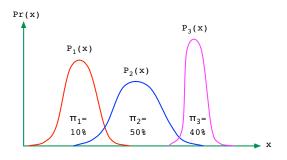
## Classification with generative models II

**ECE407** 

Based on Sanjoy Dasgupta's notes. https://cseweb.ucsd.edu/~dasgupta/

## Recall: generative model framework

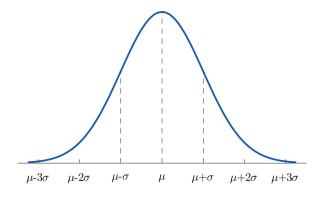


Labels 
$$\mathcal{Y} = \{1, 2, ..., k\}$$
, density  $\Pr(x) = \pi_1 P_1(x) + \cdots + \pi_k P_k(x)$ .  
where  $P_1(x) = \Pr(x|Y=1),...,P_k(x) = \Pr(x|Y=k)$ 

Approximate each  $P_j$  with a simple, parametric distribution:

- Product distributions.
   Assume coordinates are independent: naive Bayes.
- Multivariate Gaussians.
   Linear and quadratic discriminant analysis.
- · More general graphical models.

### The univariate Gaussian



The Gaussian  $\mathit{N}(\mu, \sigma^2)$  has mean  $\mu$ , variance  $\sigma^2$ , and density function

$$f_x(x) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right).$$

### The multivariate Gaussian

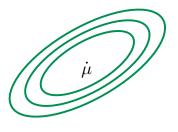


 $N(\mu, \Sigma)$ : Gaussian in  $\mathbb{R}^p$ 

- mean:  $\mu \in \mathbb{R}^p$
- covariance:  $p \times p$  matrix  $\Sigma$

$$f_{x}(x) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{p/2}} \exp\left(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)\right)$$

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Let  $X = (X_1, X_2, \dots, X_p)$  be a random draw from  $N(\mu, \Sigma)$ .

- $\mathbb{E}X = \mu$ . That is,  $\mathbb{E}X_i = \mu_i$  for all  $1 \le i \le p$ .
- $\mathbb{E}(X \mu)(X \mu)^T = \Sigma$ . That is, for all  $1 \le i, j \le p$ ,

$$\mathsf{cov}(X_i, X_j) = \mathbb{E}(X_i - \mu_i)(X_j - \mu_j) = \Sigma_{ij}$$

In particular,  $var(X_i) = \mathbb{E}(X_i - \mu_i)^2 = \Sigma_{ii}$ .

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Simplified density:

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Note that: 1- The value of the pdf at  $x_o$   $f_x(x_o)$  is not a probability.

2-  $I_p$  is the p-dimensional identity matrix.

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Each  $X_i$  is an independent univariate Gaussian  $N(\mu_i, \sigma^2)$ .

## Special case: diagonal Gaussian

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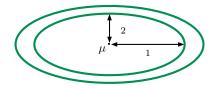
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Contours of equal density are axis-aligned ellipsoids centered at  $\mu$ :



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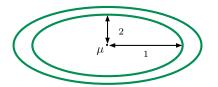
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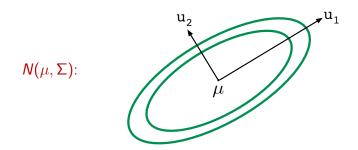
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mean is a vector!

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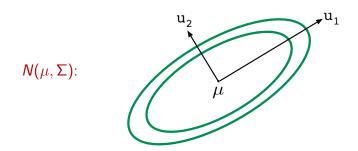
## The general Gaussian



### Eigendecomposition of $\Sigma$ :

- Eigenvalues  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_p$
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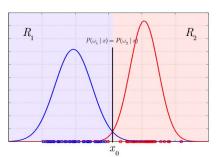


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 $N(\mu, \Sigma)$  is simply a rotated version of  $N(\mu, \text{diag}(\lambda_1, \dots, \lambda_p))$ .

Example: Two classes:  $\omega_1$  and  $\omega_2$  with  $N(\mu_i, \sigma_i)$ , respectively



- Red and blue dots are the training data. Estimate the mean and variance of distributions of each class.
- Decision threshold is  $x_0$  (assuming that class prob are equal  $\pi_1$

Estimate class probabilities  $\pi_1, \pi_2$  and fit a Gaussian to each class:

$$P_1 = N(\mu_1, \Sigma_1), P_2 = N(\mu_2, \Sigma_2)$$

E.g. If data points  $x^{(1)}, \ldots, x^{(m)} \in \mathbb{R}^p$  are class 1:

$$\mu_1 = \frac{1}{m} \left( x^{(1)} + \dots + x^{(m)} \right) \text{ and } \Sigma_1 = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu_1) (x^{(i)} - \mu_1)^T$$

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 $\pi_{1},\,\pi_{2},\,\mu_{2}$  and  $\Sigma_{2}$  are estimated from the training data in a similar manner .

Given a new point x, predict class 1 iff:

$$\pi_1 P_1(x) > \pi_2 P_2(x) \Leftrightarrow x^T M x + 2 w^T x \ge \theta,$$

where:

$$M = \frac{1}{2} (\Sigma_2^{-1} - \Sigma_1^{-1})$$

$$w = \Sigma_1^{-1} \mu_1 - \Sigma_2^{-1} \mu_2$$

and  $\theta$  is a constant depending on the various parameters.

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or divide by (m-1) instead of m Given a new point x, predict class 1 iff:

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$$\Sigma_1 = \Sigma_2$$
: linear decision boundary. Otherwise, quadratic boundary.

