Aggregating Algorithm

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Declaration

This report has been prepared on the basis of my own work. Where other published and unpublished source materials have been used, these have been acknowledged.

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Abstract

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1 Introduction (1,000) (728)

1.1 Project Scope and Objectives (205)

The aim of this project is to implement methods of Prediction with Expert Advice, such as the Aggregating Algorithm, and to evaluate their performance in different scenarios, specifically targeting real-world applications.

As an introduction to the concepts explored in the chapters to come, these methods allow for the pooling of different prediction algorithms (known as 'experts') with the goal of improving prediction accuracy—allowing the final prediction to be nearly as accurate as the best-performing expert.

This project will encompass several key areas, including:

- Explaining the Theory of Prediction with Expert Advice. To effectively experiment with different methods of Prediction with Expert Advice, the underlying theory must first be understood by conducting a review of the relevant literature.
- Implementing the Aggregating Algorithm. This project will primarily investigate the Aggregating Algorithm introduced by Vovk (see [1], [2]).
- Handling Specialist Experts. Introduced by Freund [3], Specialist Experts may refrain from making predictions at certain points, meaning that the Aggregating Algorithm has to be modified slightly [4].
- Applying Prediction with Expert Advice to Real-World Data. The methods described in this report will be applied to real-world datasets in order to evaluate their practicality outside of theoretical models, including an investigation into the perception of randomness by utilising specialist experts.

1.2 Motivation and Interest in the Subject Area (261)

The motivation for selecting a project in this subject area is rooted in both my personal and professional interests, as well as the discussions I had with my now-supervisor, Dr. Yuri Kalnishkan, before finalising my selection.

During this academic year, the module that most piqued my interest was CS5200 – On-line Machine Learning because I was interested in the techniques that allowed machine learning models to gradually improve over time as more data became available to them without the need to retrain the model on the entire newly-updated dataset; something that had not been

covered previously by other modules. Due to the module's small size and frequent absentees, I was able to gain a deeper understanding of the module, in large part due to Dr. Kalnishkan's willingness to explain portions of the syllabus in extreme detail. Alongside the lectures, I felt like I was strongly suited to the contents of the module because it has strong ties to the field of statistics – another area that I thoroughly enjoyed throughout my education.

Regarding my professional aspirations, I am set to begin my career later this year and I am of the firm belief that the work that I have done in this subject area is highly relevant, not only to the job I am to start in September, but also for my career plan due to its relevance across a variety of industries – including finance, energy, and insurance.

Ultimately, the combination of all of these factors led me to pursue a project investigating on-line prediction, and prediction with expert advice.

1.3 Structure of the Dissertation (262)

The dissertation is split into distinct chapters, each dedicated to exploring a specific aspect of the work. The following outline guides the reader through the report by providing a brief overview of the contents of each chapter.

Chapter 2 through 5 contain a literature review organised to explain the concepts that the practical portion of the dissertation aims to explore. Chapter 2 defines the problem of On-line Prediction, outlining the scenarios that it applies to, and the protocols that such problems follow. Additionally, it explores how on-line learning differs from traditional batch learning and defines concepts that will be critical to understanding the following sections. Chapter 3 introduces the problem of Prediction with Expert Advice, explaining its significance and applications in the real world, as well as exploring some algorithms that are used to solve such problems – including their theoretical bounds. Chapter 4 introduces the Aggregating Algorithm that this report is centred around, exploring how it differs from other methods of Prediction with Expert Advice. Chapter 5 focuses on Specialist Experts, defining what they are and how the base Aggregating Algorithm must be modified to accommodate them.

Chapter 6 contains the practical portion of the dissertation, explaining how the research problem was handled based on the concepts explored in the literature review, the findings from conducting the requirements analysis and design processes, and the results found when comparing an individual's idea of "random" to that of a random number generator.

Finally, Chapter 7 contains a conclusion which discusses the findings of the investigation as well as a self-evaluation of the project.

