

BLOSSOMING
POSSIBILITIES
ONE
HEART
BEAT AT
A TIME

GROUP 3
PHYSICS 173 LAB



v1.1 - Demo



Short Video: To Remember the Fallen Ones

PS: They're not dead, as of now.



Problems in Philippine Agriculture



**Weak Sustenance
and Growth of Local
Agricultural Output**



**Recent Problems in
Crop Supplies and
Mass Importation**



**Few Investments on
Food Security and
Innovation**



Market Analysis

Currently, there are 5 million famers that cultivate 9.7 million hectares or about 30% of the land in the Philippines. By offering our services to them, it will generate us a huge amount of revenue.



What's The Big Idea?

What if there is a prototype for a product that can be used for small-scale purposes that can be used by people in their homes to help with their farming needs, enabling them to be sustainable and eco-friendly?





But How Do We Do It?

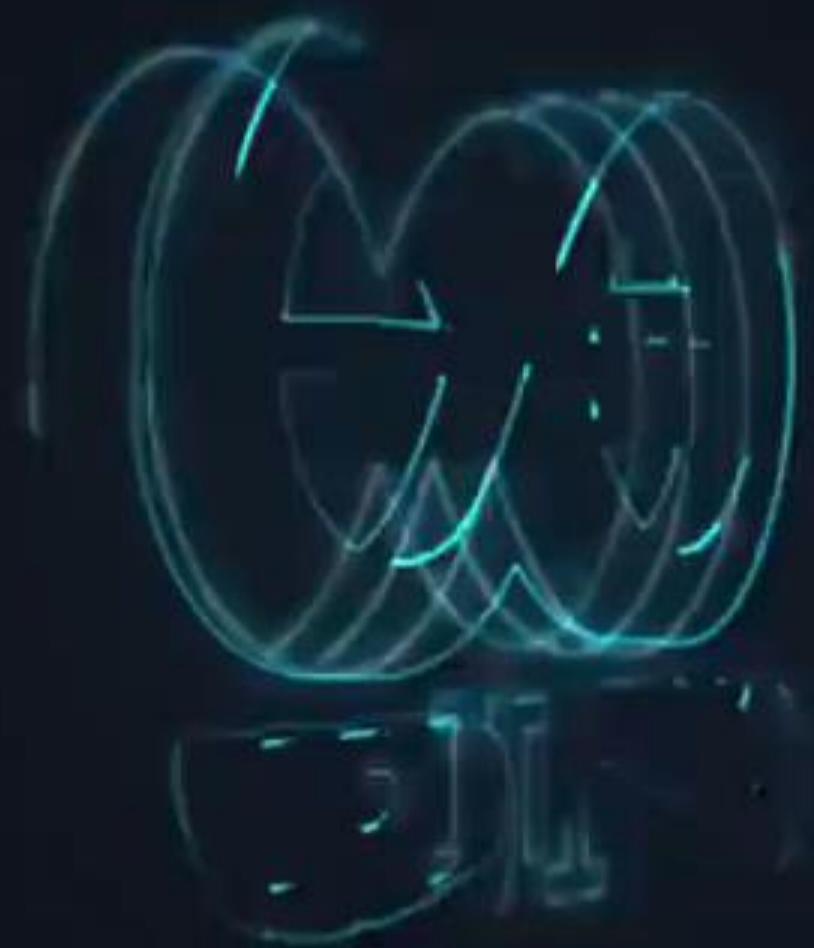
A good way to do this is by prototyping it with electronics, and what better way to do it with tiny computers that we call microprocessors?





Short Video: Arduino Explainer

Got this from YouTube



Ardu... what?

- Arduino means “strong friend” in Italian and is developed in 2005 in Ivrea, Italy by Massimo Banzi and David Cuartielles.
- Arduino boards and open-source hardware and uses an processor that is developed by .
- Coding with the Arduino board is accessible and transferrable with both compiler and interpreter languages.



Functions of Arduino

- **Arduino is great for prototyping ideas as it has easy access to I/O.**
- **Arduino is flexible and open-source, and runs on low power.**
- **Arduino's microprocessor unit can be used to make transducers and sensors that can be controlled.**

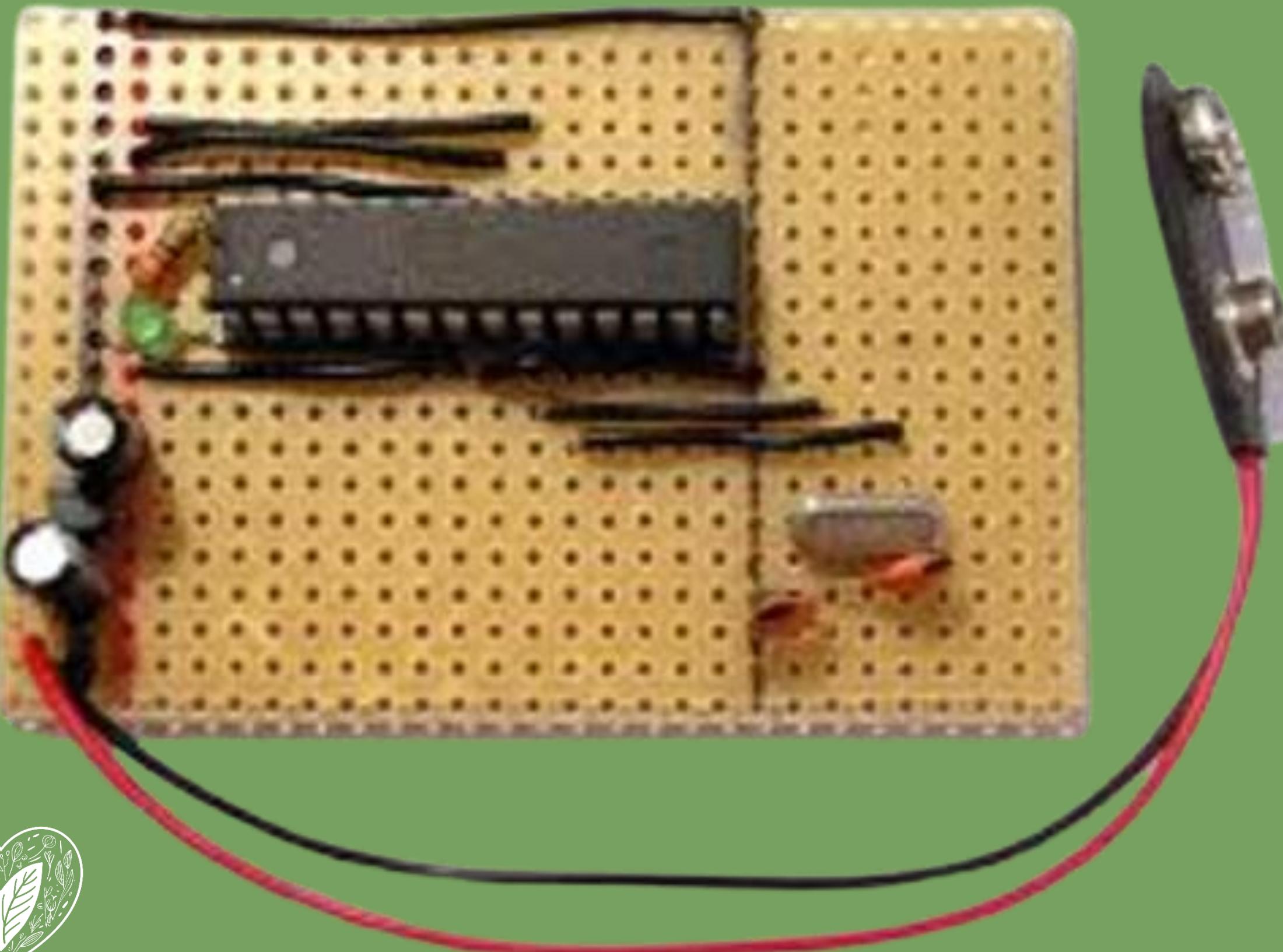


Benefits of Arduino

- **Arduino is the go-to gear for artists, hobbyists, students, and anyone with a gadgetry dream.**
- **Arduino rose out of another formidable challenge: how to teach students to create electronics, fast.**
- **With Arduino, you can control almost everything around you be it simple LED or giant robots.**



