David Hoare

Robinson College

Computer Science Tripos

Part II Dissertation

The implementation of a compiler from BASIC 78 to LLVM

2015

David Hoare

Robinson College

The implementation of a compiler from BASIC 78 to LLVM

Computer Science Tripos Part II (2015)

<word count>

Project Originator: Michael Gale

Project Supervisor: Michael Gale

The aim of the project was to implement a compiler for the ANSI X3.60-1978 standard for BASIC. The compiler was to output LLVM bytecode which can then be further compiled and assembled to target one of many instruction sets. The compiler was to be written in C#, and make would use of the LLVM API in the code generation module.

A compiler has been written in C# that efficiently compiles BASIC code to appropriate LLVM bytecode. The compiler adheres to the ANSI X.60-1978 standard for BASIC, with some additions to improve usability. The resultant LLVM bytecode successfully compiles to multiple different architectures, on which the executable files run faster than those generated by similar compilers

No special difficulties

I David Hoare of Robinson College , being a candidate for Part II of the Computer Science Tripos, hereby declare that this dissertation and the work described in it are my own work, unaided except as may be specified below, and that the dissertation does not contain material that has already been used to any substantial extent for a comparable purpose.

Table of Contents

Contents

[1 Introduction 7](#_Toc417040136)

[2 Preparation 8](#_Toc417040137)

[3 Implementation 9](#_Toc417040138)

[3.1 Parser 9](#_Toc417040139)

[3.2 Integrating the Parser 9](#_Toc417040140)

[3.3 Code Generation tools 9](#_Toc417040141)

[3.3.1 LLVM API 9](#_Toc417040142)

[3.3.2 C standard library 10](#_Toc417040143)

[3.4 Types 10](#_Toc417040144)

[3.4.1 BASIC types 10](#_Toc417040145)

[3.4.2 LLVM types 10](#_Toc417040146)

[3.5 Expressions 11](#_Toc417040147)

[3.5.1 String expressions 11](#_Toc417040148)

[3.5.2 Numeric expressions 11](#_Toc417040149)

[3.6 Compiler passes 13](#_Toc417040150)

[3.6.1 First pass 13](#_Toc417040151)

[3.6.2 Second pass 14](#_Toc417040152)

[3.6.3 Third pass 14](#_Toc417040153)

[3.7 Error Handling 15](#_Toc417040154)

[3.7.1 Exceptions 15](#_Toc417040155)

[3.7.2 ANTLR error listener 15](#_Toc417040156)

[3.8 VariableStore 15](#_Toc417040157)

[3.8.1 Storage of line and variable addresses 15](#_Toc417040158)

[3.8.2 Array operation methods 16](#_Toc417040159)

[3.9 Numeric functions 16](#_Toc417040160)

[3.9.1 Supplied numeric functions 16](#_Toc417040161)

[3.9.2 Defined numeric functions 16](#_Toc417040162)

[3.10 I/O 17](#_Toc417040163)

[3.10.1 stdin/stdout 17](#_Toc417040164)

[3.10.2 File I/O 17](#_Toc417040165)

[3.10.1 Numeric representation in I/O 17](#_Toc417040166)

[3.11 Command line options 18](#_Toc417040167)

[3.12 Further compilation and assembly 18](#_Toc417040168)

[3.12.1 llc 18](#_Toc417040169)

[3.12.2 gcc 18](#_Toc417040170)

[3.12.3 Compiling for other architectures 18](#_Toc417040171)

[3.12.4 FFT for Raspberry Pi 19](#_Toc417040172)

[4 Evaluation 20](#_Toc417040173)

[5 Conclusions 21](#_Toc417040174)

[6 Bibliography 22](#_Toc417040175)

[7 Appendices 23](#_Toc417040176)

[7.1 Fast Fourier Transform algorithm 23](#_Toc417040177)

[8 Project Proposal 25](#_Toc417040178)

[Introduction 25](#_Toc417040179)

[Resources Required 26](#_Toc417040180)

[Starting Point 26](#_Toc417040181)

[Structure and Substance of the Project 27](#_Toc417040182)

[Success Criteria 27](#_Toc417040183)

[Timetable and Milestones 27](#_Toc417040184)

[3rd-16th November 2014 27](#_Toc417040185)

[17th-30th November 2014 28](#_Toc417040186)

[1st-21st December 2014 28](#_Toc417040187)

[22nd December 2014 – 11th January 2014 28](#_Toc417040188)

[12th – 25th January 2015 28](#_Toc417040189)

[26th January – 8th February 2015 28](#_Toc417040190)

[9th – 22nd February 2015 28](#_Toc417040191)

[23rd February – 8th March 2015 28](#_Toc417040192)

[9th – 22nd March 2015 28](#_Toc417040193)

[23rd March – 28](#_Toc417040194)

# Introduction

The BASIC language was an important development in the field of Computer Science in the 60s and 70s. It was the first very human-readable, entry-level programming language aimed at home users, and an interpreter was included on most of the personal computers released at this time, thus introducing a generation to the basics of programming. Although not as widely distributed BASIC is still often used as an introductory programming language for beginners. It has also influenced many modern languages, most notably Visual Basic .NET, one of the primary languages targeting Microsoft’s .NET framework.

