#### **Caltech**

# Machine Learning & Data Mining CS/CNS/EE 155

Lecture 6:

**Conditional Random Fields** 

#### **Previous Lecture**

#### Sequence Prediction

- Input:  $x = (x, ..., x^{M})$
- Predict:  $y = (y^1,...,y^M)$
- Naïve full multiclass: exponential explosion
- Independent multiclass: strong independence assumption

#### Hidden Markov Models

- Generative model:  $P(y^i|y^{i-1})$ ,  $P(x^i|y^i)$
- Prediction using Bayes's Rule + Viterbi
- Train using Maximum Likelihood

# **Outline of Today**

- Long Prelude:
  - Generative vs Discriminative Models
  - Naïve Bayes

- Conditional Random Fields
  - Discriminative version of HMMs

#### Generative vs Discriminative

Generative Models:

**Hidden Markov Models** 

- Joint Distribution:  $P(x,y) \leftarrow Mismatch!$
- Uses Bayes's Rule to predict:  $argmax_y^2 P(y|x)$
- Can generate new samples (x,y)
- Discriminative Models:

**Conditional Random Fields** 

- Conditional Distribution:  $P(y|x) \leftarrow Same thing!$
- Can use model directly to predict:  $argmax_y$  P(y|x)
- Both trained via Maximum Likelihood

Binary (or Multiclass) prediction

$$x \in R^D$$

Model joint distribution (Generative):

$$y \in \{-1,+1\}$$

$$P(x,y) = P(x \mid y)P(y)$$

"Naïve" independence assumption:

$$P(x \mid y) = \prod_{d=1}^{D} P(x^d \mid y)$$

Prediction via:

$$\underset{y}{\operatorname{argmax}} P(y \mid x) = \underset{y}{\operatorname{argmax}} P(x \mid y) P(y) = \underset{y}{\operatorname{argmax}} P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

P(x <sub>d</sub> =1 y)	y=-1	y=+1
$P(x^1=1 y)$	0.5	0.7
$P(x^2=1 y)$	0.9	0.4
$P(x^3=1 y)$	0.1	0.5

P(y) 
$$x \in R^{D}$$
  
P(y=-1) = 0.4  $y \in \{-1,+1\}$   
P(y=+1) = 0.6

#### Prediction:

$$\underset{y}{\operatorname{argmax}} P(y \mid x) = \underset{y}{\operatorname{argmax}} P(x \mid y) P(y) = \underset{y}{\operatorname{argmax}} P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

X	P(y=-1 x)	P(y=+1 x)	Predict
(1,0,0)	0.4 * 0.5 * 0.1 * 0.9 = 0.018	0.6 * 0.7 * 0.6 * 0.5 = 0.126	y = +1
(0,1,1)	0.4 * 0.5 * 0.9 * 0.1 = 0.018	0.6 * 0.3 * 0.4 * 0.5 = 0.036	y = +1
(0,1,0)	0.4 * 0.5 * 0.9 * 0.9 = 0.162	0.6 * 0.3 * 0.4 * 0.5 = 0.036	y = -1

#### Matrix Formulation:

$$P(x,y) = P(y) \prod_{d=1}^{D} P(x^{d} \mid y) = A_{y} \prod_{d=1}^{D} O_{x^{d},y}^{d}$$

$$O_{a,b}^d = P(x^d = a \mid y = b)$$
  $A_b = P(y = b)$  (Sums to 1)

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(Sums to 1)

P(x <sub>d</sub> =1 y)	y=-1	y=+1
P(x1=1 y)	0.5	0.7
P(x <sup>2</sup> =1 y)	0.9	0.4
$P(x^3=1 y)$	0.1	0.5

$$P(y)$$
 $P(y=-1) = 0.4$ 
 $P(y=+1) = 0.6$ 

$$x \in R^D$$
$$y \in \{-1, +1\}$$

Train via Max Likelihood:

$$S = \{(x_i, y_i)\}_{i=1}^{N}$$

$$\underset{A,O}{\operatorname{argmax}} \prod_{i=1}^{N} P(x_i, y_i) = \prod_{i=1}^{N} P(y_i) \prod_{d=1}^{D} P(x_i^d \mid y_i) \qquad x \in \mathbb{R}^D$$

$$y \in \{-1, +1\}$$

- Estimate P(y) and each P(x<sup>d</sup>|y) from data
  - Count frequencies

$$A_{z} = P(y = z) = \frac{\sum_{i=1}^{N} 1_{[y_{i} = z]}}{N}$$

$$O_{a,z}^{d} = P(x^{d} = a \mid y = z) = \frac{\sum_{i=1}^{N} 1_{[(y_{i} = z) \land (x_{i}^{d} = a)]}}{\sum_{i=1}^{N} 1_{[y_{i} = z]}}$$

### Naïve Bayes vs HMMs

Naïve Bayes:

$$P(x,y) = P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

Hidden Markov Models:

"Naïve" Generative Independence Assumption

$$P(x,y) = P(End | y^{M}) \prod_{j=1}^{M} P(y^{j} | y^{j-1}) \prod_{i=1}^{M} P(x^{j} | y^{j})$$

HMMs ≈ 1<sup>st</sup> order variant of Naïve Bayes!

