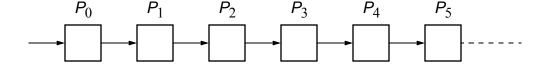
Chapter 5

## **Pipelined Computations**

## **Pipelined Computations**

Problem divided into a series of tasks that have to be completed one after the other (the basis of sequential programming).

Each task executed by a separate process or processor.



### **Example**

Add all the elements of array **a** to an accumulating sum:

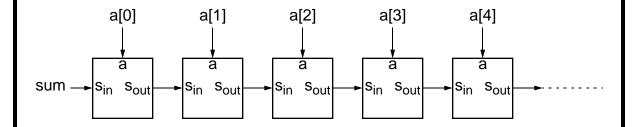
```
for (i = 0; i < n; i++)
sum = sum + a[i];
```

The loop could be "unfolded" to yield

```
sum = sum + a[0];
sum = sum + a[1];
sum = sum + a[2];
sum = sum + a[3];
sum = sum + a[4];
```

Slides for Parallel Programming Techniques and Applications Using Networked Workstations and Parallel Computers by Barry Wilkinson and Michael Allen, Prentice Hall, Upper Saddle River, New Jersey, USA, ISBN 0-13-671710-1. 2002 by Prentice Hall Inc. All rights reserved.

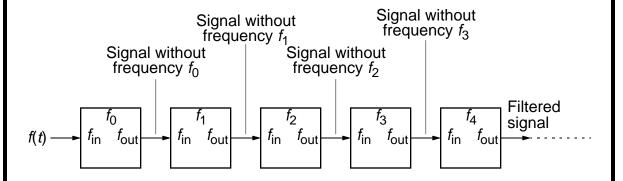
## Pipeline for an unfolded loop



### **Another Example**

Frequency filter - Objective to remove specific frequencies ( $f_0$ ,  $f_1$ ,  $f_2$ ,

 $f_3$ , etc.) from a digitized signal, f(t). Signal enters pipeline from left:

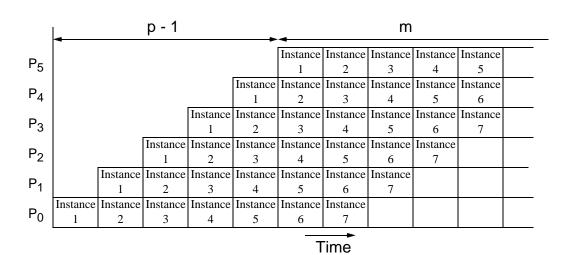


### Where pipelining can be used to good effect

Assuming problem can be divided into a series of sequential tasks, pipelined approach can provide increased execution speed under the following three types of computations:

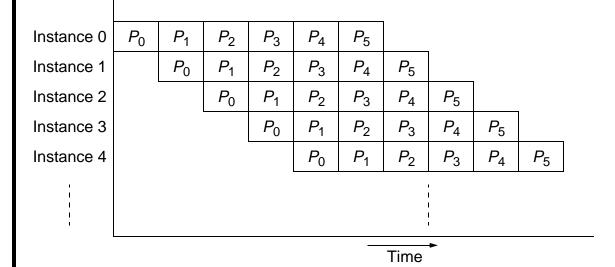
- If more than one instance of the complete problem is to be executed
- 2. If a series of data items must be processed, each requiring multiple operations
- 3. If information to start the next process can be passed forward before the process has completed all its internal operations

## "Type 1" Pipeline Space-Time Diagram

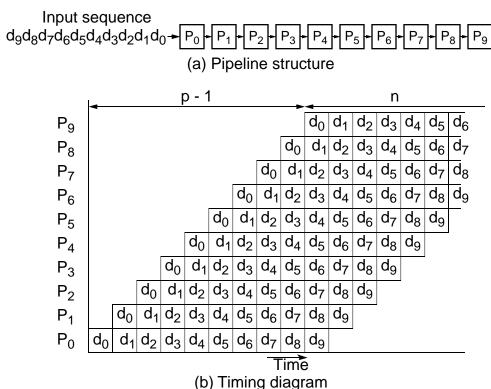


Execution time = m + p - 1 cycles for a p-stage pipeline and m instances.

## Alternative space-time diagram



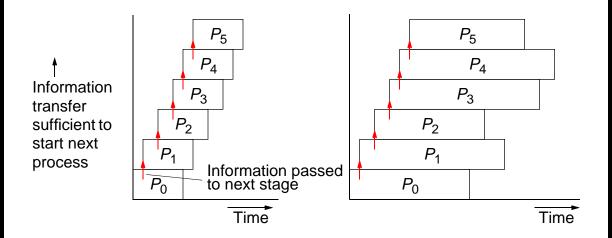
## "Type 2" Pipeline Space-Time Diagram



(b) Processes not with the

same execution time

### "Type 3" Pipeline Space-Time Diagram

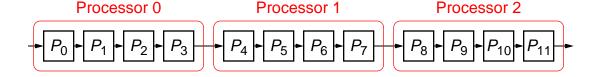


Pipeline processing where information passes to next stage before end of process.