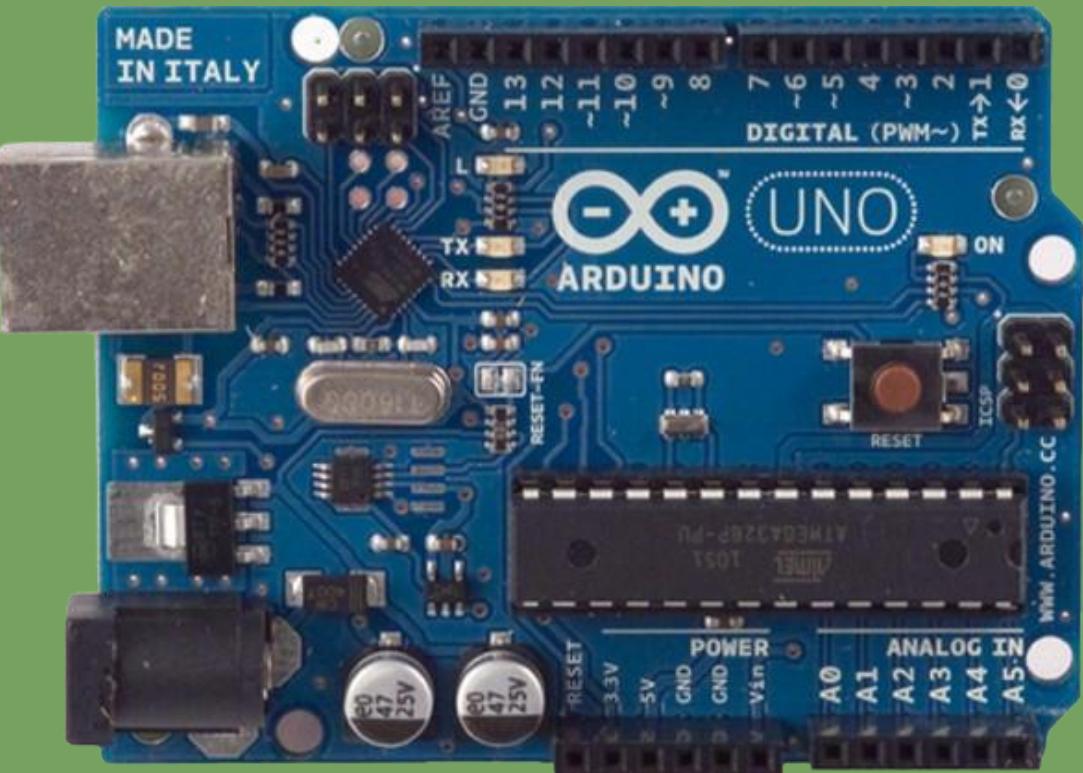
Types of Arduino



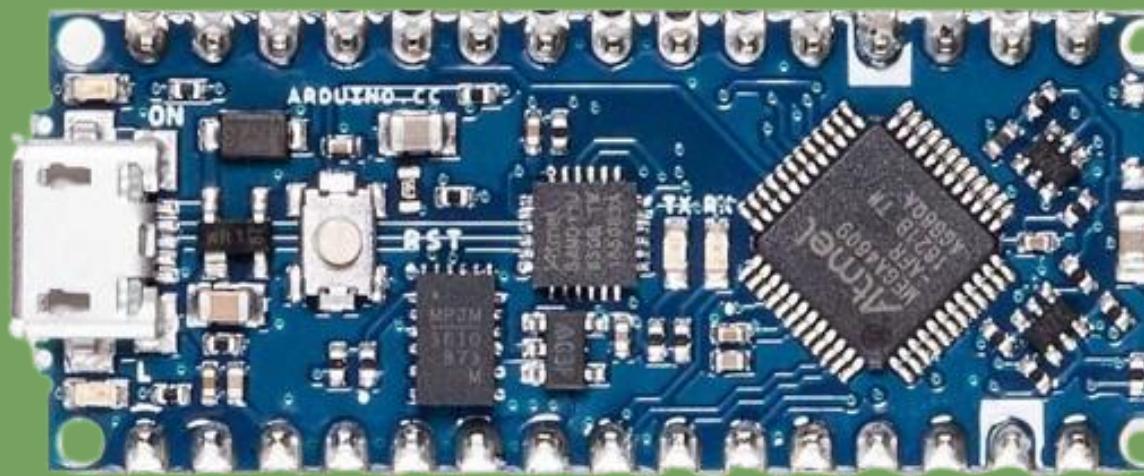
**DIY VERSION
ARDUINO
(ATMEGA328P)**



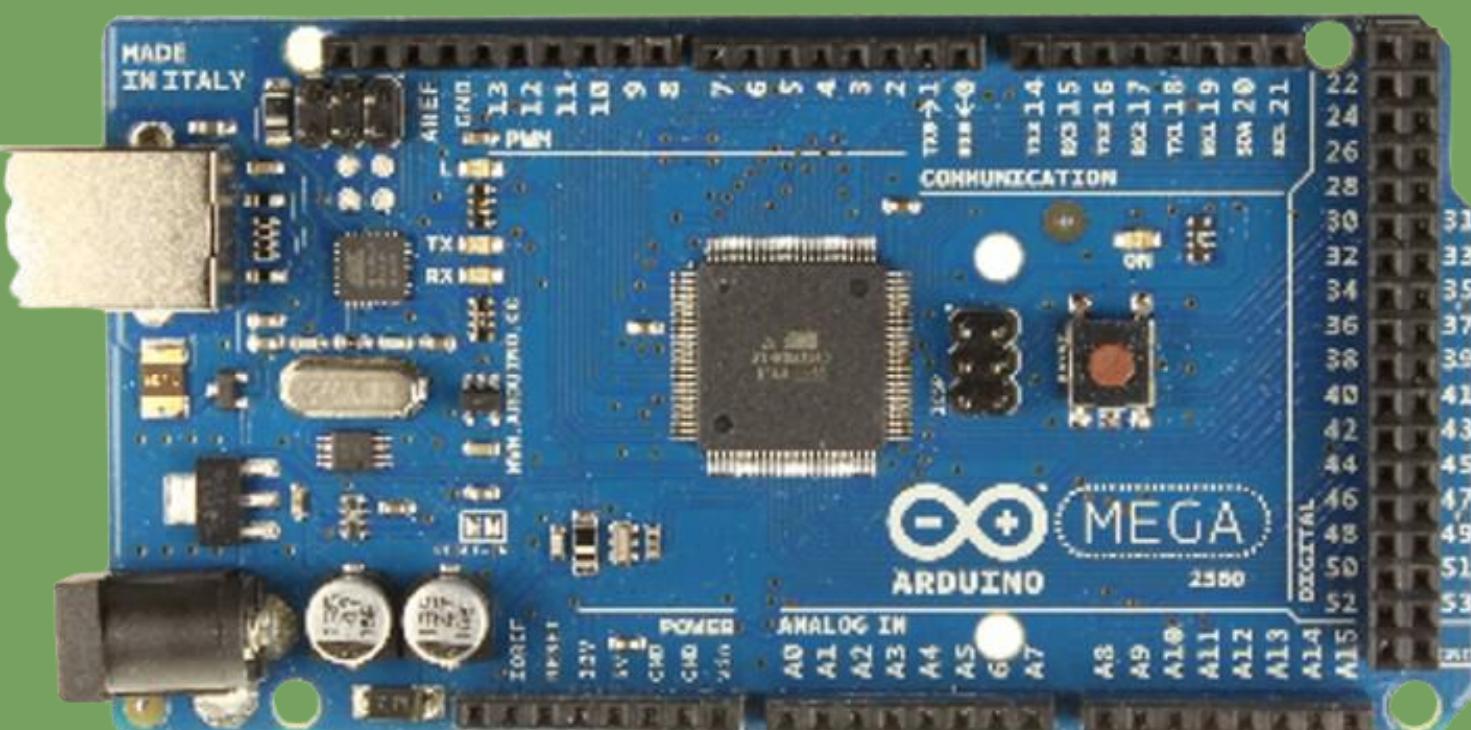
Types of Arduino



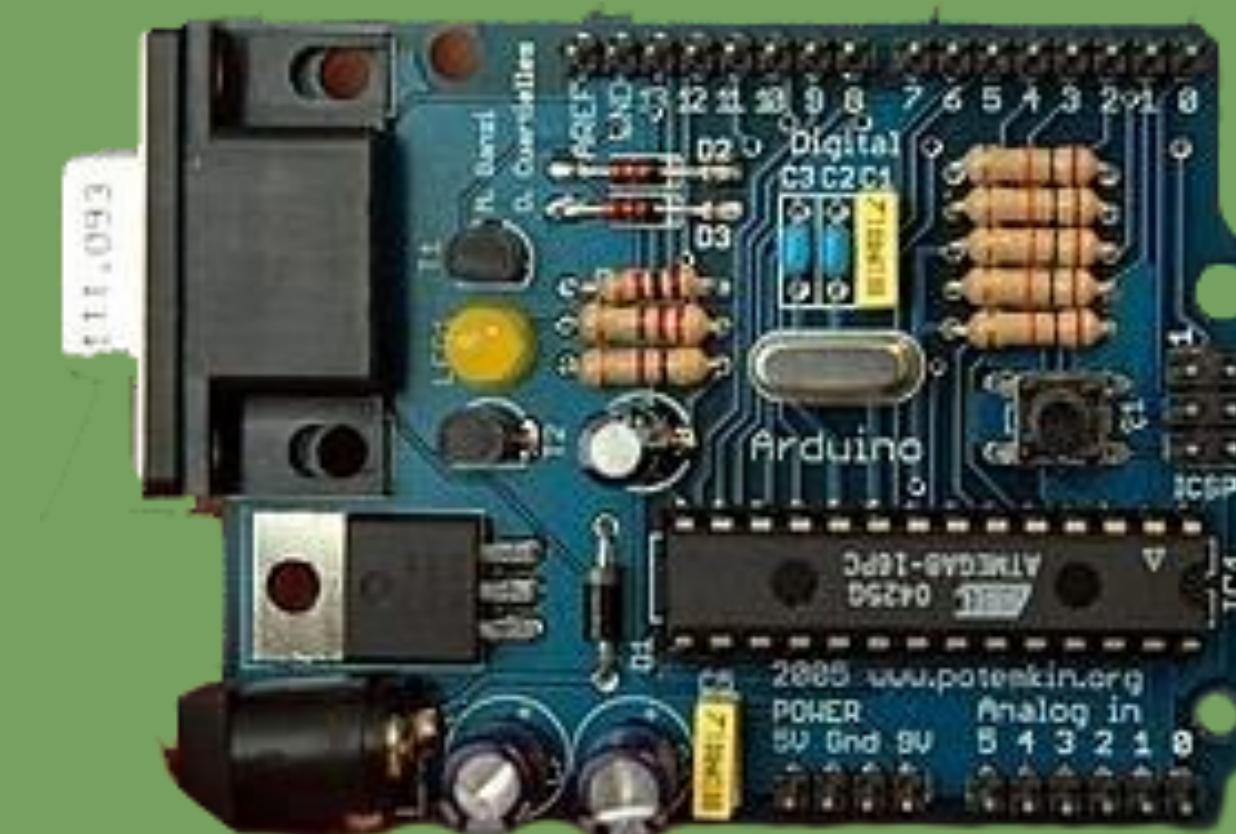
UNO



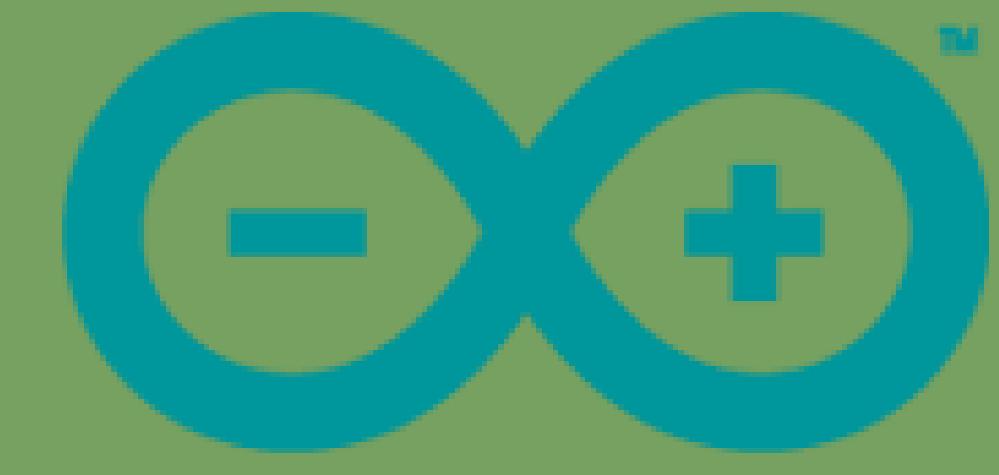
NANO



MEGA



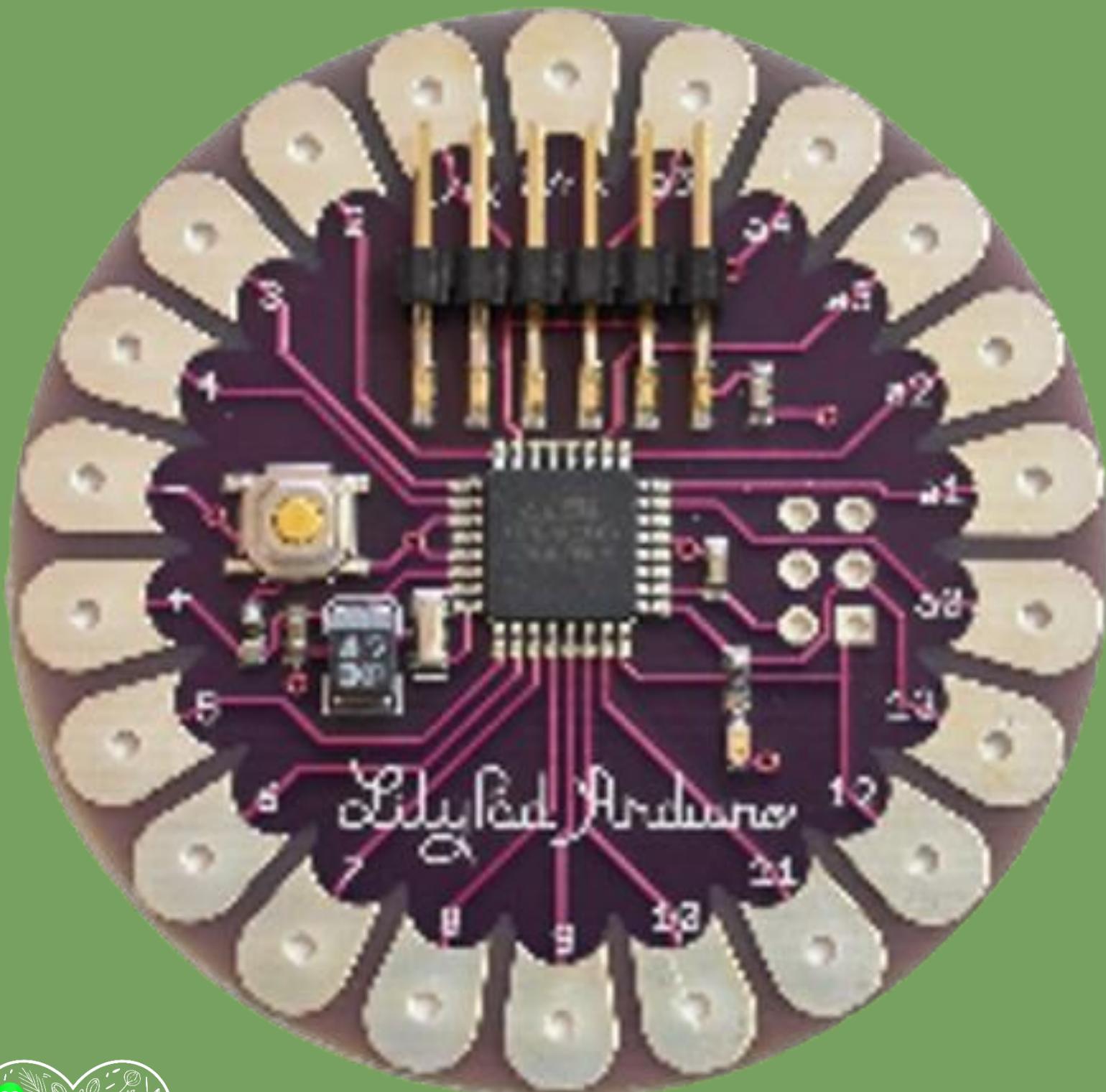
RS-232



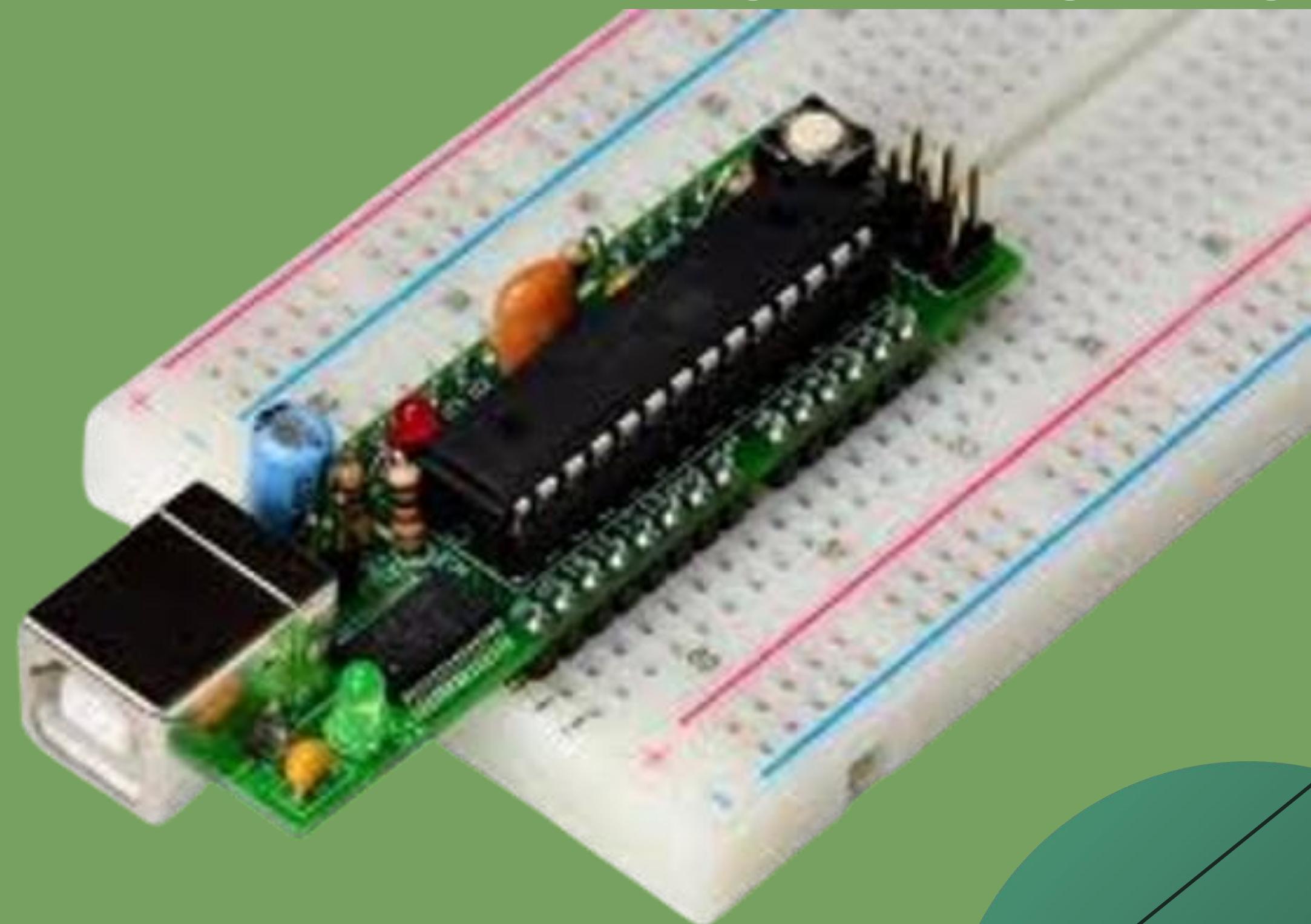
ARDUINO



Types of Arduino BOARDUINO



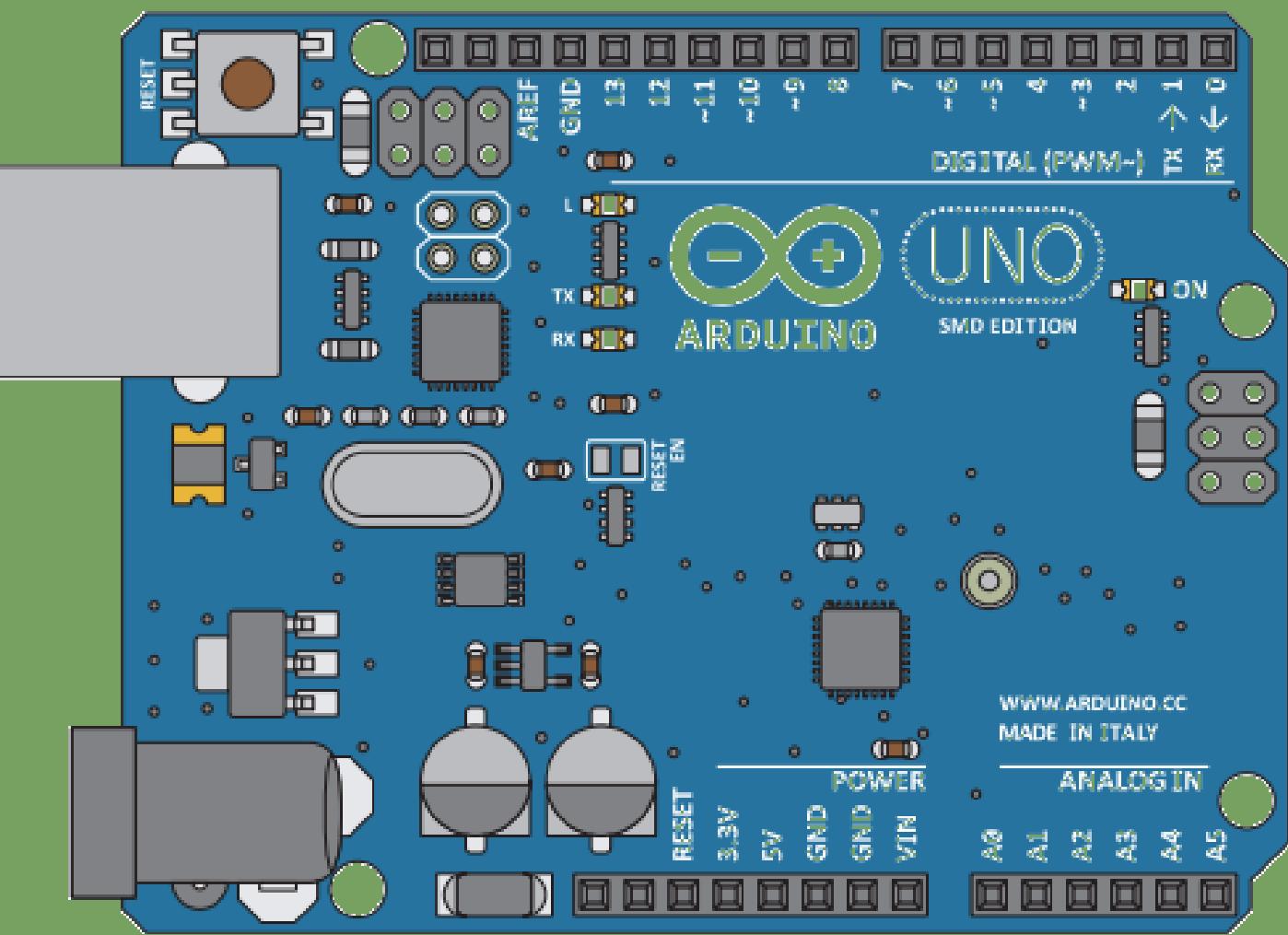
LILYPAD



The Standard Uno

- **What does it have?**

