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DIP Lecture 10

Frequency domain processing

RECAP

Inverse FT

$$f(t) = \int_{-\infty}^{\infty} \frac{1}{2\pi} F(\omega) e^{i\omega t} d\omega$$

$$F(\omega) = \mathcal{F}\{f(t)\}$$

FT:

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$$

$$f(t) = \mathcal{F}^{-1}\{F(\omega)\}$$

Intuition:

→ Measures strength of presence of particular freq. within a signal

→ How dominant each freq. component is in original signal

Unit impulse function:

→ Has integral property, shifting property

↓
Also applicable to shifted impulse

→ picks up value at origin

$$\delta(t-\lambda), \delta(t+\lambda)$$

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt = e^{-i\omega T}$$

→ F.T of shifted impulse is complex exponential

Sampling

→ Scaled version of time shifted impulses

$$s_{\Delta}(t) = \sum_{n=-\infty}^{\infty} \delta(t-n\Delta T)$$

$$\bar{f}(t) = \sum_{n=-\infty}^{\infty} f_n \delta(t-n\Delta T)$$

↕ F.T

To digitise, we take only one sample

$$\bar{F}(\omega) = \frac{1}{\Delta T} \sum_{n=-\infty}^{\infty} F\left(\omega - \frac{n}{\Delta T}\right)$$

periodicity ↙

Discrete FT:

$$F[m] = \sum_{n=0}^{M-1} f_n e^{-j\frac{2\pi mn}{M}}, m=0, 1, 2, \dots, (M-1)$$

Continuous $\leftarrow u = \frac{m}{M\Delta T}$ \rightarrow Discrete

DFT & IDFT

$$\rightarrow f_n = \frac{1}{M} \sum_{m=0}^{M-1} F_m e^{j\frac{2\pi mn}{M}}, n=0, 1, 2, \dots, (M-1)$$

$\rightarrow F[m]$ is complex value

\rightarrow Represents amplitude, phase of function

$\rightarrow F[m]$'s content at angular freq $\frac{2\pi m}{M}$

Records energy position at various freq. bands present in input similar to continuous F.T

Magnitude $\leftarrow || \cdot || = \sqrt{\text{Re}\{F[m]\}^2 + \text{Im}\{F[m]\}^2}$

Angle / Phase $\leftarrow \angle = \tan^{-1} \left[\frac{\text{Im}\{F[m]\}}{\text{Re}\{F[m]\}} \right]$

Implementation of DFT in practice:

$$\rightarrow F[m] = \sum_{n=0}^{M-1} f_n e^{-j\frac{2\pi mn}{M}}, m=0, 1, 2, \dots, (M-1)$$

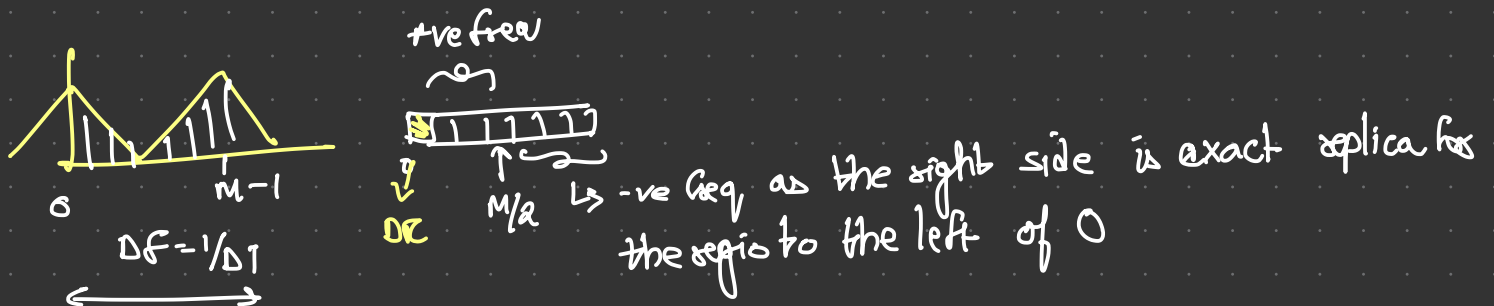
\Rightarrow Can be expressed in vectorised form

$$F = P \cdot f$$

$M \times 1 \quad M \times M \quad M \times 1$

$$[P] = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & p & p^2 & p^3 & p^4 \\ 1 & p^2 & p^4 & p^6 & p^8 \\ 1 & p^3 & p^6 & p^9 & p^{12} \\ 1 & p^4 & p^8 & p^{12} & p^{16} \end{bmatrix} \leftarrow \text{For } M=5, p = e^{-j\frac{2\pi}{5}} = \text{cis}\left(\frac{-2\pi}{5}\right), e^{-j\frac{4\pi}{5}} = p^2, \dots$$

