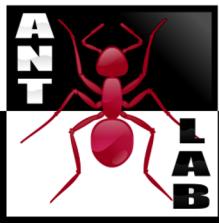
Simulate with TOSSIM a TinyOS application that:

- generate 3 motes (0, 1, 2)
- mote #0 is the sink
- mote #1 is the temperature sensor
- mote #2 is the humidity sensor



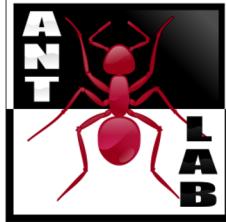
Topology





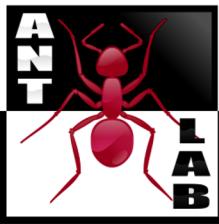
Fake temp/hum sensor

- Mote #0 only receive messages from #1 and #2
- Mote #1 sends periodic (every 1 second) messages to the sink (#0)
- Mote #2 sends periodic (every 2 seconds) messages to the sink (#0)



Messages

- Messages are composed like this:
 - type: 0 or 1 (0 for temp and 1 for hum)
 - data: the value from the fake sensor



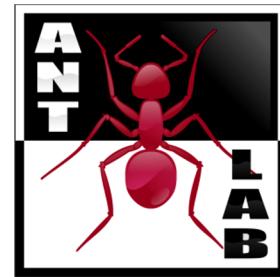
Fake temp/hum sensor

- Let's do it together!



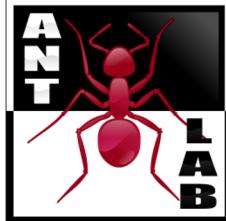
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Home Challenge #2

Simulate a Wireless Sensor Network
with TOSSIM

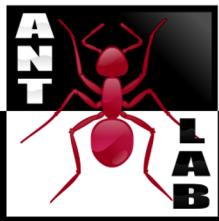


Home project #2

- Develop a TinyOS application
- Simulate the application with TOSSIM

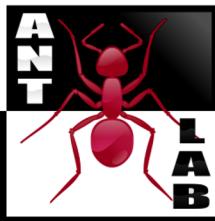
- Team: max 3 people
- Score: max 1 point

- Submit through beep
«Homework/Activity 2» folder
- Don't cheat ☺



What to deliver

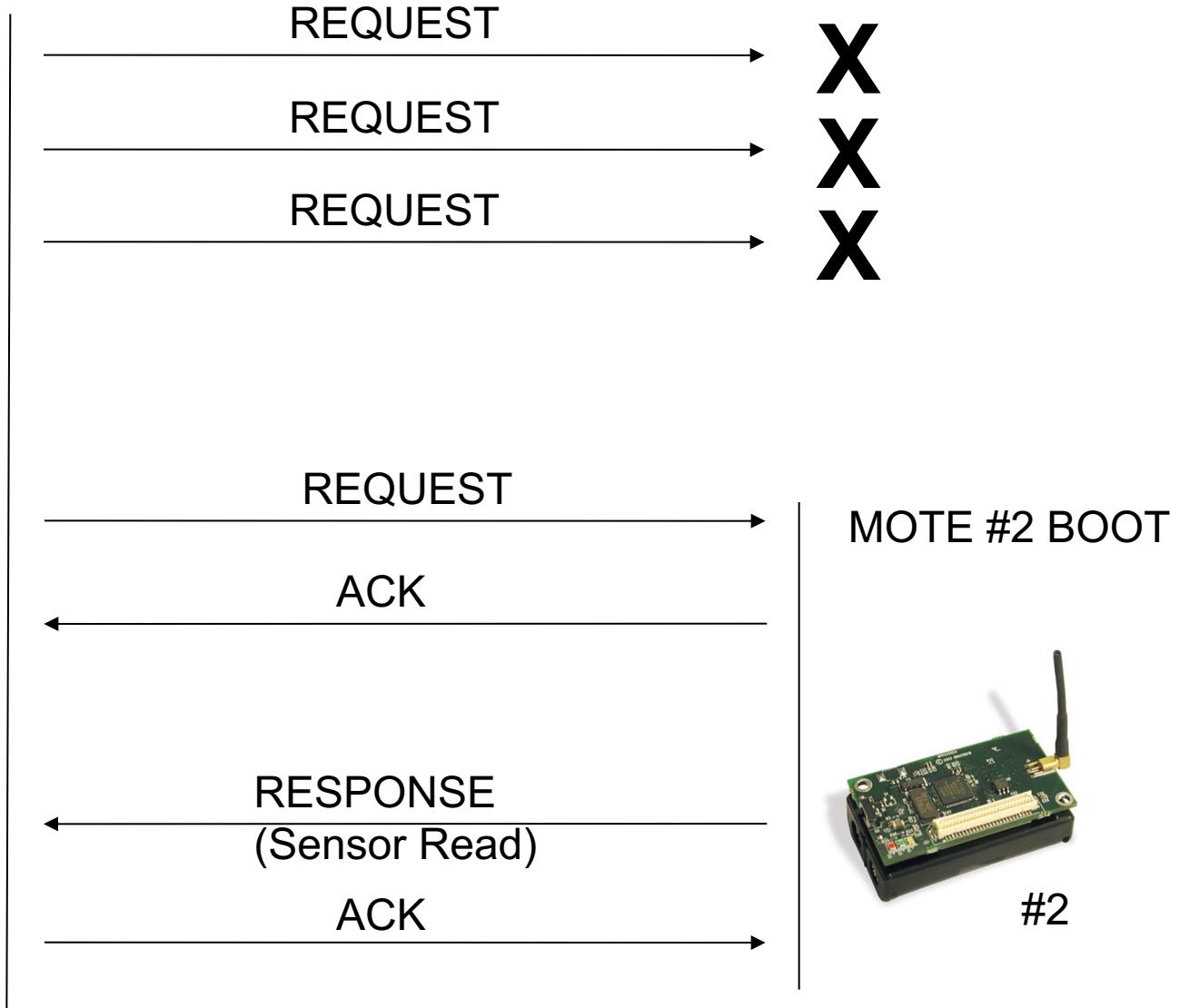
- A zip folder per group named with:
 - A folder containing all the source code (TinyOS files, python file)
 - The log of your simulation
 - A short report
- Deadline: March 29 – 23:49

