

# Distributed and Parallel Algorithms for Set Cover Problems with Small Neighborhood Covers

Archita Agarwal, Venkatesan T. Chakaravarthy, Anamitra R. Choudhury, Sambuddha Roy, Yogish Sabharwal

IBM Research - India, New Delhi

# Set Cover

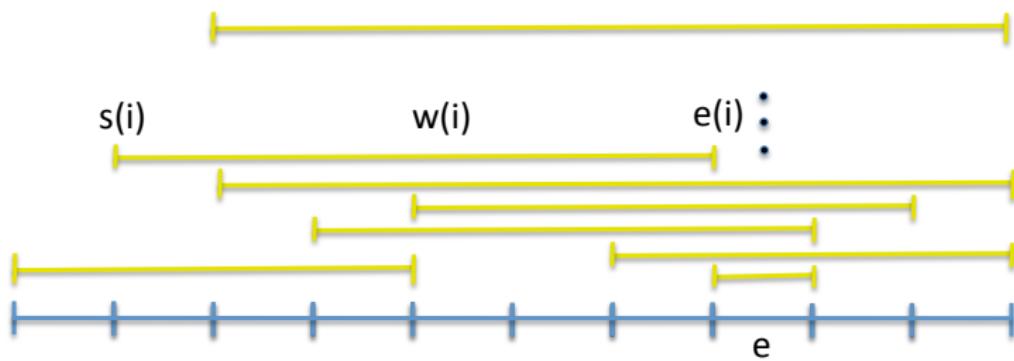
- Input: Set system  $\langle E, \mathcal{S} \rangle$
- $E : e_1, e_2, e_3, \dots, e_m$
- $\mathcal{S} : \{\dots\}, \{\dots\}, \{\dots\}, \dots, \{\dots\}$   
 $c(S_1) \ c(S_2) \ c(S_3) \ \dots \ c(S_n)$
- Output:  $\mathcal{R} \subseteq \mathcal{S}$  having minimum cost such that all the  $e \in E$  are covered

# Prior Work

- Sequential setting
  - $O(\log \Delta)$  approximation ratio,  $\Delta$  is the maximum cardinality of the sets in  $\mathcal{S}$
  - $f$  approximation ratio, where  $f$  is the *frequency parameter* which is the maximum number of sets of  $\mathcal{S}$  that any element belongs to
  - $\Omega(\log m)$ -inapproximable
- Parallel setting
  - [RV '98]  $O(\log m)$  approximation ratio
  - [KVV '94]  $O(f + \epsilon)$  approximation ratio
- Distributed setting
  - [Kuhn et al. '06]  $O(\log \Delta)$  approximation ratio
  - [KY '11]  $f$  approximation ratio
  - both the above algorithms run in  $O(\log m)$  communication rounds

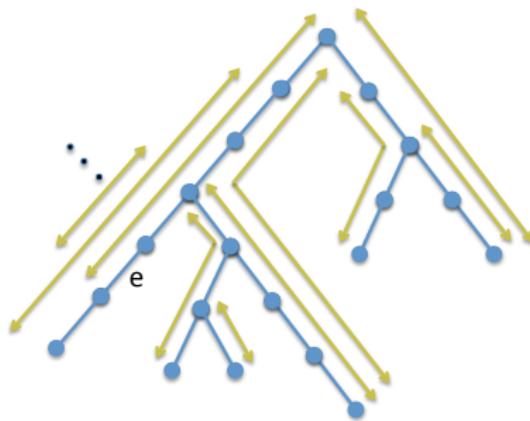
# Interval Cover

- Non constant  $f$  but
  - constant factor by Primal Dual
  - optimal by DP



# Tree Cover

- Non constant  $f$  but
  - constant factor by Primal Dual
  - optimal by DP



# Other Problems with non constant $f$

- Priority Interval Cover
  - optimal by Primal Dual
- Bag Interval Cover (NP Hard)
  - constant factor by Primal Dual

# Our contributions

- Introduction of SNC property for a class of set cover problems
  - A wide range of problems fall under this framework
- For set cover problems with non-constant  $f$  but satisfying the SNC property, we give constant factor approximation algorithms in
  - sequential setting,
  - parallel setting, and
  - distributed setting

## SNC property

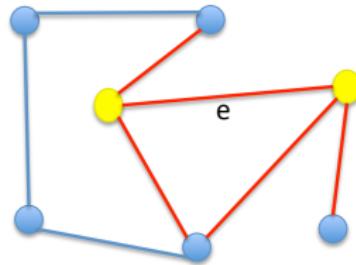
- $E : e_1, e_2, e_3, \dots, e_m$
  - $\mathcal{S} : \{\dots\}, \{\dots\}, \{\dots\}, \dots, \{\dots\}$
- 
- The *neighborhood* of an element  $e \in E$  is the set of all the elements with which it shares some set in  $\mathcal{S}$ 
    - $\mathcal{S} : \{e_1, e_2\}, \{e_1, e_2, e_3\}, \{e_1, e_4, e_6\}, \{e_2, e_5\}$
    - $\mathcal{S} : \{e_1, e_2\}, \{e_1, e_2, e_3\}, \{e_1, e_4, e_6\}, \{e_2, e_5\}$
    - neighborhood( $e_1$ ):  $\{e_1, e_2, e_3, e_4, e_6\}$
    - $\mathcal{S} : \{e_1, e_2\}, \{e_1, e_2, e_3\}, \{e_1, e_4, e_6\}, \{e_2, e_5\}$
    - neighborhood( $e_2$ ):  $\{e_1, e_2, e_3, e_5\}$
  - An element is a  $\tau$ -SNC element if its neighborhood can be covered by atmost  $\tau$  sets
    - $e_1 \rightarrow 3$ -SNC
    - $e_2 \rightarrow 2$ -SNC

