

# Modal logic for concurrent processes: the $\mu$ -calculus

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# Is Hennessy-Milner logic expressive enough?

## Is Hennessy-Milner logic expressive enough?

- It cannot detect deadlock in an arbitrary process
- or general *safety*: all reachable states verify  $\phi$
- or general *liveness*: there is a reachable states which verifies  $\phi$
- ...

... essentially because

formulas in cannot see deeper than their modal depth

# Is Hennessy-Milner logic expressive enough?

## Example

$\phi$  = a taxi eventually returns to its Central

$$\phi = \langle \text{reg} \rangle \text{true} \vee \langle - \rangle \langle \text{reg} \rangle \text{true} \vee \langle - \rangle \langle - \rangle \langle \text{reg} \rangle \text{true} \vee \langle - \rangle \langle - \rangle \langle - \rangle \langle \text{reg} \rangle \text{true} \vee \dots$$

# Revisiting Hennessy-Milner logic

## Adding regular expressions

ie, with regular expressions within modalities

$$\rho ::= \epsilon \mid \alpha \mid \rho.\rho \mid \rho + \rho \mid \rho^* \mid \rho^+$$

where

- $\alpha$  is an **action formula** and  $\epsilon$  is the **empty word**
- **concatenation**  $\rho.\rho$ , **choice**  $\rho + \rho$  and **closures**  $\rho^*$  and  $\rho^+$

## Laws

$$\langle \rho_1 + \rho_2 \rangle \phi = \langle \rho_1 \rangle \phi \vee \langle \rho_2 \rangle \phi$$

$$[\rho_1 + \rho_2] \phi = [\rho_1] \phi \wedge [\rho_2] \phi$$

$$\langle \rho_1.\rho_2 \rangle \phi = \langle \rho_1 \rangle \langle \rho_2 \rangle \phi$$

$$[\rho_1.\rho_2] \phi = [\rho_1][\rho_2] \phi$$

# Revisiting Hennessy-Milner logic

## Examples of properties

- $\langle \epsilon \rangle \phi = [\epsilon] \phi = \phi$
- $\langle a.a.b \rangle \phi = \langle a \rangle \langle a \rangle \langle b \rangle \phi$
- $\langle a.b + g.d \rangle \phi$

## Safety

- $[-^*] \phi$
- it is impossible to do two consecutive enter actions without a leave action in between:  
 $[-^*.enter. - leave^*.enter] false$
- absence of **deadlock**:  
 $[-^*] \langle - \rangle true$

# Revisiting Hennessy-Milner logic

## Examples of properties

### Liveness

- $\langle -^* \rangle \phi$
- after sending a message, it can eventually be received:  
 $[send] \langle -^*.receive \rangle true$
- after a send a receive is possible as long as an exception does not happen:  
 $[send. - excp^*] \langle -^*.receive \rangle true$

# The modal $\mu$ -calculus

- modalities with regular expressions are not enough in general
- ... but correspond to a subset of the modal  $\mu$ -calculus [Kozen83]

Add explicit *minimal/maximal fixed point operators* to Hennessy-Milner logic

$\phi ::= X \mid \text{true} \mid \text{false} \mid \neg\phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid \phi \rightarrow \phi \mid \langle a \rangle \phi \mid [a] \phi \mid \mu X. \phi \mid \nu X. \phi$

# The modal $\mu$ -calculus

## The modal $\mu$ -calculus (intuition)

- $\mu X. \phi$  is valid for all those states in the *smallest* set  $X$  that satisfies the equation  $X = \phi$  (finite paths, **liveness**)
- $\nu X. \phi$  is valid for the states in the *largest* set  $X$  that satisfies the equation  $X = \phi$  (infinite paths, **safety**)

### *Warning*

In order to be sure that a fixed point exists,  $X$  must occur positively in the formula, ie **preceded by an even number of negations**.



# Temporal properties as limits

## Example

$$A \triangleq \sum_{i \geq 0} A_i \quad \text{with} \quad A_0 \triangleq \mathbf{0} \text{ e } A_{i+1} \triangleq a.A_i$$

$$A' \triangleq A + D \quad \text{with} \quad D \triangleq a.D$$

- $A \approx A'$
- but there is no modal formula to distinguish  $A$  from  $A'$
- notice  $A' \models \langle a \rangle^{i+1} \text{true}$  which  $A_i$  fails
- a distinguishing formula would require **infinite** conjunction
- what we want to express is the possibility of doing  $a$  in **the long run**

# Temporal properties as limits

idea: introduce recursion in formulas

$$X \triangleq \langle a \rangle X$$

meaning?