LLVM is a framework for compiler construction. The principle is that compilers built with the LLVM framework output LLVM Intermediate Representation, a bytecode assembly language. This bytecode can then be compiled by an LLVM backend to native code for a target architecture. Backends exist for targeting a wide variety of instruction sets. Hence building a compiler with LLVM is an easy way of enabling the compiler to build for multiple platforms.

The LLVM framework also performs code optimisation passes on generated bytecode. This is made easier by the Static Single Assignment form of LLVM bytecode. SSA code produces a simple definition-use tree which simplifies dataflow optimisation optimisations. In particular, data redundancy detection can be performed immediately on SSA code, avoiding expensive reaching definition analysis required for non-SSA code. [LLVM: A Compilation Framework for Lifelong Program Analysis & Transformation http://web3.cs.columbia.edu/~junfeng/reliable-software/papers/llvm.pdf] LLVM-based compilers are therefore able to produce machine code that often runs faster than that produced by conventional compile pipelines.

The project brief was simple – to develop a compiler targeting LLVM IR for the BASIC programming language. The ANSI X.60-1978 standard was selected as an appropriate starting point for the definition of the language, with new features being added as necessary to update the language. From perusal of the BASIC standard I noted that the ability to read and write files was missing, so I decided this would be a useful extension to implement.

# Preparation

The first stage in any compiler is the lexer, which converts input code to a stream of lexical tokens to be passed to the parser. To avoid the tedious task of building a lexer from scratch I elected to use a lexer generator to produce this component. After exploring available tools I selected the ANTLR 4.5 parser generator for this task. ANTLR takes a standard context-free grammar and has a well-documented C# target. The system is mature and well supported and was a good choice.

A language needed to be selected with which to implement the compiler. I chose C# .NET for this purpose because of my personal experience using the language and also its object-oriented design. Looking at the 1978 BASIC standard made it clear that it would be very advantageous to the development of the parser and compiler for object-oriented language features such as inheritance and overloading to be available.

The code generation module of the compiler involved use of the LLVM API. A complication to this step was the fact that there do not exist a complete set of bindings of the (very extensive) API for .NET development. There do exist several attempts at writing said bindings at differing stages of completeness. The solution was therefore to select an appropriate set of bindings and then add to them when required functionality is not implemented. After investigating several options I opted to use the incomplete bindings written by my project supervisor Michael Gale some years ago. With Michael’s assistance I was able to add to the bindings all functionality I needed from the LLVM API when necessary.

+iterative design

# Implementation

## AST design

BASIC is a very line-based language. Statements and expressions cannot span over multiple lines, nor can multiple statements appear on a single line. The most important control-flow statement is GOTO and loop blocks are enclosed by FOR and NEXT lines. For this reason I decided to parse the BASIC code on a line-by-line basis. The lexer is passed a single line at a time, and the base structure in the AST is the Line class. This class is inherited by classes for all different line types (Line\_Goto, Line\_For, Line\_If etc).

+validation of AST

## Parser

The ANSI X3.60-1978 standard for BASIC contains a context-free grammar for the language. I adapted this into the format required by ANTLR. The grammar in the specification does not differentiate between parser and lexer rules, but ANTLR requires parser and lexer rules to be defined separately. To debug the CFG I used ANTLR 4.5’s TestRig component, which produces a graphical tree representation of how an input string is parsed by the grammar. This allowed me to pass lines of BASIC in and ensure that they were being parsed as expected. This was particularly important in the writing of the rules for expression parsing, as it allowed me to verify operator grouping rules (eg BIDMAS) were being obeyed by the parser. Once the grammar correctly interpreted the language I used ANTLR to produce the C# class files that constitute the parser. These classes then had to be integrated with the code generation module of the compiler.

I chose to integrate the parser by use of a listener module. This works by a unique method being called on entering or exiting each parser rule. These methods can then construct the internal representation of the code used by the code generation module. I implemented the BASICListener interface produced by ANTLR. This provided stubs for all methods required for the listener. I initially integrated a small subset of the parser and then implemented the code generation module for this subset. This allowed an end-to-end demonstration of the compiler from an earlier stage.

## Code Generation tools

The remainder of development was the module that actually generates LLVM bytecode from the AST.

### LLVM API

I made extensive use of the LLVM API for the generation of the LLVM IR code. The API works by defining a global context, and then splitting an input program into modules, functions and basic blocks. Because my compiler only works with a single input source file, and does not require subroutine calls, I was able to use a single LLVM module containing a single function, and hence a single entry point into the code. All sections of code dealing with code generation make use of the LLVM context, module and main function variables. To minimise the need to pass these as arguments, I create a single instance of each variable and refer to these instances throughout compilation. This is achieved by use of the singleton design pattern - they are stored as public static members in the Parser class.