2 Literature Review

2.1 Introduction

Purpose: Overview of the goals of the literature review.

Scope: Outline of the topics covered and their relevance to the dissertation.

2.2 Perceived Randomness

2.2.1 Introduction to Perceived Randomness

Definition: Explanation of what perceived randomness is.

Importance: Discussion on why perceived randomness is significant in various fields.

2.2.2 Randomness in Binary Sequences

Human vs. Algorithmic Generation

Human Perception: How humans perceive randomness.

Algorithmic Methods: Comparison of human and algorithmic sequence generation.

Methods for Generating Sequences

Techniques: Different methods for generating binary sequences.

Comparative Analysis: Evaluation of these methods in terms of perceived randomness.

2.3 Prediciton with Expert Advice

2.3.1 Introduction to On-line Prediction

Within the areas of Machine Learning and Statistics, there lies the problem of accurately "predicting future events based on past observations" [5] known as on-line prediction. This problem refers to methods where a model makes predictions sequentially and updates its parameters in real-time as new data points become available. There is a particular class of algorithm that is designed to tackle this, with one of the most notable being the "Strong" Aggregating Algorithm proposed by Volodymyr Vovk [1] which forms the basis of this study. The adjective "Strong" is emphasised with inverted commas to help distinguish the algorithm from the "Weak" Aggregating Algorithm proposed by Yuri Kalnishkan and Michael Vyugin [6] that will be touched upon but not explored in detail in this dissertation.

Given that the foundations of this dissertation lie firmly in this subject area, this section aims to lay a comprehensive foundation, exploring the key concepts and frameworks that will set the stage for the discussions in Chapter **TODO**.

On-line Prediction, Batch Learning and Timeseries Analysis

Herein the first distinction between on-line prediction and the traditional batch learning framework. With batch learning, a whole training set of labelled examples (x_i, y_i) is given to the learner at once in order to train a model. In contrast, on-line learning involves gradually feeding the learner information over time, requiring the model to continuously adapt to the new data it is given while requiring the learner to take actions on the basis of the information it already possesses instead of waiting for a complete picture. [4] This forced adaptability ensures that the predictions outputted by the algorithm remain accurate based on the information that the model deems as relevant as it gains additional knowledge, making these models particularly valuable in applications that require immediate responses and fluidity such as financial market analysis and weather forecasting.

Another distinction that needs to be made is between on-line prediction and timeseries analysis as, while these are both ways of handling sequential data in machine learning and statistics, they are unique. On-line learning is based on processing data points sequentially and updating predictive models in real-time whereas timeseries analysis is based on modelling and forecasting data that is collected over successive time intervals. The prior approach does not impose any strict assumptions about the underlying data-

generating process, even going so far as to not assume the existence of such a process [7], while the latter assumes a structured approach where observations are dependent on previous observations. These are typically modelled using stochastic processes such as autoregressive integrated moving average (ARIMA) or state-space models [8]. The majority of the literature on Online Prediction takes a similar stance that no assumptions can be made about the sequence of outcomes that are observed. Because of this, the analyses are done over the worst-case and may be better in reality [5].

Notation

In on-line prediction, we consider a scenario where the elements of a sequence, known as **outcomes**, ω_t occur at discrete times $\omega_1, \omega_2, \ldots$ which we assume to be drawn from a known **outcome space** Ω . In this problem, a learner is tasked with making **predictions** γ_t about these **outcomes** one at a time before they occur. Similarly, we assume that the learner's predictions are drawn from a known **prediction space** Γ which may or may not be the same as the **outcome space** Ω .

Once the learner has made their prediction, the true outcome is then revealed and the quality of the learner's prediction is assessed by a **loss** function $\lambda(\gamma_t, \omega_t)$. This function measures the discrepancy between the prediction and outcome or, more generally, quantifies the effect of when the prediction γ_t is confronted with the outcome ω_t [9] by mapping the input space $\Gamma \times \Omega$ to a subset of the real-number line \mathbb{R} , typically $[0, +\infty)$ [10].

