

COMS4040A Assignment 1 – Report

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1 Introduction

The k nearest neighbour (KNN) algorithm is a simple, widely used algorithm used to solve classification and regression problems[1]. Its applications vary from detecting intrusive programs[5] to text classification [4] to the analysis of nuclear magnetic resonance spectra [3].

The algorithm itself is very simple. Consider a set P of m reference points $p_i \in \mathbb{R}^d$ and a set Q of n query points $q_j \in \mathbb{R}^d$. The aim of the algorithm is to find the k nearest (according to some distance measure) points in P for each $q_j \in Q$, for some integer k.

In the brute force approach we first compute the distance between each query point and each reference point and store it in a distance matrix of size $n \times m$. We then sort each row in the matrix (keeping track of any swaps via the index matrix), before returning the $n \times k$ index sub-matrix containing the indices of the k-nearest neighbours to each query point.

Special attention must be given to the distance measure and sorting functions applied above. In this report, we consider the Euclidean and Manhattan distance measures, and for sorting we consider the quicksort, bubblesort and mergesort algorithms.

Because any distance measure in \mathbb{R}^d must take $\mathscr{O}(d)$ time to compute, the k nearest neighbours algorithm must take $\mathscr{O}(mnd)$ time to compute distances. Since quicksort and mergesort are both $\mathscr{O}(mlog(m))$ on average, and bubblesort is $\mathscr{O}(m^2)$ on average, the final algorithm must take $\mathscr{O}(nmlog(m))$ time to sort using quicksort or mergesort, and $\mathscr{O}(nm^2)$ time to sort using bubblesort. For large m, n and d, these complexities are problematic. However, as we shall see in Section 2, this can be significantly improved upon using parallel algorithms.

2 Methodology

As mentioned in Section 1, there are two computationally intensive sections in the algorithm: the distance computation and the sorting component. We shall apply Foster's Design Methodology to each of these sections individually in the hope of improving the performance of the algorithm.

2.1 Distance Computation

Consider the two distance measures. Because the only difference between these algorithms is the square of the difference in the Eucidean metric and the absolute value of the difference in the Manhattan metric, they can be dealt with in the same way. No matter the algorithm used, the distance function is performed nm times in the k nearest neighbours algorithm. Furthermore, the computation of the distance between points q_i and p_j is in no way dependent on the computation of distance between points q_s and p_t for $s \neq i$ and $t \neq j$. We will therefore collapse the for-loops in the algorithm which iterate over each q_i and p_j into nm tasks which can be divided among processors.

In practice, this partitioning is done by the OpenMP for directive with the collapse(2) clause. The communication, agglomeration and mapping steps are performed by the OpenMP compiler.

2.2 Sorting

Consider the sorting algorithms. These are all repeated n times, once for each q_i . Here, rather than focus on the loop over each i, we will focus on applying Foster's Design Methodology to each sorting algorithm individually.

Quicksort: Here we note that each call to Quicksort recursively calls Quicksort on two portions of the list. We can therefore partition each recursive call into a separate task to be executed by a thread. This is done using the OpenMP **sections/section** construct, or alternatively, the **task** construct. However, at a certain point, the overhead involved with scheduling threads becomes significant, so that sorting a small sublist in serial is actually faster than further partitioning the task. We therefore introduce a condition: if high - low < c for some cut-off c, we will sort in serial. Otherwise, we will partition further. Communication, agglomeration and mapping is then handled by the OpenMP compiler.

Mergesort: Here we note that Mergesort, like Quicksort, recursively calls Mergesort on two portions of the list. Therefore, we can parallelisze it identically: by partitioning each recursive call into a separate task using the OpenMP **sections/section** or **task** constructs. Once again, we employ the cut-off condition to reduce overhead.

Bubblesort: Here we employ an algorithm known as the Odd-Even sort or the Parallel-Neighbour sort [2], which sorts pairs of numbers in the list in parallel. These pairs alternate from 0-1, 2-3, 4-5, etc. (even) to 1-2, 3-4, 5-6, etc. (odd). This can be thought of as the parallel version of the bubblesort.

In this algorithm we partition each inner for-loop into a task using the OpenMP for directive. Once again, communication, agglomeration and mapping are handled by the OpenMP compiler.

