# **Optimality cuts**

using JuMP , GLPK , NLPModels , NLPModelsJuMP

using DataFrames

## general type

$$heta \geq e_l - E_l x$$

$$e = \sum_{i=1}^K p_i \lambda_i h_i$$

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- **p** comes from problem description
- $\lambda$  comes from solving the sub problem
- h and T are coming from sub problem with no solution

# Example

# Stage 1

$$egin{aligned} \min 100x_1 + 150x_2 \ & x_1 + x_2 \leq 120 \ & -x_1 \leq -40 \ & -x_2 \leq -20 \end{aligned}$$

```
begin
c1 = [100 ; 150]
A1 = [1 1 ; -1 0 ; 0 -1]
b1 = [120 ; -40 ; -20]
main = Model(GLPK.Optimizer)
Qvariable(main, x[1:2])
Qvariable(main, -1000 ≤ θ)
Qobjective(main, Min, c1' * x + θ)
Qconstraint(main, A1 * x .≤ b1)
optimize!(main)
x = value.(x)
```

## sub problem 1

end

$$egin{aligned} \min -24y_1 - 28y_2 \ &6y_1 + 10y_2 - 60x_1 \leq 0 \ &8y_1 + 5y_2 - 80x_2 \leq 0 \ &y_1 \leq 500 \ &y_2 \leq 100 \end{aligned}$$

### sub problem 2

$$egin{aligned} \min -28y_1 - 32y_2 \ &6y_1 + 10y_2 - 60x_1 \leq 0 \ &8y_1 + 5y_2 - 80x_2 \leq 0 \ &y_1 \leq 300 \ &y_2 \leq 300 \end{aligned}$$

```
solve_sub (generic function with 1 method)
 function solve_sub()
       \lambda = zeros(2,4)
       for i in 1:I
            sub = Model(GLPK.Optimizer)
            @variable(sub, 0 \le y[1:2])
            Qobjective(sub, Min, c2[i, :]' * y)
            Qconstraint(sub, \underline{A2} * y + \underline{A3} * \underline{x} \le \underline{b2}[i, :])
            optimize!(sub)
            all_cons = all_constraints(sub, AffExpr, MOI.LessThan{Float64})
            \lambda[i, :] = dual.(all\_cons)
       end
       return \lambda
 end
2×4 Matrix{Float64}:
 0.0 -3.0 0.0 -13.0
 -2.32 -1.76 0.0
                        0.0
 solve_sub()
no_solve_sub = no_solve_sub (generic function with 1 method)
 no_solve_sub = function no_solve_sub()
       T = zeros(2,4)
       h = zeros(2,4)
       for i in 1:I
            sub = Model(GLPK.Optimizer)
            @variable(sub, x[1:2])
            @variable(sub, 0 \le y[1:2])
```

```
no_solve_sub = function no_solve_sub()

T = zeros(2,4)

h = zeros(2,4)

for i in 1:I

sub = Model(GLPK.Optimizer)

@variable(sub, x[1:2])

@variable(sub, 0 \le y[1:2])

@objective(sub, Min, c2[i , :]' * y)

@constraint(sub, A2 * y + A3 * x .\le b2[i , :])

nlp = MathOptNLPModel(sub)

l = zeros(nlp.meta.nvar)

h[i , :] = nlp.meta.ucon

#all_var = all_variables(sub)

#var_index = [all_var[s].index.value for s in 1:length(all_var)]

#df = DataFrame(varName = all_var , varIndex = var_index)

T = Matrix(jac(nlp,l))[: , 1:2]

end

return (T, h, all_var)

end
```

#### UndefVarError: all\_var not defined

```
1. no_solve_sub() @ { Other: 18
2. top-level scope @ { Local: 1 [inlined]
```

```
• no_solve_sub()[3]
```