- the **recursive** formula is interpreted as a *fixed point* of function

$$|\langle a \rangle|$$

in  $\mathcal{PP}$

- i.e., the *solutions*,  $S \subseteq \mathbb{P}$  such that of

$$S = |\langle a \rangle|(S)$$

- how do we solve this equation?

# Solving equations ...

## over natural numbers

$$x = 3x \quad \text{one solution } (x = 0)$$

$$x = 1 + x \quad \text{no solutions}$$

$$x = 1x \quad \text{many solutions (every natural } x)$$

## over sets of integers

$$x = \{22\} \cap x \quad \text{one solution } (x = \{22\})$$

$$x = \mathbb{N} \setminus x \quad \text{no solutions}$$

$$x = \{22\} \cup x \quad \text{many solutions (every } x \text{ st } \{22\} \subseteq x)$$

## Solving equations ...

In general, for a *monotonic* function  $f$ , i.e.

$$X \subseteq Y \Rightarrow f X \subseteq f Y$$

### Knaster-Tarski Theorem [1928]

A monotonic function  $f$  in a complete lattice has a

- *unique maximal fixed point*:

$$\nu_f = \bigcup \{X \in \mathcal{PP} \mid X \subseteq f X\}$$

- *unique minimal fixed point*:

$$\mu_f = \bigcap \{X \in \mathcal{PP} \mid f X \subseteq X\}$$

- moreover the space of its solutions forms a complete lattice

## Back to the example ...

$S \in \mathcal{PP}$  is a *pre-fixed point* of  $|\langle a \rangle|$   
iff

$$|\langle a \rangle|(S) \subseteq S$$

Recalling,

$$|\langle a \rangle|(S) = \{E \in \mathbb{P} \mid \exists E' \in S . E \xrightarrow{a} E'\}$$

the set of sets of processes we are interested in is

$$\begin{aligned} Pre &= \{S \subseteq \mathbb{P} \mid \{E \in \mathbb{P} \mid \exists E' \in S . E \xrightarrow{a} E'\} \subseteq S\} \\ &= \{S \subseteq \mathbb{P} \mid \forall Z \in \mathbb{P} . (Z \in \{E \in \mathbb{P} \mid \exists E' \in S . E \xrightarrow{a} E'\} \Rightarrow Z \in S)\} \\ &= \{S \subseteq \mathbb{P} \mid \forall E \in \mathbb{P} . ((\exists E' \in S . E \xrightarrow{a} E') \Rightarrow E \in S)\} \end{aligned}$$

which can be characterized by predicate

$$(PRE) \quad (\exists E' \in S . E \xrightarrow{a} E') \Rightarrow E \in S \quad (\text{for all } E \in \mathbb{P})$$

## Back to the example ...

The set of *pre-fixed points* of

$$|\langle a \rangle|$$

is

$$\begin{aligned} Pre &= \{S \subseteq \mathbb{P} \mid |\langle a \rangle|(S) \subseteq S\} \\ &= \{S \subseteq \mathbb{P} \mid \forall_{E \in \mathbb{P}} . ((\exists_{E' \in S} . E \xrightarrow{a} E') \Rightarrow E \in S)\} \end{aligned}$$

- Clearly,  $\{A \triangleq a.A\} \in Pre$
- but  $\emptyset \in Pre$  as well

Therefore, its *least* solution is

$$\bigcap Pre = \emptyset$$

**Conclusion:** taking the **meaning** of  $X = \langle a \rangle X$  as the *least* solution of the equation leads us to equate it to *false*

... but there is another possibility ...

$S \in \mathcal{PP}$  is a *post-fixed point* of

$$|\langle a \rangle|$$

iff

$$S \subseteq |\langle a \rangle|(S)$$

leading to the following set of *post-fixed points*

$$\begin{aligned} Post &= \{S \subseteq \mathbb{P} \mid S \subseteq \{E \in \mathbb{P} \mid \exists_{E' \in S} . E \xrightarrow{a} E'\}\} \\ &= \{S \subseteq \mathbb{P} \mid \forall_{Z \in \mathbb{P}} . (Z \in S \Rightarrow Z \in \{E \in \mathbb{P} \mid \exists_{E' \in S} . E \xrightarrow{a} E'\})\} \\ &= \{S \subseteq \mathbb{P} \mid \forall_{E \in \mathbb{P}} . (E \in S \Rightarrow \exists_{E' \in S} . E \xrightarrow{a} E')\} \end{aligned}$$

(POST)     If  $E \in S$  then  $E \xrightarrow{a} E'$  for some  $E' \in S$      (for all  $E \in P$ )

- i.e., if  $E \in S$  it can perform  $a$  and this ability is maintained in its continuation

... but there is another possibility ...