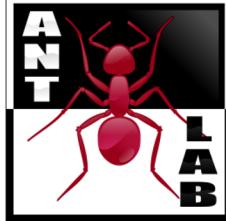


Send/ACK example



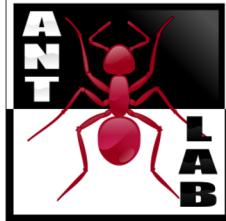
#1





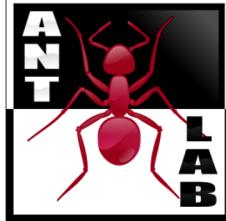
What to do

- Simulate 2 motes talking between each other
- Mote #1 sends periodic request (REQ) messages to mote #2 containing:
 - Message type: REQ
 - An incremental counter
- The periodic request is every 1000ms



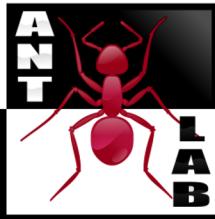
What to do

- Only on receipt of a request, mote #2 sends back a reply (RESP) message with:
 - Message type: REQ
 - The counter sent by mote #1
 - A value read from the fake sensor
- Fake sensor is just a module which return a random number, you don't need to modify it



What to do

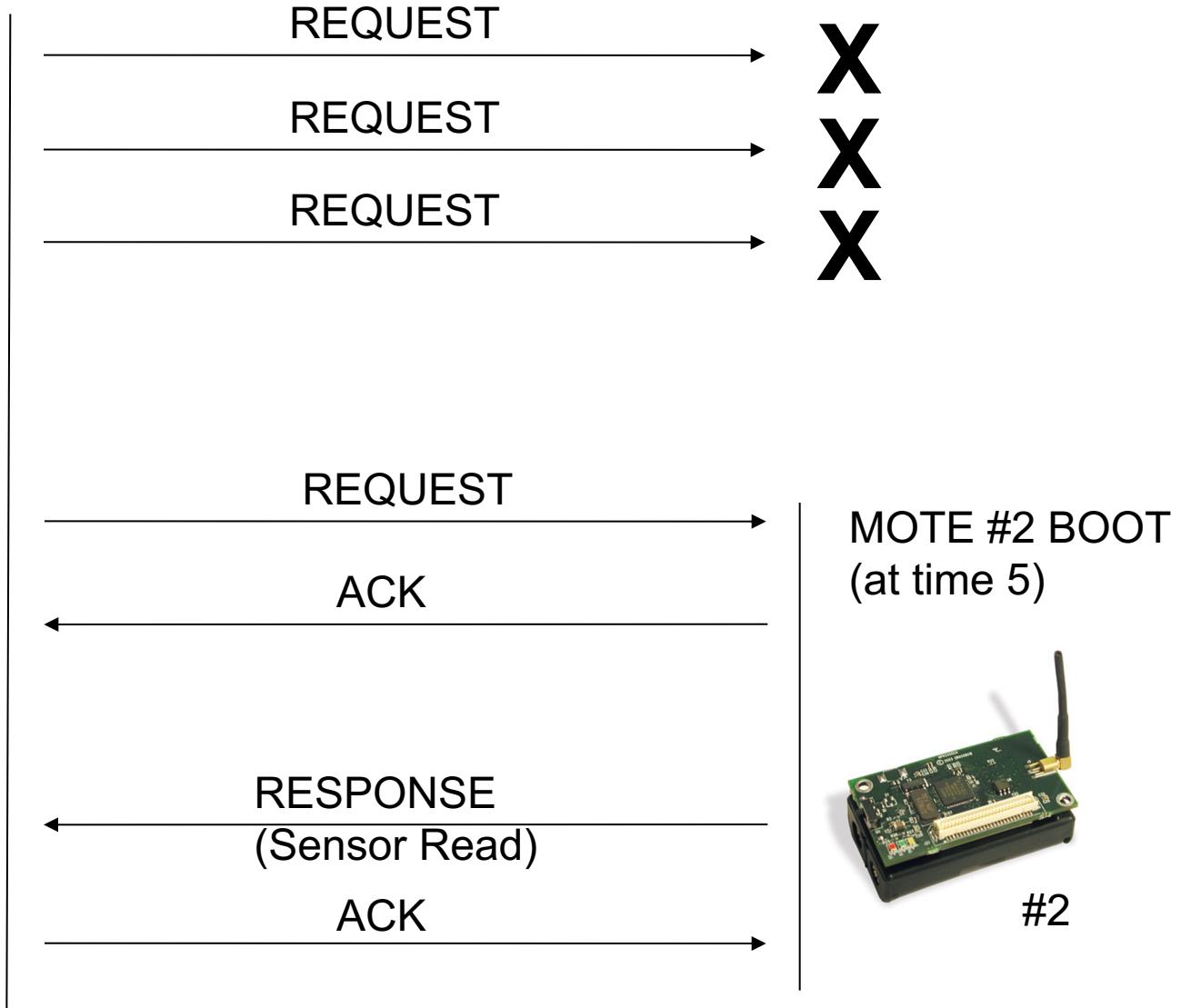
- Each message, REQ and RESP, must be acknowledged using the TinyOS built in ACK module
- Upon receipt of the ACK of the a REQ message:
 - Mote #1 stops to send requests
 - Mote #2 receive the RESP
 - The exercise is done
- Use the module PacketAcknowledgements to send the ACK, **don't** reimplement it!