Within the main function are basic blocks which are represented by the LLVM.BasicBlock class. These contain a block of code, and are represented in LLVM IR by a labelled section of bytecode. To insert code into a BasicBlock I made use of the LLVM.IRBuilder class. This provides methods such as CreateAlloca, CreateFAdd, CreateBr to easily insert IR instructions into a BasicBlock. All types of BASIC statements can be compiled to a single BasicBlock. Hence each line of BASIC corresponds to exactly one LLVM BasicBlock.

### C standard library

To compile more complex statements such as PRINT and INPUT [see below], and arithmetic function calls such as SIN and SQR [see below], I chose to make use of C standard library functions. This avoids the need to write these procedures from scratch but requires that the standard library is available at link time for static linking, or at runtime for dynamic linking.

For example, consider the following simple BASIC program:

10 LET A = SQR(9)

20 END

My compiler produces the following LLVM bytecode:

define i32 @main(i32, i8\*\*) {

line10:

%A = alloca double

%2 = call double @sqrt(double 9.000000e+00)

store double %2, double\* %A

br label %line20

line20:

ret i32 0

}

declare double @sqrt(double)

The C library function double sqrt(double) is imported at the bottom. The assignment on line 10 is compiled by allocating the space, calculating the result then storing the result in the allocated space. The calculation is performed by calling the imported library function.

## Types

### BASIC types

The BASIC standard defines just two types – string and numeric, with no differentiation between integer and floating point values. My compiler addresses this by representing all numbers internally as doubles. This allows all operations to be seamlessly compiled regardless of the initial type of the numbers. This approach requires additional steps when outputting numeric values to hide decimal places when the user expects an integer [see 3.10.3]

This approach to storing numeric values has some potential downsides. In C# a double has a size of 64 bits. A long is also 64 bits, and a signed int is 32 bits. Thus when storing integer values it can be wasteful to use a double when an int would suffice. The floating point nature of a double means that a very large range of numbers can represented, much greater than that representable with an int or long. However precision can be lost when representing very large positive or negative numbers. The mantissa size of a double is 52 bits, offering a precision of between 15 and 16 significant figures. This is greater than the precision offered by an int, but less than that provided by a long.

### LLVM types

The code generation module makes extensive use of the LLVM API’s type construct LLVM.Type. To minimise calls to the API all common types (i8, i8\*, i8\*\*, i32, double, double\*, void) are initialised at the start of execution and are stored as static members in the Parser class. This minimises calls to the LLVM API.

The LLVM.Constant corresponding to the number zero is also frequently used in various types in the code generation module. Hence I have also chosen to store this as static members in the Parser class as an 8-bit integer, a 32-bit integer and a double.

## Expressions

### String expressions

The BASIC standard specifies that string expressions consist of either a string variable or a string literal. Thus string expressions are very simple and no operations on strings are possible.

### Numeric expressions

Numeric expressions are much more versatile than string expressions. The parser rules for a numeric expression are as follows:

numericexpression : sign? term (sign term)\*;

term : factor (multiplier factor)\*;

factor : primary (CIRCUMFLEXACCENT primary)\*;

multiplier : ASTERISK | SOLIDUS;

primary : numericvariable | numericconstant | numericfunctionref | LEFTPARENTHESIS numericexpression RIGHTPARENTHESIS;

This structure allows complex recursive numeric expressions to be parsed correctly in accordance with BIDMAS rules. As an example of how expressions parse, see the parse tree on the following page. This was exported by the ANTLR4 TestRig tool, which I used to debug my context-free grammar for BASIC. The tree represents the expression 4+SIN(0.5)^2\*(A+1)\*2/4. The adherence to BIDMAS rules is shown by the fact that the tree branches in the correct order. ie first at plus signs, then by multipliers, then by indices, then by brackets, then by function calls. The LLVM bytecode for evaluation of this expression is as follows:

%2 = call double @sin(double 5.000000e-01)

%3 = call double @pow(double %2, double 2.000000e+00)