Centered DFTs



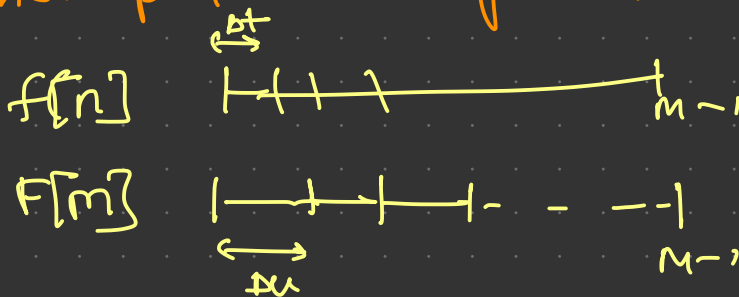
Now try to shift it where -ve lies on left



Center shift DFT formula

$$F[M] = \sum_{n=0}^{M-1} f[n] e^{-j2\pi \left(m - \frac{M-1}{2}\right) \left(n - \frac{M-1}{2}\right) / M}$$

Relationship b/w sampling & freq intervals



$$\Delta u (\text{Freq. resolution}) = \frac{1}{M \cdot \Delta T} \quad \rightarrow \text{Inverse relationship}$$

\hookrightarrow Time resolution

\rightarrow Entire freq. range spanned by M components, $B = M \Delta u = \frac{1}{\Delta T}$

2D DFT & IDFT

$$F[m,n] = \sum_{y=0}^{N-1} \sum_{x=0}^{M-1} f[x,y] e^{-2\pi j \left(\frac{mx}{M} + \frac{ny}{N} \right)}$$

$$f[x,y] = \sum_{y=0}^{N-1} \sum_{x=0}^{M-1} \frac{1}{MN} F[m,n] e^{+2\pi j \left(\frac{mx}{M} + \frac{ny}{N} \right)}$$

Shifting origin,

$$f[x,y] e^{j2\pi \left[\frac{u_0 x}{M} + \frac{v_0 y}{N} \right]} \longleftrightarrow F(u-u_0, v-v_0)$$

With increasing spatial resolution, freq. resolution decreases

Better visualisations

→ Amplitude rescaling:

$$G(k,l) = \log(1 + F(k,l))$$

Magnitude vs Phase:

→ $|f(u,v)|$ decreases with higher spatial freq.

→ Phase appears less informative

In general, natural images could have same mag. transform so we look into phase

Time complexity:

Direct Computation: $N = 2^n$

DFT: N^2

FFT: $N \log N \rightarrow$ Fastest using Cooley-Tukey Algorithm

Image enhancement & filtering in Freq. Domain

→ Low pass filters:

→ Inverse of product of F & m

$$F^{-1} \{ F \cdot m \}$$

→ Matrix m where threshold

$$m(x,y) = \begin{cases} 1, & \text{if } (x,y) \text{ is closer to center than} \\ 0, & \text{" " " further than threshold} \end{cases}$$

Sharp filter cutoff can cause ringing effect

→ Gaussian filtering:

→ Can be applied in freq. domain

→ Similar steps as done in spatial domain

↳ Create filter

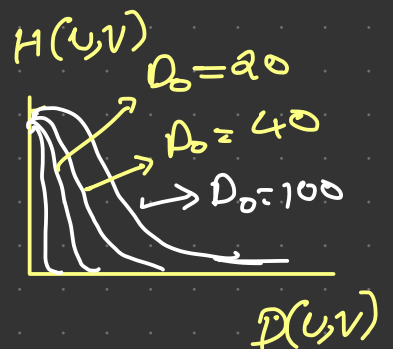
↳ Multiply DFT of img with filter

↳ Invert result

→ F.T of Gaussian = Gaussian

→ Gaussian low pass filters

(GLPF) $H(u,v) = e^{-D^2(u,v)/2D_0^2}$



→ Ideal high pass filtering

→ Opposite of low pass filtering [removes center (low freq. values)]

→ Causes SHARPENING

→ If using circle, size effects

↳ Higher cutoff \Rightarrow More info. removed