



CMSC 170: Games

Min-Max Algorithm

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LEARNING OUTCOMES



At the end of the session, the students should be able to:

- understand the Min-Max Algorithm;
- understand the use of Alpha and Beta Pruning; and
- implement min-max algorithm and alpha beta pruning in a 2-player deterministic game.



Games

Every game has different sets of properties.



Games

We will discuss 2-player deterministic games and how to make an Al agent.



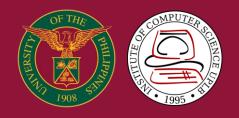
States

We can define it as S as the set of states. Ex. $S = \{S_0\}$ //start of the game



Player

There are also P as the of players. Ex. $P=\{P_1,P_2\}$



Result

There are also results in games. Result(s,a) -> s'



Results(s,a) $\rightarrow s'$

s' are the new states made when action a is done to a state s.



Actions(s,p)

provides the set of possible actions/moves for a player.



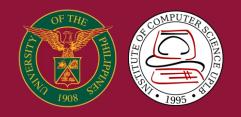
Terminal

It returns true when the state is terminal or there is an end result or false otherwise.



Utility(s,p)

Returns the current value of the state s to a player p.



Utility

It is expresses the value of the current game state to the player. It is usually expressed as +/- numbers or 0's or 1's.



Zero-Sum Games

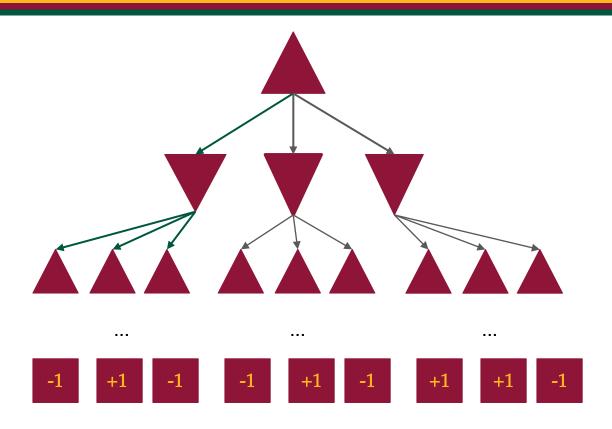
These are games where the overall sum of the utilities for both the players is 0.



Zero-Sum Games

Ex. The utility for a win is 1 and for the loss is -1.

