# Robotic Manipulation Exercise Practicalities

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## Exercise session overview

- Exercise sessions every Wednesday 08:15-10:00 in TU3 and Thursday
   10:15-12:00 in AS3.
- Voluntary presence.
- Bring your own laptops to these sessions.
- Teacher assistants (TAs) present to help you.

## Requirements

- A Linux system (we provide and support Ubuntu 18.04 with installed ROS on that)
- ROS Melodic (<a href="http://wiki.ros.org/melodic/Installation/Ubuntu">http://wiki.ros.org/melodic/Installation/Ubuntu</a>)
- Catkin tools https://catkin-tools.readthedocs.io/en/latest/installing.html
- MoveIt! For Melodic: <a href="https://moveit.ros.org/install/">https://moveit.ros.org/install/</a>
- The MuJoCo simulator *mujoco200 linux*: <a href="https://www.roboti.us/">https://www.roboti.us/</a>
- The MuJoCo license found in MyCourses under "For Aalto users". **IMPORTANT**: The license is for **personal use only** and cannot be redistributed!
- You can download an already configured virtual machine including the above programs except MuJoCo.

## Communication

- The preferred means of communication is the course slack channel (<u>roboticmanip2020.slack.com</u>)(<u>joinable slack link</u>) and not email.
- When you sign up to the slack workspace use your aalto username as the Nick name as we will link this to your gitlab repository.
- If you have specific problems with your code do not send it over email or slack.

  Instead, tell us that you have some problems and push your latest commits to the gitlab repository and we will pull it from there and start investigating.
- Usually more than one student have similar problems and thus we advocate
  asking questions in the exercise slack channels to enable students to help each
  other out.
- TAs and the lecturer will, per default, not answer emails or slack messages during the weekends.

## Exercises

#### In total six problems:

- Introduction to ROS.
- Simple pick and place with Movelt
- Planning algorithms benchmark in Movelt
- Visual perception
- roscontrol
- Dual-arm manipulation

## Tentative exercise schedule

The exercises are introduced on the following exercise sessions:

- 15th of January intro to exercise 1
- 22nd of January intro to exercise 2
- 5th of February intro to exercise 3
- 19th of February intro to exercise 4
- 4th of March intro to ROS control
- 18th of March tutorial on exercise 6

The deadline would be two weeks after releasing each assignment.

## Submissions

- Each solution include at least source code written in C++ that solves the problem and for most of the exercises you also need to submit a report written in English.
- The report (saved as PDF) should answer the questions posed in the assignment which can, for example, be the following 1 Which planner is fastest and why? Plot the running times and answer the questions by comparing the algorithms
- If the exercise requires you to submit both a report and code you need to submit both. Otherwise, your solution will be rejected and you will be awarded with 0 points.
- Each student forks the exercise into their own gitlab group, solves the exercise there, and finally upload everything to the respective repository before deadline

# Grading

- If the exercise requires both code and a report the report accounts for 50% and the code for 50% of all points awarded for that exercise. Otherwise, one or the other accounts for 100% of the points.
- The code is graded based on correctness (0-100%).
- The report is graded based on:
  - Correctness (0-100%),
  - How well it is written (satisfactory, good, excellent).
  - We will grade both language and structure of the report. For example, the report should be
    easy to read and coherent, and you need to refer to all figures, tables etc. Think of every
    single report as a part of your future MSc. thesis
- TAs will push, to your gitlab repository, the grade and feedback for the given exercise.

## Exercise rules

- Exercises are handed in and done individually
- You are allowed to discuss the problems but not share solutions. No copying
  of exercises (neither code nor report). If we notice plagiarism it is reported
  and consequences follow.
- No late submissions are accepted.
- You are allowed to miss one exercise; although this will probably affect your grade negatively. Missing more than this requires a valid excuse such as a doctor's statement of you being ill.