- **14 Digital In/Out pins (6 can be used as PWM)**
- **6 Analog Inputs**
- **A USB Connection**
- **A Power Jack**
- **Reset Button**
- **On-board LED**
- **SCL/SDA pins (Serial Clock/ Serial Data pins)**



- **In short, it contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started.**



POWER
5V / 3.3V /
GND

**Analog
INPUTS**

PWR IN

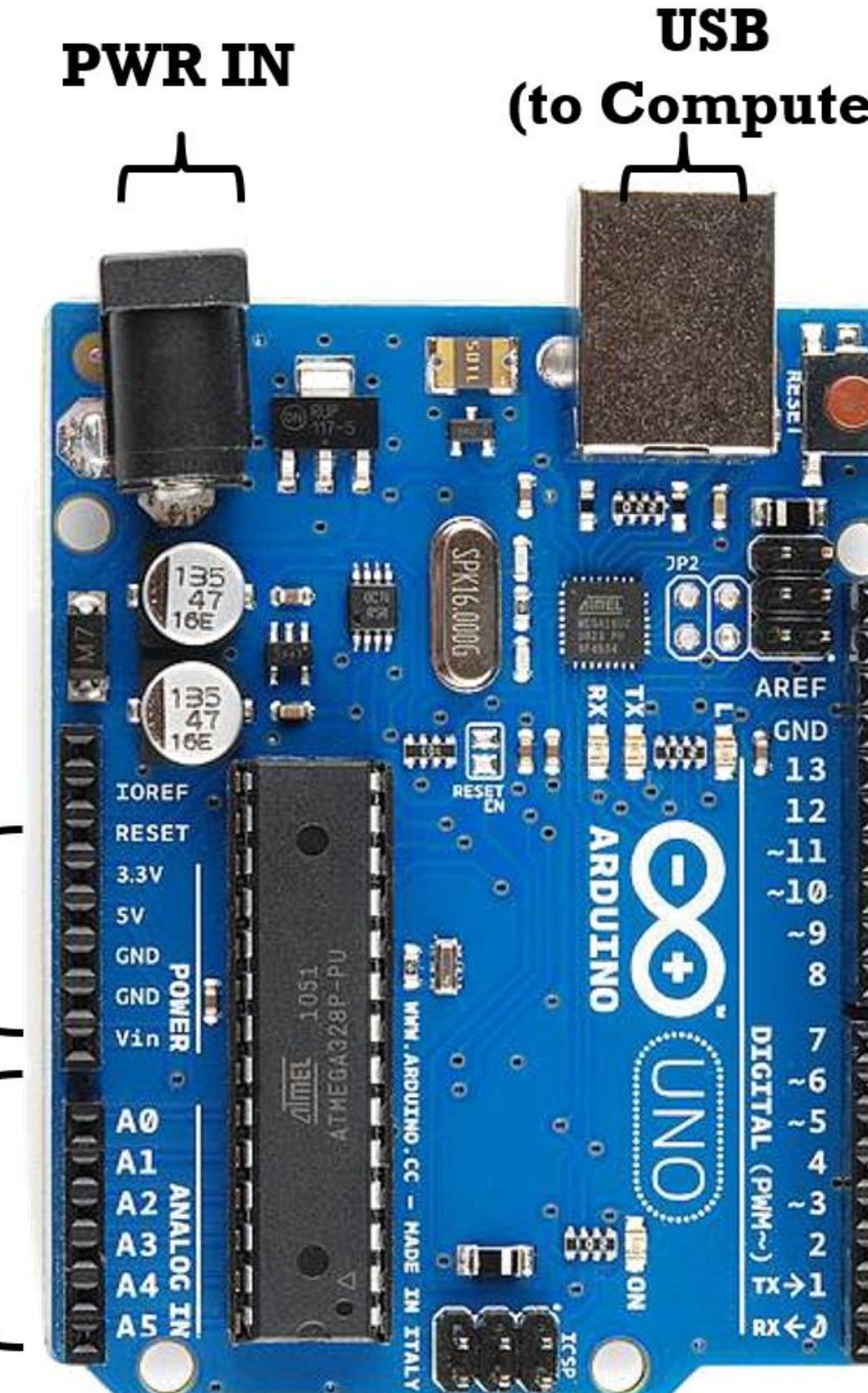
PWR IN

USB
(to Computer)

RESET

SCL\SDA
(I2C Bus)

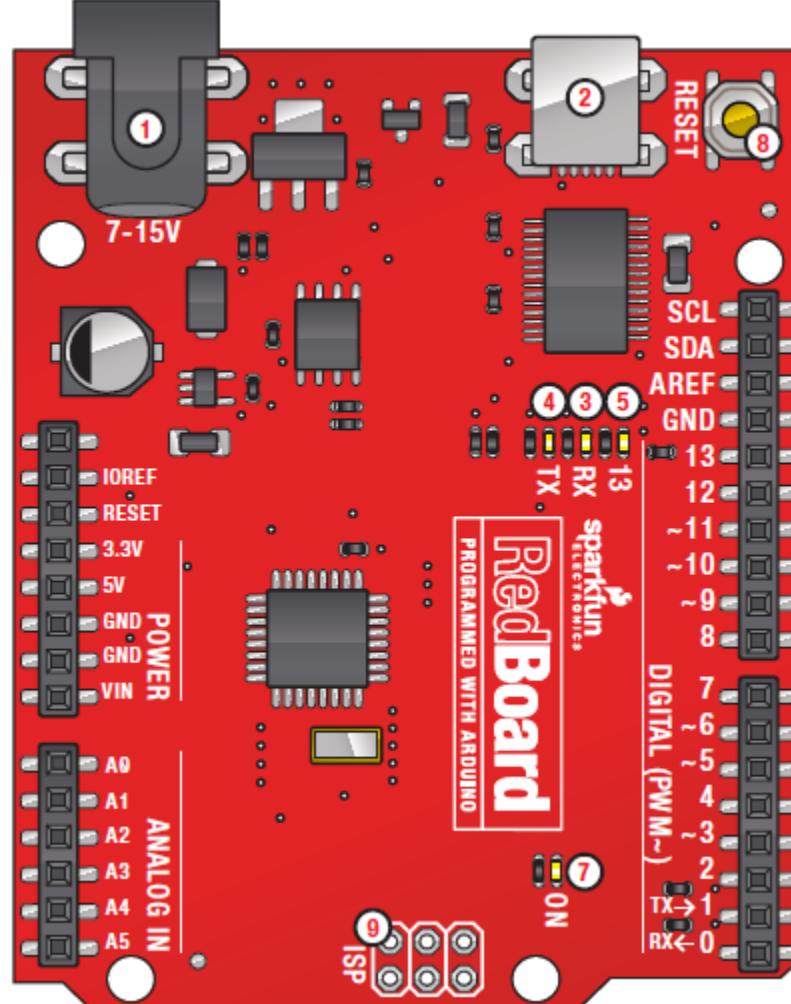
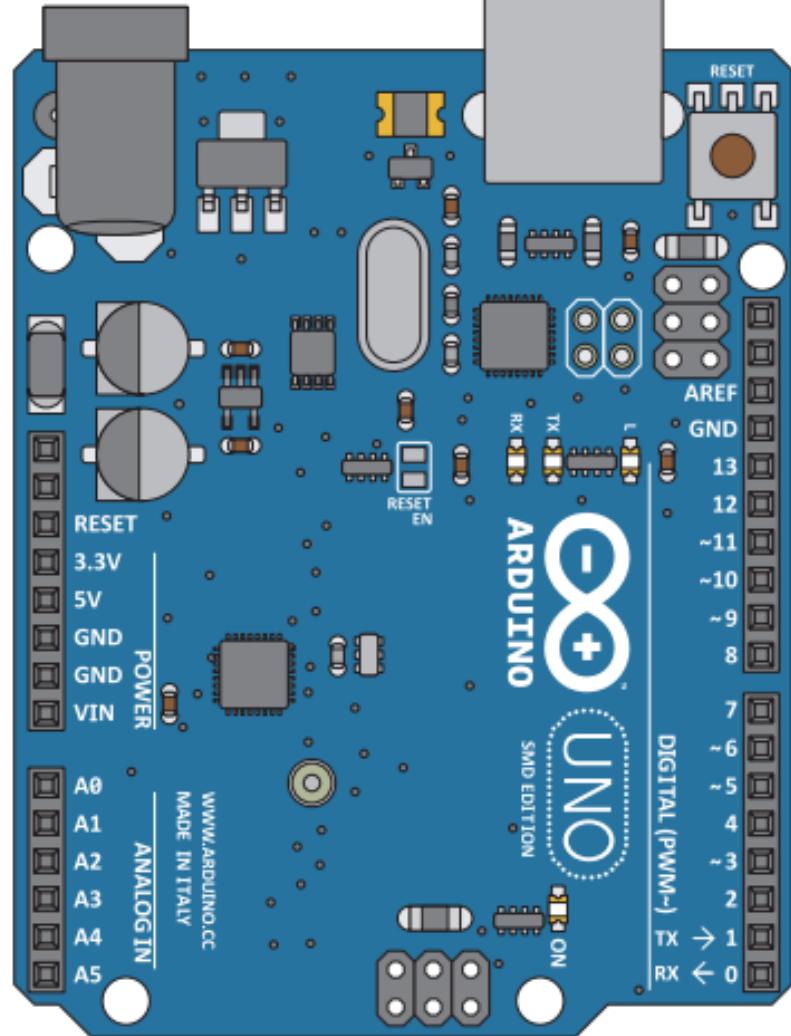
Digital I\O
PWM(3, 5, 6, 9, 10,
11)



