# COMS4040A&COMS7045A: High Performance Computing & Scientific Data Management Introduction to OpenMP: Part I

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- Overview
- OpenMP Core Features
  - Parallel Region Construct
  - Synchronization
  - Work Sharing
    - Loop Construct
    - Reduction
    - Sections/Section Construct



#### Outline

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# What is OpenMP?

#### Open specifications for Multi Processing

- An Application Program Interface (API) that may be used to explicitly direct multi-threaded, shared memory parallelism.
- Comprised of three primary API components:
  - Compiler Directives
  - Runtime Library Routines
  - Environment Variables
- API is specified for C, C++ and Fortran.
- Portable
- Easy to use



# **OpenMP Programming Model**

 OpenMP is designed for multi-processor/core, shared memory machines.

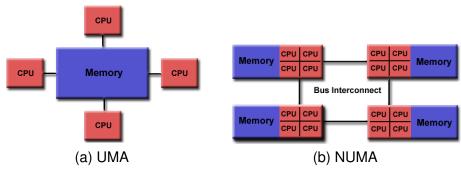


Figure: The shared memory model of parallel computation.



# OpenMP Programming Model Cont.

#### Thread Based Parallelism:

- OpenMP programs accomplish parallelism exclusively through the use of threads.
- A thread of execution is the smallest unit of processing that can be scheduled by an operating system.
- Threads exist within the resources of a single process. Without the process, they cease to exist.
- Typically, the number of threads match the number of machine processors/cores. However, the actual use of threads is up to the application.



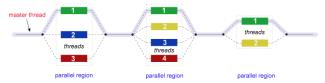
# OpenMP Programming Model Cont.

- Explicit Parallelism:
  - OpenMP is an explicit (not automatic) programming model, offering the programmer full control over parallelization.
- Compiler Directive Based: Most OpenMP parallelism is specified through the use of compiler directives which are embedded in C/C++ or Fortran source code.



# OpenMP Programming Model Cont.

- Fork Join Model: OpenMP programs begin as a single process: the master thread. The master thread executes sequentially until the first parallel region construct is encountered.
  - FORK:
    - The master thread then creates a team of parallel threads;
    - Becomes the master of this group of threads;
    - Asssigned the thread number 0 within the group.
  - JOIN: When the team threads complete the statements in the parallel region construct, they synchronize and terminate, leaving only the master thread.







## OpenMP API Overview

- Three components: Compiler Directives, Runtime Library Routines, Environment Variables.
  - Compiler Directives: Appear as comments in your source code to guide the compilers.
  - The OpenMP API includes an ever-growing number of run-time library routines.
  - OpenMP provides several environment variables for controlling the execution of parallel code at run-time.



# OpenMP API Overview Cont.

- OpenMP core syntax:
  - Most of the constructs in OpenMP are compiler directives:
     #pragma omp constructs [clause [clause]...]
  - OpenMP code structure: Structured block. A block of one or more statements with one point of entry and one point of exit at the end.
  - Function prototypes and types in the file: #include (omp.h)



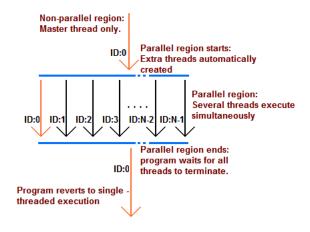


Figure: OpenMP parallel construct execution model



# Compiling OpenMP Programs

# Exercise 1: Write a multi-threaded C program that prints "Hello World!". (hello\_omp.c)

```
1 #include <stdio.h>
2 #include <omp.h>
3 int main()
4
   //Parallel region with default number of threads
    #pragma omp parallel
   //Start of the parallel region
     //Runtime library function to return a thread number
      int ID = omp_get_thread_num();
10
     printf("Hello World! (Thread %d)\n", ID);
11
12
    }//End of the parallel region
```



# Compiling OpenMP Programs Cont.

- To compile, type **gcc** -fopenmp hello\_omp.c -o hello\_omp.
- To run, type ./hello\_omp



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# Parallel Region Construct

A parallel region is a block of code that will be executed by multiple threads. This is the fundamental OpenMP parallel construct.