(just one interpretation...)

## Naïve Bayes vs HMMs

• Naïve Bayes: 
$$P(y) = A_y \prod_{d=1}^{D} O_{x^d, y}^d$$

Hidden Markov Models:

"Naïve" Generative **Independence Assumption** 

$$P(x,y) = A_{End,y^{M}} \prod_{j=1}^{M} A_{y^{j},y^{j-1}} \prod_{j=1}^{M} O_{x^{j},y^{j}}$$

$$P(x|y)$$

HMMs ≈ 1<sup>st</sup> order variant of Naïve Bayes!

(just one interpretation...)

# Summary: Naïve Bayes

- Joint model of (x,y):
  - "Naïve" independence assumption each x<sup>d</sup>

$$P(x,y) = P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

"Generative Model" (can sample new data)

Use Bayes's Rule for prediction:

$$\underset{y}{\operatorname{argmax}} P(y \mid x) = \underset{y}{\operatorname{argmax}} P(x \mid y) P(y) = \underset{y}{\operatorname{argmax}} P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

- Maximum Likelihood Training:
  - Count Frequencies

#### Learn Conditional Prob.?

• Weird to train to maximize:

$$S = \{(x_i, y_i)\}_{i=1}^{N}$$

$$\underset{A,O}{\operatorname{argmax}} \prod_{i=1}^{N} P(x_{i}, y_{i}) = \underset{A,O}{\operatorname{argmax}} \prod_{i=1}^{N} P(y_{i}) \prod_{d=1}^{D} P(x_{i}^{d} \mid y_{i})$$

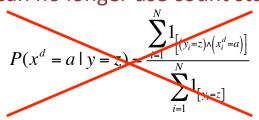
$$x \in R^{D}$$
$$y \in \{-1, +1\}$$

When goal should be to maximize:

$$\underset{A,O}{\operatorname{argmax}} \prod_{i=1}^{N} P(y_i \mid x_i)$$

#### **Breaks independence!**

Can no longer use count statistics



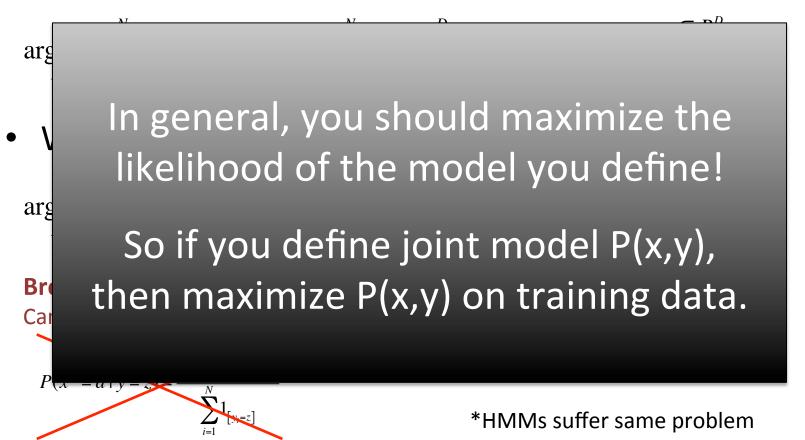
$$p(x) = \sum_{y} P(x, y) = \sum_{y} P(y) \prod_{d=1}^{D} P(x^{d} \mid y)$$

\*HMMs suffer same problem

#### Learn Conditional Prob.?

• Weird to train to maximize:

$$S = \{(x_i, y_i)\}_{i=1}^{N}$$



# **Summary: Generative Models**

Joint model of (x,y):

P(x,y)

- Compact & easy to train...
- ...with ind. assumptions
  - E.g., Naïve Bayes & HMMs

Θ often used to denote all parameters of model

• Maximize Likelihood Training: 
$$\underset{\Theta}{\operatorname{argmax}} \prod_{i=1}^{N} P(x_i, y_i)$$

- $\operatorname{argmax} P(y \mid x)$  Mismatch w/ prediction goal:
  - But hard to maximize P(y|x)

$$S = \{(x_i, y_i)\}_{i=1}^{N}$$

#### Discriminative Models

Conditional model:

- P(y|x)
- Directly model prediction goal
- Maximum Likelihood:

$$\underset{\Theta}{\operatorname{argmax}} \prod_{i=1}^{N} P(y_i \mid x_i)$$

Matches prediction goal: arg

$$\underset{y}{\operatorname{argmax}} P(y \mid x)$$

What does P(y|x) look like?