## SNC property

- For any subset  $X$ , the set system restricted to  $X$  is defined as  $\langle X, \mathcal{S}' \rangle$  where  $\mathcal{S}' = \{S \cap X : S \in \mathcal{S}\}$
- For a  $\tau$ , if any restriction of the set system contains atleast one  $\tau$ -SNC element, we call the set system as  $\tau$ -SNC set system

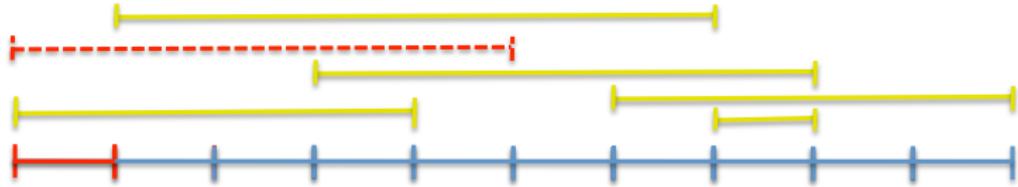
## Examples: Vertex Cover : 2-SNC

- Each edge (element) is incident upon 2 vertices (sets)



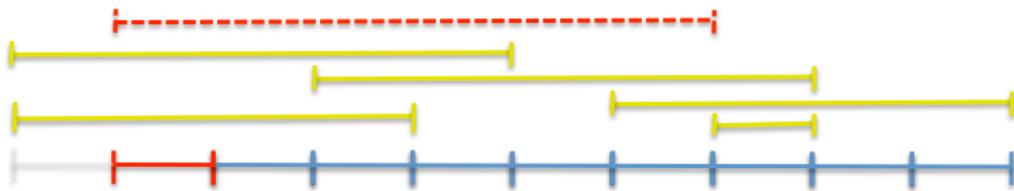
## Examples: Interval Cover : 1-SNC

- The leftmost element is a 1-SNC element – Its neighborhood can be covered by the interval spanning it and extending most towards the right



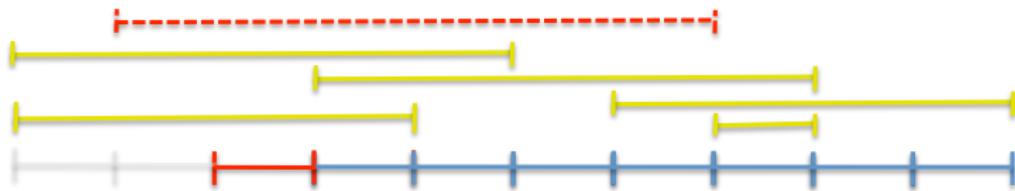
## Examples: Interval Cover : 1-SNC

- After removing this 1-SNC element, we can find another 1-SNC element



## Examples: Interval Cover : 1-SNC

- After removing this 1-SNC element, we can find another 1-SNC element



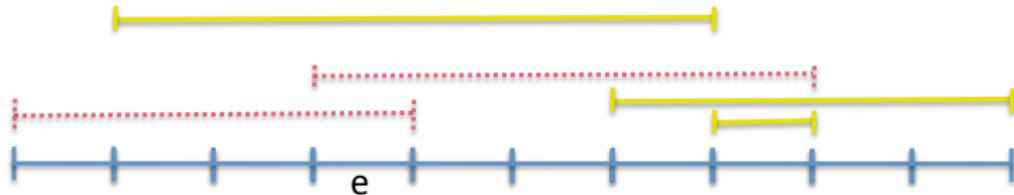
## Examples: Interval Cover : 1-SNC

- Only after we have removed the leftmost 1-SNC element, we find a new 1-SNC element



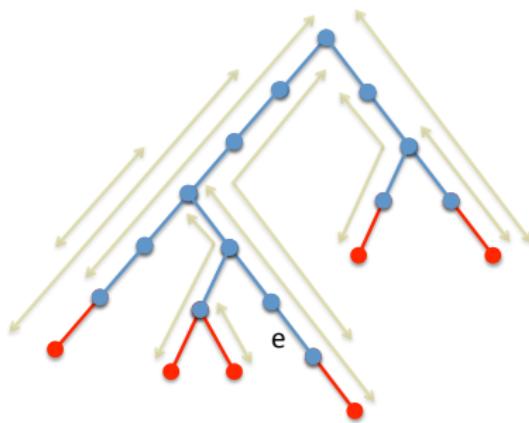
## Examples: Interval Cover : 2-SNC

- Can be viewed as a 2-SNC set system as well
- The neighborhood of any timeslot (element) can be covered by 2 intervals (sets) - the one extending most towards the left and the one extending most towards the right



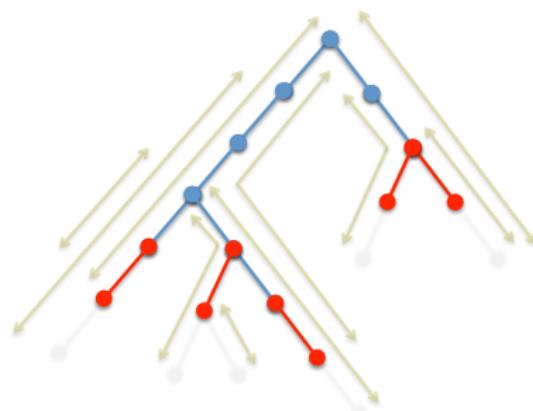
## Examples: Tree Cover : 1-SNC

- All the leaves are 1-SNC elements – Their neighborhood can be covered by the interval extending most towards the root