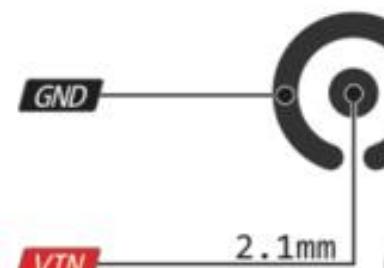




UNO PINOUT



7-12V Depending
on current drawn



⚠️ Absolute MAX per pin 40mA
recommended 20mA

🚫 Absolute MAX 200mA
for entire package

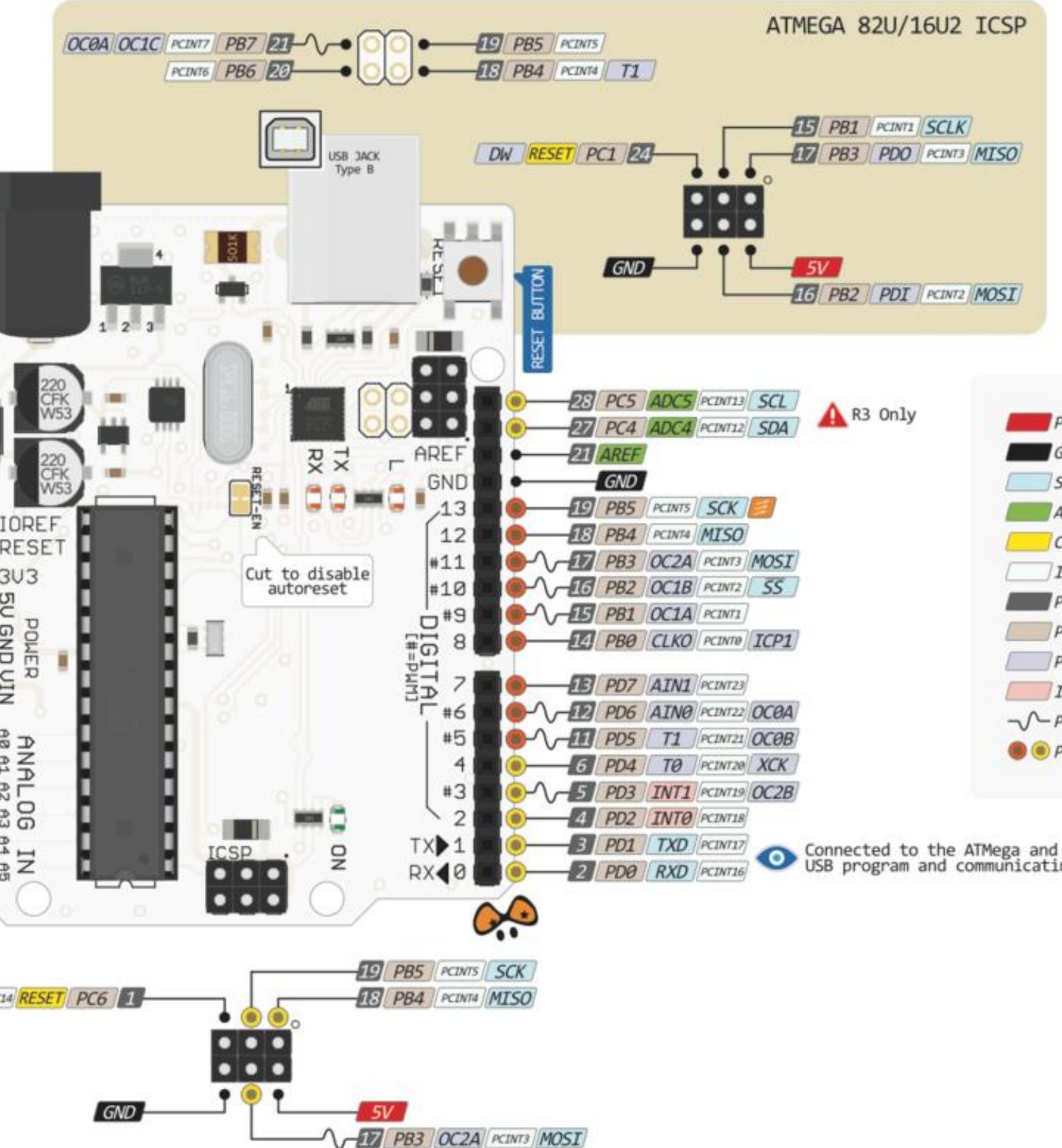
IOREF provides a logic reference
voltage for shields that use it.
It is connected to the 5V bus.

R3 Only **⚠️**
IOREF → NC
PCINT14 → RESET → PC6 → 1
3V3 → GND
5V → GND
GND → GND
VIN → GND

The input voltage to the board when
it is running from external power. **👁️**
Not USB bus power.

3V3 → GND
5V → GND
GND → GND
VIN → GND
PCINT8 → ADC0 → PC0 → 23
PCINT9 → ADC1 → PC1 → 24
PCINT10 → ADC2 → PC2 → 25
PCINT11 → ADC3 → PC3 → 26
SDA → PCINT12 → ADC4 → PC4 → 27
SCL → PCINT13 → ADC5 → PC5 → 28

⚠️ The power sum for each pin's
group should not exceed 100mA



bq

www.bq.com



17 JUL 2014

ver 3 rev 0

Most Significant Bit

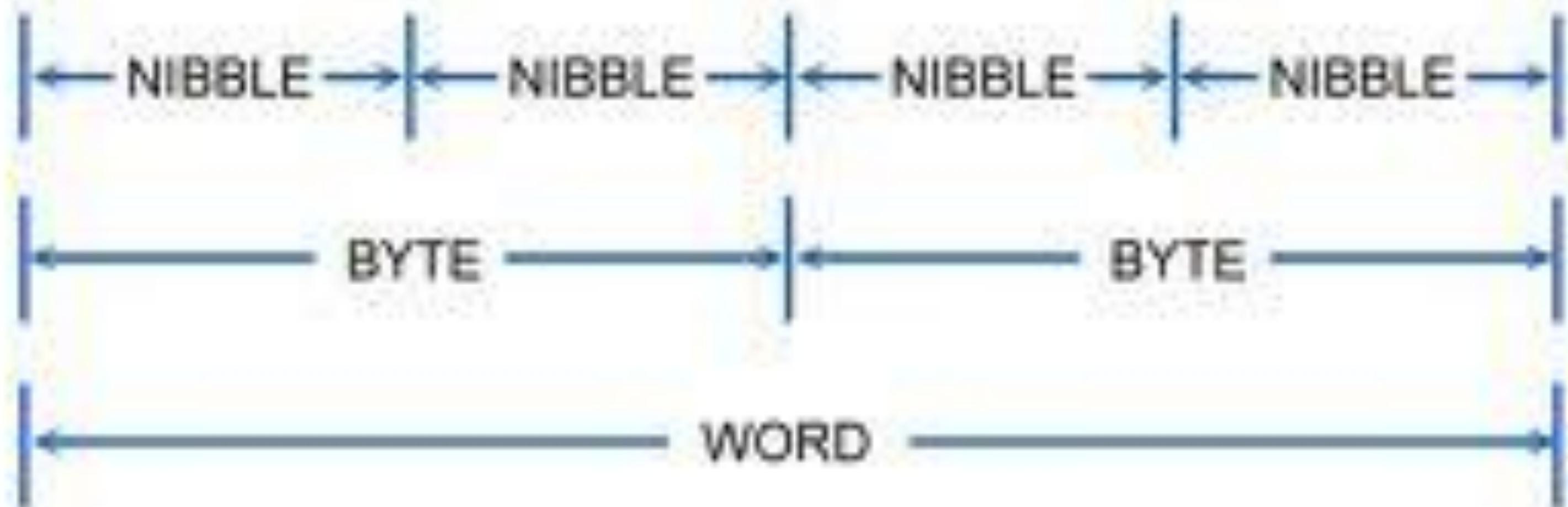
(MSB)



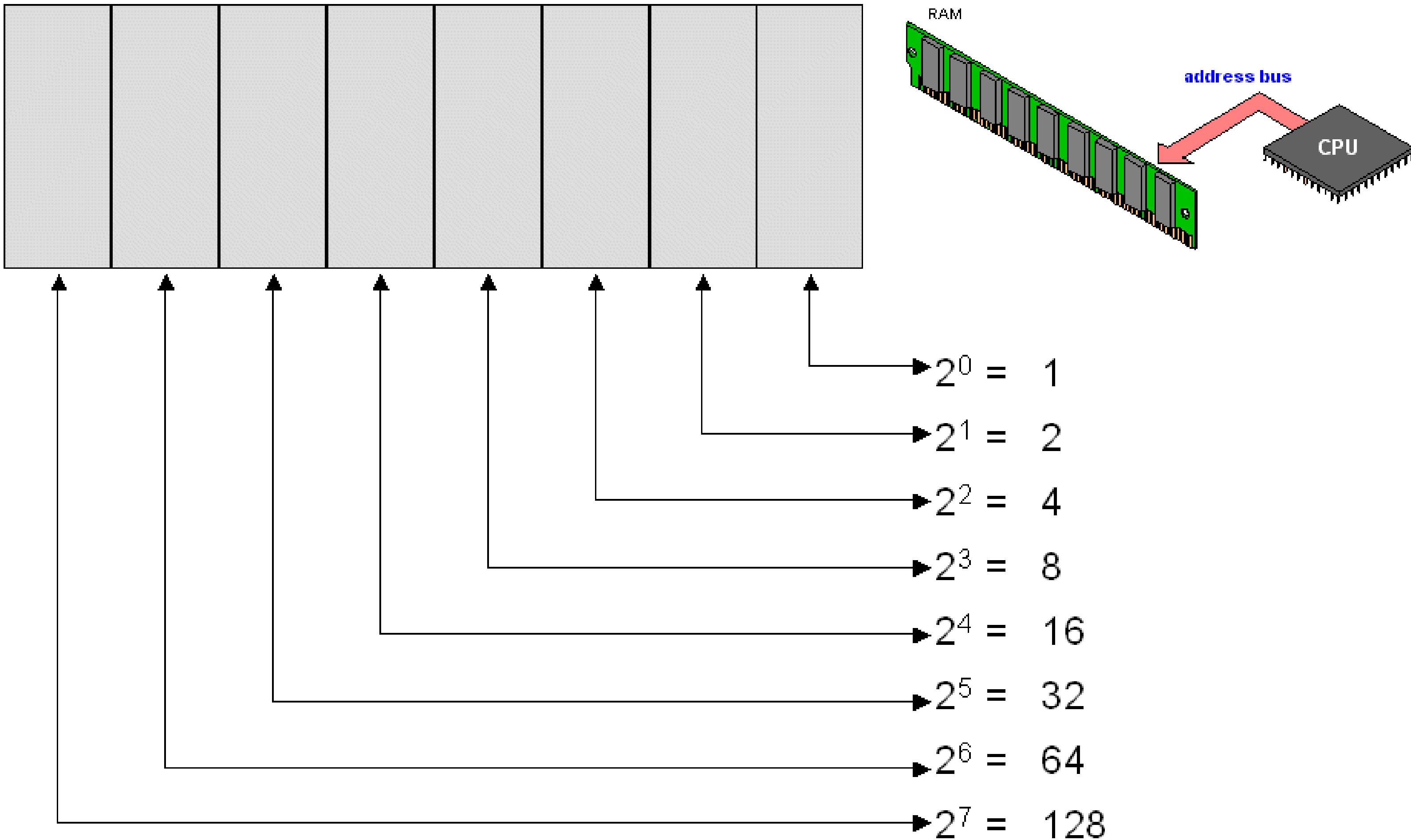
1	0	1	1	1	0	0	1	1	0	1	0	1	0	1	1
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Least Significant Bit

(LSB)



Bit positions: 8 7 6 5 4 3 2 1



TYPE	NAME	VALUE	
int	number →	1	Stored only integer
int	sum →	500500	Stored only integer
double	radius →	5.5	Stored only floating-point number
double	area →	95.0334	Stored only floating-point number
String	greeting →	Hello	Stored only texts
String	statusMsg →	Game Over	Stored only texts

A variable has a **name**, stores a **value** of the declared type.



How To Code???

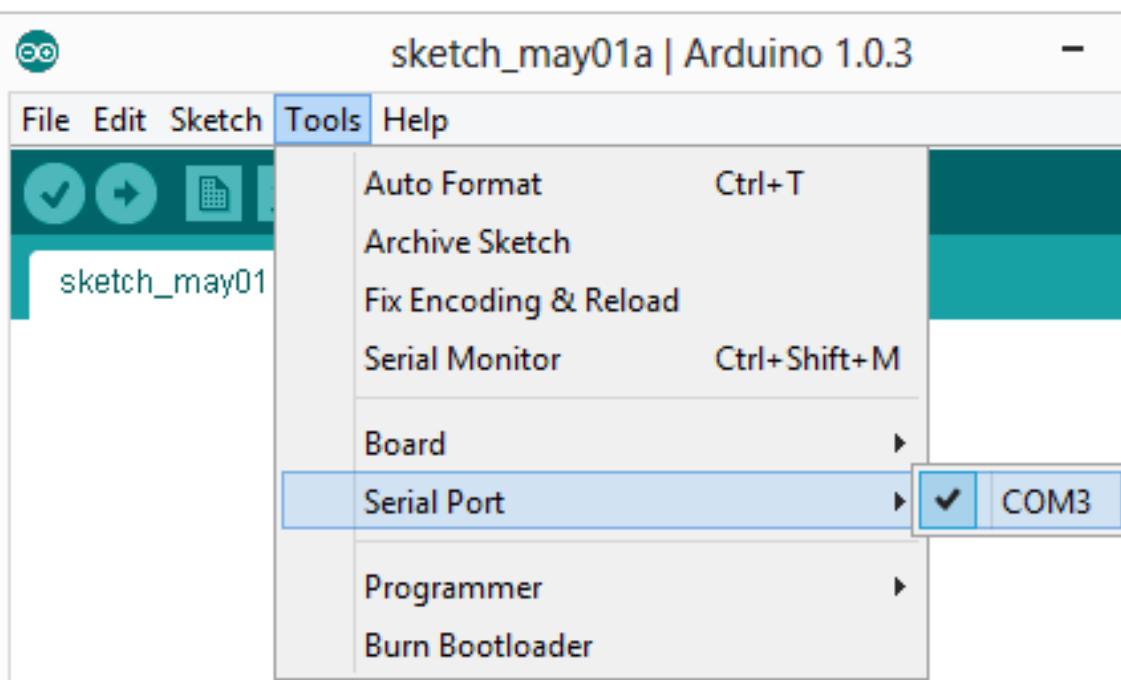
- You need to download **Arduino IDE (Integrated Development Environment)**.
- Arduino IDE is available for all Mac, Windows, and Linux. There is also a direct to shell version (**Arduino CLI**, available on **Github** and an **IOT** version).
- Arduino IDE has Legacy (no dark mode available but can handle discontinued official hardware) and the new IDE (has dark mode and can handle newer official hardware).



How To Code???

- You need to familiarize yourself with the IDE and what it can offer to your board (or other open-source boards) to have it easily detected by your computer to install it.
- To use transducers and sensors, make sure that it is compatible with Arduino or other MCU's like Arduino clones and Arduino Alternatives (i.e. Teensy, NodeMCU, ESP32, etc.)





