# Meta Learning with Implicit Gradients

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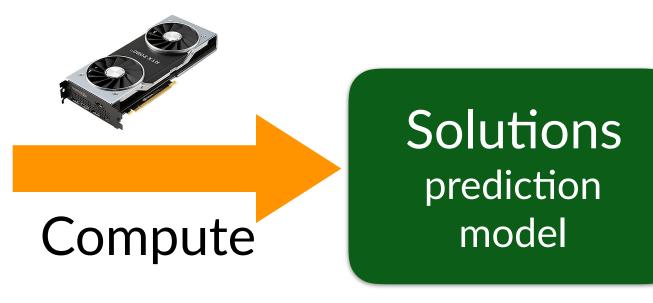
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#### Introduction

The standard machine learning paradigm







Successful if easy, cheap, and safe to collect large amount of data.

For many applications like robotics, user personalization, or low resource translation, big-data is non-existent, costly, or sensitive. Meta Learning: Learning algorithmic procedures which enable efficient learning of new tasks by encoding adaptable representations

# **Problem Setting**

task index (# tasks = N)

model (weights)

 $\theta$  meta parameters (init, Ir, #steps)  $\mathscr{L}$  loss function

learning algorithm (e.g. SGD)

task (training) dataset

$$\min_{\theta} \left\{ F(\theta) := \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}_i \left( \phi_i = \mathcal{A}(\mathcal{D}_i, \theta) \right) \right\}$$

Learn a set of meta parameters  $\theta^*$ that make  $\mathcal{A}$  behave efficiently

$$\nabla_{\theta} \mathcal{L}_{i}(\theta) = \frac{d\phi_{i}}{d\theta} \nabla_{\phi} \mathcal{L}_{i}(\phi_{i})$$

For new task $(\tau)$ :  $\phi_{\tau} = \mathcal{A}(\mathcal{D}_{\tau}, \theta^*)$  hard to compute, easy to compute

Idea: Optimize  $F(\theta)$  through gradient based iterative algorithms.

**Requirement:** Efficient computation of task meta-gradients  $\nabla_{\theta} \mathcal{L}_i(\theta)$ 

MAML [1]: Backpropagate through the iterative steps of  $\mathcal{A}$ 

- Restricts algorithms: each atomic operation needs to be first order and differentiable (no line-search, trust-region, randomization)
- Memory complexity is linear in the length of  $\mathcal{A}$  (can't optimize well)
- Vanishing gradients when backpropagating through long paths

## The Implicit MAML Algorithm

Interpret as bi-level optimization and use implicit function theorem

Short hands :  $\mathscr{L}_i(\phi) \equiv \mathscr{L}_i(\phi, \mathscr{D}_i^{test})$  and  $\hat{\mathscr{L}}_i(\phi) \equiv \mathscr{L}_i(\phi, \mathscr{D}_i^{tr})$ 

$$\min_{\theta} F(\theta) := \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}_i \left( \mathcal{A}_i^*(\theta) \right) \text{ where }$$

$$\mathcal{A}_i^*(\theta) := \arg\min_{\phi} G_i(\phi, \theta) = \hat{\mathcal{L}}_i(\phi) + \frac{\lambda}{2} \|\phi - \theta\|_2^2$$

Regularization leads to non-vanishing gradient and analytical expression

**Lemma** (Implicit gradient): Let  $\phi_i^* := \mathscr{A}_i^*(\theta)$ . Then, we have

$$\nabla_{\theta} \mathcal{L}_{i}(\theta) = \left(I + \frac{1}{\lambda} \nabla_{\phi}^{2} \hat{\mathcal{L}}_{i}(\phi_{i}^{*})\right)^{-1} \nabla_{\phi} \mathcal{L}_{i}(\phi_{i}^{*})$$