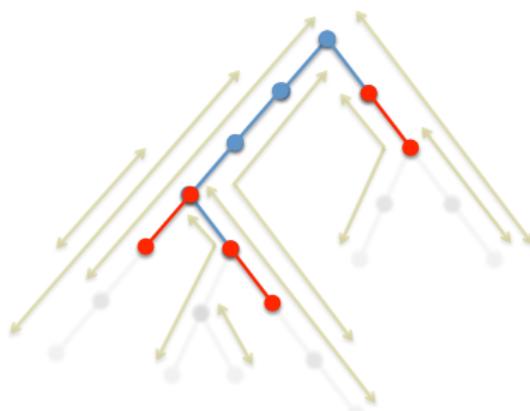
## Examples: Tree Cover : 1-SNC

- Any restriction of a tree is a tree in itself. After removing all the 1-SNC element, we can find other 1-SNC elements



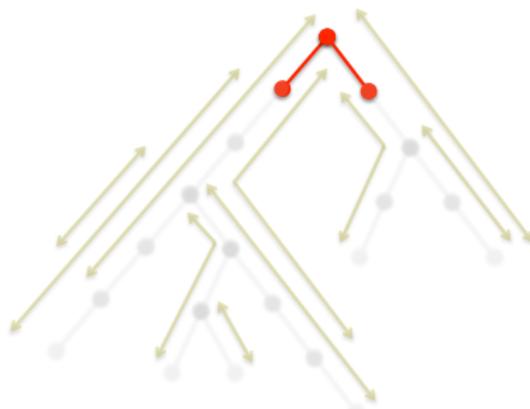
## Examples: Tree Cover : 1-SNC

- Any restriction of a tree is a tree in itself. After removing all the 1-SNC element, we can find other 1-SNC elements



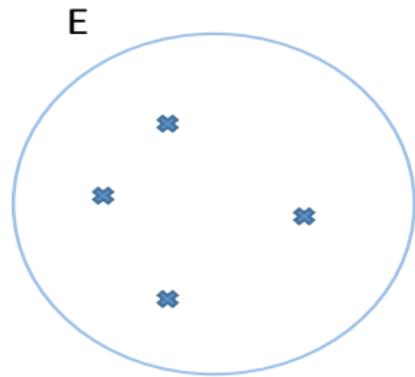
## Examples: Tree Cover : 1-SNC

- Any restriction of a tree is a tree in itself. After removing all the 1-SNC element, we can find other 1-SNC elements



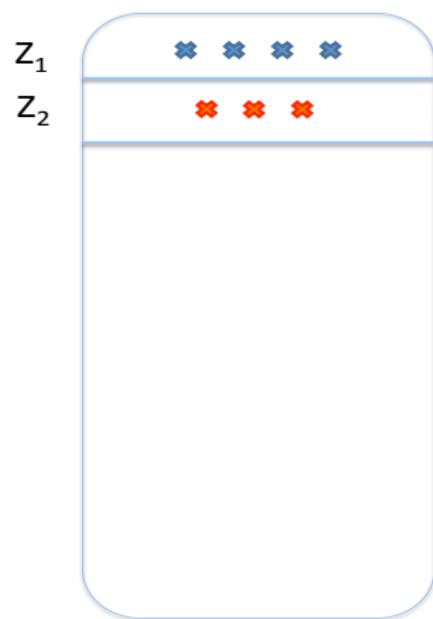
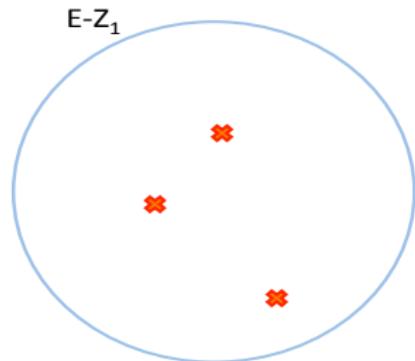
# Layer Decomposition

- In the given set system, find all  $\tau$ -SNC elements. Put them in layer  $Z_1$



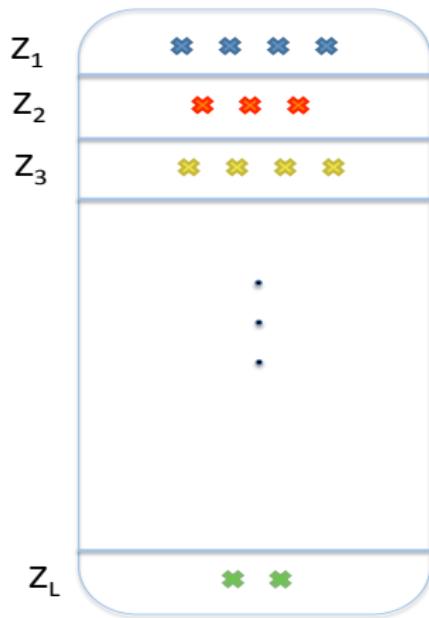
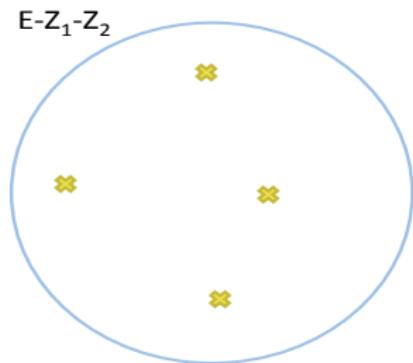
# Layer Decomposition