### Common covariance: $\Sigma_1 = \Sigma_2 = \Sigma$

Linear decision boundary: choose class 1 iff

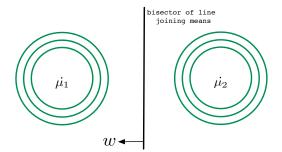
$$x \cdot \underbrace{\Sigma^{-1}(\mu_1 - \mu_2)}_{w} \geq \theta.$$

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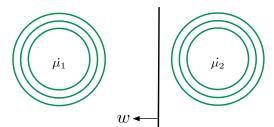
$$\times \underbrace{\Sigma^{-1}(\mu_1 - \mu_2)}_{w} \geq \theta.$$

Example 1: Spherical Gaussians with  $\Sigma = I_p$  and  $\pi_1 = \pi_2$ .

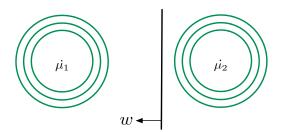


Example 2: Again spherical, but now  $\pi_1 > \pi_2$ .

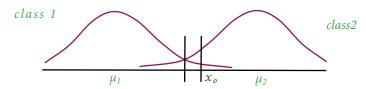
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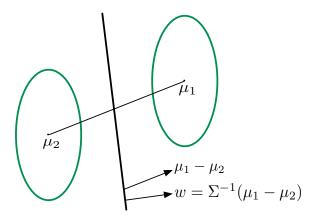


#### 1-D example:

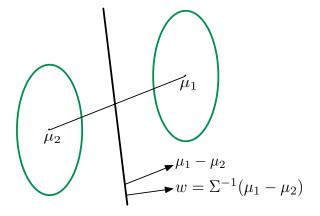


Decision boundary is  $x_0$  is closer to the mean of class 2 because  $\pi_1 > \pi_2$ 

#### Example 3: Non-spherical.



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#### Rule: $w \cdot x \ge \theta$

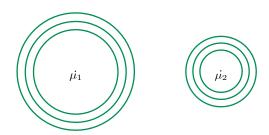
- $w, \theta$  dictated by probability model, assuming it is a perfect fit
- Common practice: choose w as above, but fit  $\theta$  to minimize training/validation error

# **Different covariances:** $\Sigma_1 \neq \Sigma_2$

Quadratic boundary: choose class 1 iff  $x^T M x + 2w^T x \ge \theta$ , where:

$$M = \frac{1}{2} (\Sigma_2^{-1} - \Sigma_1^{-1})$$
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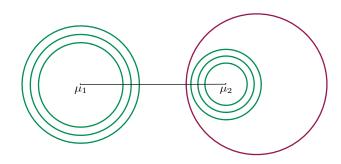


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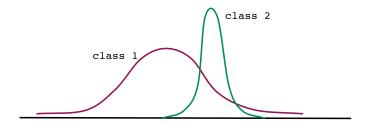
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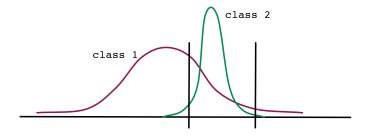
Example 1:  $\Sigma_1 = \sigma_1^2 I_p$  and  $\Sigma_2 = \sigma_2^2 I_p$  with  $\sigma_1 > \sigma_2$ 



### Example 2: Same thing in 1-d. $\mathcal{X} = \mathbb{R}$ .

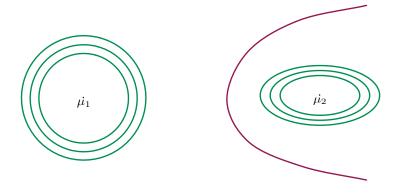


Example 2: 1-D example.  $\mathcal{X} = \mathbb{R}$ .

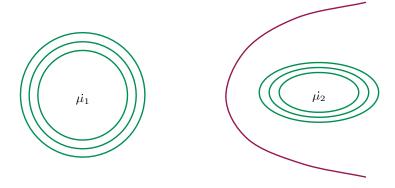


You may have two decision thresholds

### Example 3: A parabolic boundary.



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Many other possibilities!

### Multiclass discriminant analysis

k classes: weights  $\pi_j$ , class-conditional distributions  $P_j = N(\mu_j, \Sigma_j)$ .

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To class a point x, pick arg  $\max_j f_j(x)$ .

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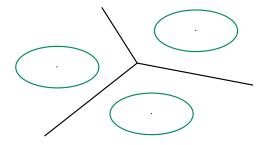
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To class a point x, solve  $\operatorname{argmax}_{j} f_{j}(x)$ .

Example: If  $\Sigma_1 = \cdots = \Sigma_k$ , the boundaries are **linear**.



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Use only first- and second-order statistics of the classes.

| Class 1         | Class 2                     |
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| mean $\mu_1$    | mean $\mu_2$                |
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- 1. Projected means are well-separated, i.e.  $(w \cdot \mu_1 w \cdot \mu_2)^2$  is large.
- 2. Projected within-class variance is small.



better than



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- Projected variances:  $w^T \Sigma_1 w$  and  $w^T \Sigma_2 w$
- Average projected variance:

$$\frac{n_1(w^T\Sigma_1w)+n_2(w^T\Sigma_2w)}{n_1+n_2}=w^T\Sigma w,$$

where 
$$\Sigma = (n_1\Sigma_1 + n_2\Sigma_2)/(n_1 + n_2)$$
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Solution:  $w \propto \Sigma^{-1}(\mu_1 - \mu_2)$ . Look familiar?