Syntax:

```
#pragma omp parallel [clause[[,] clause] ... ]
structured block
```



#### Typical clauses in clause list:

Degree of concurrency:

```
num_threads(<integer expression>)
```

- Data scoping:
  - private(<variable list>)
  - firstprivate(<variable list>)
  - shared(<variable list>)
  - default(<data scoping specifier>)
- Conditional parallelization:if (<scalar expression>),
   determines whether the parallel construct creates threads.



• Interpreting an OpenMP parallel directive

```
#pragma omp parallel if (is_parallel==1) \
num_threads(8) shared(b) private(a) \
firstprivate(c) default(none)
{
/* structured block */
}
```



You create threads in OpemMP with the parallel construct.

#### Example (1)

Create a 4-thread parallel region using *num\_threads* clause.

```
#include <stdio.h>
  #include <omp.h>
  int main()
4
5
    //Parallel region with default number of threads
    #pragma omp parallel num_threads(4)
    //Start of the parallel region
      //Runtime library function to return a thread number
      int ID = omp_get_thread_num();
10
      printf("Hello World! (Thread %d)\n", ID);
11
    }//End of the parallel region
12
13
```

#### Example (2)

Create a 4-thread parallel region using runtime library routine.

```
#include <stdio.h>
#include <omp.h>
int main()

{
    omp_set_num_threads(4);
    #pragma omp parallel

    int ID = omp_get_thread_num();
    printf("Hello World! (Thread %d)\n", ID);
}

}
```



Different ways to set the number of threads in a parallel region:

- Using runtime library function *omp\_set\_num\_threads()*.
- Setting clause num\_threads, e.g., #pragma omp parallel num\_threads (8).
- Specify at runtime using environmental variable
   OMP\_NUM\_THREADS, e.g., export OMP\_NUM\_THREADS=8

**Exercise 2:** Compile and run "parallel\_region.c". change the number of threads in the parallel region using different ways.



# Computing the $\pi$ Using Integration

**Exercise 3:** Compute the number  $\pi$  using numerical integration:

$$\int_{0}^{1} \frac{4.0}{1+x^2} = \pi.$$

- Write a serial program for the problem.
- Parallelize the serial program using OpenMP directive.
- Compare the results from 1 and 2.

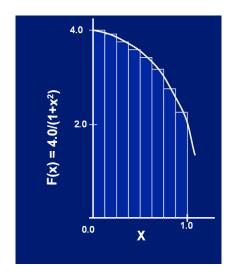


Figure: Approximating the  $\pi$  using numerical integration  $\frac{\pi}{\text{UNIVERSITY}}$ 

# Serial Program for Computing Π

```
static long num_steps = 1000000;
2 double step;
3 int main ()
    int i;
    double x, pi, sum = 0.0;
    step = 1.0/(double) num_steps;
    for (i=0;i< num_steps; i++) {</pre>
      x = (i+0.5) * step;
      sum = sum + 4.0/(1.0+x*x);
10
11
      pi = step * sum;
12
```

**Exercise 4:** Parallelize the serial pi program pi.c using OpenMP parallel construct.

# Parallel Program for Computing Π — Method I

```
static long num_steps = 1000000;
2 double step;
3 #define NUM THREADS 2
4 int main () {
    int i, nthreads;
    double pi, sum[NUM THREADS];
6
    step = 1.0/(double) num_steps;
    omp set num threads (NUM THREADS);
8
    #pragma omp parallel
9
      int i, id, tthreads; double x;
11
      tthreads = omp_get_num_threads();
12
      id = omp_get_thread_num();
13
14
      if (id==0) nthreads=tthreads;
      for (i=id, sum[id]=0.0;i< num_steps; i=i+tthreads) {</pre>
15
        x = (i+0.5)*step;
16
        sum[id] = sum[id] + 4.0/(1.0+x*x);
17
18
    for (i=0, pi=0.0; i < nthreads; i++)</pre>
19
        pi += step * sum[i];
20
```

# False Sharing (1)

If independent data elements happen to sit on the same cache line, each update will cause the cache lines to "slosh back and forth" between threads...this is called **false sharing**.