- Restrict the set system to  $E - Z_1$ . Find all  $\tau$ -SNC elements in the restriction



# Layer Decomposition

- Continue till all the elements belong to some layer  $Z_k$



# Layer Decomposition: Length

- Interval Cover

- 1-SNC  $\rightarrow L = \Omega(m)$
- 2-SNC  $\rightarrow L = 1$

# Layer Decomposition: Length

- Interval Cover
  - 1-SNC  $\rightarrow L = \Omega(m)$
  - 2-SNC  $\rightarrow L = 1$
  
- Tree Cover
  - 1-SNC  $\rightarrow L = \Omega(m)$
  - *Theorem: For a 2-SNC tree cover system, the number of layers  $L = O(\log m)$*

## Layer Decomposition: Length

There exists a procedure for computing the layer decomposition of a given  $\tau$ -SNC set system.

- In the sequential setting, it can be implemented in polynomial time.
  - In the distributed setting, it can be implemented in  $O(L)$  communication rounds.
  - In the parallel setting, the algorithm takes  $L$  iterations each of which can be implemented in NC.
- 
- For parallel and distributed setting the decomposition length ( $L$ ) should be  $O(\log m)$

# Our Results

- $\tau$  sequential approximation algorithm for any  $\tau$ -SNC set system
- $8\tau^2$  parallel approximation algorithm for a  $\tau$ -SNC set system of logarithmic length
- $\tau$  distributed approximation algorithm for a  $\tau$ -SNC set system of logarithmic length

# Primal Dual Framework

## Primal

$$\begin{aligned} \min \quad & \sum_{S \in \mathcal{S}} x(S) \cdot w(S) \\ & \sum_{S \in \mathcal{S}: e \in S} x(S) \geq 1 \quad (\forall e \in E) \\ & x(S) \geq 0 \quad (\forall S \in \mathcal{S}) \end{aligned}$$

## Dual

$$\begin{aligned} \max \quad & \sum_{e \in E} \alpha(e) \\ & \sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S}) \\ & \alpha(e) \geq 0 \quad (\forall e \in E) \end{aligned}$$

# Primal Dual Framework

- A primal-dual algorithm would generally have
  - Forward Phase
  - Reverse Delete Phase
- *Forward Phase*
  - Increase the dual variables
  - If some constraint becomes tight, pick the variable corresponding to that constraint in the primal solution
  - Output  $\langle A, \alpha \rangle$ , where  $A$  and  $\alpha$  are the primal and dual solutions respectively
- *Reverse Delete Phase*
  - Take the primal solution  $A$  produced in the forward phase and *drop* redundant items from it
  - Output  $\langle B, \alpha \rangle$ , where  $B \subseteq A$

## Primal Dual Framework: Approx. Complementary Slackness Conditions

- We say that the pair  $\langle A, \alpha \rangle$  is  $\lambda$ -maximal, if for any  $S \in \mathcal{A}$ , the corresponding dual constraint is approximately tight:

$$\sum_{e \in S} \alpha(e) \geq \lambda \cdot w(S)$$

- We say that the pair  $\langle B, \alpha \rangle$  satisfies the primal slackness conditions approximately, if for any  $e \in E$ , if  $\alpha(e) > 0$  then

$$|\{S \in B : S \text{ covers } e\}| \leq \mu.$$

- The overall factor achieved is  $\frac{1}{\lambda} \cdot \mu$

# Primal Dual Framework: Forward Phase

## Dual

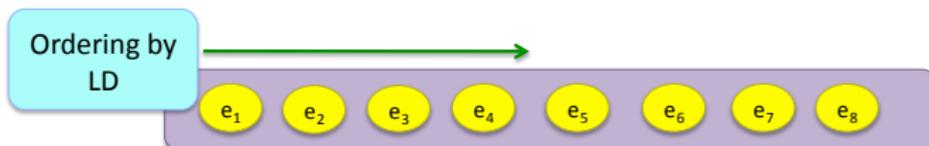
$$\begin{aligned} \max \quad & \sum_{e \in E} \alpha(e) \\ \text{subject to} \quad & \sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S}) \\ & \alpha(e) \geq 0 \quad (\forall e \in E) \end{aligned}$$

Some ordering



# $O(\tau)$ sequential algorithm: Forward Phase

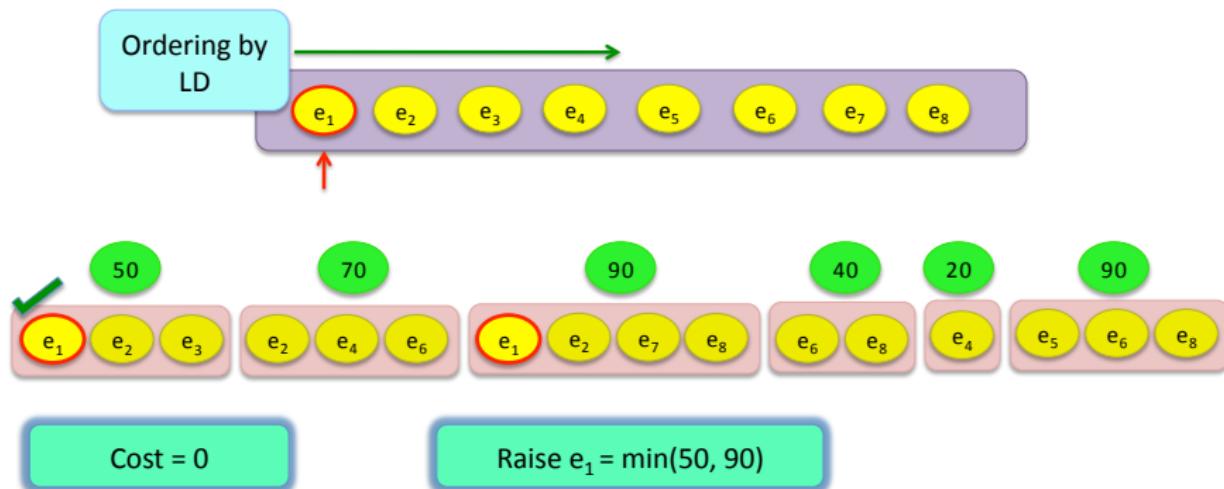
- Arrange the elements according to layer decomposition order
- Scan them from left to right