3 Empirical Analysis

The following experiments were run on an Intel i7-7700 CPU @ 3.60GHz with 4 cores and, therefore, 4 threads were used. Random points in \mathbb{R}^d were generated using the *generatePoints.py* file and stored in text files which were read in by the programs. For each experiment, the time taken to calculate every distance and the time taken to sort every list were measured and tabulated. Thus the total time is comprised only of these two measures.

In the first experiment, n varied between n = 200, n = 800 and n = 1600, with constant d = 32 and m = 1000. All 3 sorting algorithms and both distance metrics are used in the serial and parallel (using OpenMP sections construct) approaches. The results are tabulated below.

Figure 1: $d = 32$, $m = 1000$											
			N = 200			N = 800		N = 1600			
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.02133	0.023122	0.044452	0.074729	1.074729	2.074729	4.074729	5.074729	6.074729	
		47.98%	52.02%		3.60%	51.80%		67.08%	83.54%		
	Euclid Mergesort	0.018935	0.020924	0.039859	0.078226	0.083202	0.161428	0.146966	0.166312	0.313278	
	Eucliu Mergesort	47.50%	52.50%		48.46%	51.54%		46.91%	53.09%		
	Euclid Bubblesort	0.019371	0.531754	0.551125	0.074229	2.143703	2.217932	0.147234	4.304201	4.451435	
Serial	Luciiu Dubbiesoit	3.51%	96.49%		3.35%	96.65%		3.31%	96.69%		
Serial	Manhattan Quicksort	0.048478	0.020886	0.069364	0.191908	0.084287	0.276195	0.392653	0.170683	0.563336	
	Mailiattaii Quicksoft	69.89%	30.11%		69.48%	30.52%		69.70%	30.30%		
	Manhattan Mergesort	0.04822	0.020996	0.069216	0.191624	0.084608	0.276232	0.382254	0.166384	0.548638	
	maimattan mergesort	69.67%	30.33%		69.37%	30.63%		69.67%	30.33%		
	Manhattan Bubblesort	0.048939	0.532164	0.581103	0.196771	2.199062	2.395833	0.383467	4.262315	4.645782	
		8.42%	91.58%		8.21%	91.79%		8.25%	91.75%		
			N = 200			N = 800			N = 1600		
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.005218	0.022326	0.027544	0.019432	0.089591	0.109023	0.039463	0.178609	0.218072	
		18.94%	81.06%		17.82%	82.18%		18.10%	81.90%		
	Euclid Mergesort	0.005017	0.012565	0.017582	0.02015	0.049569	0.069719	0.039265	0.097854	0.137119	
	•	28.53%	71.47%		28.90%	71.10%		28.64%	71.36%		
	Euclid Bubblesort	0.005279	0.302504	0.307783	0.01984	1.206996	1.226836	0.039092	2.407322	2.446414	
Parallel - Sections		1.72%	98.28%	0.005400	1.62%	98.38%	0.400040	1.60%	98.40%	0.070477	
	Manhattan Quicksort	0.01245	0.022688	0.035138	0.050333	0.08931	0.139643	0.097206	0.182271	0.279477	
		35.43%	64.57%	0.005004	36.04%	63.96%	0.00044	34.78%	65.22%	0.405500	
	Manhattan Mergesort	0.012906	0.012428	0.025334	0.049283	0.048857	0.09814	0.097688	0.097834	0.195522	
	_	50.94%	49.06%	0.200700	50.22%	49.78%	4.000040	49.96%	50.04%	2 400205	
	Manhattan Bubblesort	0.012222 3.96%	0.296567 96.04%	0.308789	0.049104 3.93%	1.201139 96.07%	1.250243	0.097324 3.89%	2.401881 96.11%	2.499205	

What is immediately clear is that bubblesort is by far the slowest of the sorting algorithms, in both serial and parallel. Mergesort is on average slightly faster than quicksort in serial, and noticeably faster than quicksort in parallel. Overall, the parallel approach is much faster, with quicksort being 1.77 times as fast, bubblesort being 1.85 times as fast and mergesort being 2.59 times as fast. What is also clear is that the Euclidean distance metric is, on average, faster than the Manhattan metric, in both approaches.