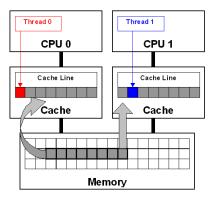


Figure: False sharing



# False Sharing (2)

- Processors usually execute operations faster than they access data in memory.
- To address this problem, a block of relatively fast memory is added to a processor — cache.
- The design of cache considers the temporal and spatial locality.
- For example, x is a shared variable and x = 5, my\_y, my\_z are private variable, what will be the value of my\_z?

```
if me==0 {
my_y = x;
x++;
}
else if me==1 {
my_z = x;}
```



# Cache Coherence (1)

#### Example (3)

Suppose x = 2 is a shared variable, y0, y1, z1 are private variable. If the statements in Table 1 are executed at the indicated times, then x = ?, y0 = ?, y1 = ?, z1 = ?

Time	Core 0	Core 1
0	y0 = x;	y1 = 3 * x;
1	x = 7;	Statements not involving <i>x</i>
2	Statements not involving $x$	z1=4*x;

Table: Example - cache coherence



# Cache Coherence (2)

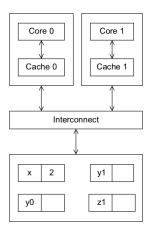


Figure: Example - cache coherence cont.



## Cache Coherence (3)

Cache coherence problem - The caches for single processor systems provide no mechanism for insuring that when the caches of multiple processors store the same variable, an update by one processor to the cache variable is 'seen' by the other processors. That is, the cached value stored by the other processors is also updated.



# False Sharing (3)

- Suppose two threads with separate caches access different variables that belong to the same cache line. Further suppose at least one of the threads updates its variable.
- Even though neither thread has written to a shared variable, the cache controller invalidates the entire cache line and forces the other threads to get the values of the variables from main memory.
- The threads aren't sharing anything (except a cache line), but the behaviour of the threads with respect to memory access is the same as if they were sharing a variable. Hence the name false sharing.
- Avoiding false sharing having each thread use its own private storage, and then update the shared variable when they are done.



# Parallel Program for Computing Π — Method II

```
static long num_steps = 1000000;
2 double step;
3 #define NUM THREADS 2
4 int main () {
    int i, nthreads, tthreads, id;
    double pi = 0.0, sum = 0.0, x;
6
    step = 1.0/(double) num_steps;
    omp set num threads (NUM THREADS);
8
    #pragma omp parallel
9
      tthreads = omp_get_num_threads();
11
      id = omp_get_thread_num();
12
      if (id==0) nthreads=tthreads;
13
14
      for (i=id;i< num_steps; i=i+tthreads) {</pre>
15
        x = (i+0.5)*step;
        sum = sum + 4.0/(1.0+x*x);
16
17
      pi += step * sum;
18
19
```

#### Race Condition

- When multiple threads update a shared variable, the computation exhibits non-deterministic behaviour — race condition. That is, two or more threads attempt to access the same resource.
- If a block of code updates a shared resource, it can only be updated by one thread at a time.



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# Synchronization

- Synchronization: Bringing one or more threads to a well defined and known point in their execution. Barrier and mutual exclusion are two most often used forms of synchronization.
  - Barrier: Each thread wait at the barrier until all threads arrive.
  - Mutual exclusion: Define a block of code that only one thread at a time can execute.
- Synchronization is used to impose order constraints and to protect access to shared data.
- In Method II of computing  $\pi$ ,

```
sum = sum + 4.0/(1.0+x*x); is called a critical section.
```

 Critical section - a block of code executed by multiple threads that updates a shared variable, and the shared variable can only be updated by one thread at a time.

# High level synchronizations in OpenMP

 critical: Mutual exclusion. Only one thread at a time can enter a critical section.

#pragma omp critical

```
1 float result;
 #pragma omp parallel
4
    float B; int i, id, nthrds;
    id = omp_get_thread_num();
6
    nthrds = omp get num threads();
    for(i = id; i < nthrds; i+= nthrds)</pre>
      B = big job(i);
      #pragma omp critical
        result += calc(B);
13
14
15
```

# High level synchronizations in OpenMP Cont.

- atomic: Basic form. Provides mutual exclusion but only applies to the update of a memory location.
- #pragma omp atomic

The statement inside the *atomic* must be one of the following forms:

```
• x op = expr, where op \in (+ =, - =, * =, / =, % =)
```