%temp = load double\* %A

%addtmp = fadd double %temp, 1.000000e+00

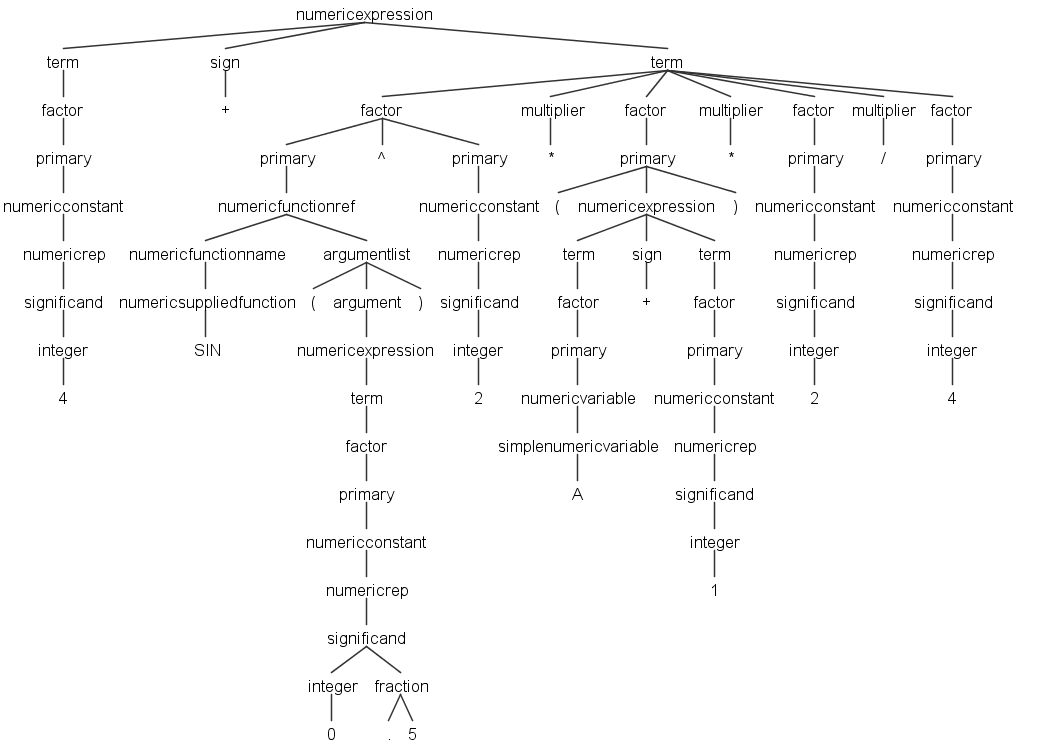
%multmp = fmul double %3, %addtmp

%multmp1 = fmul double %multmp, 2.000000e+00

%divtmp = fdiv double %multmp1, 4.000000e+00

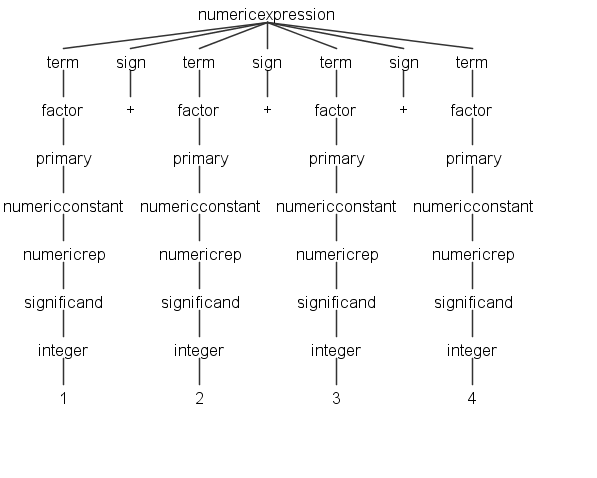
%addtmp2 = fadd double 4.000000e+00, %divtmp

We can see that the sin() function is handled first, by calling a C library function [see 3.3.2 or 3.91]. The power is then compiled in the same way. Then the bracket is evaluated by loading variable A and adding 1 to it. The multiplication and division operations are then compiled, with the outer addition being performed last.



Parse tree for 4+SIN(0.5)^2\*(A+1)\*2/4

Numeric expressions also demonstrate the earliest optimisation performed by the LLVM API. Consider the trivial example expression 1+2+3+4. This is parsed into the below parse tree.



My compiler compiles this expression by emitting three fadd instructions, feeding in a constant double and the result of the previous instruction [see how I compile expressions]. However, the resultant LLVM code for the statement LET A=1+2+3+4 is as follows:

%A = alloca double

store double 1.000000e+01, double\* %A

We see that the LLVM API has detected that the repeated fadd instructions are pointless and inefficient and has simplified the code to the equivalent to LET A=10.

## Compiler passes

My compiler makes three passes through the list of Line objects returned by the parser.

### First pass

The first pass calls the code() function on each line, which generates the LLVM IR for the line. Recursive code() calls are made to AST structures used within the line to compile these structures. After each line is processed, a reference to the corresponding Line object is placed in Parser.variables.lines, a dictionary indexed against BASIC line numbers. This dictionary is used to compile GOTO and other control-flow statements in the third pass. Parser.variables is a static instance of VariableStore [see 3.8]

### Second pass

The second compiler pass calls the jumpToNext() method on each line, passing a reference to the sequential next line of the program. This method is defined in the abstract Line class and inserts a br instruction at the end of the BasicBlock associated with the line, causing a jump to the BasicBlock associated with the following line.

The jumpToNext() method is overridden in classes inheriting Line that represent lines where this jump is not necessary, ie lines containing control-flow statements. For example, the override jumpToNext() method for Line\_Goto is empty, as execution should not pass to the next line after a GOTO statement.

The jumpToNext() method for Line\_Next does not create a jump to the next line, but instead stores the next line in a member variable. This reference will be needed to construct the conditional jump created in the third pass. Similarly the jumpToNext() method for Line\_For stores the following line in a variable, but also creates a jump to it, as execution always passes to the next line following a FOR statement.