# First Try

• Model P(y|x) for every possible x

P(y=1 x)	x <sup>1</sup>	x <sup>2</sup>
0.5	0	0
0.7	0	1
0.2	1	0
0.4	1	1

$$x \in \{0,1\}^D$$
$$y \in \{-1,+1\}$$

- Train by counting frequencies
- Exponential in # input variables D!
  - Need to assume something... what?

# Log Linear Models! (Logistic Regression)

$$P(y \mid x) = \frac{\exp\{w_y^T x - b_y\}}{\sum_{k} \exp\{w_k^T x - b_k\}} \qquad x \in \mathbb{R}^{D}$$
$$y \in \{1, 2, ..., K\}$$

- "Log-Linear" assumption
  - Model representation to linear in D
  - Most common discriminative probabilistic model

#### Prediction: Training:

$$\underset{v}{\operatorname{argmax}} P(y \mid x) \leftarrow \operatorname{Match!} \rightarrow \underset{\Theta}{\operatorname{argmax}} \prod_{i=1}^{N} P(y_i \mid x_i)$$

# Naïve Bayes vs Logistic Regression

#### • Naïve Bayes:

- Strong ind. assumptions
- Super easy to train...
- ...but mismatch with prediction

#### • Logistic Regression:

- "Log Linear" assumption
  - Often more flexible than Naïve Bayes
- Harder to train (gradient desc.)...
- ...but matches prediction

$$P(x,y) = A_{y} \prod_{d=1}^{D} O_{x^{d},y}^{d}$$

$$P(y) \qquad P(x|y)$$

$$P(y \mid x) = \frac{\exp\left\{w_y^T x - b_y\right\}}{\sum_k \exp\left\{w_k^T x - b_k\right\}}$$

$$x \in R^{D}$$
$$y \in \{1, 2, ..., K\}$$

## Naïve Bayes vs Logistic Regression

- NB has K parameters for P(y) (i.e., A)
- LR has K parameters for bias b
- NB has K\*D parameters for P(x|y) (i.e, O)
- LR has K\*D parameters for w
- Same number of parameters!

Naïve Bayes

$$P(x,y) = A_{y} \prod_{d=1}^{D} O_{x^{d},y}^{d}$$

$$P(y) \qquad P(x|y)$$

**Logistic Regression** 

$$P(x,y) = A_{y} \prod_{d=1}^{D} O_{x^{d},y}^{d}$$

$$P(y \mid x) = \frac{e^{w_{y}^{T}x - b_{y}}}{\sum_{k} e^{w_{k}^{T}x - b_{k}}}$$

$$p(y) \quad P(x \mid y)$$

$$x \in \{0,1\}^{D}$$

$$y \in \{1,2,...,K\}$$

## Naïve Bayes vs Logistic Regression

#### Intuition:

Both models have same "capacity" NB spends a lot of capacity on P(x) LR spends all of capacity on P(y|x)

#### No Model Is Perfect!

(Especially on finite training set) NB will trade off P(y|x) with P(x)LR will fit P(y|x) as well as possible

Generative	Discriminative
<ul><li>P(x,y)</li><li>Joint model over x and y</li><li>Cares about everything</li></ul>	<ul><li>P(y x) (when probabilistic)</li><li>Conditional model</li><li>Only cares about predicting well</li></ul>
Naïve Bayes, HMMs	Logistic Regression, CRFs
Max Likelihood	<ul> <li>Max (Conditional) Likelihood</li> <li>(=minimize log loss)</li> <li>Can pick any loss based on y</li> <li>Hinge Loss, Squared Loss, etc.</li> </ul>
Always Probabilistic	Not Necessarily Probabilistic  • Certainly never joint over P(x,y)
Often strong assumptions <ul><li>Keeps training tractable</li></ul>	<ul><li>More flexible assumptions</li><li>Focuses entire model on P(y x)</li></ul>
Mismatch between train & predict • Requires Bayes's rule	Train to optimize predict goal
Can sample anything	Can only sample y given x
Can handle missing values in x	Cannot handle missing values in x