- i.e., if  $E \in S$  it can perform  $a$  and this ability is maintained in its continuation
- the *greatest* subset of  $\mathbb{P}$  verifying this condition is the set of processes with at least an infinite computation

**Conclusion:** taking the **meaning** of  $X = \langle a \rangle X$  as the *greatest* solution of the equation characterizes the property **occurrence of  $a$  is possible**



## The general case

- The meaning (i.e., **set of processes**) of a formula  $X \triangleq \phi X$  where  $X$  occurs free in  $\phi$
- is a *solution* of equation

$$X = f(X) \quad \text{with} \quad f(S) = |\{S/X\}\phi|$$

in  $\mathcal{PP}$ , where  $|\cdot|$  is extended to formulae with variables by  $|X| = X$

## The general case

The Knaster-Tarski theorem gives precise characterizations of the

- *smallest* solution: the intersection of all  $S$  such that

$$(\text{PRE}) \quad \text{If } E \in f(S) \text{ then } E \in S$$

to be denoted by

$$\mu X . \phi$$

- *greatest* solution: the union of all  $S$  such that

$$(\text{POST}) \quad \text{If } E \in S \text{ then } E \in f(S)$$

to be denoted by

$$\nu X . \phi$$

In the previous example:

$$\nu X . \langle a \rangle \text{true}$$

$$\mu X . \langle a \rangle \text{true}$$

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# The modal $\mu$ -calculus: syntax

... Hennessy-Milner + **recursion** (i.e. fixed points):

$$\phi ::= X \mid \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \langle K \rangle \phi \mid [K] \phi \mid \mu X . \phi \mid \nu X . \phi$$

where  $K \subseteq Act$  and  $X$  is a set of propositional variables

- Note that

$$true \stackrel{abv}{=} \nu X . X \quad \text{and} \quad false \stackrel{abv}{=} \mu X . X$$

# The modal $\mu$ -calculus: denotational semantics

- Presence of variables requires models parametric on *valuations*:

$$V : X \rightarrow \mathcal{P}\mathbb{P}$$

- Then,

$$|X|_V = V(X)$$

$$|\phi_1 \wedge \phi_2|_V = |\phi_1|_V \cap |\phi_2|_V$$

$$|\phi_1 \vee \phi_2|_V = |\phi_1|_V \cup |\phi_2|_V$$

$$|[K]\phi|_V = |[K]|(|\phi|_V)$$

$$|\langle K \rangle \phi|_V = |\langle K \rangle|(|\phi|_V)$$

- and add

$$|\nu X. \phi|_V = \bigcup \{S \in \mathbb{P} \mid S \subseteq |[S/X]\phi|_V\}$$

$$|\mu X. \phi|_V = \bigcap \{S \in \mathbb{P} \mid |[S/X]\phi|_V \subseteq S\}$$

# Notes

where

$$|[K]|X = \{F \in \mathbb{P} \mid \text{if } F \xrightarrow{a} F' \wedge a \in K \text{ then } F' \in X\}$$

$$|\langle K \rangle|X = \{F \in \mathbb{P} \mid \exists_{F' \in X, a \in K} . F \xrightarrow{a} F'\}$$

# Modal $\mu$ -calculus

## Intuition

- look at modal formulas as set-theoretic combinators
- introduce mechanisms to specify their fixed points
- introduced as a generalisation of Hennessy-Milner logic for processes to capture **enduring** properties.

## References

- **Original reference:** *Results on the propositional  $\mu$ -calculus*, D. Kozen, 1983.
- **Introductory text:** *Modal and temporal logics for processes*, C. Stirling, 1996

# Notes

The modal  $\mu$ -calculus [Kozen, 1983] is

- *decidable*
- strictly *more expressive* than PDL and CTL\*

Moreover

- The *correspondence theorem* of the induced **temporal logic** with **bisimilarity** is kept