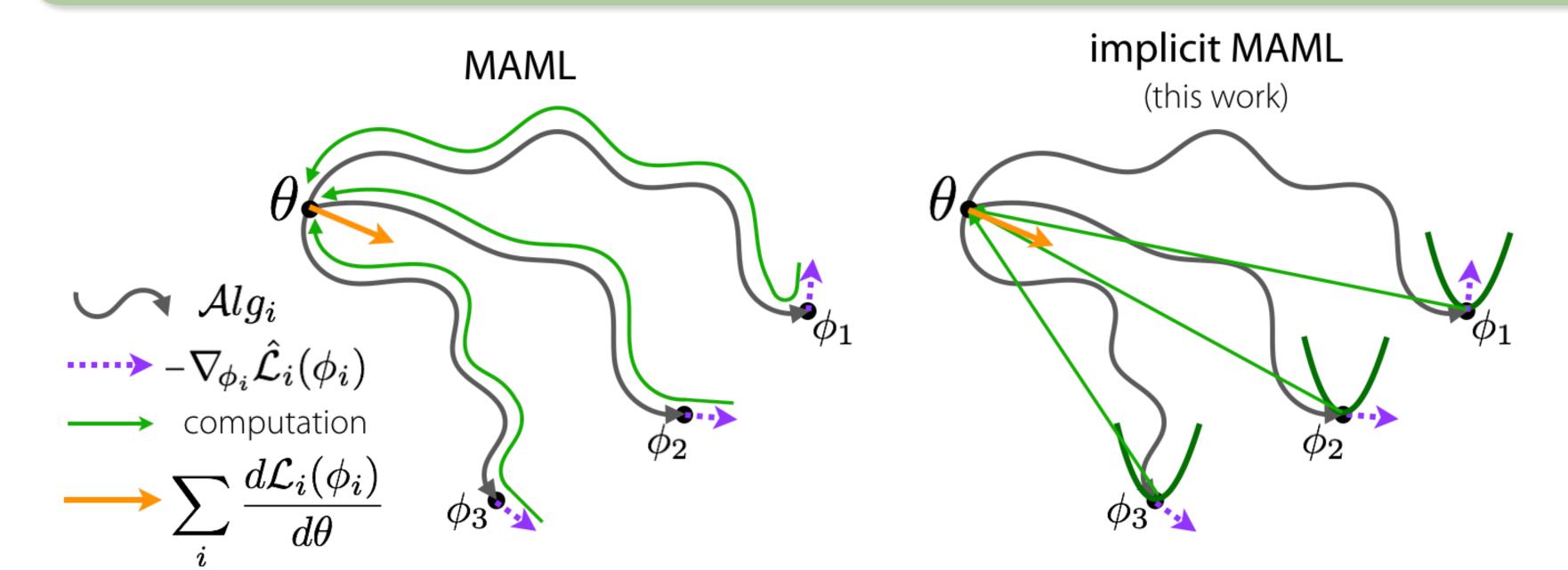
Note: The gradient depends only on the result of  ${\mathscr A}$  and not the path!

#### Practical Algorithm (Implicit MAML or iMAML)

- 1. Solve inner optimization approximately to find  $\|\phi_i \phi_i^*\| \leq \delta$
- 2. Approximately find meta-gradient using conjugate gradient algorithm that requires only Hessian-vector products to get

$$\|g_i - \left(I + (1/\lambda) \nabla_{\phi}^2 \hat{\mathcal{L}}_i(\phi_i)\right)^{-1} \nabla_{\phi} \mathcal{L}_i(\phi_i)\| \le \delta$$

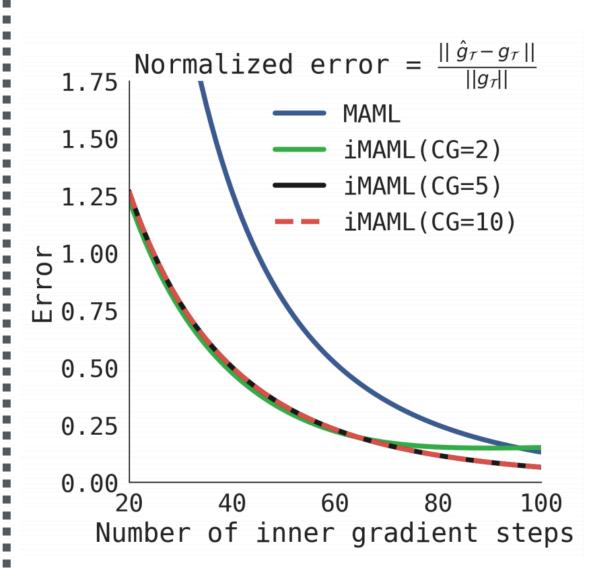
**Theorem** (error is controllable) If  $G_i(\phi, \theta)$  is strongly convex in  $\phi$ , for above algorithm, we have bounded error  $||g_i - \nabla_{\theta} \mathcal{L}_i(\theta)|| \leq O(\delta)$ 



**Table:** Compute and memory complexity. D = diameter,  $\kappa$  = condition number of inner level.  $\dagger$  compares with  $\mathscr{A}$ , while \* compares with  $\mathscr{A}^*$ 