### **Conditional Random Fields**

#### "Log-Linear" 1st Order Sequential Model

$$P(y \mid x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^{M} \left( u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}} \right) \right\}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

aka "Partition Function"

$$F(y,x) = \sum_{j=1}^{M} \left( u_{y^{j},y^{j-1}} + w_{y^{j},x^{j}} \right)$$

**Scoring Function** 

Scoring transitions Scoring input features

$$P(y \mid x) = \frac{\exp\{F(y,x)\}}{Z(x)} \qquad \log P(y \mid x) = F(y,x) - \log(Z(x))$$

$$P(y \mid x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^{M} \left( u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}} \right) \right\}$$

11		u <sub>N,*</sub>	u <sub>v,*</sub>
$u_{N,V}$	u <sub>*,N</sub>	-2	1
	u <sub>*,V</sub>	2	-2
	U <sub>*,Start</sub>	1	-1

	W <sub>N,*</sub>	W <sub>V,*</sub>	W <sub>V,Fish</sub>
<b>W</b> *,Fish	2	1	,
<b>W</b> <sub>*,Sleep</sub>	1	0	
, ,			

$$P(N,V \mid "Fish \ Sleep") = \frac{1}{Z(x)} \exp\left\{u_{N,Start} + w_{N,Fish} + u_{V,N} + w_{V,Sleep}\right\} = \frac{1}{Z(x)} \exp\left\{4\right\}$$

$$Z(x) = Sum$$

$$(N,N) = \exp(1+2-2+1) = \exp(2)$$

$$(N,V) = \exp(1+2+2+0) = \exp(4)$$

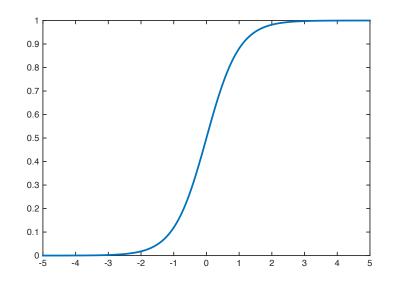
$$(V,N) = \exp(-1+1+2+1) = \exp(3)$$

$$(V,V) = \exp(-1+1-2+0) = \exp(-1)$$

- x = "Fish Sleep"
- y = (N,V)

$$P(N,V \mid "Fish \ Sleep") = \frac{1}{Z(x)} \exp\{u_{N,Start} + w_{N,Fish} + u_{V,N} + w_{V,Sleep}\}$$

 $P(N,V \mid "Fish \ Sleep")$ \*hold other parameters fixed



$$u_{N,Start} + v_{N,Fish} + u_{V,N} + v_{V,Sleep}$$

#### **Basic Conditional Random Field**

- Directly models P(y|x)
  - Discriminative
  - Log linear assumption
  - Same #parameters as HMM<sup>2</sup>
  - 1<sup>st</sup> Order Sequential LR
- How to Predict?
- How to Train?
- Extensions?

CRF spends all model capacity on P(y|x), rather than P(x,y)

$$F(y,x) = \sum_{j=1}^{M} \left( u_{y^{j},y^{j-1}} + w_{y^{j},x^{j}} \right)$$

$$P(y \mid x) = \frac{\exp\{F(y,x)\}}{\sum_{y'} \exp\{F(y',x)\}}$$

$$\log P(y \mid x) = F(y, x) - \log \left( \sum_{y'} \exp \left\{ F(y', x) \right\} \right)$$

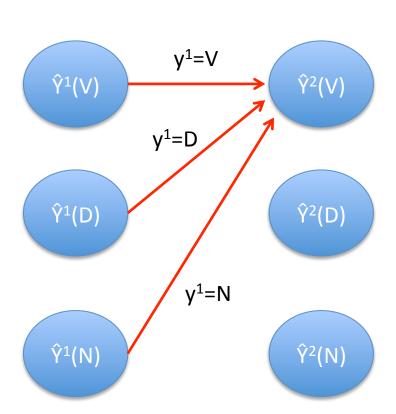
#### Predict via Viterbi

$$\underset{y}{\operatorname{argmax}} P(y \mid x) = \underset{y}{\operatorname{argmax}} \log P(y \mid x) = \underset{y}{\operatorname{argmax}} F(y, x)$$

$$= \underset{y}{\operatorname{argmax}} \sum_{j=1}^{M} \left( u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}} \right)$$
Scoring transitions Scoring input features