Example 1:  $X \triangleq \phi \vee \langle a \rangle X$

Look for fixed points of

$$f(X) \triangleq |\phi| \cup |\langle a \rangle|(X)$$

# Example 1: $X \triangleq \phi \vee \langle a \rangle X$

$$\begin{aligned}
 (\text{PRE}) \quad & \text{If } E \in f(X) \text{ then } E \in X \\
 \equiv \quad & \text{If } E \in (|\phi| \cup |\langle a \rangle|(X)) \text{ then } E \in X \\
 \equiv \quad & \text{If } E \in \{F \mid F \models \phi\} \cup \{F \in \mathbb{P} \mid \exists F' \in X . F \xrightarrow{a} F'\} \\
 & \text{then } E \in X \\
 \equiv \quad & \text{if } E \models \phi \vee \exists E' \in X . E \xrightarrow{a} E' \text{ then } E \in X
 \end{aligned}$$

The *smallest* set of processes verifying this condition is composed of processes with at least a computation along which  $a$  can occur *until*  $\phi$  holds. Taking its *intersection*, we end up with processes in which  $\phi$  holds in a *finite* number of steps.

# Example 1: $X \triangleq \phi \vee \langle a \rangle X$

$$\begin{aligned}
 (\text{POST}) \quad & \text{If } E \in X \text{ then } E \in f(X) \\
 \equiv \quad & \text{If } E \in X \text{ then } E \in (|\phi| \cup |\langle a \rangle|(X)) \\
 \equiv \quad & \text{If } E \in X \text{ then } E \in \{F \mid F \models \phi\} \cup \{F \in X \mid \exists F' \in X . F \xrightarrow{a} F'\} \\
 \equiv \quad & \text{If } E \in X \text{ then } E \models \phi \vee \exists E' \in X . E \xrightarrow{a} E'
 \end{aligned}$$

The *greatest* fixed point also includes processes which keep the possibility of doing  $a$  without ever reaching a state where  $\phi$  holds.

## Example 1: $X \triangleq \phi \vee \langle a \rangle X$

- *strong until*:

$$\mu X . \phi \vee \langle a \rangle X$$

- *weak until*

$$\nu X . \phi \vee \langle a \rangle X$$

Relevant particular cases:

- $\phi$  holds after internal activity:

$$\mu X . \phi \vee \langle \tau \rangle X$$

- $\phi$  holds in a finite number of steps

$$\mu X . \phi \vee \langle - \rangle X$$

## Example 2: $X \triangleq \phi \wedge \langle a \rangle X$

(PRE) If  $E \models \phi \wedge \exists_{E' \in X} . E \xrightarrow{a} E'$  then  $E \in X$

implies that

$$\mu X . \phi \wedge \langle a \rangle X \Leftrightarrow \text{false}$$

(POST) If  $E \in X$  then  $E \models \phi \wedge \exists_{E' \in X} . E \xrightarrow{a} E'$

implies that

$$\nu X . \phi \wedge \langle a \rangle X$$

denote all processes which verify  $\phi$  and have an *infinite* computation

## Example 2: $X \triangleq \phi \wedge \langle a \rangle X$

### Variant:

- $\phi$  holds along a finite or infinite  $a$ -computation:

$$\forall X. \phi \wedge (\langle a \rangle X \vee [a] \text{false})$$

### In general:

- *weak safety*:

$$\forall X. \phi \wedge (\langle K \rangle X \vee [K] \text{false})$$

- *weak safety*, for  $K = \text{Act}$  :

$$\forall X. \phi \wedge (\langle - \rangle X \vee [-] \text{false})$$

# Example 3: $X \triangleq [-]X$

(POST) If  $E \in X$  then  $E \in [[-]](X)$

$\equiv$  If  $E \in X$  then (if  $E \xrightarrow{x} E'$  and  $x \in Act$  then  $E' \in X$ )

implies  $\nu X. [-]X \Leftrightarrow true$

(PRE) If (if  $E \xrightarrow{x} E'$  and  $x \in Act$  then  $E' \in X$ ) then  $E \in X$

implies  $\mu X. [-]X$  represent *finite* processes (why?)