- $\bullet$  ++ x
- $\bullet$  -- X

```
#pragma omp parallel
2 {
3    .....
4    double tmp, B;
5    B = calc();
6    tmp = big_calc(B);
7    #pragma omp atomic
8    X += tmp;
9    ....
10 }
```

# High level synchronizations in OpenMP Cont.

barrier: Each thread waits until all threads arrive.

```
#pragma omp barrier
```

```
#pragma omp parallel

int id=omp_get_thread_num();

A[id]=calc1(id);

#pragma omp barrier

B[id]=calc2(id, A);

.....

}
```



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## **Worksharing Construct**

- A parallel construct by itself creates an SPMD program, i.e., each thread redundantly executes the same code.
- How do you split up pathways through the code between threads within a team? Worksharing.
- Worksharing
  - Loop construct: Splits up a loop iterations among the threads in a team. The name of the loop construct is for.
  - sections/section constructs
  - single construct
  - task construct



## **Loop Construct**

### Example (4)

Given arrays A[N] and B[N]. Find A = A + B.

```
1 .....
2 //Serial
3 for (i=0; i < N; i++)
4 a[i]=a[i]+b[i];</pre>
```

```
1 .....
2 //Using loop construct
3 #pragma omp parallel
4 #pragma omp for
5 {
6 for (i=0; i<N; i++)
7 a[i] = a[i] + b[i];
8 }</pre>
```

```
//Using parallel construct
  #pragma omp parallel
    int id, i, nthrds, istart,
         iend:
    id i= omp_get_thread_num()
5
    nt.hrds =
        omp_get_num_threads();
    istart = id * N/nthrds;
    iend = (id+1) * N/nthrds;
    if (id==nthrds-1)
10
      iend = N;
    for (i=istart; i<iend; i++)</pre>
11
      a[i] = a[i] + b[i];
12
```

## Loop Construct Cont.

- The schedule clause specifies how the iterations of the loop are assigned to the threads in a team.
- The syntax is #pragma omp for schedule(kind [, chunk]).
- Schedule kinds:
  - **schedule(static [,chunk])**: Deals out blocks of iterations of size chunk to each thread in a round robin fashion.
    - The iterations can be assigned to the threads before the loop is executed.
  - schedule(dynamic [,chunk]): Each thread grabs chunk size of iterations off a queue until all iterations have been handled. The default is 1.
    - The iterations are assigned while the loop is executing



#### Schedule clause

- schedule(guided [,chunk]): Threads dynamically grab blocks of iterations. The size of the block starts large and shrinks down to size chunk as the calculation proceeds. The default is 1.
- schedule(runtime): Schedule and chunk size taken from the OMP\_SCHEDULE environment variable.
  - For example, export OMP\_SCHEDULE="static,1"
- schedule(auto): Left up to the runtime or compiler to choose.



#### More on schedule

- Most OpenMP implementations use a roughly block partition.
- There is some overhead associated with schedule.
- The overhead for dynamic is greater than static, and the overhead for guided is the greatest.
- If each iteration of a loop requires roughly the same amount of computation, then it is likely that the default distribution will give the best performance.
- If the cost of the iterations decreases linearly as the loop executes, then a static schedule with small chunk size will probably give the best performance.
- If the cost of each iteration can not be determined in advance, then schedule (runtime) can be used.



# The number of threads active (1)

The omp\_set\_dynamic routine enables or disables dynamic adjustment of the number of threads available for the execution of subsequent parallel regions.

 omp\_set\_dynamic() – A call to this function with nonzero argument allows OpenMP to choose any number of threads between 1 and the set number of threads.

### Example

```
omp_set_dynamic(1);
#pragma omp parallel num_threads(8)
```

allows the OpenMP implementation to choose any number of threads between 1 and 8.



# The number of threads active (2)

#### Example

```
omp_set_dynamic(0);
#pragma omp parallel num_threads(8)
```

only allows the OpenMP implementation to choose 8 threads. The action in this case is implementation dependent.

 omp\_get\_dynamic() – You can determine the default setting by calling this function.



## Example

### Example (5)

Add various schedule clause in Example\_ploop.c to see the number of threads created in the parallel region.

