Practices in Visual Computing II
Spring 2023

Lab #1: PyTorch Review

# Deep Learning Frameworks / PyTorch

- ▶ What is a deep learning framework?
  - abstract certain things away to faster develop and test new ideas.
  - automatically compute gradients!
  - run it on efficiently on a GPU
  - ► Frameworks: PyTorch, TensorFlow, MXNet, CNTK, ...
- ► Why PyTorch?
  - very similar to Numpy, hence, beginner friendly.
  - ► great for fast and flexible development.

#### **Tensor**

► Construct a Tensor

### **Operations**

► Multiple syntaxes, e.g. Addition

```
y = torch.rand(8, 3)
print(x + y)

print(torch.add(x, y))

# providing an output tensor as argument
result = torch.empty(8, 3)
torch.add(x, y, out=result)
print(result)

# adds x to y
y.add_(x)
print(y)
```

► Other operations including transposing, indexing, slicing, linear algebra etc. at https://pytorch.org/docs/stable/torch.html

# **Bridge to Numpy**

► PyTorch → Numpy

```
a = torch.ones(5)
b = a.numpy()
```

► Numpy → PyTorch

```
a = np.ones(5)
b = torch.from_numpy(a)
```

► Tensors can only be converted to Numpy when they are on CPU

# **Difference to Numpy**

► GPU acceleration

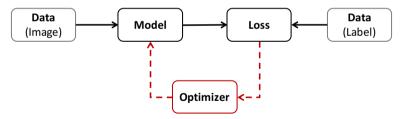
```
if torch.cuda.is_available():
    x = x.cuda()
    y = y.cuda()
    z = x + y
    print(z)
    print(z.cpu()) # ''.to'' can change dtype
```

```
tensor([2.9218], device='cuda:0')
tensor([2.9218], dtype=torch.float64)
```

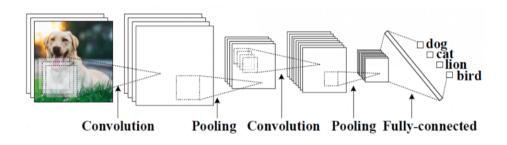
# **Autograd Demo**

Calculate the derivative of  $Q = 3a^3 - b^2$  in a = 2, b = 6

- ► Model → torch.nn.Module
- ▶ Loss  $\rightarrow$  torch.nn.Module.Loss
- ightharpoonup Optimizer ightarrow torch.optim
- ► Data → torch.utils.data



### Model



#### Model

▶ Define a model as a class that inherits from torch.nn.Module

```
class Net(nn.Module):
```

► Define layers in the \_\_init\_\_() method

```
def __init__(self):
    ...
```

▶ Define computation flow given an input x in the forward() method

```
def forward(self, x):
    ...
```

► backward() is automatically defined

#### Model

```
import torch
import torch.nn as nn
import torch.nn.functional as F
class Net(nn.Module):
   def init (self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 6, 5)
        self.conv2 = nn.Conv2d(6, 16, 5)
   def forward(self, x):
        x = F.max_pool2d(F.relu(self.conv1(x)), (2, 2))
        x = F.max_pool2d(F.relu(self.conv2(x)), 2)
        return x
```

### Model

► PyTorch contains a bunch of standard layers which are also subclasses of torch.nn.Module:

•	Convolution layers	nn.Conv2d( $C_{in}$ , $C_{out}$ , $K$ )
•	Pooling layers	${\tt nn.MaxPool2d}(K)$
•	Non-linear activations	nn.ReLU()
•	Normalization layers	${\tt nn.BatchNorm2d}(N)$
•	Linear layers	$\mathtt{nn.Linear}(C_{in}\texttt{,}C_{out})$

► It is also easy to implement custom layers:
https://pytorch.org/docs/stable/notes/extending.html#extending-torch-nn

#### Loss

- ► Loss function returns a non-negative value *J* measuring the distance between network estimation and the ground truth
- ► PyTorch contains a branch of loss functions which are also subclasses of torch.nn.Module:
  - ► L1Loss
  - ► MSELoss
  - ► CrossEntroyLoss
  - ► NLLLoss
  - ► SmoothL1Loss
  - ▶ ..

#### Loss

► Example of using a loss function

```
loss = nn.CrossEntropyLoss()
input = torch.randn(3, 5, requires_grad=True)
target = torch.empty(3, dtype=torch.long).random_(5)
output = loss(input, target)
output.backward()
```

# **Optimizer**

▶ Optimizer decides how to update the parameters in the model, e.g.

$$\theta = \theta - \eta \nabla J(\theta)$$

- ► PyTorch implements a set of optimization algorithms in torch.optim:
  - ► SGD
  - ► SGD + Momentum
  - ► Adam
  - ▶ ...

### **Optimizer**

► 1. Construct an Optimizer

```
optimizer = optim.SGD(model.parameters(), lr = 0.01, momentum=0.9)
```

▶ 2. Take an optimization step for every batch/sample

```
for input, target in dataset:
    # clear saved gradients before computing gradient for the new batch
    optimizer.zero_grad()

output = model(input)
    loss = loss_fn(output, target)

loss.backward()

# update parameters in model
    optimizer.step()
```

#### Data

- ► PyTorch provides Dataset, DataLoader in torch.utils.data that allows batching data, shuffling data and load data with multiple processes.
- ► For small scale of dataset it is fine to implement your own data loader.

# **Saving Models**

► Save/Load state\_dict (Recommended)

```
# save
torch.save(model.state_dict(), PATH)
# load
model = TheModelClass(*args, **kwargs)
model.load_state_dict(torch.load(PATH))
model.eval()
```

► Save/Load entire model

```
# save
torch.save(model, PATH)
# load
# Model class must be defined somewhere
model = torch.load(PATH)
model.eval()
```

### **MNIST Classification**

Upload the lab1.ipynb to Google Colab.

#### Tasks:

- [1] Calculate the normalization constants for MNIST
- [2] Build a Pytorch dataloader
- [3] Implement the MLP class
- [4] Implement the device
- [5] Implement the training loop.
- [6] Implement the optimizer
- [7] Reach a test accuracy of > 95 % on MNIST with an MLP
- [8] Implement the CNN class
- [9] Reach a test accuracy of > 97 % on MNIST with a CNN

# References

► PyTorch official tutorials: https://pytorch.org/tutorials/

► Stanford Course on Deep Learning for Computer Vision: http://cs231n.stanford.edu/slides/2018/cs231n\_2018\_lecture08.pdf

► PyTorch tutorial with code examples: https://github.com/MorvanZhou/PyTorch-Tutorial