$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

# $O(\tau)$ sequential algorithm: Forward Phase

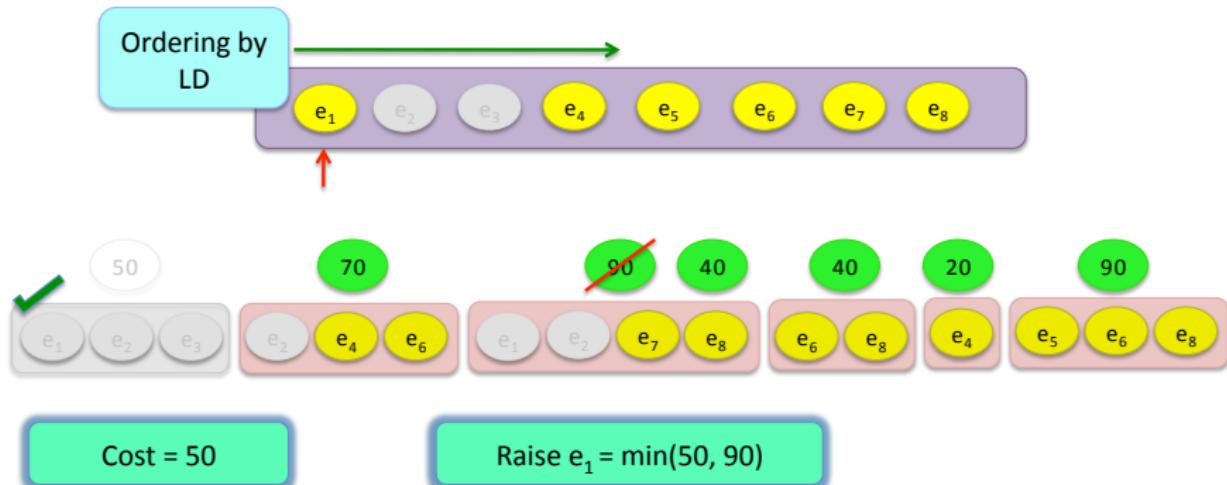
- Raise the first uncovered element to the maximum possible cost



$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

# $O(\tau)$ sequential algorithm: Forward Phase

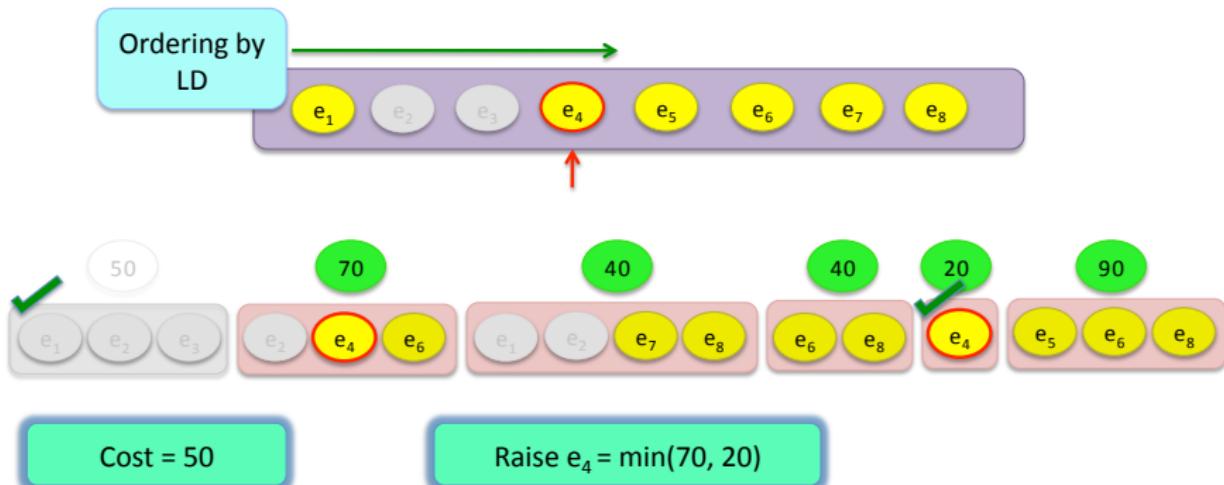
- Include the *tight* set in the solution
- Remove the elements that got *freely* covered by this picked up set