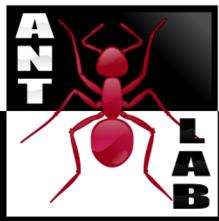


Send/ACK example



#1





PacketAcknowledgements

- Read the documentation
- Available at /home/user/Desktop/tinyos-main/doc/nesdoc/telosb/index.html

Commands

command error_t noAck(message_t *msg)

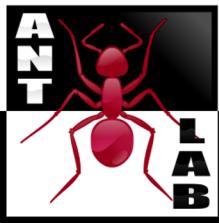
Tell a protocol that when it sends this packet, it should not use synchronous acknowledgments.

command error_t requestAck(message_t *msg)

Tell a protocol that when it sends this packet, it should use synchronous acknowledgments.

command bool wasAcked(message_t *msg)

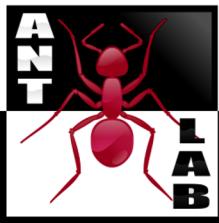
Tell a caller whether or not a transmitted packet was acknowledged.



Template

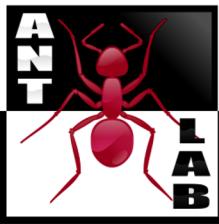
- In the folder SendACK_template there's a draft of the code to fill in
- Try to use as much as possible that draft
- Files to modify:
 - SendAck.h
 - SendAckAppC.nc
 - SendAckC.nc

```
***** AMSend interface *****  
event void AMSend.sendDone(message_t* buf,error_t err) {  
    /* This event is triggered when a message is sent... */  
    /*  
     * STEPS:  
     * 1. Check if the packet is sent  
     * 2. Check if ack is received (Read the docs!)|  
     * 2a. If yes stop the timer, the program is done  
     * 2b. Otherwise: send again a request  
     * Always: use debug statements  
    */  
}
```



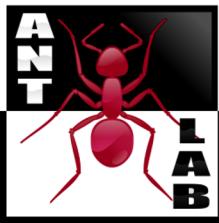
Simulation

- Simulation is done in TOSSIM
 - Mote #1 at time 0
 - Mote #2 after 5 seconds



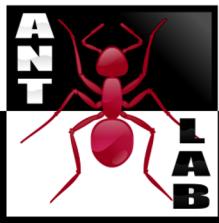
Message structure

- Only one message type containing:
 - msg_type: REQ/RESP
 - msg_counter: incremental integer
 - value: value from the fake sensor



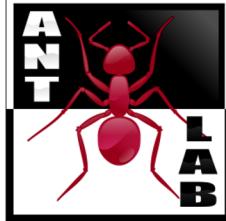
Hints

- 1) Create the message structure
- 2) Choose which modules you'll use
- 3) Write the modules in the ...AppC.n and in the ...C.nc files
- 4) Wire the modules in the ...AppC.nc file
- 5) Implement the logic in the ...C.nc file



Hints

- Run the code often to check syntax or compiler errors, not only at the end!
- Use a lot of debug statements (DBG/DBG_CLEAR)
- Read the docs
- Use the examples seen before as scheme
- Think!



Commands

- Compile the mote's code
 - `make micaz sim`
- Run the simulation
 - `python RunSimulationScript.py`
- Before run a simulation, recompile the mote's code if you have modified it