Across several time steps T, the learner will suffer multiple losses which can be referred to as their cumulative loss up to time T. Their performance is measured by this cumulative loss, so their natural objective is to suffer as low a cumulative loss as they can.

Protocol 1 On-line Prediction Framework

- 1: FOR $t = 1, 2, \dots$
- 2: learner L outputs $\gamma_t \in \Gamma$
- 3: nature outputs $\omega_t \in \Omega$
- 4: learner L suffers loss $\lambda(\gamma_t, \omega_t)$
- 5: END FOR

2.3.1.1 Games and Mixability

The combination of a prediction space, outcome space, and loss function can be referred to with a triple $\langle \Gamma, \Omega, \lambda \rangle$, known as a **Game** G. TODO: Explain mixability and touch on (Kalnishkan & Vyugin, 2008) [6]

Prediction with Expert Advice

Framework: Description of the prediction with expert advice framework. **Mechanisms:** Detailed explanation of how this framework operates.

Protocol 2 Prediction with Expert Advice Framework

```
1: FOR t = 1, 2, \dots
```

- experts E_1, \ldots, E_N output predictions $\gamma_t^1, \ldots, \gamma_t^N \in \Gamma$ 2:
- learner L outputs $\gamma_t \in \Gamma$ 3:
- nature outputs $\omega_t \in \Omega$ 4:
- experts E_1, \ldots, E_N suffer losses $\lambda(\gamma_t^1, \omega_t), \ldots, \lambda(\gamma_t^N, \omega_t)$ 5:
- learner L suffers loss $\lambda(\gamma_t, \omega_t)$
- 7: END FOR

Aggregating Algorithm (AA) 2.3.3

Algorithm Description: Introduction to the Aggregating Algorithm. Functionality: How the Aggregating Algorithm works in practice.

Algorithm 1 Aggregating Algorithm (AA)

- 1: initialise weights $w_0^i = q_i, i = 1, 2, \dots, N$
- 2: FOR t = 1, 2, ...
- read the experts' predictions $\gamma_t^i, i = 1, 2, \dots, N$ 3:
- normalise the experts' weights $p_{t-1}^i = w_{t-1}^i / \sum_{j=1}^N w_{t-1}^j$ 4:
- output $\gamma_t \in \Gamma$ that satisfies the inequality for all $\omega \in \Omega$: $\lambda(\gamma_t, \omega) \leq -\frac{C}{\eta} \ln \sum_{i=1}^N p_{t-1}^i e^{-\eta \lambda(\gamma_t^i, \omega)}$ observe the outcome ω_t 5:
- 6:
- update the experts' weights $w_t^i = w_{t-1}^i e^{-\eta \lambda(\gamma_t^i, \omega_t)}, i = 1, 2, \dots, N$ 7:
- 8: END FOR

$$\operatorname{Loss}_{T}(L) \leq C \cdot \operatorname{Loss}_{T}(\mathcal{E}_{i}) + \frac{C}{\eta} \ln \frac{1}{q_{i}}$$
(1)

- 2.3.3.1Weak Aggregating Algorithm (WAA)
- 2.3.3.2Fixed Share Algorithm

2.3.4Aggregating Algorithm for Specialist Experts (AASE)

Specialisation: Differences between general and specialist experts. **Algorithm Adaptation:** How the Aggregating Algorithm is adapted for specialist experts.