Upload

The screenshot shows the Arduino IDE interface with the title bar "Blink | Arduino 1.0.6". The code editor displays the "Blink" sketch, which includes setup and loop functions for an LED. The status bar at the bottom indicates "Arduino Uno on COM3". A red arrow points from the word "Upload" to the upload icon in the toolbar.

```
// the setup function runs once when you press reset or power the
void setup() {
    // initialize digital pin 13 as an output.
    pinMode(13, OUTPUT);
}

// the loop function runs over and over again forever
void loop() {
    digitalWrite(13, HIGH);      // turn the LED on (HIGH is the voltage
    delay(1000);                // wait for a second
    digitalWrite(13, LOW);       // turn the LED off by making the volt
    delay(1000);                // wait for a second
}
```

Done compiling.

Binary sketch size: 1,082 bytes (of a 32,256 byte maximum)

1

Compile

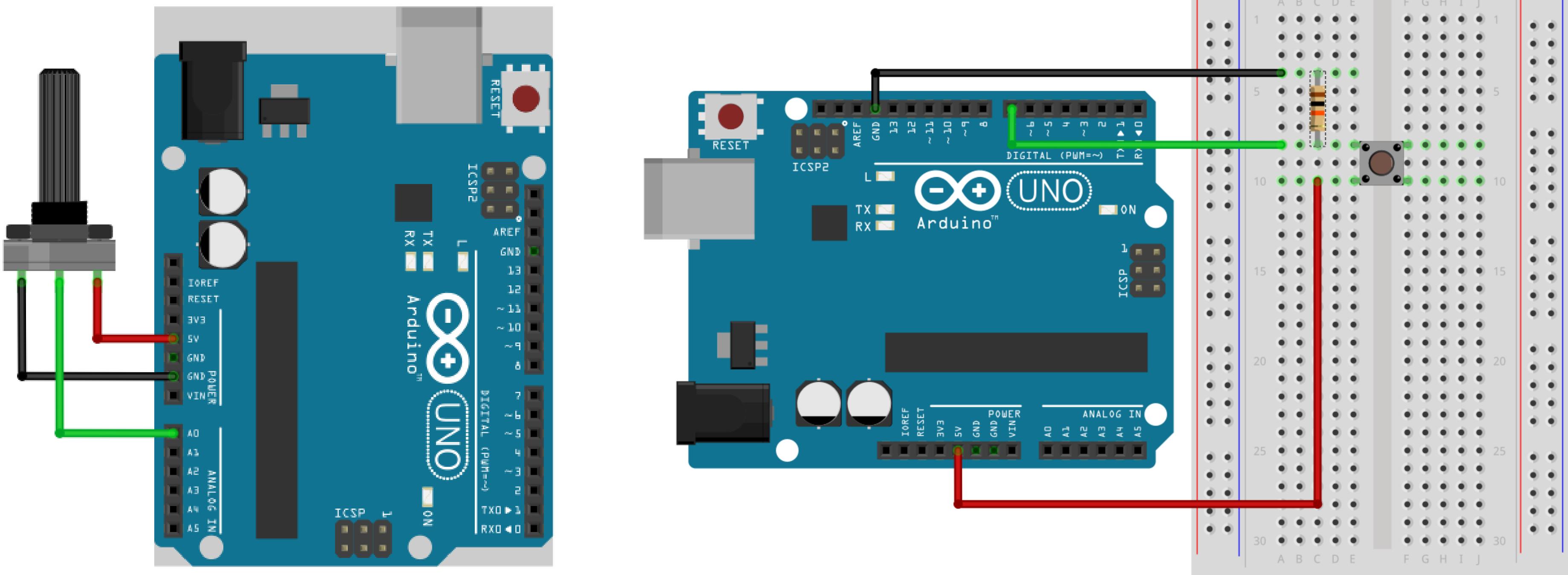
Status Message



Analog Versus Digital

- All Arduino signals are either Analog or Digital
- All computers including Arduino, only understand Digital
- It is important to understand the difference between Analog and Digital signals since Analog signals require an Analog to Digital conversion





“sketch” – a program you write to run on an Arduino board

“pin” – an input or output connected to something.
e.g. output to an LED, input from a knob.

“digital” – value is either HIGH or LOW.

(aka on/off, one/zero) e.g. switch state

“analog” – value ranges, usually from 0-255.

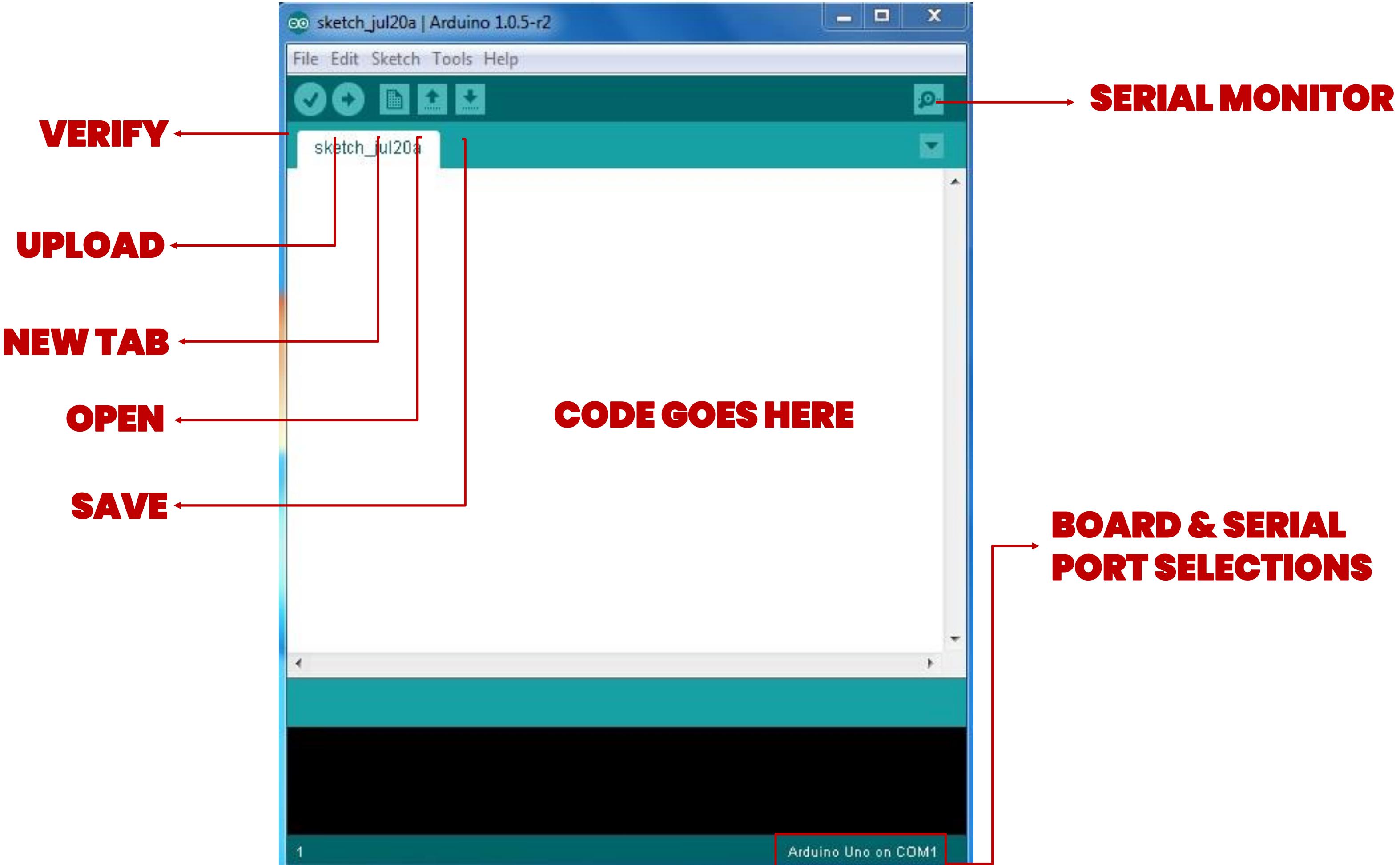
e.g. LED brightness, motor speed, etc.



Serial But Not Killer...

- “Serial” because data is broken into bits, each sent one after another in a single wire.
- Compiling turns your program into binary data (ones and zeros)
- Uploading sends the bits through USB cable to the Arduino
- The two LEDs near the USB connector blink when data is transmitted.
 - RX blinks when the Arduino is receiving data.
 - TX blinks when the Arduino is transmitting data.





Eh, No Naptime?

- The Arduino is usually programmed with Embedded C, this is not necessarily similar to C, C++, or C#, but instead is a modified language of its own that is compatible mainly with Arduino boards and Arduino clones.
- The void setup part sets up the different transducers or sensors to initiate a working code, while the void loop part presents the code indefinitely.



Eh, No Naptime?

- **The newest IDE doesn't have all the files necessary to run a specific sensor, at this point you as the programmer should know where to find these files in order to run a specific sensor.**
- **It is a good practice to be at least familiar with what the transducer or sensor can do before doing the coding part, like testing if the sensor in question works or not.**



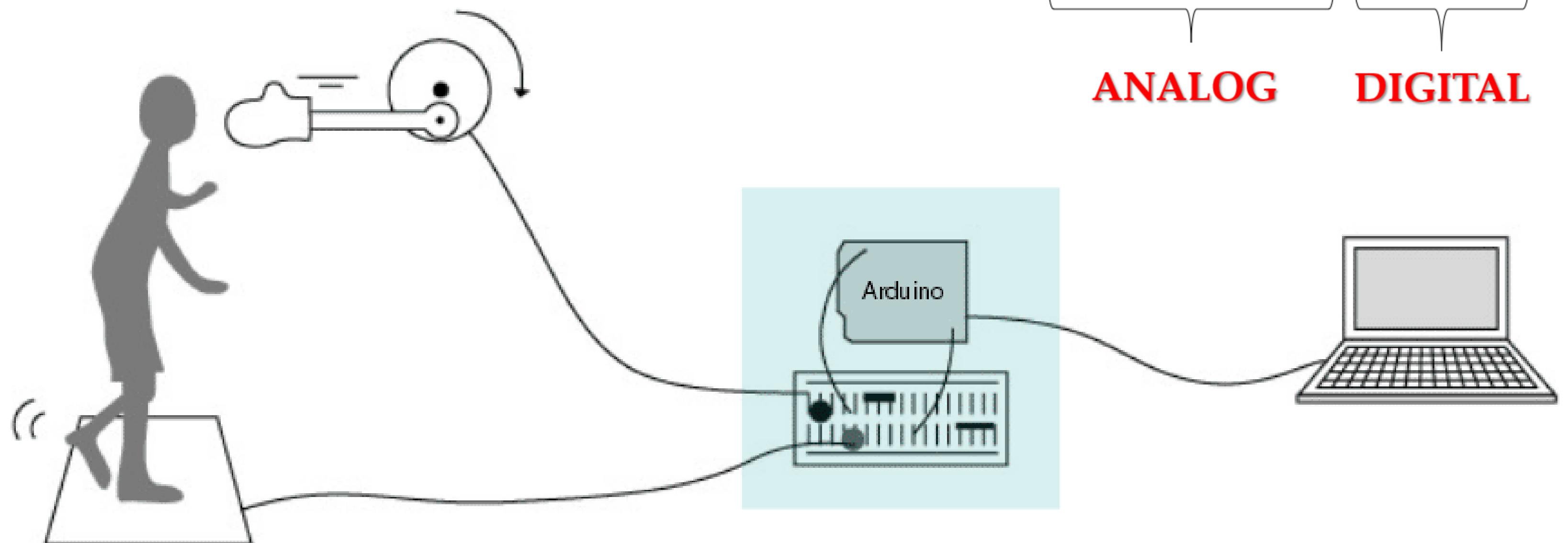
Input Versus Output

- **Everything is referenced from the perspective of the microcontroller.**
- **Inputs is a signal going into the board.**
- **Output is any signal exiting an electrical system.**
- **Almost all systems that use physical computing will have some form of output**
- **Often – Outputs include LEDs, a motor, a servo, a piezo element, a relay and an RGB LED**



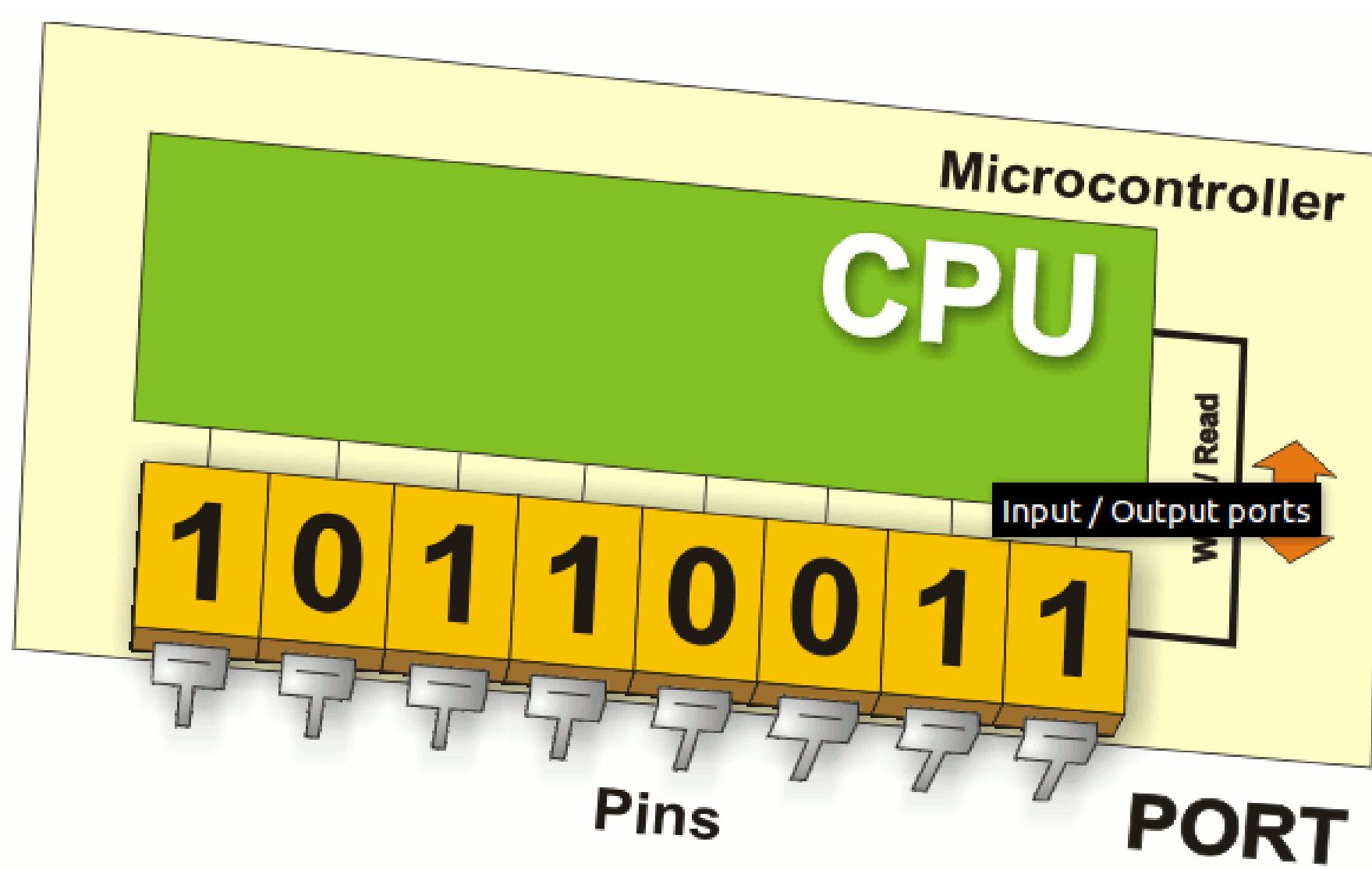
VAIO

ANALOG **DIGITAL**



Output is **ALWAYS** Digital





To output a signal that pretends to be Analog use this code:

`analogWrite (pinNumber, value);`

- Where pin is one of the analog output pins: 3, 5, 6, 9, 10, 11

Where value is a number ranging from: 0 – 255.