Maintain length-k prefix solutions	$\hat{Y}^{k}(T) = \left(\underset{y^{1:k-1}}{\operatorname{argmax}} F(y^{1:k-1} \oplus T, x^{1:k})\right) \oplus T$
Recursively solve for length-(k+1) solutions	$\hat{Y}^{k+1}(T) = \left(\underset{y^k}{\operatorname{argmax}} F(\hat{Y}^k(y^k) \oplus T, x^{1:k+1})\right) \oplus T$ $= \left(\underset{y^k}{\operatorname{argmax}} F(\hat{Y}^k(y^k), x^{1:k}) + u_{T, y^k} + w_{T, x^{k+1}}\right) \oplus T$
Predict via best length-M solution	$\underset{y}{\operatorname{argmax}} F(y, x) = \underset{y \in \{\hat{Y}^{M}(T)\}_{T}}{\operatorname{argmax}} F(y, x)$

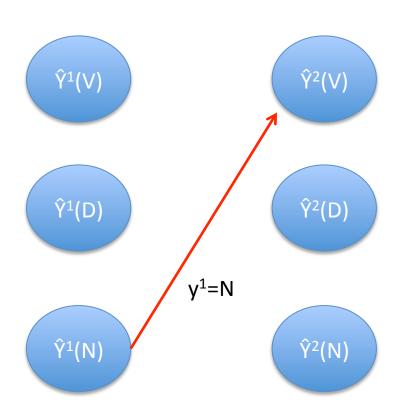
**Solve:** 
$$\hat{Y}^2(V) = \left( \underset{y^1}{\operatorname{argmax}} F(\hat{Y}^1(y^1), x^1) + u_{V, y^1} + w_{V, x^2} \right) \oplus V$$
  
Store each  $\hat{Y}^1(T) \& F(\hat{Y}^1(T), x^1)$ 



 $\hat{Y}^1(T)$  is just T

**Solve:** 
$$\hat{Y}^2(V) = \left( \underset{y^1}{\operatorname{argmax}} F(\hat{Y}^1(y^1), x^1) + u_{V, y^1} + w_{V, x^2} \right) \oplus V$$

Store each  $\hat{Y}^1(T) \& F(\hat{Y}^1(T), x^1)$ 



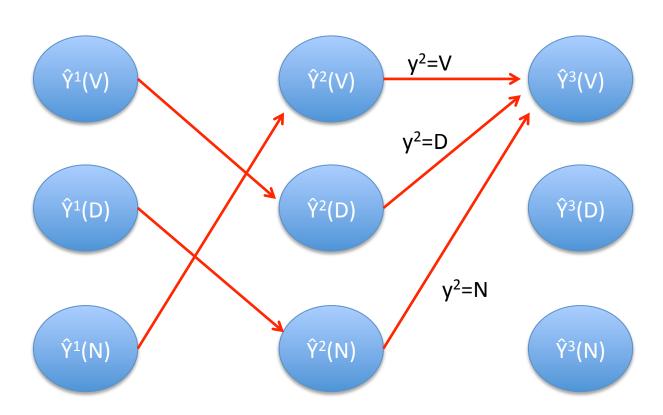
 $\hat{Y}^1(T)$  is just T

Ex: 
$$\hat{Y}^2(V) = (N, V)$$

**Solve:** 
$$\hat{Y}^3(V) = \left( \underset{y^2}{\operatorname{argmax}} F(\hat{Y}^2(y^2), x^{1:2}) + u_{V, y^2} + w_{V, x^3} \right) \oplus V$$

Store each  $\hat{Y}^1(T) \& F(\hat{Y}^1(T), x^1)$ 

Store each  $\hat{Y}^2(Z) \& F(\hat{Y}^2(Z), x^{1:2})$ 



 $\hat{Y}^1(Z)$  is just Z

Ex:  $\hat{Y}^2(V) = (N, V)$ 

**Solve:** 
$$\hat{Y}^M(V) = \left( \underset{y^{L-1}}{\operatorname{argmax}} F(\hat{Y}^{M-1}(y^{M-1}), x^{1:M-1}) + u_{V,y^{M-1}} + w_{V,x^M} \right) \oplus V$$

Ex:  $\hat{Y}^3(V) = (D, N, V)$ 

Store each Store each Store each  $\hat{Y}^2(T) \& F(\hat{Y}^2(T), x^{1:2})$  $\hat{Y}^3(T) \& F(\hat{Y}^3(T), x^{1:3})$  $\hat{Y}^{1}(Z) \& F(\hat{Y}^{1}(Z), x^{1})$  $\hat{Y}^2(V)$  $\hat{Y}^3(V)$ Ŷ¹(V)  $\hat{Y}^L(V)$  $\hat{Y}^2(D)$  $\hat{Y}^3(D)$ Ŷ¹(D)  $\hat{Y}^L(D)$  $\hat{Y}^2(N)$  $\hat{Y}^1(N)$ Ŷ3(N)  $\hat{Y}^L(N)$ 