Algorithm 2 Aggregating Algorithm for Specialist Experts (AASE)

- 1: initialise weights $w_0^i = q_i, i = 1, 2, \dots, N$
- 2: FOR t = 1, 2, ...
- read the awake experts' predictions $\gamma_t^i, i = 1, 2, \dots, N$ 3:
- normalise the awake experts' weights 4:

$$p_{t-1}^i = w_{t-1}^i / \sum_{j:\mathcal{E}_i \text{ is awake }} w_{t-1}^j$$

 $\begin{array}{l} p_{t-1}^i = w_{t-1}^i / \sum_{j:\mathcal{E}_j \text{ is awake}} w_{t-1}^j \\ \text{output } \gamma_t \in \Gamma \text{ that satisfies the inequality for all } \omega \in \Omega \text{:} \\ \lambda(\gamma_t, \omega) \leq -\frac{C}{\eta} \ln \sum_{i:E_i \text{ is awake}} p_{t-1}^i e^{-\eta \lambda(\gamma_t^i, \omega)} \\ \text{observe the outcome } \omega_t \end{array}$ 5:

$$\lambda(\gamma_t,\omega) \leq -rac{C}{n}\ln\sum_{i:E_i ext{ is awake}} p_{t-1}^i e^{-\eta\lambda(\gamma_t^i,\omega)}$$

- 6:
- update the awake experts' weights $w_t^i = w_{t-1}^i e^{-\eta \lambda(\gamma_t^i,\omega_t)}$ 7:
- update the sleeping experts' weights $w_t^i = w_{t-1}^i e^{-\eta \lambda(\gamma_t, \omega_t)/C(\eta)}$ 8:
- 9: END FOR

The learner following this algorithm achieves loss that satisfies:

$$\sum_{\substack{t=1,2,\dots,T:\\\mathcal{E}_i \text{ is awake}\\\text{on step } t}}^T \lambda(\gamma_t,\omega_t) \le C \cdot \sum_{\substack{t=1,2,\dots,T:\\\mathcal{E}_i \text{ is awake}\\\text{on step } t}}^T \lambda(\gamma_t^i,\omega_t) + \frac{C}{\eta} \ln \frac{1}{q_i}$$
 (2)

2.4 Conclusions

Summary: Recap of key points covered in the literature review.

Implications: Implications of the reviewed literature for the current study.

3 On-line Prediction (1,250)

3.1 Introduction (125)

Within the scope of Machine Learning, there is a particular class of algorithms which can be used to make accurate predictions about the future based on past sequential data. One of the most notable among these is the "Strong" Aggregating Algorithm proposed by Volodymyr Vovk [1] which is a powerful algorithm designed for On-line Prediction, specifically catering to the framework of Prediction with Expert Advice. The "strong" adjective is used purposefully in this context to distinguish it from the "Weak" Aggregating Algorithm proposed by Yuri Kalnishkan and Michael Vyugin [6]. Given that the basis of discussion within this dissertation is focussed around this subject matter, this chapter aims to lay a comprehensive foundation of the key concepts before delving into them further in the chapters to come.

3.2 Preliminaries (54)

We begin by defining the On-line Prediction framework. On-line Prediction is a "central problem in statistics and machine learning" that is concerned with "predicting future events based on past observations." [5] It refers to a method in which a model makes predictions sequentially and updates its parameters in real-time as new data points become available.

On-line Prediction and Batch Learning (145)

This marks the first distinction between on-line prediction and the traditional batch learning framework because on-line prediction requires approaches and algorithms that are significantly different. With batch learning, a whole training set of labelled examples (x_i, y_i) is given to the learner at once in order to train a model. In contrast, on-line learning involves gradually feeding the learner information over time, requiring the model to continuously adapt to the new data it is given while requiring the learner to take actions on the basis of the information it already possesses instead of waiting for a complete picture. [4] This forced adaptability ensures that the predictions outputted by the algorithm remain accurate based on the information that the model deems as relevant as it gains additional knowledge, making these models particularly valuable in applications that require immediate responses and fluidity such as financial market analysis and weather forecasting.