Consider now the same experiment with m = 10000.

Figure 2: $d = 32$, $m = 10000$											
			N = 200			N = 800		N = 1600			
	Dist Sort			Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.185437	0.278401	0.463838	0.742582	1.142975	1.885557	1.49807	2.263777	3.761847	
	Euclid Quicksort	39.98%	60.02%		39.38%	60.62%		39.82%	60.18%		
	Euclid Mergesort	0.185513	0.270867	0.45638	0.745718	1.086814	1.832532	1.504401	2.174905	3.679306	
	Euclid Mergesort	40.65%	59.35%		40.69%	59.31%		40.89%	59.11%		
	Euclid Bubblesort	0.184268	69.25875	69.443018	0.737184	276.673706	277.41089	1.515635	555.761849	557.277484	
Serial	Euclid Bubblesoft	0.27%	99.73%		0.27%	99.73%		0.27%	99.73%		
Serial	Manhattan Quicksort	0.471655	0.278674	0.750329	1.932381	1.127525	3.059906	3.823178	2.227547	6.050725	
	Mannattan Quicksort	62.86%	37.14%		63.15%	36.85%		63.19%	36.81%		
	Manhattan Mergesort	0.47597	0.274112	0.750082	1.904061	1.093334	2.997395	3.903143	2.232834	6.135977	
	Marinattan Mergesort	63.46%	36.54%		63.52%	36.48%		63.61%	36.39%		
	Manhattan Bubblesort	0.471319	69.964528	70.435847	1.887251	279.456457	281.343708	3.847039	555.535158	559.382197	
		0.67%	99.33%		0.67%	99.33%		0.69%	99.31%		
			N = 200			N = 800			N = 1600		
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.047862	0.297711	0.345573	0.190373	1.194485	1.384858	0.379271	2.390482	2.769753	
	Luciia Quicksort	13.85%	86.15%		13.75%	86.25%		13.69%	86.31%		
	Euclid Mergesort	0.072815	0.155163	0.227978	0.190162	0.625722	0.815884	0.388684	1.25202	1.640704	
	Luciia Mergesort	31.94%	68.06%		23.31%	76.69%		23.69%	76.31%		
	Euclid Bubblesort	0.047736	16.933148	16.980884	0.19027	66.511185	66.701455	0.383545	142.115242	142.498787	
Parallel - Sections	Luciia Bubbicsort	0.28%	99.72%		0.29%	99.71%		0.27%	99.73%		
raialei – Sections	Manhattan Quicksort	0.120505	0.297456	0.417961	0.480964	1.194215	1.675179	0.974073	2.382374	3.356447	
	marriattari Quickoort	28.83%	71.17%		28.71%	71.29%		29.02%	70.98%		
	Manhattan Mergesort	0.12055	0.154432	0.274982	0.481281	0.626853	1.108134	0.966649	1.241424	2.208073	
		43.84%	56.16%		43.43%	56.57%		43.78%	56.22%		
	Manhattan Bubblesort	0.120661	16.675757	16.796418	0.481504	68.690477	69.171981	1.251648	132.479225	133.730873	
		0.72%	99.28%		0.70%	99.30%		0.94%	99.06%		

Here it is even more clear that the bubblesort is inefficient, as its time complexity scales quadratically in m. With such a large m, the advantages of the parallel approach are even more apparent, with quicksort speeding up by a factor of 1.61, mergesort by 2.53 and bubblesort by 4.07.

We now vary d = 64,128,256,512 and keep n = 800, m = 5000 constant. For brevity's sake, we consider only the quicksort algorithm.