Ex:  $\hat{Y}^2(V) = (N, V)$ 

 $\hat{Y}^1(T)$  is just T

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# Computing P(y|x)

- Viterbi doesn't compute P(y|x)
  - Just maximizes the numerator F(y,x)

$$P(y \mid x) = \frac{\exp\{F(y,x)\}}{\sum_{y'} \exp\{F(y',x)\}} = \frac{1}{Z(x)} \exp\{F(y,x)\}$$

- Also need to compute Z(x)
  - aka the "Partition Function"

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

# **Computing Partition Function**

- Naive approach is iterate over all y'
  - Exponential time, L<sup>M</sup> possible y'!

$$Z(x) = \sum_{y'} \exp\{F(y', x)\} \qquad F(y, x) = \sum_{j=1}^{M} \left(u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}}\right)$$

• Notation:  $G^{j}(a,b) = \exp\{u_{a,b} + w_{a,x^{j}}\}$ 

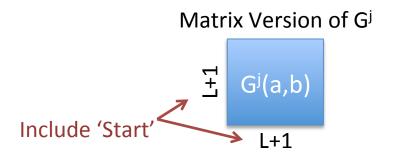
$$P(y \mid x) = \frac{1}{Z(x)} \prod_{i=1}^{M} G^{j}(y^{j}, y^{j-1})$$

$$Z(x) = \sum_{y'} \prod_{j=1}^{M} G^{j}(y'^{j}, y'^{j-1})$$

## **Matrix Semiring**

$$Z(x) = \sum_{y'} \prod_{j=1}^{M} G^{j}(y'^{j}, y'^{j-1})$$

$$G^{j}(a,b) = \exp\left\{u_{a,b} + w_{a,x^{j}}\right\}$$



$$G^{1:2}(a,b) \equiv \sum_{c} G^{2}(a,c)G^{1}(c,b)$$

$$G^{1:2} = G^2 G^1$$

$$G^{i:j}(a,b) \equiv$$
 $G^{i:j}$ 
 $G^{j-1}$ 
...
 $G^{i+1}$ 

# Path Counting Interpretation

Interpretation G¹(a,b)

 $\mathsf{G}^1$ 

- L+1 start & end locations
- Weight of path from 'b' to 'a' in step 1
- G<sup>1:2</sup>(a,b)



- Weight of all paths
  - Start in 'b' beginning of Step 1
  - End in 'a' after Step 2

## Computing Partition Function

Consider Length-1 (M=1)

$$Z(x) = \sum_{a} G^{1}(a, Start)$$

Sum column 'Start' of G1!

M=2

$$Z(x) = \sum_{a,b} G^{2}(b,a)G^{1}(a,Start) = \sum_{b} G^{1:2}(b,Start)$$
Sum column 'Start' of G<sup>1:2</sup>!

General M

Sum column 'Start' of G<sup>1:M</sup>!

- Do M (L+1)x(L+1) matrix computations to compute  $G^{1:M}$
- Z(x) = sum column 'Start' of  $G^{1:M}$

$$G^{1:M} = G^{M} G^{M-1} \cdots G^{2} G^{1}$$

#### Train via Gradient Descent

- Similar to Logistic Regression
  - Gradient Descent on negative log likelihood (log loss)

$$\underset{\Theta}{\operatorname{argmin}} \sum_{i=1}^{N} -\log P(y_i \mid x_i) = \underset{\Theta}{\operatorname{argmin}} \sum_{i=1}^{N} -F(y_i, x_i) + \log (Z(x))$$

Θ often used to denote all parameters of model

Harder to differentiate!

• First term is easy:

$$\partial_{u_{ab}} - F(y, x) = -\sum_{j=1}^{M} 1_{[(y^j, y^{j-1}) = (a, b)]}$$

– Recall:

$$F(y,x) = \sum_{j=1}^{M} \left( u_{y^{j},y^{j-1}} + w_{y^{j},x^{j}} \right)$$

$$\partial_{w_{az}} - F(y, x) = -\sum_{j=1}^{M} 1_{[(y^j, x^j) = (a, z)]}$$

# Differentiating Log Partition

Lots of Chain Rule & Algebra!