On-line Prediction and Timeseries Analysis (167)

Another distinction that needs to be made is between on-line prediction and timeseries analysis as, while these are both ways of handling sequential data in machine learning and statistics, they are unique. On-line learning is based on processing data points sequentially and updating predictive models in real-time whereas timeseries analysis is based on modelling and forecasting data that is collected over successive time intervals. The prior approach does not impose any strict assumptions about the underlying datagenerating process, even going so far as to not assume the existence of such a process [7], while the latter assumes a structured approach where observations are dependent on previous observations. These are typically modelled using stochastic processes such as autoregressive integrated moving average (ARIMA) or state-space models [8]. The majority of the literature on Online Prediction takes a similar stance that no assumptions can be made about the sequence of outcomes that are observed. Because of this, the analyses are done over the worst-case and may be better in reality [5].

Notation (275)

We can now introduce the commonly-used notation for On-line Prediction. Consider the scenario where the elements of a sequence called **outcomes** ω_t occur sequentially in discrete time $\omega_1, \omega_2, \ldots$ which we assume are drawn from an **outcome space** Ω that is known beforehand.

A learner is tasked with predicting these *outcomes* one at a time by making **predictions** γ_t before they occur. Similarly, we assume that these predictions are drawn from a known **prediction space** Γ which may or may not be the same as the *outcome space* Ω .

Once the learner has made their prediction, the true outcome is then revealed and the quality of the learner's prediction is assessed by a **loss** function $\lambda(\gamma_t, \omega_t)$. This function measures the discrepancy between the prediction and outcome or, more generally, quantifies the effect of when prediction γ_t is confronted with the outcome ω_t [9] by mapping the input space $\Gamma \times \Omega$ to a subset real-number line \mathbb{R} , typically $[0, +\infty)$. In this scenario, γ_t can be thought of as the action taken in a situation of uncertainty and, as the uncertainty is lifted, the learner faces reality ω_t and faces the consequences of their action $\lambda(\gamma_t, \omega_t) : \Gamma \times \Omega \to [0, +\infty)$ [10].

Protocol 3 On-line Prediction Framework

1: FOR t = 1, 2, ...

2: learner outputs $\gamma_t \in \Gamma$

3: nature announces $\omega_t \in \Omega$

4: learner suffers loss $\lambda(\gamma_t, \omega_t)$

5: END FOR

Over multiple time steps T, the learner will suffer multiple losses which can be denoted as the cumulative loss up to time T. Their performance is measured by this cumulative loss, so a natural objective is to suffer as low a cumulative loss as it can.

$$Loss_T(L) = \sum_{t=1}^{T} \lambda(\gamma_t, \omega_t)$$
 (3)

Games (200)

A "Game" \mathcal{G} is the choice of triple $<\Gamma,\Omega,\lambda>$ describing a **prediction environment**. In this dissertation, we will only look at four common games—for more examples, see [2]. Binary Games is a term used for any game where $\Gamma=\Omega=[0,1]$. In such scenarios, there are two common loss functions to be considered.

- 1. Square (Brier's) Loss $\lambda_{SQ}(\gamma, \omega) = (\gamma \omega)^2$,
- 2. Absolute Loss $\lambda_{ABS}(\gamma, \omega) = |\gamma \omega|^2$

If we now consider the discrete binary game where $\Gamma = [0, 1]$ and $\Omega = \{0, 1\}$, a logarithmic loss function can be used.

3. Logarithmic Loss —
$$\lambda_{\text{LOG}}(\gamma, \omega) = \begin{cases} -\ln(1-\gamma) & \text{if } \omega = 0, \\ -\ln\gamma & \text{if } \omega = 1 \end{cases}$$

Finally, there is the simple prediction game where $\Gamma = \Omega = \{0, 1\}$, and loss function

4.
$$\lambda(\gamma, \omega) = \begin{cases} 0 & \text{if } \omega = \gamma, \\ 1 & \text{otherwise} \end{cases}$$

With such a game, the cumulative learner's loss $\text{Loss}_T(L)$ is equal to the number of mistakes made.