### Third pass

The final compiler pass calls the processGoto() method for each line. The body of this method in Line is blank, as for most lines there is no need for further compilation. This pass is only used for lines which contain control-flow statements. A case in point is the GOTO statement. This cannot be compiled earlier as it depends on the ability to translate an in-code line number to a BasicBlock reference for the target line. This cannot be done until all lines have first been processed, and the Parser.variables.lines dictionary has been filled [see 3.8.1 and?]. Hence in this pass a Line\_Goto will retrieve the BasicBlock associated with the in-code line number and create a br instruction to this block. Similar operations are performed in this pass for lines containing FOR, NEXT or IF statements, as these all depend on the BasicBlock for a target line being initialised.

## Error Handling

### Exceptions

I have defined a new System.Exception which I have named CompileException. I use this to represent handled compile-time errors, ie errors where the compiler knows what has gone wrong. These exceptions can then be differentiated from other System.Exceptions in catch blocks to provide differing information to the user. The constructor for CompileException takes a string containing a descriptive error message to be displayed to the user.

Throughout all stages of compilation, the line number currently being processed is stored statically in the Parser class as Parser.lineNumber. This means that should a CompileException be thrown at any point during lexing, parsing or code generation, the error message can include the line number where the error is found. This has obvious advantages for users debugging their BASIC code.

### ANTLR error listener

When initialising the ANTLR BASICParser class used to parse the input code, the default ANTLR BaseErrorListener is removed from the BASICParser, and an overloaded error listener class is attached instead. I have named this class ANTLRErrorListener. This overrides the default error behaviour (to output any error immediately to stdout) so the more advanced error information supplied by the ANTLR system is only displayed if the compiler has been executed with the –debug flag set. This error information includes the line number where the error was encountered, but as the source code is fed to the parser line-by-line this number is always 1. ANTLRErrorListener also addresses this problem by instead outputting Parser.currentLine, which contains the correct line number.

## VariableStore

### Storage of line and variable addresses

The VariableStore class is used to contain dictionaries and lists which store allocation addresses and other key information relating to variables defined and used in the BASIC code. VariableStore is initialised as a public static variable Parser.variables in the Parser class, and is thus accessible throughout the compilation process. [strings vs stringpointers + stringisPointer] [purpose for each dictionary].

### Array operation methods

VariableStore also contains two important methods for the handling of arrays, initialiseArray() and arrayItem(). These initialise a numeric array and return a pointer to an item in the array respectively.

Initialisation involves emitting a simple alloca instruction but including a second argument stipulating the number of items for which memory should be allocated. The initialiseArray() method takes any LLVM.Value as the array size, allowing arrays to be initialised with arbitrary length. Thus an array can be defined with a length specified by the user at runtime. This poses a slight problem in that numeric values are stored as doubles throughout, and array indexing is one of the few times where an integer value is required. To get around this an fptoui instruction is emitted. This casts the supplied floating point value to an unsigned integer, casting towards zero, which can be used to initialise the array. A reference to the head of the array is stored in arrays, a dictionary indexed against the name of the array. The size of the array is stored in the dictionary arraySizes – this is necessary for compilation of a WRITE statement, where the call to helper function writeArrayToFile requires the length of the array.

arrayItem() simply retrieves the array pointer from arrays and returns a pointer to the requested item. Again, the LLVM.Value supplied as the array index is cast to an unsigned integer. A call to arrayItem() before initialiseArray() indicates that the array has been referenced before it is defined with a corresponding DIM statement. In many languages this would result in an exception, however the BASIC specification states that this is actually allowed, and the array in question should be initialised with a default length of 11 items.

## Numeric functions

### Supplied numeric functions

The BASIC standard defines eleven supplied numeric functions that must be included in the implementation. These functions (ABS, ATN, COS, EXP, INT, LOG, RND, SGN, SIN, SQR, TAN) all map fairly directly onto C equivalents. Hence I chose to compile these by calling the relevant C function. I took a similar approach to compile PRINT and INPUT statements, making calls to printf and scanf respectively. This means the standard C library will need to be present at link time (a reasonable assumption).

### Defined numeric functions

To easily broaden the functionality of the language, I implemented the ability to call external C functions defined in files included at link time. These function calls can either have a single double argument or none. A key example was in the fast Fourier transform algorithm I implemented as part of the evaluation process, where I used this feature to implement the modulo operator and Pi [see eval].

## I/O

### stdin/stdout

stdin and stdout are read/written to with the PRINT and INPUT statements. These are compiled by calling the C functions printf and scanf respectively.

### File I/O

A useful feature missing from the original BASIC spec is file IO. Particularly when using algorithms which worked with large arrays of numbers it became tedious to type in input data at the command line and read output data from stdout. To address this I defined two additional statements – READ and WRITE. The format of these statements is:

READ A filename

WRITE A filename

where A is a pre-defined array and filename is a string expression containing the filename to read/write. These statements are compiled by calling two C helper functions I placed in the file libBASICLLVM.c [appendix]. These helper functions are passed pointers to the array and the string containing the filename, along with the length of the array being passed. They open a file pointer to the specified file and use fgets/fprintf to perform the operation.