$$\partial_{u_{ab}} \log(Z(x)) = \frac{1}{Z(x)} \partial_{u_{ab}} Z(x) = \frac{1}{Z(x)} \partial_{u_{ab}} \sum_{y'} \exp\{F(y', x)\}$$

$$= \frac{1}{Z(x)} \sum_{y'} \partial_{u_{ab}} \exp\{F(y', x)\}$$

$$= \frac{1}{Z(x)} \sum_{y'} \exp\{F(y', x)\} \partial_{u_{ab}} F(y', x) = \sum_{y'} \frac{\exp\{F(y', x)\}}{Z(x)} \partial_{u_{ab}} F(y', x)$$

$$= \sum_{y'} P(y' | x) \partial_{u_{ab}} F(y', x) = \sum_{y'} \left[ P(y' | x) \sum_{j=1}^{M} 1_{[(y'^j, y'^{j-1}) = (a, b)]} \right]$$

$$= \sum_{j=1}^{M} \sum_{y'} P(y' | x) 1_{[(y'^j, y'^{j-1}) = (a, b)]} = \sum_{j=1}^{M} P(y^j = a, y^{j-1} = b | x)$$

$$= \sum_{j=1}^{M} \sum_{y'} P(y' | x) 1_{[(y'^j, y'^{j-1}) = (a, b)]} = \sum_{j=1}^{M} P(y^j = a, y^{j-1} = b | x)$$

$$= \sum_{j=1}^{M} \sum_{y'} P(y' | x) 1_{[(y'^j, y'^{j-1}) = (a, b)]} = \sum_{j=1}^{M} P(y^j = a, y^{j-1} = b | x)$$

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# **Optimality Condition**

$$\underset{\Theta}{\operatorname{argmin}} \sum_{i=1}^{N} -\log P(y_i \mid x_i) = \underset{\Theta}{\operatorname{argmin}} \sum_{i=1}^{N} -F(y_i, x_i) + \log (Z(x))$$

Consider one parameter:

$$\partial_{u_{ab}} \sum_{i=1}^{N} -F(y_i, x_i) = -\sum_{i=1}^{N} \sum_{j=1}^{M_i} 1_{\left[(y_i^j, y_i^{j-1}) = (a, b)\right]} \qquad \partial_{u_{ab}} \sum_{i=1}^{N} \log(Z(x)) = \sum_{i=1}^{N} \sum_{j=1}^{M_i} P(y_i^j = a, y_i^{j-1} = b \mid x_i)$$

Optimality condition:

$$\sum_{i=1}^{N} \sum_{j=1}^{M_i} 1_{\left[(y_i^j, y_i^{j-1}) = (a,b)\right]} = \sum_{i=1}^{N} \sum_{j=1}^{M_i} P(y_i^j = a, y_i^{j-1} = b \mid x_i)$$

- Frequency counts = Cond. expectation on training data!
  - Holds for each component of the model
  - Each component is a "log-linear" model and requires gradient desc.

## Forward-Backward for CRFs

$$\alpha^{1}(a) = G^{1}(a, Start)$$

$$\alpha^{j}(a) = \sum_{b} \alpha^{j-1}(b)G^{j}(a,b)$$

$$\beta^{M}(b) = 1$$

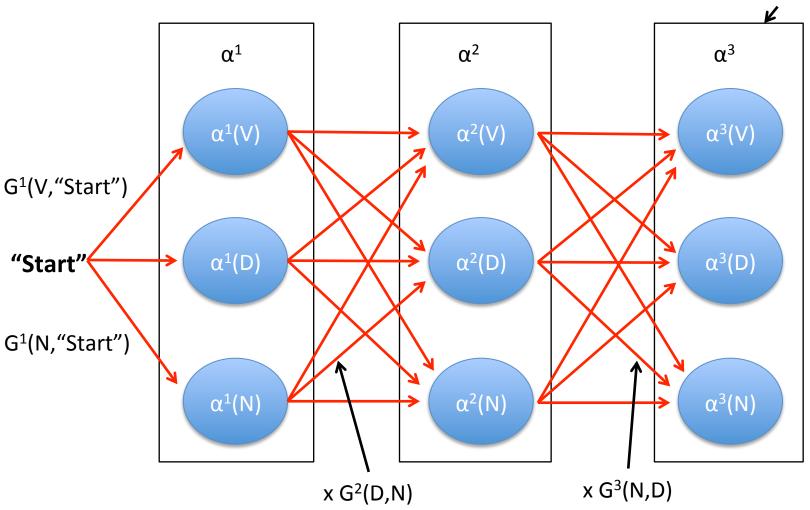
$$\beta^{j}(b) = \sum_{a} \beta^{j+1}(a)G^{j}(a,b)$$

$$P(y^{j} = b, y^{j-1} = a \mid x) = \frac{\alpha^{j-1}(a)G^{j}(a,b)\beta^{j}(b)}{Z(x)}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\} \qquad F(y, x) = \sum_{j=1}^{M} \left(u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}}\right) \quad G^{j}(a, b) = \exp\{u_{a, b} + w_{a, x^{j}}\}$$