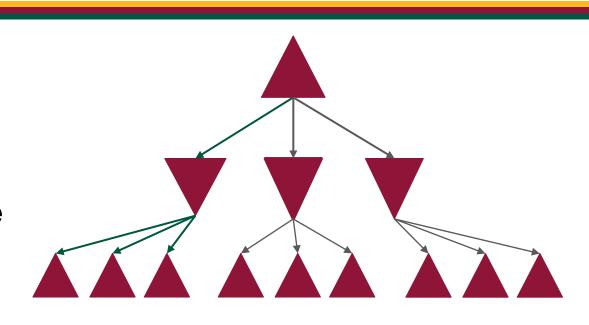








Game Tree



-1

+1

-1

-1

+1

-1

+1

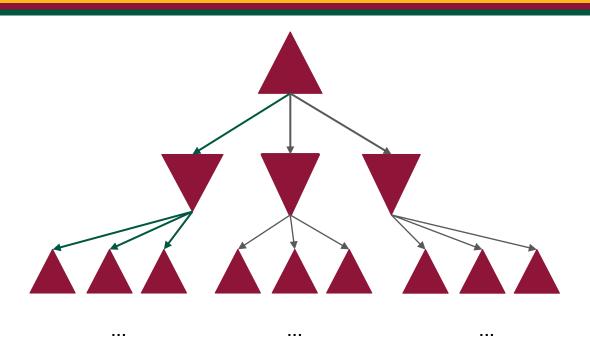
+1

-1

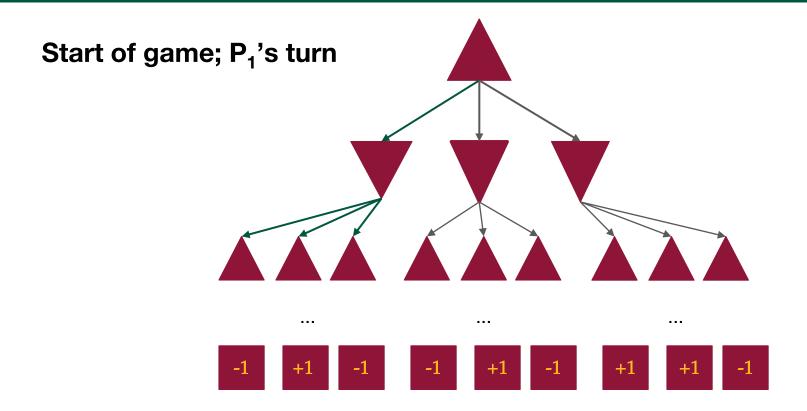




Game Tree



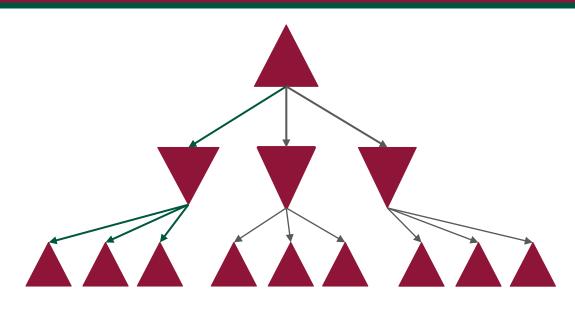






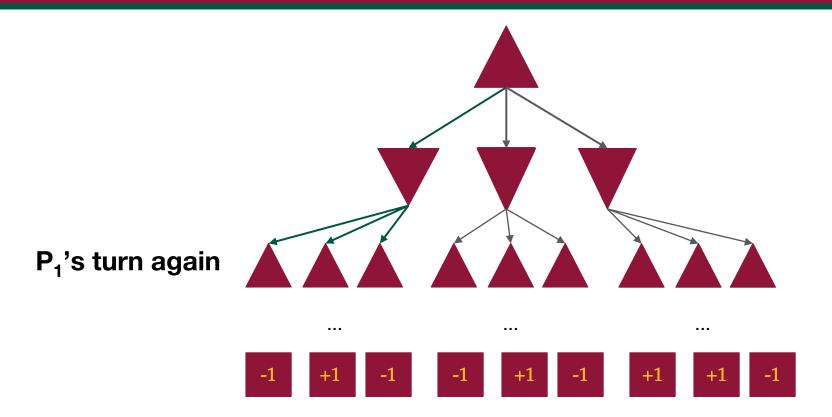




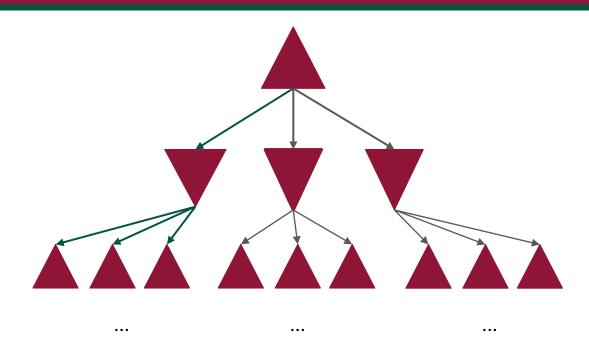












Terminal states



+1

-1



+1

-1

+1

+1

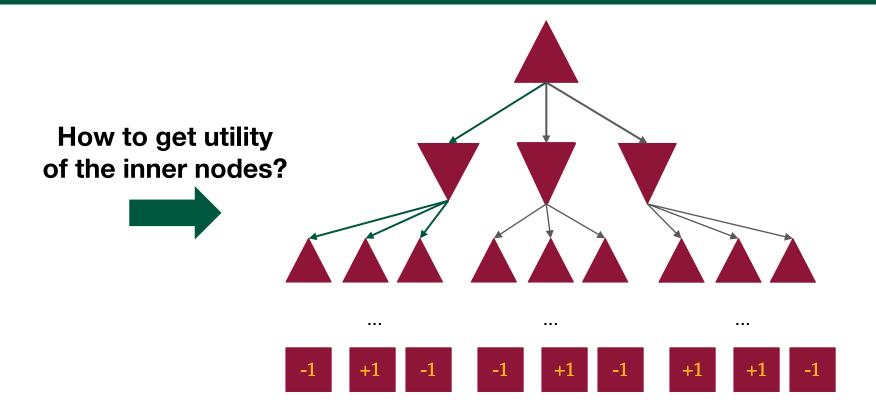
-1



Each node has a utility value. P₁ attempts to maximize the values; P₂ attempts to minimize the value thus resulting to an adversarial environment.