### Numeric representation in I/O

As mentioned in [3.4.1] numeric values are always represented as doubles in the LLVM bytecode generated by my compiler. This addresses the ambiguity of numeric data types in the BASIC specification. However this poses a problem when outputting numeric variables using PRINT or WRITE. Consider the following example code

LET A = 10

PRINT A

The user would reasonably expect the output to be “10”. However the number is being represented internally as the double “10.00000…” and will be output as such. I chose to address this by using the format argument accepted by printf and fprintf. This is a string argument which specifies how a numeric variable should be represented as a string. The “%g” format specifier outputs the number using the shortest possible representation, so the double “10.00000000…” is output as “10”, while numeric values which require a higher level of precision are still returned to an appropriate number of decimal places.

## Command line options

I implemented a small number of command line options to make the compiler more usable and versatile. The –debug flag is used to enable verbose output. Without this option the compiler will only output to stdout if there is an error. With –debug enabled other diagnostic information is displayed. Detailed errors reported by the ANTLR parser are shown, and the entire LLVM module is dumped to stdout once code generation is complete. The –o option is used to specify an output file.

The –output option instructs the compiler to perform further processing on the generated bytecode. The options are LL, S or EXE, which produce a .ll bytecode file, a .s assembly file or an executable respectively. This option is discussed further in [3.12 ?]

## Further compilation and assembly

### llc

By passing my compiler the command line option –output=S, after compiling BASIC source to LLVM bytecode, the bytecode is further compiled into an assembly file. This works by calling the llc tool provided with LLVM. This is a static compiler for LLVM bytecode.

### gcc

By passing my compiler the command line option –output=EXE, the output bytecode is first passed to llc for compilation to assembly, then the assembly is passed to gcc (the GNU Compiler Collection). This is a versatile open-source compiler. Here it is used simply to assemble and link the assembly generated by llc and produce a .exe executable file. In addition to the generated assembly gcc is passed the library file libBASICLLVM.c which contains the helper functions necessary for the File IO functions [see 3.9]

### Compiling for other architectures

By passing the –output option to my compiler, an executable is produced which will run natively on the current machine. However, a key advantage of using an LLVM-based compiler is that the bytecode can be compiled for a variety of different architectures. This can be achieved by specifying –output=LL (or not passing an output argument) and then running the bytecode through llc and gcc separately. [see 4.2 for example]

The target architecture is specified to llc by use of a string descriptor known as a target triple. A target triple generally takes the format <architecture>-<vendor>-<system>. Examples of architecture include i686,arm and mips. Examples of vendor include pc, apple and ibm. Examples of system include win32, linux and darwin. So for example target triple for the machine I was developing on is i686-pc-win32. The target triple is passed to llc by using the –mtriple= argument.

### Soft vs hard float ABI

The application binary interface defines how code modules interact with each other, including the way arguments are passed to functions. In my case, this applies to the way my code passes arguments to functions contained in libBASICLLVM and to C library functions. The Raspberry Pi uses a “hard float” ABI (Application Binary Interface). This means floating point arithmetic is supported by the hardware. Conversely, soft float ABI systems do not have dedicated floating point hardware, and floating point arithmetic must be handled with software.

The two float passing conventions are not compatible. Thus assembly targeting a Raspberry Pi must be compiled with hard float ABI specified so it links correctly with the C libraries present on a Raspberry Pi. This is done with the –float-abi=hard argument when calling llc.

# Evaluation

The initial aim of the project was to produce a correctly working compiler. Therefore the obvious first step was to run a number of test programs through the compiler to ensure the expected output was produced. This was a valuable bug-finding exercise and verified that the compiler was indeed correctly compiling the BASIC code. To assist with this task I made use of LLVM’s lli tool. This is an interpreter which works directly on the LLVM IR bytecode produced by my compiler, running it in real-time by use of a just-in-time compiler. This allowed me to rapidly test output without needing to compile the bytecode to native assembly.

Part of the reason for using LLVM was the cross-platform nature of its backend, allowing a variety of architectures to be targeted by the compiler. I was developing on a 64-bit Windows machine, on which code was being successfully compiled and run. To test the cross-platform capabilities of the compiler, I compiled some BASIC test code for the ARM platform, 32-bit Windows and 64-bit Linux architectures. I then assembled and ran the resultant assembly on machines using the respective instruction sets. To test the ARM output I used a Raspberry Pi [see 3.11.4?]. The code compiled and ran successfully on all architectures I tested it on.

## LLVM optimisation passes

The level of optimisation performed by LLVM when compiling bytecode to assembly is selected by using the –Ox argument when calling llc, where x is a number from zero to three. To demonstrate the impact this has on assembly size, I wrote the following trivial BASIC program:

LET A = 3

LET A = 5

LET B = A

PRINT B

END

The program is clearly inefficient - the first line is not needed as the value it assigns A is superseded by the following line. Correction of these types of inefficiency are simplified by LLVM’s use of static single assignment form, which transforms the code into something more like this:

A­1 = 3

A2 = 5

B1 = A2

print(B1)

We can see that variables are only assigned once, and it is easy to see that the A1 variable is never used after definition and is therefore redundant and can be removed. It is also easier for an optimising compiler to make this observation – the *use-define tree* is more straightforward to calculate.