$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

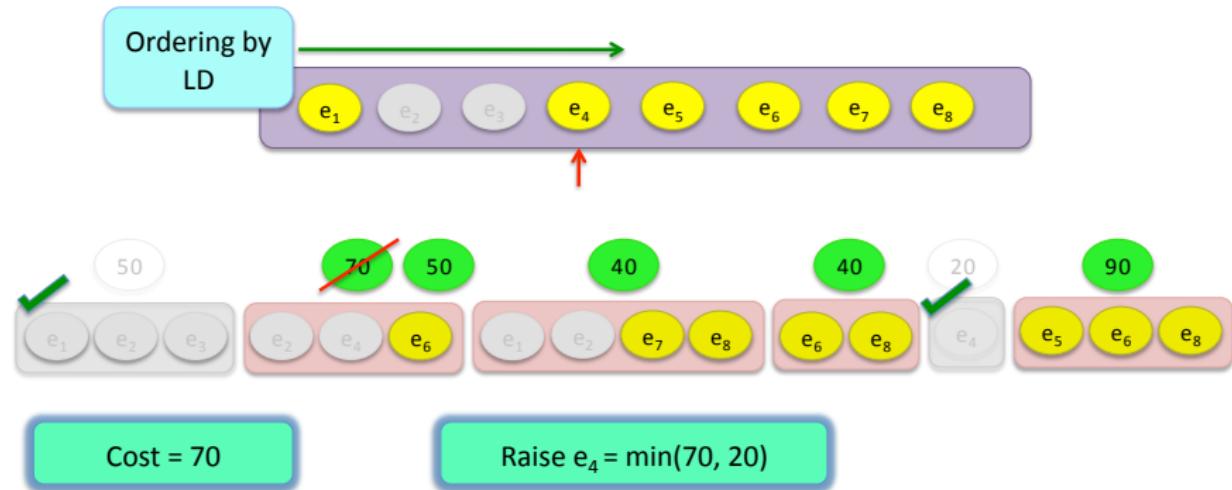
# $O(\tau)$ sequential algorithm: Forward Phase

- Look for the next uncovered element in the ordering and repeat the process



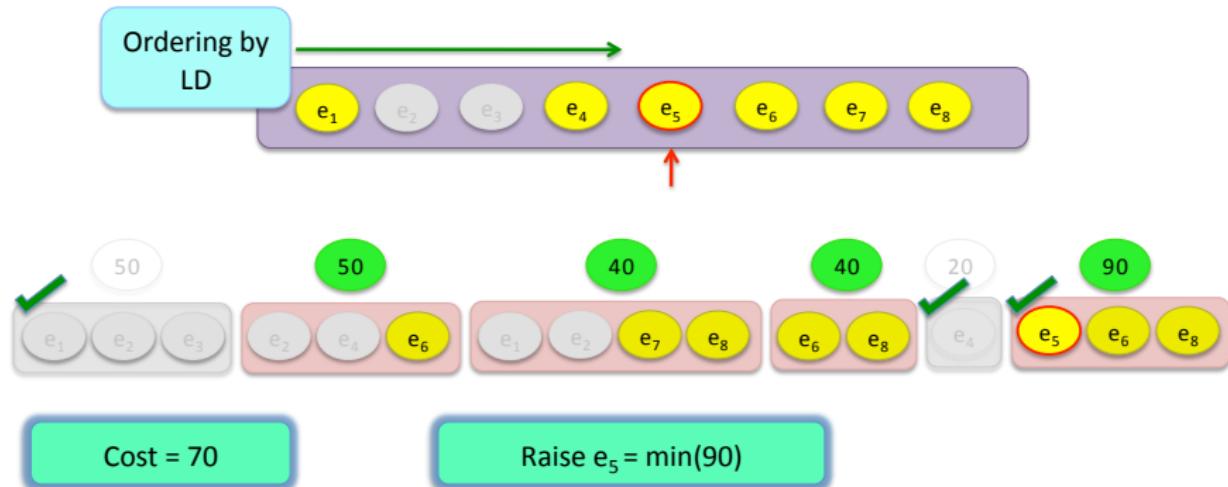
$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

# $O(\tau)$ sequential algorithm: Forward Phase



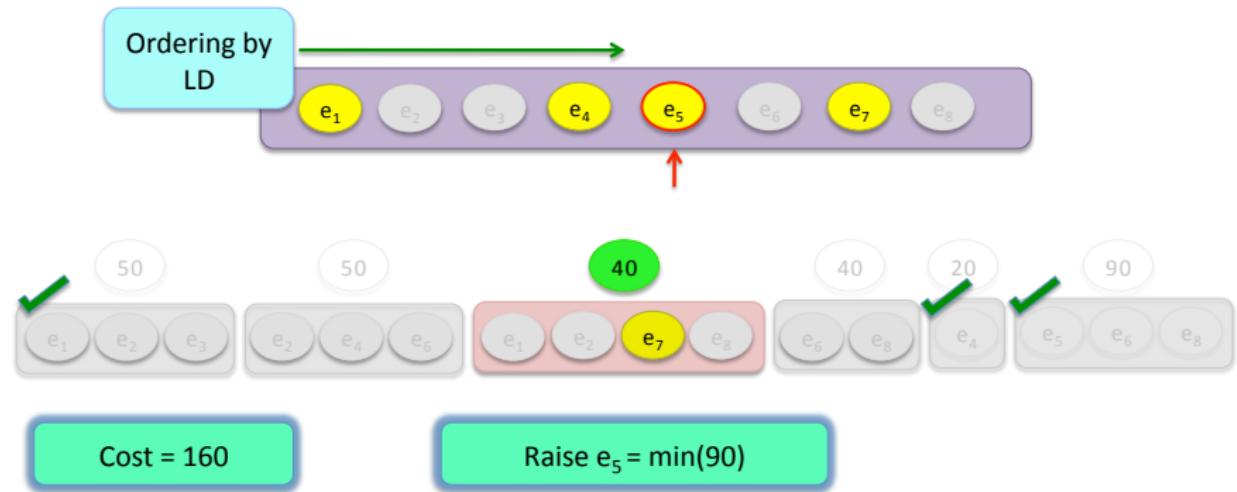
$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

