News Article Classification (Multi-Label Learning: ML-KNN & BP-MLL)

Lauren Contard, Archit Datar, Bobby Lumpkin, Haihang Wu

The Ohio State University
STAT 6500



Overview

- Introduction and Problem Statement
- KNN Based Approaches
 - Binary Relevance
 - ML-KNN Algorithm
 - Results
- Neural Network Based Approaches
 - Architectures: Feed Forward & Recurrent Networks
 - Loss Functions: Cross Entropy vs BPMLL
 - Results
- 4 Discussion and Conclusions

Introduction and Problem Statement

KNN Based Approaches

Overall Approach: This ML-KNN algorithm takes a parametric, Bayesian approach towards estimating the Bayes Optimal Classifier. As with the single-label algorithm, it does this using the K nearest neighbors of an instance. Namely...

Overall Approach: This ML-KNN algorithm takes a parametric, Bayesian approach towards estimating the Bayes Optimal Classifier. As with the single-label algorithm, it does this using the K nearest neighbors of an instance. Namely...

• Given a test instance, t, \vec{Y}_t is determined using the MAP estimate:

Overall Approach: This ML-KNN algorithm takes a parametric, Bayesian approach towards estimating the Bayes Optimal Classifier. As with the single-label algorithm, it does this using the K nearest neighbors of an instance. Namely...

• Given a test instance, t, \vec{Y}_t is determined using the MAP estimate:

$$\begin{split} \vec{y_t}(\ell) &= \underset{b \in \{0,1\}}{\operatorname{argmax}} \mathbb{P}\left(\mathbf{H}_b^{\ell} | E_{\vec{C_t}(\ell)}^{\ell}\right), \quad \ell \in \mathcal{Y} \\ &= \underset{b \in \{0,1\}}{\operatorname{argmax}} \frac{\mathbb{P}\left(\mathbf{H}_b^{\ell}\right) \cdot \mathbb{P}\left(E_{\vec{C_t}(\ell)}^{\ell} | \mathbf{H}_b^{\ell}\right)}{\mathbb{P}\left(E_{\vec{C_t}(\ell)}^{\ell}\right)} \\ &= \underset{b \in \{0,1\}}{\operatorname{argmax}} \mathbb{P}\left(\mathbf{H}_b^{\ell}\right) \cdot \mathbb{P}\left(E_{\vec{C_t}(\ell)}^{\ell} | \mathbf{H}_b^{\ell}\right) \end{split}$$

Overall Approach: This ML-KNN algorithm takes a parametric, Bayesian approach towards estimating the Bayes Optimal Classifier. As with the single-label algorithm, it does this using the K nearest neighbors of an instance. Namely...

• Given a test instance, t, \vec{Y}_t is determined using the MAP estimate:

$$\begin{split} \vec{y_t}(\ell) &= \operatorname*{argmax}_{b \in \{0,1\}} \mathbb{P}\left(\mathbf{H}_b^{\ell} | E_{\vec{c}_t(\ell)}^{\ell}\right), \quad \ell \in \mathcal{Y} \\ &= \operatorname*{argmax}_{b \in \{0,1\}} \frac{\mathbb{P}\left(\mathbf{H}_b^{\ell}\right) \cdot \mathbb{P}\left(E_{\vec{c}_t(\ell)}^{\ell} | \mathbf{H}_b^{\ell}\right)}{\mathbb{P}\left(E_{\vec{c}_t(\ell)}^{\ell}\right)} \\ &= \operatorname*{argmax}_{b \in \{0,1\}} \mathbb{P}\left(\mathbf{H}_b^{\ell}\right) \cdot \mathbb{P}\left(E_{\vec{c}_t(\ell)}^{\ell} | \mathbf{H}_b^{\ell}\right) \end{split}$$

• Where we take a Bayesian approach towards estimating the prior probabilities, $\mathbb{P}\left(\mathbf{H}_{b}^{\ell}\right)$, and conditional probabilities, $\mathbb{P}\left(E_{\vec{C}_{t(\ell)}}^{\ell}|\mathbf{H}_{b}^{\ell}\right)$.

Notation:

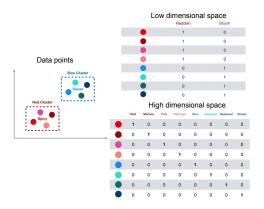
• Let N(x) denote the set of K nearest neighbors of x, identified in the training set.

- Let N(x) denote the set of K nearest neighbors of x, identified in the training set.
- Let $\vec{C}_x(\ell) = \sum_{a \in N(x)} \vec{y}_a(\ell)$ ($\ell \in \mathcal{Y}$) define a membership counting vector.

- Let N(x) denote the set of K nearest neighbors of x, identified in the training set.
- Let $\vec{C}_x(\ell) = \sum_{a \in N(x)} \vec{y}_a(\ell)$ ($\ell \in \mathcal{Y}$) define a membership counting vector.
- Let H_0^ℓ denote the event that test instance t does not have a label ℓ and let H_1^ℓ denote the event that it does have label ℓ .

- Let N(x) denote the set of K nearest neighbors of x, identified in the training set.
- Let $\vec{C}_x(\ell) = \sum_{a \in N(x)} \vec{y}_a(\ell)$ ($\ell \in \mathcal{Y}$) define a membership counting vector.
- Let H_0^ℓ denote the event that test instance t does not have a label ℓ and let H_1^ℓ denote the event that it does have label ℓ .
- Let E_j^{ℓ} $(j \in \{1, ..., K\})$ denote the event that, among the K nearest neighbors of t, there are exactly j instances which have label ℓ .

ML-KNN Algorithm: Reasons for dimension reduction



Having a high dimensional feature space causes Euclidian distances between points to be fairly similar as the distance vector components are partitioned across many dimensions. ?

Neural Network Based Approaches

Discussion and Conclusions

References