In this report, we are primarily concerned with the **Discrete Binary Square Loss Game**, i.e. $\Gamma = [0, 1], \Omega = \{0, 1\}, \lambda_{SQ}(\gamma, \omega) = (\gamma - \omega)^2$

3.3 Conclusion

4 Prediction with Expert Advice (1,250)

- Outcomes $(\omega_1, \omega_2, ...)$ happen in sequence. All outcomes come from an outcome space, $\omega \in \Omega$. In the Simple Prediction Game, $\Omega = \{0,1\}$, i.e. bits.
- Before we see any outcomes, we make a prediction γ_t . All predictions come from a prediction space $\gamma \in \Gamma$. In the Simple Prediction Game, $\Gamma = \{0,1\}$, i.e. bits.

Algorithm 3 Prediction with Expert Advice

```
1: FOR t = 1, 2, ...
```

- 2: the experts $E_1, ..., E_N$ output predictions $\gamma_t^1, ..., \gamma_t^N \in \Gamma$
- 3: the learner L outputs $\gamma_t \in \Gamma$
- 4: the nature outputs $\omega_t \in \Omega$
- 5: the experts $E_1, ..., E_N$ suffer losses $\lambda(\gamma_t^1, \omega_t), ..., \lambda(\gamma_t^N, \omega_t)$
- 6: the learner L suffers loss $\lambda(\gamma_t, \omega_t)$
- 7: END FOR

5 Aggregating Algorithm (2,500)

Describe the concept of the aggregating algorithm, its purpose, and how it synthesizes predictions from multiple experts to improve overall accuracy.

Algorithm 4 Aggregating Algorithm

```
1: initialise weights w_0^i = q_i, i = 1, 2, ..., N

2: FOR t = 1, 2, ...

3: read experts' predictions \gamma_t^i, i = 1, 2, ..., N

4: normalise the weights p_{t-1}^i = w_{t-1}^i / \sum_{j=1}^N w_{t-1}^j

5: output \gamma_t \in \Gamma satisfying for all \omega \in \Omega the inequality \lambda(\gamma_t, \omega) \leq -\frac{C}{\eta} \ln \sum_{i=1}^N p_{t-1}^i e^{-\eta \lambda(\gamma_t^i, \omega)}

6: observe the outcome \omega_t
```

7: update the experts' weights $w_t^i = w_{t-1}^i e^{-\eta \lambda(\gamma_t^i, \omega_t)}, i = 1, 2, \dots, N$

8: END FOR

5.1 Weak Aggregating Algorithm

Explain the weak aggregating algorithm, its methodology, and its advantages. Discuss how it differs from stronger aggregating methods and its specific use cases.

5.2 Fixed Share Algorithm

Discuss the fixed share algorithm, its mechanics, and how it balances the use of different experts over time. Explain its relevance and application in dynamic environments.

5.3 Switching Experts

Analyze the strategy of switching between experts based on performance. Discuss the criteria for switching and its impact on prediction accuracy.

5.4 Specialist Experts & Sleeping Experts

Describe the role of specialist experts who focus on specific types of data or conditions. Discuss how their specialized knowledge enhances overall predictive performance.

Algorithm 5 Aggregating Algorithm for Specialist Experts (AASE)

```
1: initialise weights w_0^i = q_i, i = 1, 2, \dots, N
      FOR t = 1, 2, ...
3:
              read the predictions, \gamma_t^n, of awake experts
              normalise the weights of awake experts
4:
              \begin{array}{l} p_{t-1}^i = w_{t-1}^i / \sum_{i:E_i \text{ is awake}} w_{t-1}^i \\ \text{solve the system } (\omega \in \Omega): \end{array}
5:
                 \lambda(\gamma,\omega) \stackrel{\circ}{\leq} -\frac{C}{\eta} \ln \sum_{n:E_n \text{ is awake}}^{n} p_t^n e^{-\eta \lambda(\gamma_t^n,\omega)} w.r.t. \gamma and output a solution \gamma_t
6:
              observe the outcome \omega_t
              update the awake experts' weights w^n_t = w^n_{t-1} e^{-\eta \lambda(\gamma^n_t,\omega)}
7:
              update the sleeping experts' weights w_t^n = w_{t-1}^n e^{-\eta \lambda(\gamma_t,\omega)/C(\eta)}
8:
     END FOR
```