# $O(\tau)$ sequential algorithm: Forward Phase



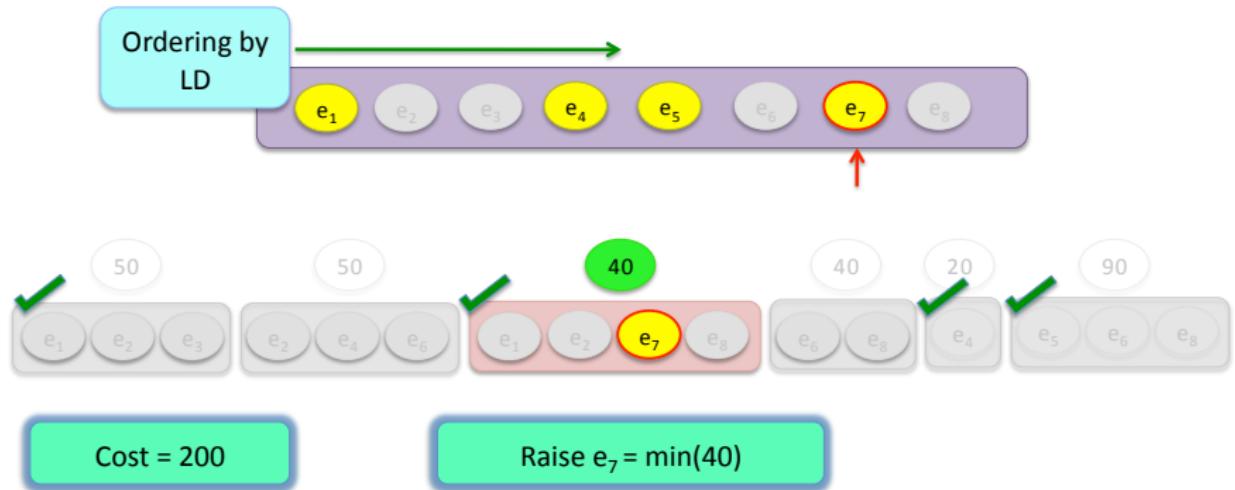
$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

# $O(\tau)$ sequential algorithm: Forward Phase



$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

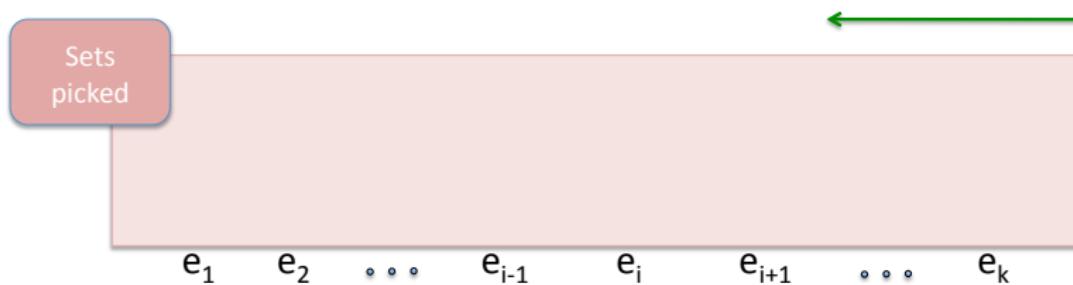
# $O(\tau)$ sequential algorithm: Forward Phase



$$\sum_{e \in S} \alpha(e) \leq w(S) \quad (\forall S \in \mathcal{S})$$

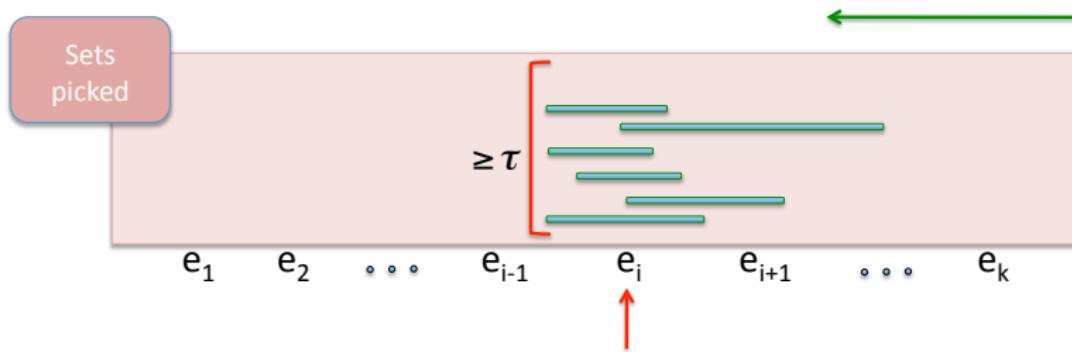
## $O(\tau)$ sequential algorithm: Reverse Delete Phase

- Only look at the elements *raised* in the forward phase
- Arrange them in the order they were raised and scan them in the reverse direction