(a) Processes with the same

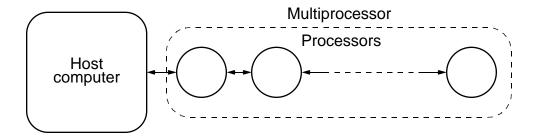
execution time

If the number of stages is larger than the number of processors in any pipeline, a group of stages can be assigned to each processor:

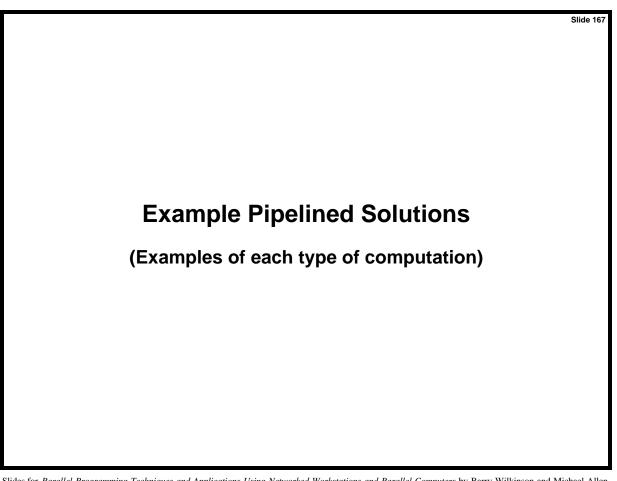


### **Computing Platform for Pipelined Applications**

Multiprocessor system with a line configuration.

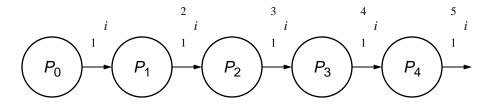


Strictly speaking pipeline may not be the best structure for a cluster - however a cluster with switched direct connections, as most have, can support simultaneous message passing.



### **Pipeline Program Examples**

### **Adding Numbers**



Type 1 pipeline computation

Basic code for process  $P_i$ :

```
recv(&accumulation, P-1);
accumulation = accumulation + number;
send(&accumulation, P+1);
```

except for the first process,  $P_0$ , which is

```
send(&number, P);
```

and the last process,  $P_{n-1}$ , which is

```
recv(&number, P_{n-2});
accumulation = accumulation + number;
```

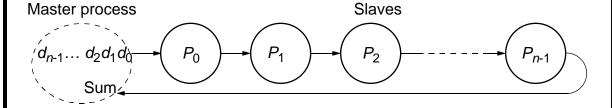
### **SPMD** program

```
if (process > 0) {
  recv(&accumulation, P<sub>-1</sub>);
  accumulation = accumulation + number;
}
if (process < n-1) send(&accumulation, P<sub>1</sub>);
```

The final result is in the last process.

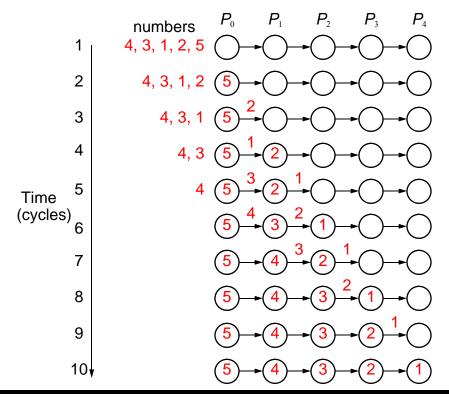
Instead of addition, other arithmetic operations could be done.

# Pipelined addition numbers with a master process and ring configuration

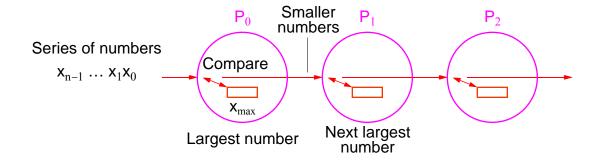


## **Sorting Numbers**

A parallel version of insertion sort.



## Pipeline for sorting using insertion sort



Type 2 pipeline computation

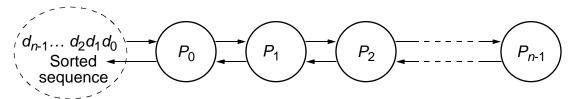
The basic algorithm for process  $P_i$  is

```
recv(&number, P<sub>-1</sub>);
if (number > x) {
  send(&x, P<sub>1+1</sub>);
  x = number;
} else send(&number, P<sub>+1</sub>);
```

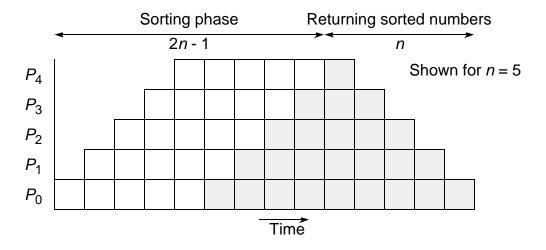
With n numbers, how many the ith process is to accept is known; it is given by n - i. How many to pass onward is also known; it is given by n - i - 1 since one of the numbers received is not passed onward. Hence, a simple loop could be used.