5.5 Comparison with Model Selection

Compare the approach of prediction with expert advice to traditional model selection methods. Highlight the advantages and limitations of each approach.

6 Specialist Experts (2,500)

First introduced in the work of Freund et al. [3], 'specialist experts' can be thought of as an extension to the traditional on-line prediction framework that allows 'experts' to abstain from making predictions.

These experts are referred to as 'specialists' because they can be thought of as only making predictions "when the instance to be predicted falls within their area of expertise." In such cases where the expert is actively making a prediction, the expert is deemed to be 'awake', and is 'asleep' otherwise.

A prediction algorithm may see that its internal confidence is low and decide to skip a turn in order to re-train. Alternatively, an algorithm may simply break down.

A natural idea for handling sleeping experts is to assume that a sleep expert "joins the crowd". Imagine that the sleeping expert sides with the learner and outputs the learner's prediction for that turn.

This modifies the Aggregating Algorithm, but that's to be discussed later!

In order to accommodate these 'specialist experts', we must modify the on-line prediction framework slightly. Similarly to the traditional framework, on-line learning with specialist experts can be thought of as a game that is played between a prediction algorithm, hereafter referred to as the 'learner', and an adversary, hereafter referred to as the 'nature'. The game is played in discrete iterations $t=1,\ldots,T$, consisting of the same five steps:

- 1. The nature chooses a set of specialists that are 'awake' at iteration t, $E_t \subseteq \{1, \ldots, N\}$.
- 2. For each 'awake' specialist in the set chosen by the nature, $i \in E_t$, a prediction for that discrete iteration is output, \hat{y}_i^t .
- 3. The learner makes its own prediction based on the predictions of each awake specialist, \hat{y}_t .
- 4. The nature chooses an outcome y_t .
- 5. The learner suffers loss $\ell_L^t = L(\hat{y}_t, y_t)$.
- 6. The 'awake' specialists suffer loss $\ell_i^t = L(\hat{y}_t^i, y_t)$ while specialists that are asleep suffer no loss.

- We still assume that there are N 'experts', some of which may be 'specialist', indexed from $\{1, \ldots, N\}$.
- Predictions and Outcomes are real-valued numbers from a bounded range [0, 1].
- Loss: $L: [0,1] \times [0,1] \to [0,\infty)$ associates a non-negative loss to each (prediction, outcome) pair.

To-Do

- How do we evaluate the performance of an algorithm?
 - In order to give the algorithm a meaningful bound, we compare the difference between the total loss of the algorithm and the total loss of the experts.
 - The total loss of the insomniac algorithm is compared against the loss of the best expert, but this doesn't make sense in this scenario because not all the experts are awake all the time, and may not make predictions.
 - Prove that the algorithm doesn't suffer large losses regardless of the adversary's strategy.
- How does this improve computational efficiency?
 - Discuss Problem Decomposition.
 - Naive algorithms make use of extremely large sets of experts which can make the calculation of predictions computationally expensive and infeasible.
 - By allowing for specialist experts, only a select handful of those experts make a prediction at a given time which can significantly reduce the computational load required.
- Discuss the applications of 'Specialist Experts'.
 - Markov Models
 - * Talk about your theory and what your implemented code is about!
 - Switching Experts

6.1 Applications of Specialist Experts

7 Practical (5,000)

8 Conclusion (1,500)

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