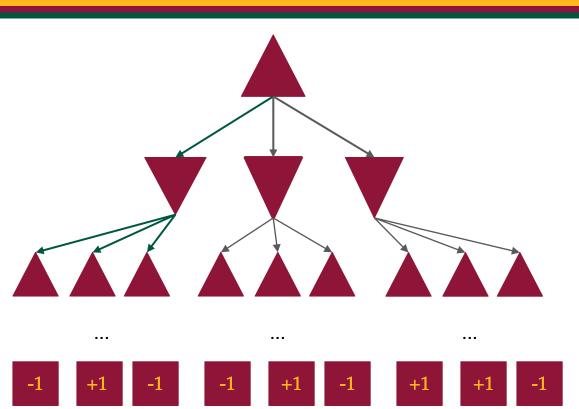






Use the terminal states to Return the values by following the min-max behavior of P₁ and P₂







```
value (s):
```

if $s \square$ is : utility(s)

if $s \triangle$ is : maxValue(s)

If $s \nabla$ is : minValue(s)



```
maxValue(s):
```

```
m = -\infty
for a, s' in successors(s):
v = value(s')
m = max(m,v)
return m
```





```
minValue(s):

m = +∞

for a, s' in successors(s):

v = value(s')

m = min(m,v)

return m
```

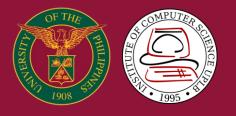


It has a time complexity of O(B^m)



BRANCHING FACTOR

approximate number of choice (successors) a player has at each node.



DEPTH

total number of turns for P₁ and P₂ to reach a terminal state





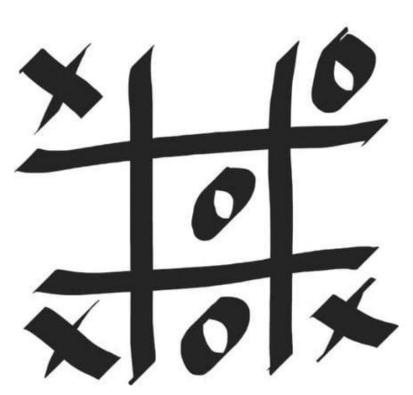
This is our current state s.







We set X as the maximizer and O as the minimizer.



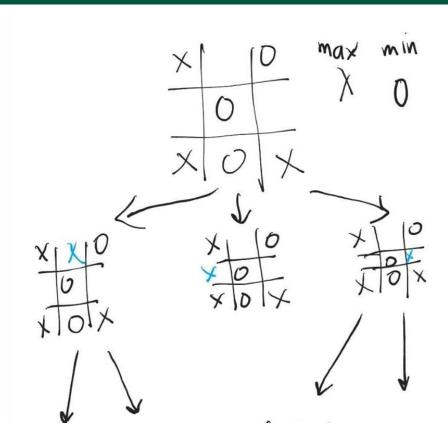


Its X's Turn







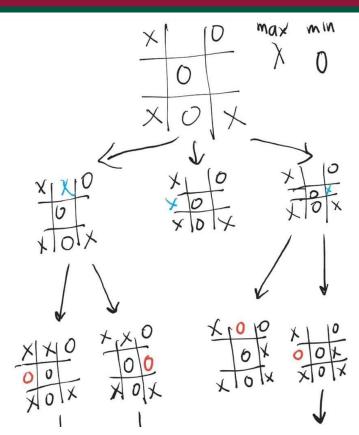






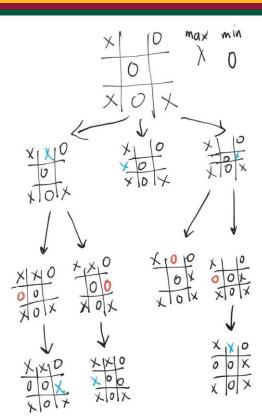


Its 0's Turn





Its X's Turn





ALPHA-BETA PRUNING

The algorithm used to avoid searching subtrees of moves that won't be considered.



ALPHA(α)

The best solution (lower bound) for the maximizer on the path to the root.



BETA(β)

The best solution (upper bound) for the minimizer on the path to the root.





```
value (s, \alpha ,\beta):
```

if $s \square$ is : utility(s)

if $s \wedge is = maxValue(s,\alpha,\beta)$

If s_{∇} is : minValue(s, α, β)



```
maxValue(s,\alpha,\beta):
        m = -\infty
    for a, s' in successors(s):
        v = value(s', \alpha, \beta)
        m = max(m,v)
        if v >= \beta:
            return m
        \alpha = \max(\alpha, m)
    return m
```



```
minValue(s,\alpha,\beta):
        m = +\infty
    for a, s' in successors(s):
        v = value(s', \alpha, \beta)
        m = min(m,v)
        if v \le : \alpha
            return m
        \beta = \min(\beta, m)
    return m
```





For questions and inquiries, you can email me at

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EXERCISE on MinMax Algorithm





Create a tictactoe program with a MinMax AI agent. It must have a user interface. It must ask whether the user or the AI would go first.

SOME REMINDERS:

- Naming convention for exercise: surname_minmax.
- Python or Java can only be used for the exercise.
- Do not forget to put a journal in your ReadMe file in Github.
- Lastly, Honor and Excellence.