# Safety and liveness

- *weak liveness*:

$$\mu X . \phi \vee \langle - \rangle X$$

- *strong safety*

$$\nu X . \psi \wedge [-] X$$

making  $\psi = \neg\phi$  both properties are *dual*:

- there is at least a computation reaching a state  $s$  such that  $s \models \phi$
- all states  $s$  reached along all computations maintain  $\phi$ , ie,  $s \models \neg\phi$



# Safety and liveness

Qualifiers *weak* and *strong* refer to a **quantification over computations**

- *weak liveness*:

$$\mu X . \phi \vee \langle - \rangle X$$

(corresponds to Ctl formula  $E F \phi$ )

- *strong safety*

$$\nu X . \psi \wedge [-] X$$

(corresponds to Ctl formula  $A G \psi$ )

cf, linear time vs branching time

# Duality

$$\neg(\mu X . \phi) = \nu X . \neg\phi$$

$$\neg(\nu X . \phi) = \mu X . \neg\phi$$

Example:

- *divergence*:

$$\nu X . \langle \tau \rangle X$$

- *convergence* (= all non observable behaviour is *finite*)

$$\neg(\nu X . \langle \tau \rangle X) = \mu X . \neg(\langle \tau \rangle X) = \mu X . [\tau]X$$

# Safety and liveness

- *weak safety*:

$$\forall X. \phi \wedge (\langle - \rangle X \vee [-] \text{false})$$

(there is a computation along which  $\phi$  holds)

- *strong liveness*

$$\mu X. \neg \phi \vee ([-] X \wedge \langle - \rangle \text{true})$$

(a state where the complement of  $\phi$  holds can be *finitely* reached)

## Conditional properties

$\phi_1 =$

After collecting a passenger (*icr*), the taxi drops him at destination (*fcr*)

Second part of  $\phi_1$  is **strong liveness**:

$$\mu X . [-fcr]X \wedge \langle - \rangle true$$

holding only after *icr*.

Is it enough to write:

$$[icr](\mu X . [-fcr]X \wedge \langle - \rangle true)$$

?

what we want does not depend on the initial state: it is *liveness embedded into strong safety*:

$$\forall Y . [icr](\mu X . [-fcr]X \wedge \langle - \rangle true) \wedge [-]Y$$

## Conditional properties

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$$\forall Y . [icr](\mu X . [-fcr]X \wedge \langle - \rangle true) \wedge [-]Y$$

## Conditional properties

The previous example is *conditional liveness* but one can also have

- **conditional safety:**

$$\nu Y. (\neg \phi \vee (\phi \wedge \nu X. \psi \wedge [-]X)) \wedge [-]Y$$

(whenever  $\phi$  holds,  $\psi$  cannot cease to hold)

## Cyclic properties

$\phi$  = every second action is *out*

is expressed by

$$\nu X . [-]([-\text{out}] \text{false} \wedge [-]X)$$

$\phi$  = *out* follows *in*, but other actions can occur in between

$$\nu X . [\text{out}] \text{false} \wedge [\text{in}](\mu Y . [\text{in}] \text{false} \wedge [\text{out}]X \wedge [-\text{out}]Y) \wedge [-\text{in}]X$$

Note that the use of *least fixed points* imposes that the amount of computation between *in* and *out* is finite

## Cyclic properties

$\phi$  = a state in which *in* can occur, can be reached an infinite number of times

$$\nu X . \mu Y . (\langle in \rangle true \vee \langle - \rangle Y) \wedge ([-] X \wedge \langle - \rangle true)$$

$\phi$  = *in* occurs an infinite number of times

$$\nu X . \mu Y . [-in] Y \wedge [-] X \wedge \langle - \rangle true$$

$\phi$  = *in* occurs an finite number of times

$$\mu X . \nu Y . [-in] Y \wedge [in] X$$



# $\mu$ -calculus in mCRL2

## The verification problem

- Given a specification of the system's behaviour is in mCRL2
- and the system's requirements are specified as properties in a temporal logic,
- a model checking algorithm decides whether the property holds for the model: the property can be verified or refuted;
- sometimes, witnesses or counter examples can be provided

## Which logic?

*$\mu$ -calculus* with **data**, **time** and **regular expressions**

# Example: The dining philosophers problem

## Formulas to verify Demo

- No deadlock (every philosopher holds a left fork and waits for a right fork (or vice versa):

$$[true^*] \langle true \rangle true$$

- No starvation (a philosopher cannot acquire 2 forks):

$$forall\ p:Phil. \ [true^*. !eat(p)^*] \ \langle !eat(p)^*. eat(p) \rangle true$$

- A philosopher can only eat for a finite consecutive amount of time:

$$forall\ p:Phil. \ \nu X. \ \mu Y. \ [eat(p)]Y \ \&\& \ [!eat(p)]X$$

- there is no starvation: for all reachable states it should be possible to eventually perform an  $eat(p)$  for each possible value of  $p:Phil$ .

$$[true^*](forall\ p:Phil. \ \mu Y. \ ([!eat(p)]Y \ \&\& \ \langle true \rangle true))$$