`pinMode(pin, mode)`

Sets pin to either INPUT or OUTPUT

`digitalRead(pin)`

Reads HIGH or LOW from a pin

`digitalWrite(pin, value)`

Writes HIGH or LOW to a pin

Electronic stuff

Output pins can provide 40 mA of current

Writing HIGH to an input pin installs a 20KΩ pullup



Power Supply

Processor

Memory

Timers & Counters

Communication
Ports

Input & Output

Application Specific
Circuits

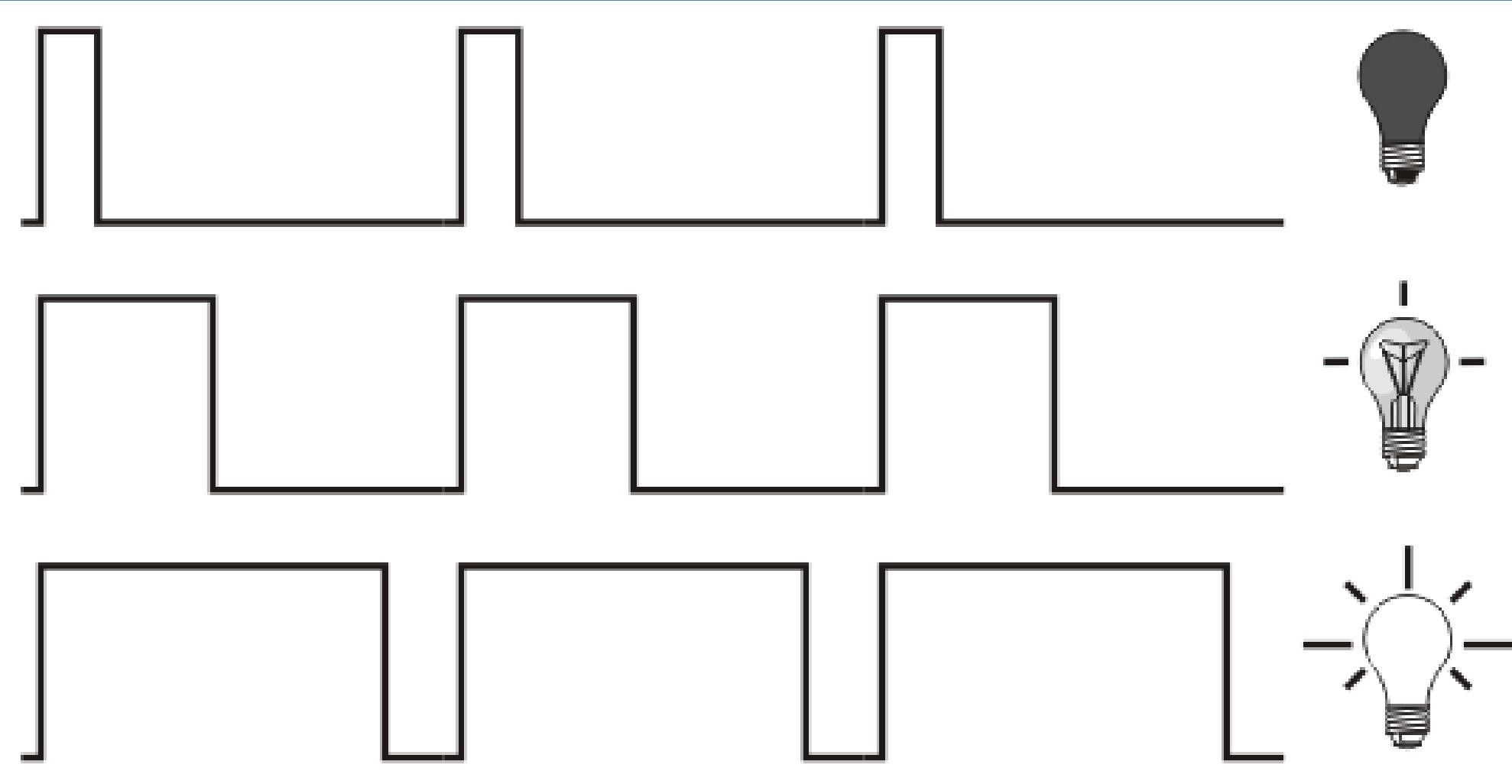
Software
Components

Embedded Systems

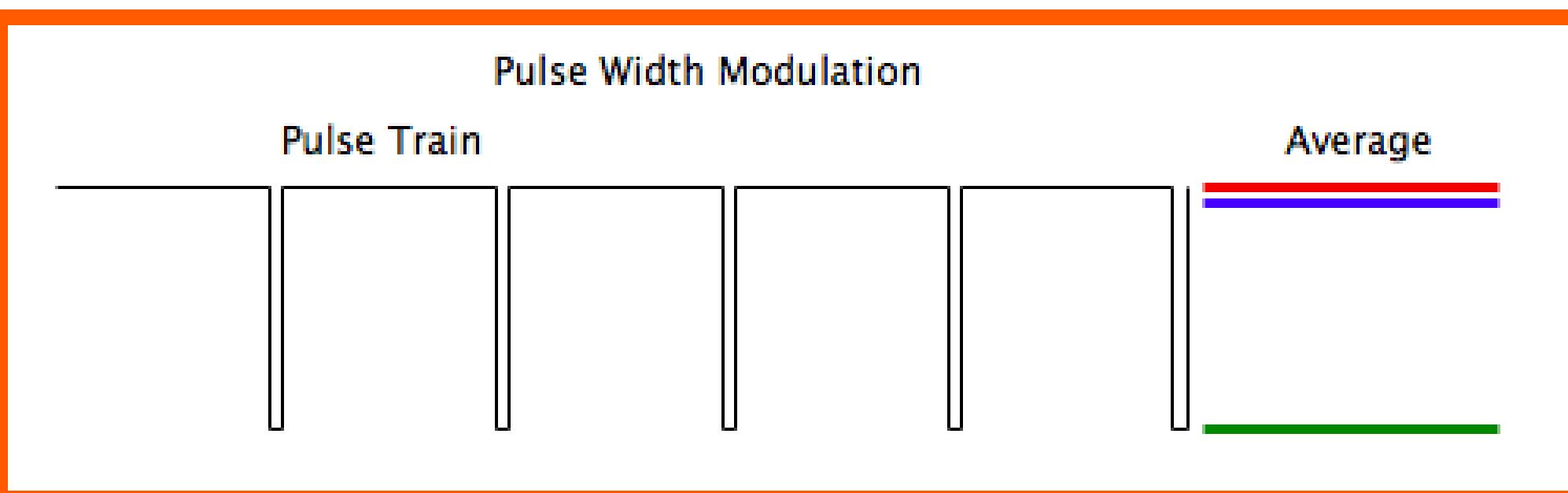
- **Assembler**
- **Emulator**
- **Debugger**
- **Compiler**

“An **embedded system** is a computer system with a dedicated function within a larger mechanical or electrical system, often with real-time computing constraints. It is embedded as part of a complete device often including hardware and mechanical parts. Embedded systems control many devices in common use today.”





D: 0%



Sender

1011000

Receiver



Pulse Width Modulation

Hackerman Time

- ***setup()* function**

- Called when a sketch starts.
- To initialize variables, pin modes, start using libraries, etc.
- Will only run once, after each power-up or reset of the Arduino board.

- ***loop()* function**

- Loops consecutively.
- Code in the *loop()* section of the sketch is used to actively control the Arduino board.

- ***Commenting***

- Any line that starts with two slashes (//) will not be read by the compiler, so you can write anything you want after it.



Hackerman Time

- ***pinMode()***

- Instruction used to set the mode (INPUT or OUTPUT) in which we are going to use a pin.
- Eg: `pinMode (13, OUTPUT);`
- i.e. setting pin13 as output.

- ***digitalWrite()***

- Write a HIGH or a LOW value to a digital pin.
- Eg: `digitalWrite (11, HIGH);`
- i.e. setting pin 11 to high.



Hackerman Time

- ***digitalRead()***

- Reads the value from a specified digital pin, either HIGH or LOW
- Eg: int inPin=7;
 val = digitalRead(inPin);
- ie. reads the value from inPin and assigns it to val.

- ***delay()***

- Pauses the program for the amount of time (in milliseconds) specified as parameter.
- Eg: delay(1000);
- i.e. waits for a second (1000 ms = 1 s)