Figure 3: $n = 800$, $m = 5000$													
		N = 800, M = 5000											
		D = 64			D = 128			D = 256			D = 512		
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total
	Euclid Quicksort	0.674948	0.515213	1.190161	1.315786	0.515559	1.831345	2.841606	0.535521	3.377127	5.132581	0.506111	5.638692
Serial		56.71%	43.29%		71.85%	28.15%		84.14%	15.86%		91.02%	8.98%	
	Manhattan Quicksort	1.976354	0.520283	2.496637	4.081035	0.512601	4.593636	8.34295	0.510896	8.853846	16.495382	0.506719	17.002101
		79.16%	20.84%		88.84%	11.16%		94.23%	5.77%		97.02%	2.98%	
			D = 64			D = 128			D = 256			D = 512	
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total
Parallel – Sections	Euclid Quicksort	0.177186	0.553123	0.730309	0.351709	0.55312	0.904829	0.686863	0.550247	1.23711	1.34542	0.541005	1.886425
		24.26%	75.74%		38.87%	61.13%		55.52%	44.48%		71.32%	28.68%	
	Manhattan Quicksort	0.501356	0.551249	1.052605	1.285376	0.600948	1.886324	2.097209	0.54858	2.645789	4.200083	0.543786	4.743869
		47 63%	52 37%		68 14%	31 86%		70 27%	20 73%		88 54%	11.46%	

Here it is easily observed that the Manhattan metric is much slower than the Euclidean one. This is likely due to the presence of a conditional statement when evaluating $|p_i - q_i|$. We also note the effectiveness of the parallelisation, which on average sped the Euclidean calculation by a factor of 2.74 and the Manhattan calculation by a factor of 3.19.

Finally, we consider different approaches in parallelisation. Here, we test the serial version against the same parallel version used above (using the OpenMP **sections** construct) and against a parallel version which instead uses the OpenMP **task** construct. In this experiment, n is varied, d = 128 and m = 5000. For brevity's sake, we consider only the Euclidean distance metric. We do not consider the bubblesort, as it is implemented with the OpenMP **for** construct.

			Figure	4: d = 1	28, m = 50	000					
			_		D = 128, M = 50	00					
			N = 200 N = 800 N =								
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.340829	0.127135	0.467964	1.310158	0.509183	1.819341	2.655198	1.021084	3.676282	
Coriol	Eucha Quicksort	72.83%	27.17%		72.01%	27.99%		72.23%	27.77%		
Serial	Fuelid Managed	0.33894	0.128812	0.467752	1.335546	0.513219	1.848765	2.716285	1.008583	3.724868	
	Euclid Mergesort	72.46%	27.54%		72.24%	27.76%		72.92%	27.08%		
			N = 200			N = 800		N = 1600			
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Euclid Quicksort	0.097136	0.136048	0.233184	0.344492	0.545125	0.889617	0.685049	1.092301	1.77735	
Parallel - Sections		41.66%	58.34%		38.72%	61.28%		38.54%	61.46%		
Parallel - Sections	Euclid Mergesort	0.089513	0.072728	0.162241	0.34213	0.289784	0.631914	0.71208	0.600064	1.312144	
		55.17%	44.83%		54.14%	45.86%		54.27%	45.73%		
			N = 200			N = 800			N = 1600		
		Dist	Sort	Total	Dist	Sort	Total	Dist	Sort	Total	
	Fuelid Quickcort	0.085774	0.054641	0.140415	0.341588	0.218592	0.56018	0.694535	0.440426	1.134961	
Denettet Teels	Euclid Quicksort	61.09%	38.91%		60.98%	39.02%		61.19%	38.81%		
Parallel – Task	Euclid Mergesort	0.089108	0.072744	0.161852	0.343702	0.292879	0.636581	0.697322	0.583481	1.280803	
		55.06%	44.94%		53.99%	46.01%		54.44%	45.56%		

The task approach does indeed improve performance, performing the quicksort algorithm 1.58 times faster and the mergesort algorithm 1.01 times faster than the sections approach.

4 Summary

From the above, we can conclude that parallelisation, especially with the OpenMP **task** and **for** constructs, vastly improves performance. As expected mergesort and quicksort (both $\mathcal{O}(mlog(m))$) greatly outperform the bubblesort ($\mathcal{O}(nm^2)$). This is especially noticeable for larger values of m and n. We also conclude that the Euclidean distance metric is faster than the Manhattan distance.

Despite the challenges of parallel computing (such as overcoming issues like false sharing and balancing the overhead of thread creation and scheduling against the benefits of parallelism), the above experiments are a testament to the advantages of the approach when dealing with larger data size. Further work could involve applying parallelism to other parts of the program, such as data reading. It could also involve experimenting with more distance metrics and sorting algorithms.

References

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