# Insertion sort with results returned to the master process using a bidirectional line configuration

#### Master process



### Insertion sort with results returned

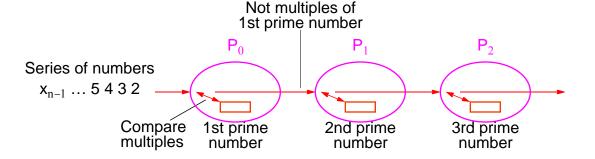


### **Prime Number Generation**

#### **Sieve of Eratosthenes**

Series of all integers is generated from 2. First number, 2, is prime and kept. All multiples of this number are deleted as they cannot be prime. Process repeated with each remaining number. The algorithm removes nonprimes, leaving only primes.

### **Pipeline for Prime Number Generation**



Type 2 pipeline computation

The code for a process,  $P_i$ , could be based upon

```
recv(&x, P<sub>i-1</sub>);
/* repeat following for each number */
recv(&number, P<sub>i-1</sub>);
if ((number % x) != 0) send(&number, P<sub>i</sub>P<sub>i</sub>);
```

Each process will not receive the same amount of numbers and the amount is not known beforehand. Use a "terminator" message, which is sent at the end of the sequence:

```
recv(&x, P<sub>i-1</sub>);
for (i = 0; i < n; i++) {
  recv(&number, P<sub>i-1</sub>);
  if (number == terminator) break;
  if (number % x) != 0) send(&number, P<sub>i</sub>);
}
```

## **Solving a System of Linear Equations**

### **Upper-triangular form**

$$a_{n-1,0}x_0 + a_{n-1,1}x_1 + a_{n-1,2}x_2 \dots + a_{n-1,n-1}x_{n-1} = b_{n-1}$$

$$\vdots$$

$$a_{2,0}x_0 + a_{2,1}x_1 + a_{2,2}x_2 = b_2$$

$$a_{1,0}x_0 + a_{1,1}x_1 = b_1$$

$$a_{0,0}x_0 = b_0$$

where the a's and b's are constants and the x's are unknowns to be found.

### **Back Substitution**

First, the unknown  $x_0$  is found from the last equation; i.e.,

$$x_0 = \frac{b_0}{a_{0.0}}$$

Value obtained for  $x_0$  substituted into next equation to obtain  $x_1$ ; i.e.,

$$x_1 = \frac{b_1 - a_{1,0} x_0}{a_{1,1}}$$

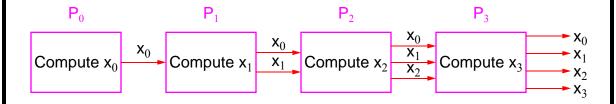
Values obtained for  $x_1$  and  $x_0$  substituted into next equation to obtain  $x_2$ :

$$x_2 = \frac{b_2 - a_{2,0} x_0 - a_{2,1} x_1}{a_{2,2}}$$

and so on until all the unknowns are found.

### **Pipeline Solution**

First pipeline stage computes  $x_0$  and passes  $x_0$  onto the second stage, which computes  $x_1$  from  $x_0$  and passes both  $x_0$  and  $x_1$  onto the next stage, which computes  $x_2$  from  $x_0$  and  $x_1$ , and so on.



### Type 3 pipeline computation

The *i*th process (0 < i < n) receives the values  $x_0, x_1, x_2, ..., x_{i-1}$  and computes  $x_i$  from the equation:

$$x_{i} = \frac{b_{i} - a_{i,j}x_{j}}{a_{i,i}}$$

### **Sequential Code**

Given the constants  $a_{i,j}$  and  $b_k$  stored in arrays a[][] and b[], respectively, and the values for unknowns to be stored in an array, x[], the sequential code could be

```
x[0] = b[0]/a[0][0]; /* computed separately */
for (i = 1; i < n; i++) {* for remaining}
unknowns */
   sum = 0;
   for (j = 0; j < i; j++
      sum = sum + a[i][j]*x[j];
   x[i] = (b[i] - sum)/a[i][i];
}</pre>
```

### **Parallel Code**

Pseudocode of process  $P_i$  (1 < i < n) of could be

```
for (j = 0; j < i; j++) {
  recv(&x[j], P<sub>1-1</sub>);
  send(&x[j], P<sub>1+1</sub>);
}
sum = 0;
for (j = 0; j < i; j++)
  sum = sum + a[i][j]*x[j];
x[i] = (b[i] - sum)/a[i][i];
send(&x[i], P<sub>1+1</sub>);
```

Now additional computations after receiving and resending values.

## Pipeline processing using back substitution