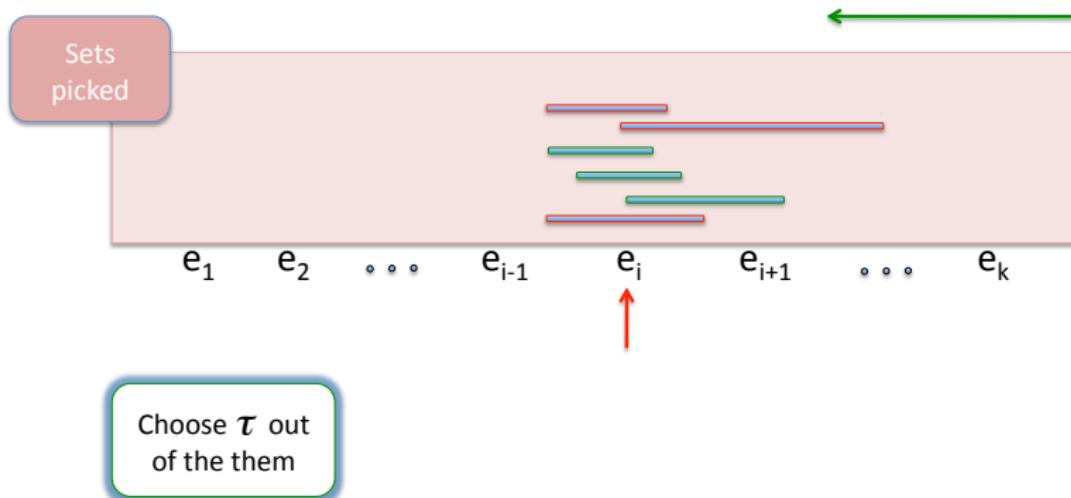
## $O(\tau)$ sequential algorithm: Reverse Delete Phase

- It's possible that more than  $\tau$  sets are spanning an element raised in the forward phase



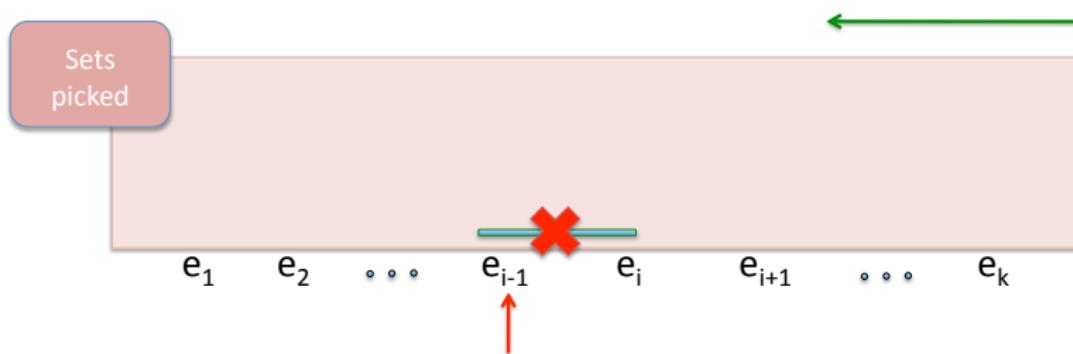
## $O(\tau)$ sequential algorithm: Reverse Delete Phase

- Bad!! *Compress them!!*
- Choose at most  $\tau$  out of them



## $O(\tau)$ sequential algorithm: Reverse Delete Phase

- After the compression, can we still guarantee coverage?
- Elements to its left are not dependent on it for their coverage.
- No set picked up in  $i - 1$  iterations can span  $e_i$ ; else  $e_i$  wouldn't have been raised in the forward phase



## $O(\tau)$ sequential algorithm: Reverse Delete Phase

- What about the elements to its right?
  - $e_i$  is  $\tau$  SNC in the restriction to its right (Layer decomposition)
- 
- $\lambda = 1$ , and
  - $\mu = \tau$ . Hence, we have  $O(\tau)$  approximation algorithm

# Parallel Algorithm: Comparison with [KYY '94]

Constant  $f$  sequential setting

- Raise one variable at a time
- Produce maximal solutions ( $\lambda = 1$ )
- # of iterations =  $\Omega(m)$

[KYY'94] parallel setting

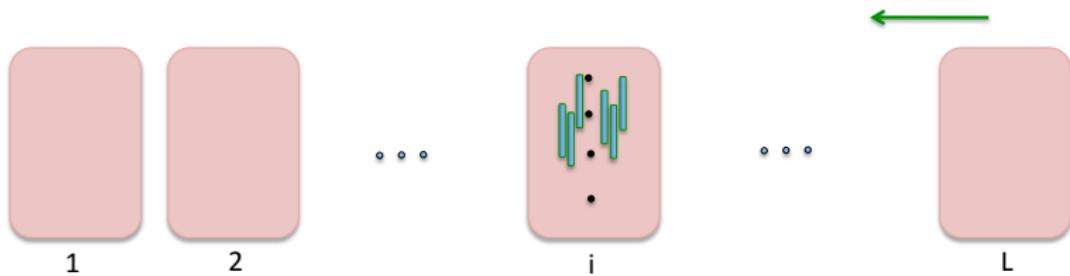
- Raise multiple variables simultaneously
- Produce near maximal solutions ( $\lambda = 1 - \epsilon$ )
- # of iterations =  $O(\frac{1}{\epsilon} f \log m)$

Our Results in Parallel setting

- Go according to layer decomposition. Inside each layer,
  - Raise multiple variables simultaneously
  - Produce  $(1/8)$  maximal solutions (worse than [KYY])
  - # of iterations  $O(\log m)$  (got rid of  $f$ )
- Total # of iterations  $O(L \log m)$

# Parallel Algorithm: Reverse Delete

- Complicated!
- $\mu = \tau^2$
- # of iterations  $O(L^2)$



# Open problems in parallel setting

- Approximation Ratio:  $O(\tau^2) \rightarrow O(\tau)$
- # of iterations:  $O(L^2) \rightarrow O(L)$
- Find algorithms for  $\tau$ -SNC systems beyond logarithmic length

*Thank you!*