Hackerman Time

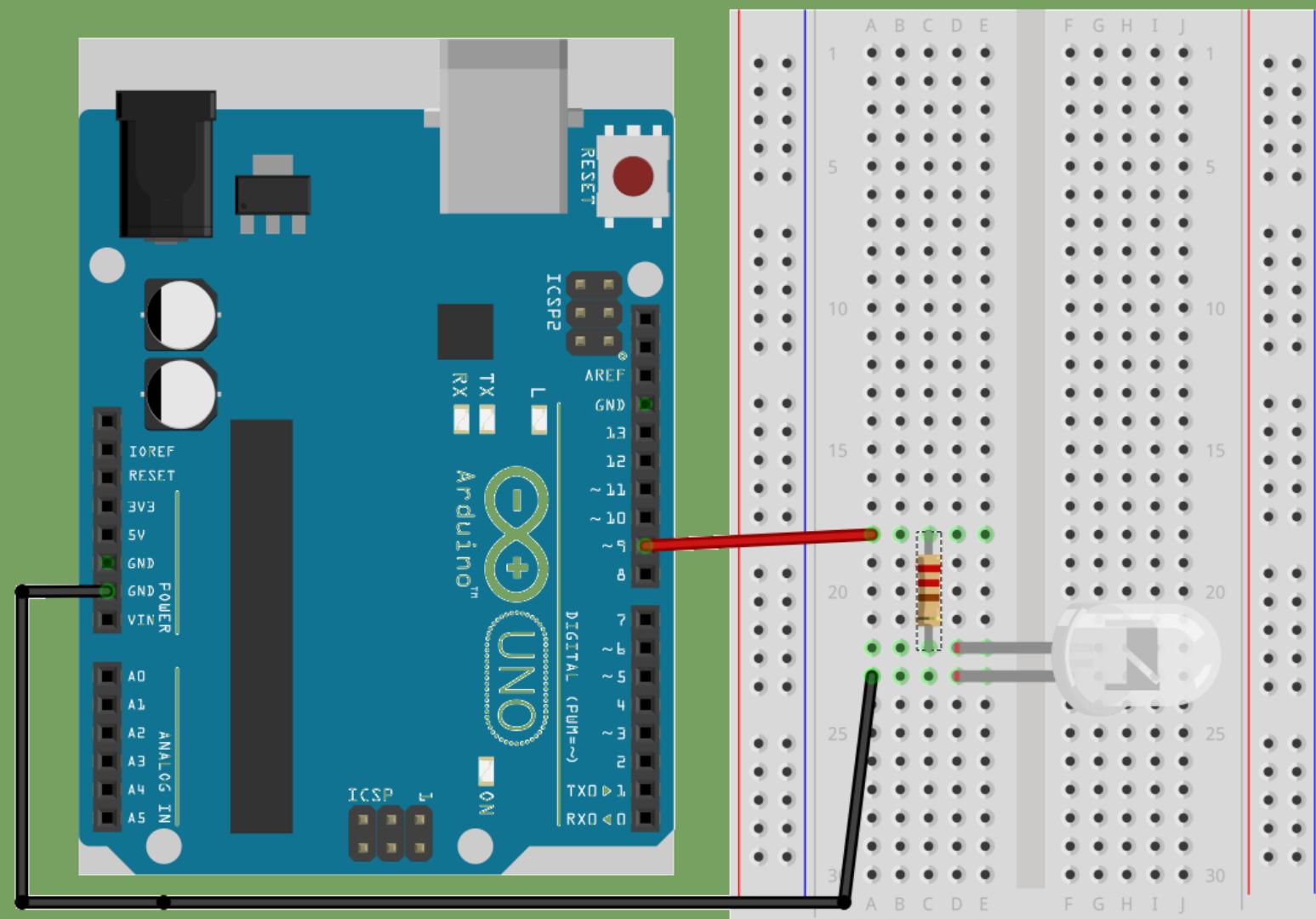
Turn LED
ON

Wait

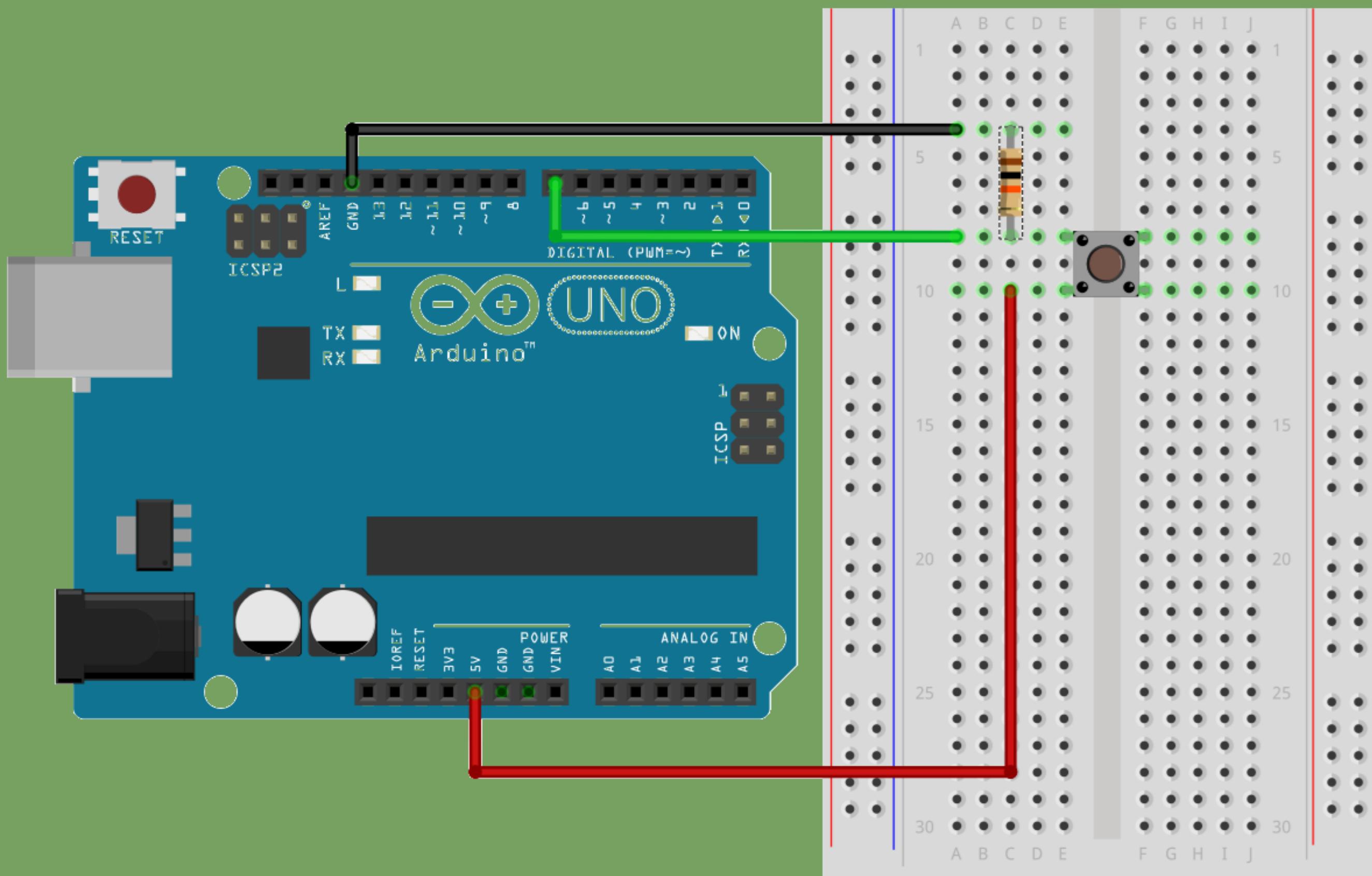
Turn LED
OFF

Wait

Rinse &
Repeat



Digital Reading



Digital Sensors

- Digital sensors are more straight forward than Analog
- No matter what the sensor there are only two settings: On and Off
- Signal is always either HIGH (On) or LOW (Off)
- Voltage signal for HIGH will be a little less than 5V on your Uno
- Voltage signal for LOW will be 0V on most systems

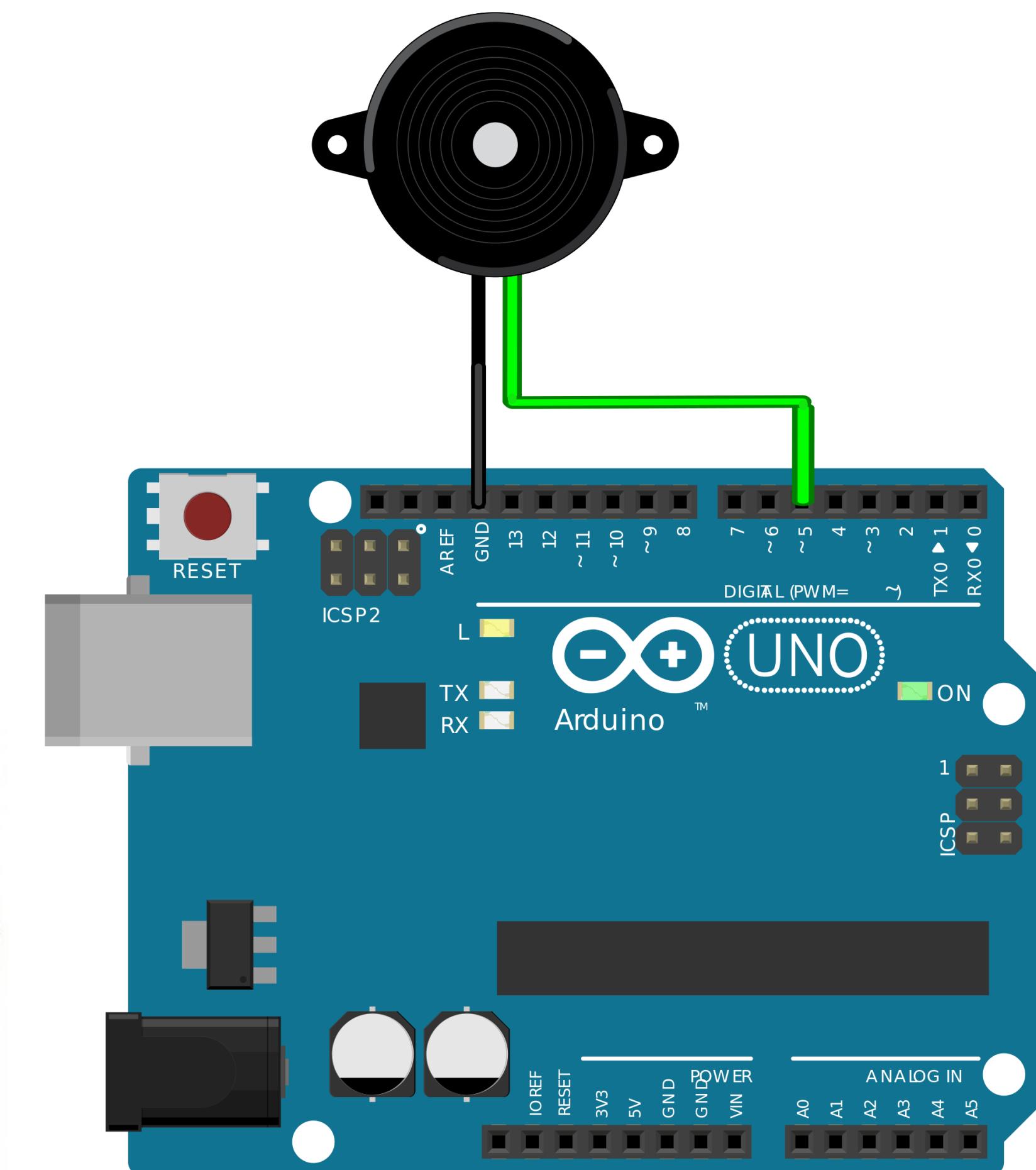
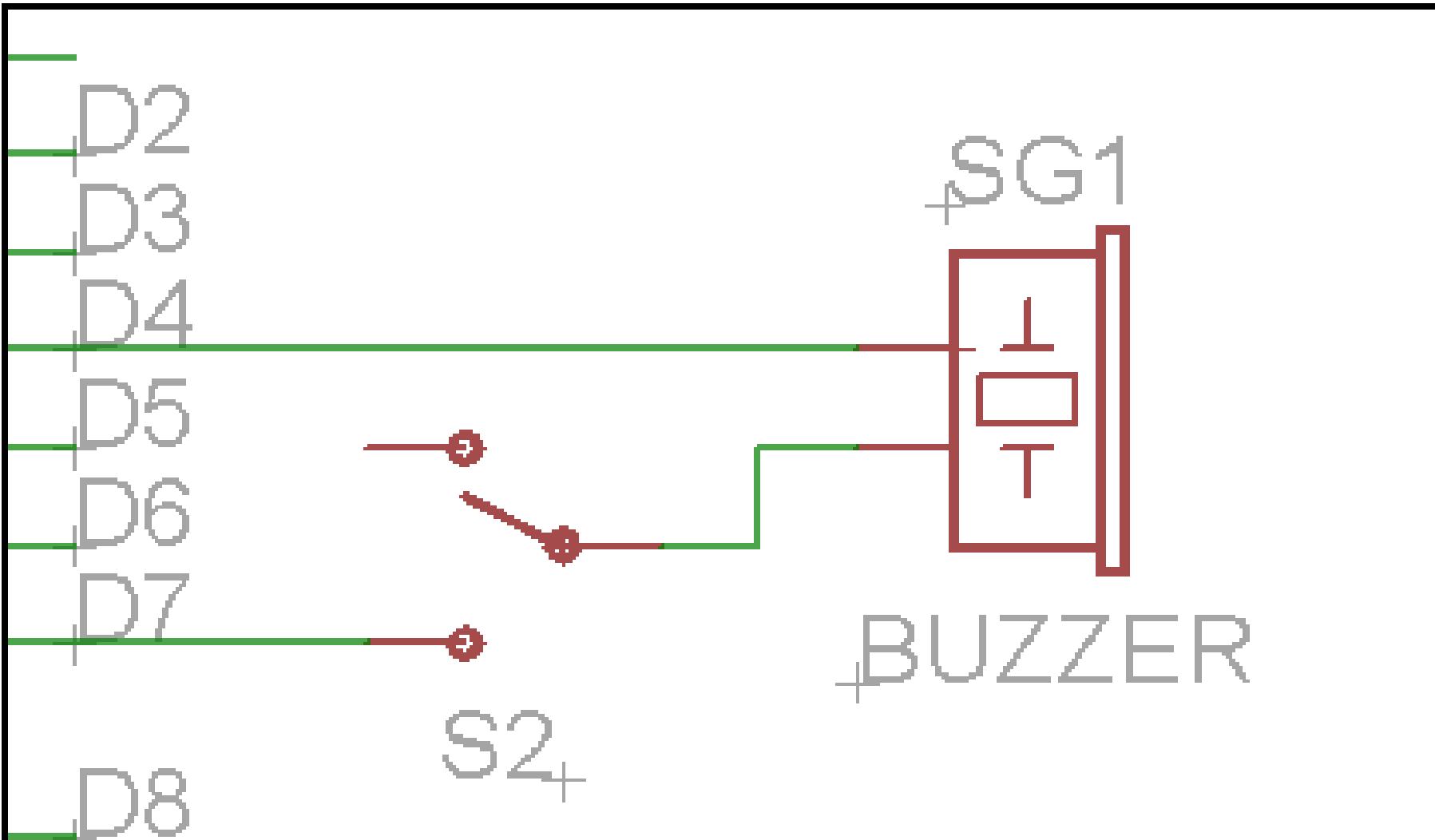


Make Some Noise

An example of a digital sensor is a BUZZER.

- **Code:** `tone(pin, freq, duration);`
- **pin** – the OUTPUT pin the buzzer is connected to
- **freq** – unsigned int (0 ... 65,535)
- **duration** – unsigned long (0 ... $2^{32} - 1$)





Buzzer for Arduino



Make Some Noise

- The Buzzer is connected between two digital pins.
- You must set both pins as OUTPUTs –
`pinMode(4, OUTPUT);`
- `pinMode(7, OUTPUT);`
- Use `tone(4, 440);` to generate a 440 Hz sound.



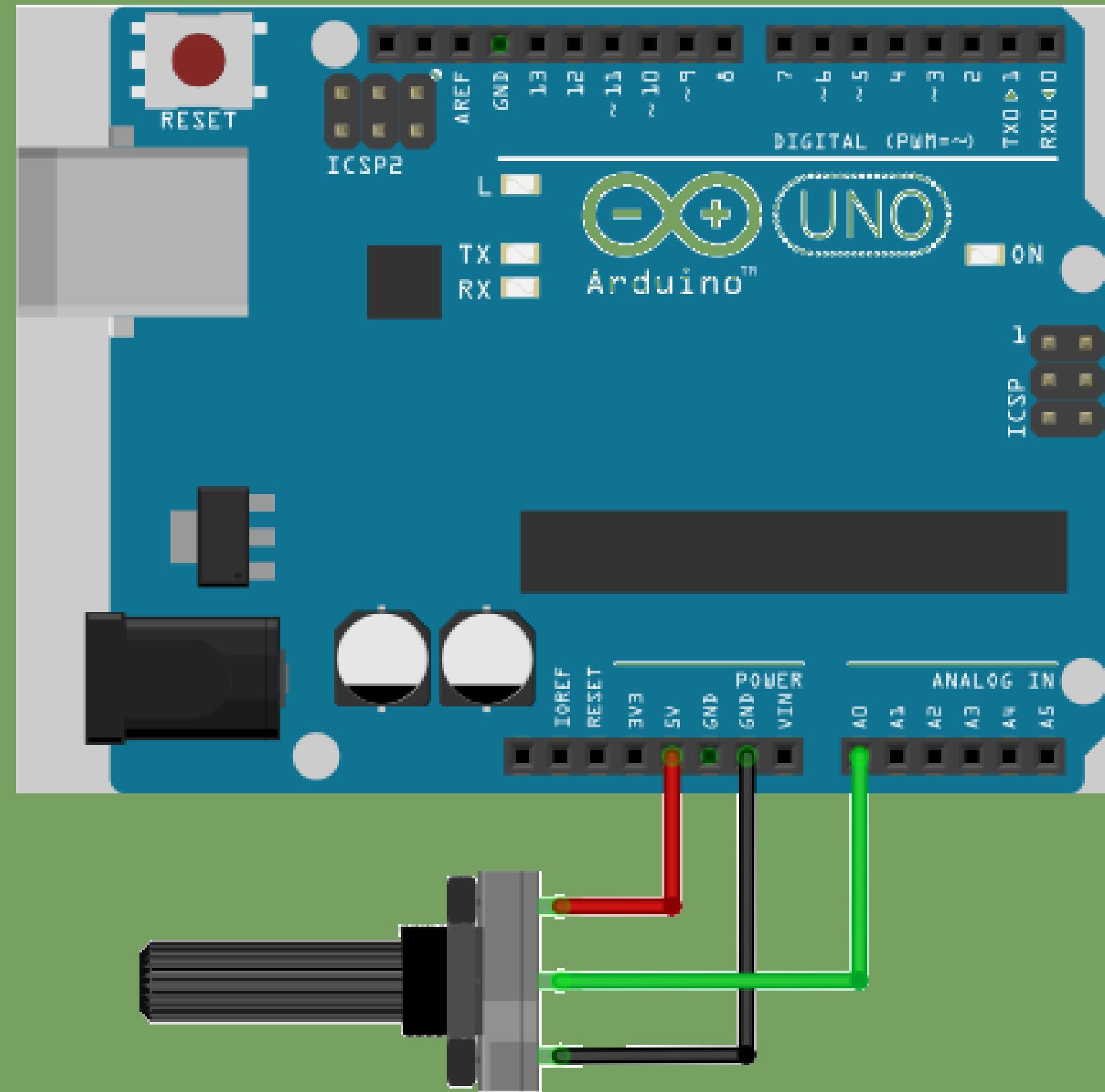
Make Some Noise

Note	Frequency (Hz)
C ₄	261
C [#] ₄ /D ^b ₄	277
D ₄	293
D [#] ₄ /E ^b ₄	311
E ₄	329
F ₄	349
F [#] ₄ /G ^b ₄	369
G ₄	392
G [#] ₄ /A ^b ₄	415
A ₄	440
A [#] ₄ /B ^b ₄	466
B ₄	493