I ran this program through my compiler to compile it to bytecode, then passed it to llc with the –O0 flag set. This tells llc not to perform any optimisation passes when compiling the code. The resultant assembly file size was 1,315 bytes. By passing the –O3 flag (most aggressive optimisation option instructing llc to perform the largest number of optimisation algorithms) I produced a file of size 898 bytes. This is a substantial improvement for such a trivial inefficiency.

I performed the same experiment with my BASIC fast Fourier transform example (which is reasonably efficiently coded). The assembly file without optimisation was 40KB and with 3-pass optimisation was 21KB.

## FFT for Raspberry Pi

As a real-world example and to give my compiler a real workout I implemented the Fast Fourier Transform (FFT) algorithm in BASIC. This is an efficient algorithm for computing the discrete Fourier transform of a sampled signal which decomposes the signal into its constituent frequencies and their relative sizes. I found an implementation of FFT for a different dialect of BASIC [http://www.nicholson.com/dsp.fft1.html] and adapted it to fit my specification.

The FFT program gave me an opportunity to test the NumericDefinedFunction feature. The algorithm makes use of Pi and the modulo function, neither of which are BASIC supplied functions. I wrote two simple functions MOD2() and PI() in C which wrap around the library function fmod() and C constant M\_PI respectively [appendix]. My compiler detected the non-supplied function and passed it through in the assembly. By linking the compiled code with the helper functions the code worked correctly.

As an example of the ability to target multiple architectures I compiled my Fast Fourier Transform program to run on a Raspberry Pi. I ran gcc –dumpmachine on the Raspberry Pi which returns the appropriate target triple for the current system (in this case arm-linux-gnueabihf). I ran the source code through my compiler to generate fft.ll. I then ran this through llc using the argument –mtriple=arm-linux-gnueabihf. I also passed the argument –float-abi=hard. This instructs llc to generate assembly which uses “hard float ABI” (this is explained in the next section). llc produced fft.s which I transferred to the Raspberry Pi then ran through gcc. I used the command

gcc fft.s libBASICLLVM.c additionalFunctions.c –o fft.out

which assembled and linked three source files to produce the executable fft.out. This ran and produced expected output.

# Conclusions

Blah

# Bibliography

Blah

# Appendices

## Fast Fourier Transform algorithm

The following BASIC code for performing a fast Fourier transform is based on an implementation for a different dialect of BASIC found here: [<http://www.nicholson.com/dsp.fft1.html>]

PRINT "F?"

INPUT F

PRINT "m?"

INPUT M

PRINT ""

LET N = 2^M

DIM V(N)

DIM G(N)

READ V "v.csv"

READ G "g.csv"

PRINT V(0),V(1),V(2),V(3)

PRINT G(0),G(1),G(2),G(3)

LET Q = 0

LET P = 0

LET A = 0

FOR K=0 TO N-1

LET X = K

LET R = 0

FOR I=1 TO M

LET R = R\*2

IF MOD2(X) <> 1 THEN 20

LET R = R+1

20 LET X = INT(X/2)

NEXT I

IF R <= K THEN 40

LET Q = V(R)

LET V(R) = V(K)

LET V(K) = Q

LET P = G(R)

LET G(R) = G(K)

LET G(K) = P

40 NEXT K

LET B = 2

45 IF B > N THEN 60

LET C = B/2

LET D = N/B

FOR Z = 0 TO C-1

LET A = Z \* D

LET A1 = 2\*PI()\*A/N

LET A3 = A+N/4

LET A2 = 2\*PI()\*A3/N

LET H = SIN(A2)

LET W = SIN(A1)

IF F > -1 THEN 50

LET W = -W

50 FOR X = 0 TO (N-B) STEP B

LET I = Z + X

LET J = C + I

LET Q = H \* V(J) - W \* G(J)

LET P = H \* G(J) + W \* V(J)

LET Y = V(I)

LET S = G(I)

LET V(J) = Y - Q

LET G(J) = S - P

LET V(I) = Y + Q

LET G(I) = S + P

NEXT X

NEXT Z

LET B = B \* 2

GOTO 45

60 IF F > -1 THEN 70

LET A = 1/N

FOR L=0 TO N-1

LET V(L) = V(L)\*A

LET G(L) = G(L)\*A

NEXT L

70 PRINT V(0),V(1),V(2),V(3)

PRINT G(0),G(1),G(2),G(3)

WRITE V "v2.csv"

WRITE G "g2.csv"

PRINT V(0),V(1),V(2),V(3)

PRINT G(0),G(1),G(2),G(3)

END

# Project Proposal

## Introduction

From the late 70s to the early 90s, the most widely used programming language was BASIC (Beginner's All-purpose Symbolic Instruction Code). A BASIC interpreter was included on the vast majority of consumer microcomputers released during this period. As its name suggests, the language was designed with ease of use in mind – the commands are designed to be human readable and potentially confusing syntax (eg semicolons at ends of lines) was omitted. This was significant at the time as it was the first language with ease of use as a consideration – other languages used at the time (FORTRAN, COBOL etc) were much harder to understand, and hence less accessible to less technical users.