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Algorithm	Compute	Memory	Error
MAML (GD + full back-prop)	$\kappa \log \left( rac{D}{\delta}  ight)$	$Mem( abla \hat{\mathcal{L}}_i) \cdot \kappa \ \log\left(rac{D}{\delta} ight)$	$O^{\dagger}$
MAML (Nesterov's AGD + full back-prop)	$\sqrt{\kappa}\log\left(rac{D}{\delta} ight)$	$Mem( abla \hat{\mathcal{L}}_i) \cdot \sqrt{\kappa} \ \log\left(rac{D}{\delta} ight)$	$0^{\dagger}$
Truncated back-prop (GD) [2]	$\kappa \log \left( rac{D}{\delta}  ight)$	$Mem( abla \hat{\mathcal{L}}_i) \cdot \kappa \ \log\left(rac{1}{\epsilon} ight)$	$\epsilon^{\dagger}$
Implicit MAML (this work)	$\sqrt{\kappa}\log\left(\frac{D}{\delta}\right)$	$Mem( abla \hat{\mathcal{L}}_i)$	$\delta^*$

### Experiments



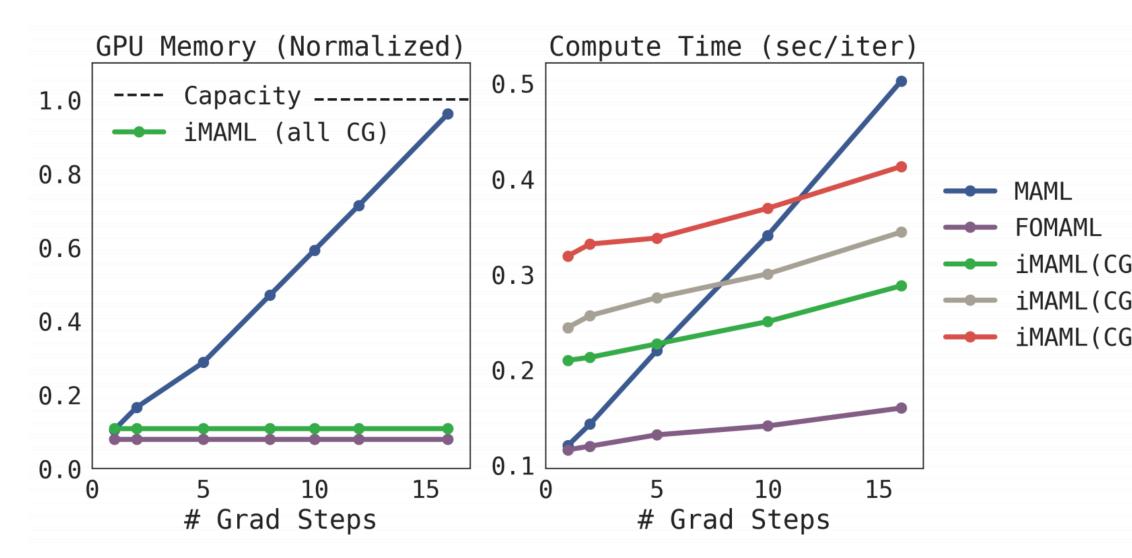


Figure: (left) MAML and iMAML computation vs exact meta-gradient on a synthetic example. (right) Compute and memory on 20-way-5-shot Omniglot

**Table:** Comparison of algorithms on Omniglot. Gradient descent (GD) and Hessian-Free (w/ line-search) algorithms considered for  $\mathcal{A}$ .  $\lambda=2.0$  and CG=5

Algorithm	5-way 1-shot	5-way 5-shot	20-way 1-shot	20-way 5-shot
MAML [15]	$98.7 \pm 0.4\%$	$\textbf{99.9} \pm \textbf{0.1\%}$	$95.8 \pm 0.3\%$	$98.9 \pm 0.2\%$
first-order MAML [15]	$98.3 \pm 0.5\%$	$99.2 \pm 0.2\%$	$89.4 \pm 0.5\%$	$97.9 \pm 0.1\%$
Reptile [43]	$97.68 \pm 0.04\%$	$99.48 \pm 0.06\%$	$89.43 \pm 0.14\%$	$97.12 \pm 0.32\%$
iMAML, GD (ours)	$99.16 \pm 0.35\%$	$99.67 \pm 0.12\%$	$94.46 \pm 0.42\%$	$98.69 \pm 0.1\%$
iMAML, Hessian-Free (ours)	$99.50 \pm 0.26\%$	$99.74 \pm 0.11\%$	$96.18 \pm 0.36\%$	$99.14 \pm 0.1\%$

#### Summary

- No vanishing meta-gradients due to use of regularization
- Meta-gradient depends only on final result of algorithm, not path
- Wider class of algorithms are supported by implicit MAML
- Implicit MAML is provably efficient in computation and memory, provably convergent, and leads to empirical gains on benchmarks
- FOMAML and Reptile are CG=0 approximations of iMAML

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