Note	Frequency (Hz)
C ₅	523
C [#] ₅ /D ^b ₅	554
D ₅	587
D [#] ₅ /E ^b ₅	622
E ₅	659
F ₅	698
F [#] ₅ /G ^b ₅	739
G ₅	783
G [#] ₅ /A ^b ₅	830
A ₅	880
A [#] ₅ /B ^b ₅	932
B ₅	987



Analog Reading



Analog Sensors

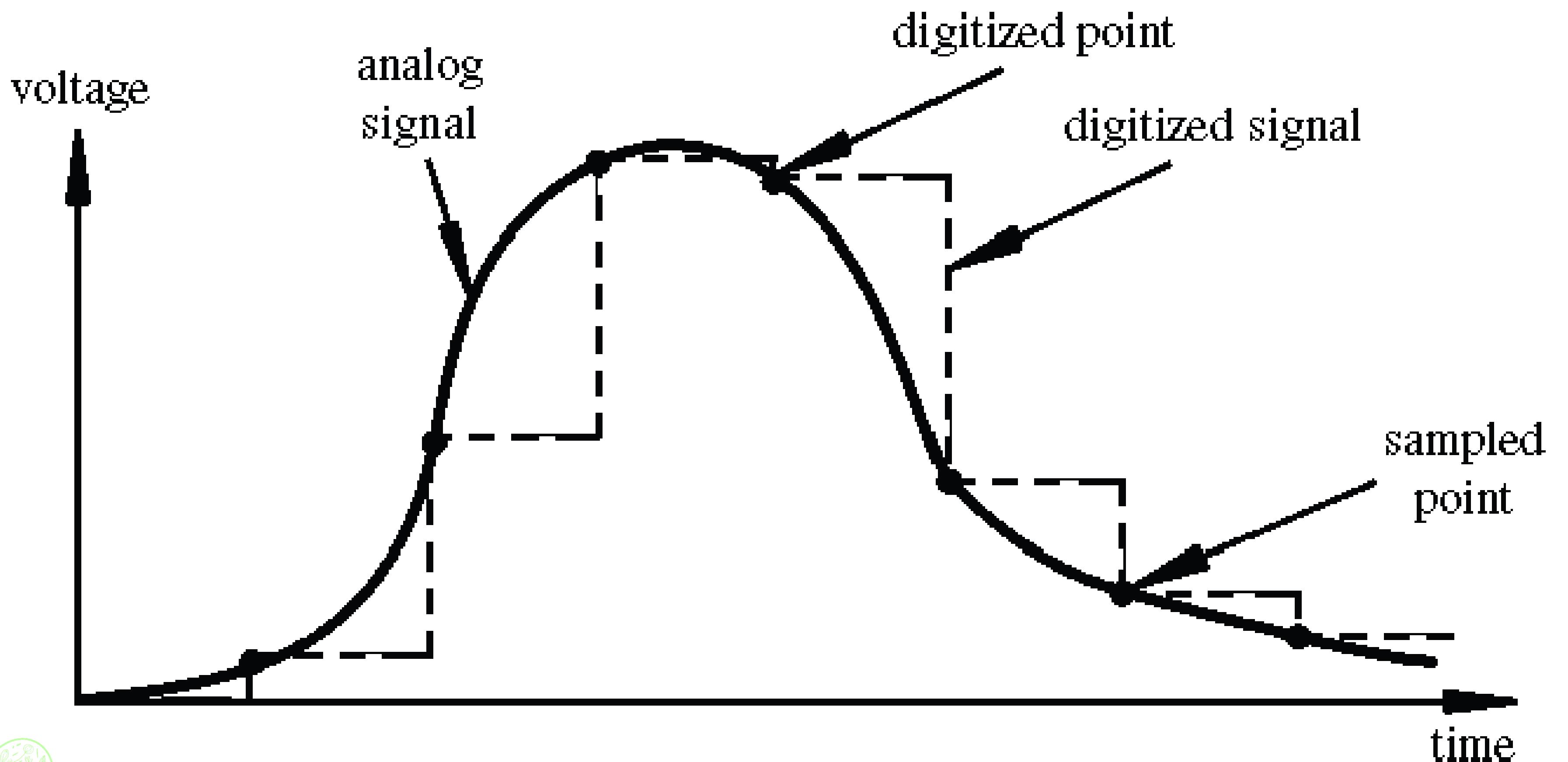
Sensors	Variables
Microphone	Sound, Volume
Photoresistor	Light Level
Potentiometer	Dial Position
Temp Sensor	Temperature
Flex Sensor	Bend
Accelerometer	Tilt / Acceleration



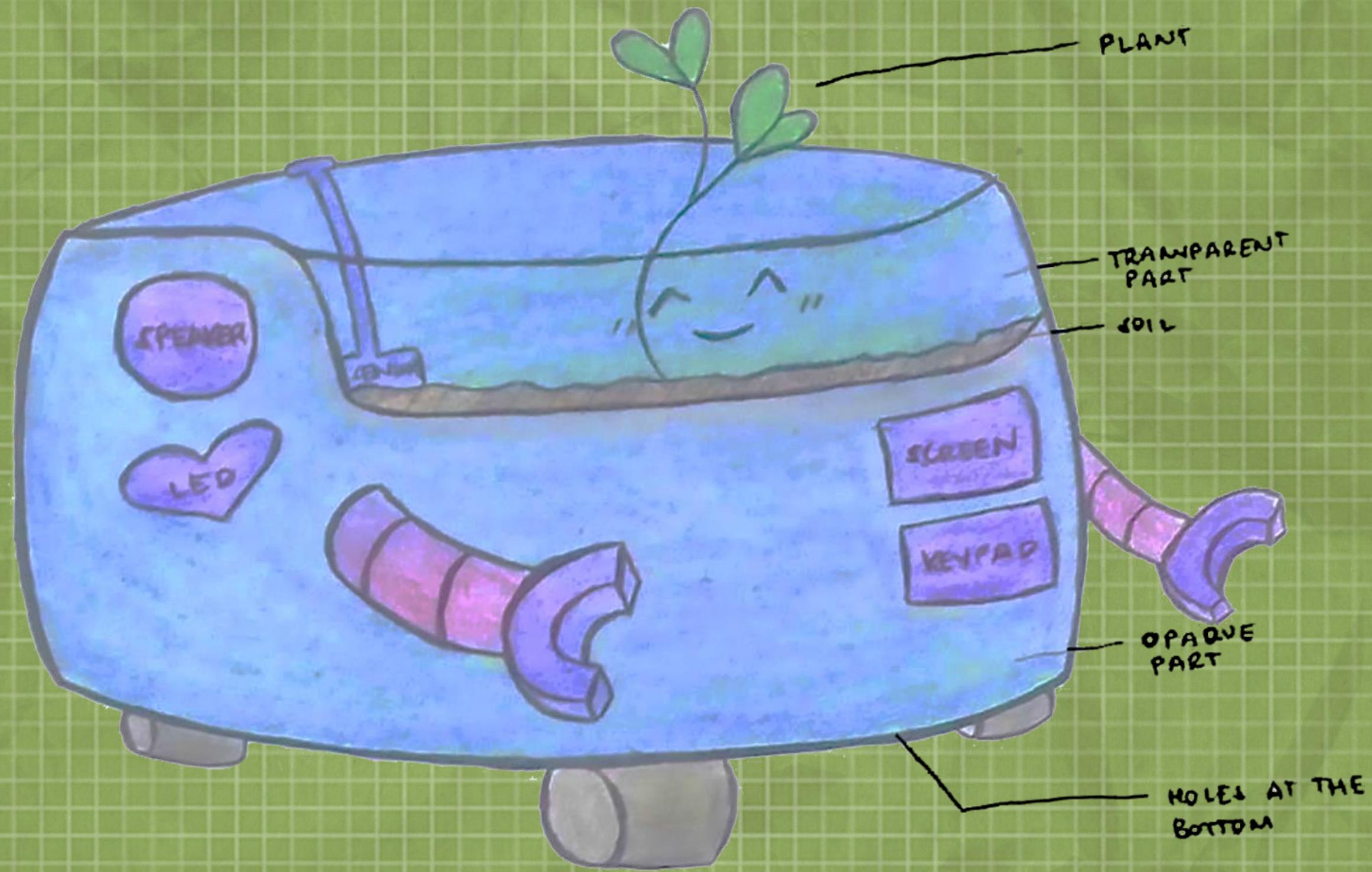
Analog Sensors

- Digital has two values: **on** and **off**
- Analog has many (infinite) values
- Computers don't really do analog, they **quantize**
- Remember the 6 analog input pins---here's how they work





Product Design



Project Roadmap

PLANNING PHASE: OCTOBER 2023

Brainstorming of Project HEART and its components using Arduino.

SIMULATION PHASE: NOVEMBER 2023

Simulation of Arduino components of Project HEART via Wokwi.

BUILD PHASE I: NOVEMBER 2023

Building of Project HEART along with Arduino components.

Project Roadmap

BUILD PHASE 2: DECEMBER 2023

Building of Project HEART along with
Arduino components.

TESTING PHASE: DECEMBER 2023

Testing of Project HEART along with
Arduino components.

PRESENTATION: DECEMBER 2023

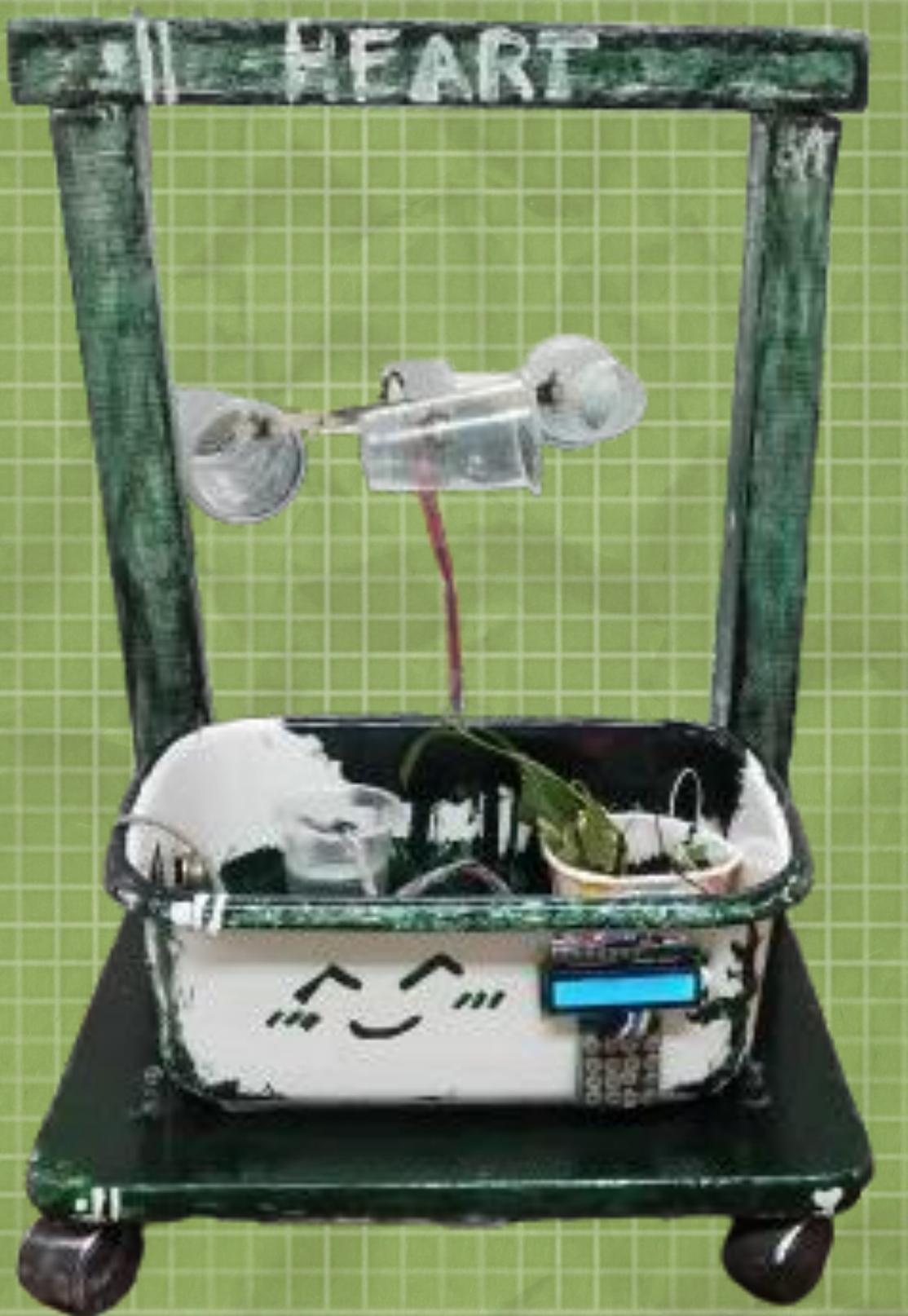
Final presentation of Project HEART
and its capabilities.



Product Video: Blossoming Possibilities

Product pitch of Project HEART

Finished Product



PROFILES



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FOR QUESTIONS
OR CONCERNs



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