

/Users/archanar/Kinematic
_factor/adat_devel/lib
/ensem/ensem_observable.h

```
graph TD; A["/Users/archanar/Kinematic_factor/adat_devel/lib/ensem/ensem_observable.h"] --> B["ensem_obsscalar.h"]; A --> C["ensem_obsvector.h"]; A --> D["ensem_obstensor.h"];
```

ensem_obsscalar.h

ensem_obsvector.h

ensem_obstensor.h