

# Gradients for Discrete Latent Variables

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# Problem Description

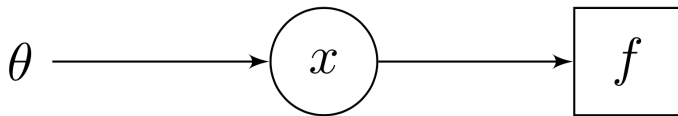
- Given a generic directed acyclic computation graph with discrete latent variables, we need gradient estimators for loss function.
- Naive backpropagation (with or without reparametrization) is not possible.

Discrete latent variables are very commonly encountered:

- Reinforcement Learning (Policy Gradients!)
- Conditional Computation (Mixture of Experts)
- GANs for structured outputs (especially Natural Language)

A very general and widely research problem. But, even today it is practically an open problem (with potentially wide reaching impact).

# A Generic Setup



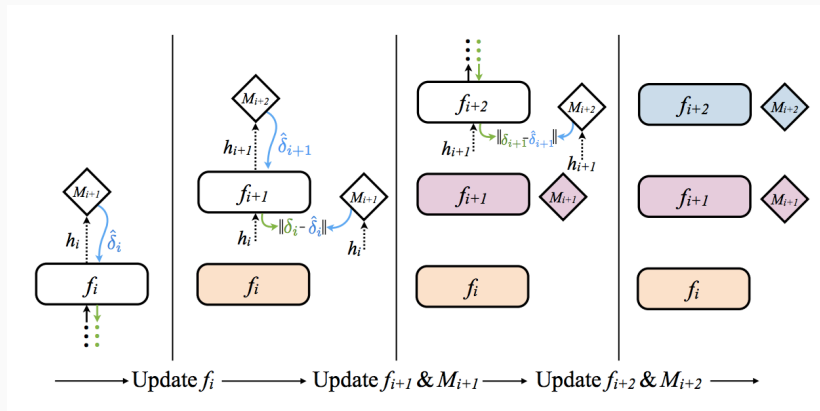
# Current Set of Solutions

A fair amount of research has gone into the solution of this problem:

- **REINFORCE**: The staple gradient estimator, which is the basis of “Policy Gradients” in RL. Usually a very high variance estimator, but, variance can be controlled using “baselines” (NVIL, MuProp etc.)
- **Straight Through**: A biased estimator, but works well in practice for small scale problems.
- **Gumbel-Softmax/Concrete**: A recently proposed estimator which uses samples a *reparametrizable continuous distribution* to represent samples from a discrete distribution (in limit). Usually has trouble scaling up as the discrete latent variables become higher dimensional.
- **REBAR**: A recently proposed unbiased estimator with low variance.

# A Detour: Synthetic Gradients

Recently proposed framework to compute gradients, which tries to decouple feedforward layers using “subnetworks”. A classic example of deep learning going meta!



## Another Detour: REINFORCE

### Classic log-gradient trick

Given latent variable  $x \sim p(x|\theta)$ , we require:

$$\frac{\partial \mathbb{E}_x[f(x)]}{\partial \theta} = \mathbb{E}_x[f(x) \frac{\partial \log p}{\partial \theta}] \approx \frac{1}{L} \sum_{i=1}^L f(x_i) \frac{\partial \log p(x_i|\theta)}{\partial \theta}$$

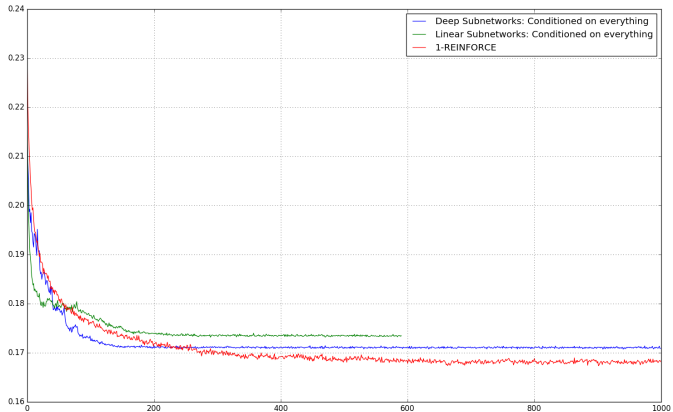
This is unbiased and with large number of samples, is a good approximation of the “true” gradient. Practically though, one sample is considered in which the high variance kicks in. Although, many solutions using “baselines” are used to reduce variance.

# Synthetic Gradients for Expectation Modelling?

- Neural networks have a natural tendency to average, when using the MSE loss.
- Idea: Use the unbiased REINFORCE as the training signal for a subnetwork.
- Hope is that the neural network would cut through the noise, and model the expectation if fed with enough examples.
- Skipping a lot of details!



# Results



Questions?