LLVM is a compilation platform written in C++. The principle is that high level languages are compiled into LLVM's bytecode language, which is then run through the LLVM compiler, which can target many different CPU architectures. The advantages of this approach are numerous. It is clearly much easier to write software to target multiple architectures, as once the code is compiled to bytecode the LLVM backend can compile this to machine code for any appropriate architecture. The bytecode is also in Static Single Assignment form. This means the LLVM framework is able to make many compile-time optimisations without needing to perform expensive tree-based operations.

The classic problem with distributing BASIC programs is that it is generally an interpreted language, so developers rely on end-users having a compatible interpreter installed. There does not currently exist a compiler from a BASIC standard to LLVM bytecode. This would allow straightforward and optimised compilation from BASIC to any system architecture supported by the LLVM framework.

An example follows of how a trivial BASIC program might be translated into LLVM code:

BASIC

x% = 3

x% = x% + 4

x% = x% \* 5

LLVM

%x1 = 3

%tmp1 = 4

%x2 = add i16 %x1, %tmp1

%tmp2 = 5

%x3 = mul i16 %x2, %tmp2

The project is to implement a fully functional compiler for BASIC. The compiler will output LLVM bytecode which can then be compiled by the LLVM framework to target a large array of end-user architectures. The BASIC dialect I have chosen to implement is ANSI X3.60-1978 (BASIC 78).

I have chosen to use Microsoft's C# language to implement this compiler. This provides a feature-rich, mature platform for development. C# is object-oriented and type safe, and has valuable traits for writing compilers. It is also a language which I am very familiar with, reducing the amount of studying necessary before programming can begin.

## Resources Required

* Windows PC – My preferred development environment. I will use my own machine.
* Microsoft Visual Studio – This provides a mature compiler and IDE for C# in which the compiler will be written. Any edition of Visual Studio will suffice.
* Private off-site Git repository – this will provide version control and backups for both the source code and the dissertation.

## Starting Point

* I have a working knowledge of compilers and their structure from the IB Compiler Construction course
* I have experience working with both BASIC and C#
* The project will make use of the LLVM compilation framework. An appropriate set of C# bindings for the library will be used.
* A parser generator for C# will be used to produce a skeleton parser as a starting point for the project.

## Structure and Substance of the Project

As with the development of any compiler, the project will require the production of modules for lexing, parsing and code generation. The object oriented nature of C# lends itself to this modular way of working.

The first step will be to select an appropriate parser generator. An appropriate context-free grammar to represent the syntax of BASIC must be fed into the generator such that a correct lexer/parser is returned. A set of classes must be constructed that represent all features and constructs representable in the language. This is where the use of an object-oriented language such as C# becomes advantageous, as I can use subclassing and inheritance to produce a meaningful and structured set of classes. Once these classes are designed, the parser will have to be adapted to return the appropriate instance of the classes, forming an abstract syntax tree. A pretty printer would be helpful for debugging at this stage.

Once the classes are designed, the actual code generator must be written. This involves taking the AST and returning the appropriate LLVM bytecode. Appropriate C# bindings for the LLVM library will make this process more straightforward and will optimise the LLVM code as it is generated. This is the phase of development which will take the longest, but a gradual approach to the build is acceptable. I intend to initially implement arithmetic operations and build from there.

## Success Criteria

The goal is to produce a working compiler from the ANSI X.360-1978 dialect of BASIC to valid LLVM bytecode written in C#. A selling point for LLVM is compile-time optimisation so it would be interesting to evaluate the performance of programs compiled using my compiler against those compiled using an existing, more conventional BASIC compilation pipeline. The size of the executables produced by each compiler could also be compared.

## Timetable and Milestones

### 3rd-16th November 2014

Read up on LLVM and its bytecode dialect. Write simple programs in LLVM language to explore how the Clang compiler and its optimisation techniques work. Study BASIC 78 in depth and get familiar with all the features that will have to be implemented by the compiler.

### 17th-30th November 2014

Write some compilers for toy languages in C#. Select an appropriate set of C# bindings for the LLVM library and get familiar with how they work/any shortcomings.

### 1st-21st December 2014

Further study of languages. Make any necessary changes to the C# bindings for LLVM. Begin to design and implement the classes necessary for representation of BASIC's simple data structures in C#.

### 22nd December 2014 – 11th January 2014

Complete the development of necessary classes. Continue to write compilers targeting LLVM in C#.

### 12th – 25th January 2015

Write a context-free grammar for BASIC 78. Use a parser generator to produce an appropriate parser.

### 26th January – 8th February 2015

Implement code generation for simple arithmetic and assignment operations. Implement classes necessary for representing flow control operators.

### 9th – 22nd February 2015

Implement code generation for BASIC input and output, looping and GOTO operators.

### 23rd February – 8th March 2015

Implement subroutine functionality. At this stage the compiler will be largely complete and optimisation/additional features can be added. Begin writing initial chapters of dissertation.

### 9th – 22nd March 2015

Extensive testing of compiler. Clean up any untidy/inefficient portions of code. Continue to write dissertation.

### 23rd March –

Send first draft of dissertation to supervisor and continually redraft chapters. Send draft to DoS by 21st April for feedback and complete and submit final dissertation early May.