### Example (6)

Use omp\_set\_dynamic() in Example\_ploop.c to inspect the interaction with num\_threads clause.



## Loop Construct Cont.

Basic approach to parallelize a loop:

- Find compute intensive loops
- Make the loop iterations independent, so they can safely execute in any order without loop carried dependencies.
- Place the appropriate OpenMP directives and test.

### Example

Removing a loop carried dependency.

```
1 //Loop dependency
2 int i, j, A[MAX];
3 j=5;
4 for (i=0; i<MAX; i++) {</pre>
   j+=2;
   A[i]=biq(j);
8 //Removing loop dependency
  int i, A[MAX];
  //Shortcut: "parallel for"
  #pragma omp parallel for
    for (i=0; i<MAX; i++) {</pre>
12
      int j=5+2*(i+1);
13
      A[i]=biq(j);
14
15
```

### Reduction

```
double ave=0.0, A[MAX];
int i;
for(i=0;i<MAX;i++) {
   ave+=A[i];
}
ave = ave/MAX;
.....</pre>
```

We are aggregating multiple values into a single value—**reduction**. Reduction operation is supported in most parallel programming environments.

- OpenMP reduction clause: reduction(op:list).
- Inside a parallel or a work-sharing construct
  - A local copy of each list variable is made and initialized depending on the operation specified by the operator "op".
  - Each thread updates its own local copy
  - Local copies are aggregated into a single value.



### Reduction Cont.

 Associative operands that can be used with reduction (for C/C++) and their common initial values.

Ор	Initial value	Ор	Initial value
+	0	&	~0
*	1		0
-	0	^	0
min	Large number (+)	&&	1
max	Most neg. number		0



#### Exercise

- Exercise 6: Parallelize the serial pi program with a loop construct.
   Your goal is to minimize the number of changes made to the serial code.
- Exercise 7: Parallelize saxpy:

$$y(i) = a * x(i) + y(i), 1 \le i \le n.$$
 (1)

Parallelize the serial version saxpy\_v0.c of saxpy.

<u>Exercise 8:</u> Parallelize the dot product of two vectors. That is, given two vectors X and Y with n elements each,

$$\mathbf{X} \cdot \mathbf{Y} = \sum_{i=1}^{n} x_i y_i. \tag{2}$$

Explore using different OpenMP parallelization methods. You may start with the serial version dotProd\_v0.c

# Data dependences

 Data dependences occur in loops in which the computation in one iteration depends on the results of one or more previous iterations.

```
fibo[0]=1;
fibo[1]=1;
for(i=2;i<n;i++)
  fibo[i]=fibo[i-1]+fibo[i-2];</pre>
```

• If we parallelize this code segment as follows, what happens?

```
fibo[0]=1;
fibo[1]=1;
#pragma omp parallel for num threads(thread count)
for(i=2;i<n;i++)
  fibo[i]=fibo[i-1]+fibo[i-2];</pre>
WITS
```

# Data dependences cont.

- A loop in which the results of one or more iterations depend on other iterations cannot, in general, be correctly parallelized by OpenMP.
- The dependence of the computation of fibo[6] on the computation of fibo[5] is called a data dependence.
- Since the value of fibo[5] is calculated in one iteration, and the result is used in a subsequent iteration, the dependence is also called a loop carried dependence.



## Data dependence cont.

- At least one of the statements must write or update the variable in order for the statements to represent a dependence;
- In order to detect a loop carried dependence, we should only concern ourselves with variables that are updated by the loop body;
- That is, we should look for variables that are read or written in one iteration, and written in another.



### Sections/Section Construct

- sections directive enables specification of task parallelism
- The sections worksharing construct gives a different structured blocks to each thread.
- Syntax:

```
#pragma omp sections [clause[[,] clause]...]
{
    [#pragma omp section]
    structured block
    [#pragma omp section
    structured block]
    ...
}
```

 Each section must be a structured block of code that is independent of other sections.



### Sections/Section Construct Cont.

#### An example:

```
#pragma omp parallel
    #pragma omp sections
4
      #pragma omp section
        x calc();
6
      #pragma omp section
        y_calc();
      #pragma omp section
        z_calc();
12
```



### **Exercises**

- Complete all the exercises in the class.
- Read Chapter 17 in Quinn's book



#### References

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