# Path Interpretation

Total Weight of paths from "Start" to "V" in 3<sup>rd</sup> step



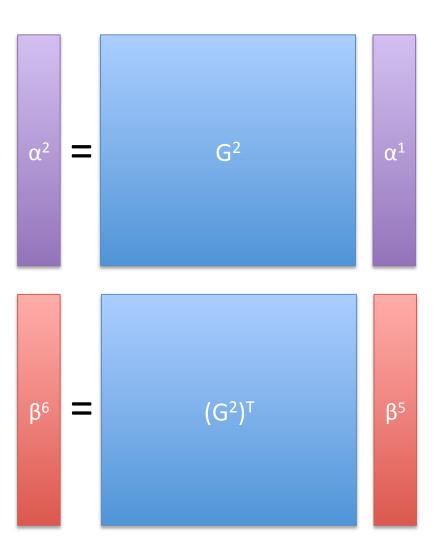
β just does it backwards

## **Matrix Formulation**

Use Matrices!

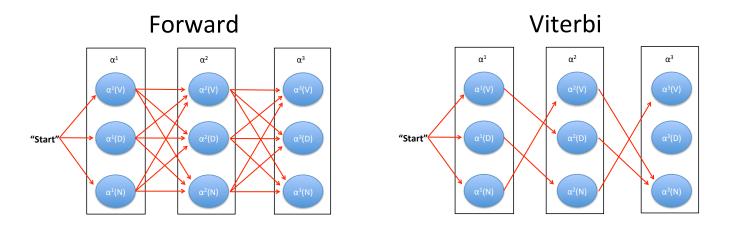
Fast to compute!

• Easy to implement!



#### **Path Interpretation:**

#### Forward-Backward vs Viterbi



- Forward (and Backward) sums over all paths
  - Computes expectation of reaching each state
  - E.g., total (un-normalized) probability of  $y^3$ =Verb over all possible  $y^{1:2}$
- Viterbi only keeps the best path
  - Computes best possible path to reaching each state
  - E.g., single highest probability setting of  $y^{1:3}$  such that  $y^3$ =Verb

# **Summary: Training CRFs**

- Similar optimality condition as HMMs:
  - Match frequency counts of model components!

$$\sum_{i=1}^{N} \sum_{j=1}^{M_i} 1_{\left[ (y_i^j, y_i^{j-1}) = (a,b) \right]} = \sum_{i=1}^{N} \sum_{j=1}^{M_i} P(y_i^j = a, y_i^{j-1} = b \mid x_i)$$

- Except HMMs can just set the model using counts
- CRFs need to do gradient descent to match counts
- Run Forward-Backward for expectation
  - Just like HMMs as well

## More General CRFs

$$P(y \mid x) = \frac{\exp\{F(y, x)\}}{\sum_{y'} \exp\{F(y', x)\}} \qquad F(y, x) = \sum_{j=1}^{M} \theta^{T} \phi_{j}(y^{j}, y^{j-1} \mid x)$$

$$F(y,x) = \sum_{j=1}^{M} \theta^{T} \phi_{j}(y^{j}, y^{j-1} \mid x)$$

#### Reduction:

$$\phi_{j}(a,b \mid x) = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\longleftrightarrow u_{a,b}$$

$$\theta^{T} \phi_{j}(y^{j}, y^{j-1} \mid x) = u_{y^{j}, y^{j-1}} + w_{y^{j}, x^{j}}$$

$$\theta \text{ is "flattened" weight vector Can extend } \phi_{j}(a,b \mid x)$$

Old:  

$$F(y,x) = \sum_{j=1}^{M} \left( u_{y^{j},y^{j-1}} + w_{y^{j},x^{j}} \right)$$

$$\theta^T \phi_j(y^j, y^{j-1} \mid x) = u_{y^j, y^{j-1}} + w_{y^j, x^j}$$

#### More General CRFs

$$P(y \mid x) = \frac{\exp\{F(y, x)\}}{\sum_{y'} \exp\{F(y', x)\}} \qquad F(y, x) = \sum_{j=1}^{M} \theta^{T} \phi_{j}(y^{j}, y^{j-1} \mid x)$$

#### 1<sup>st</sup> order Sequence CRFs:

$$F(y,x) = \sum_{j=1}^{M} \left[ \theta_2^T \psi_j(y^j, y^{j-1}) + \theta_1^T \varphi_j(y^j \mid x) \right]$$

$$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \qquad \phi_j(a,b \mid x) = \begin{bmatrix} \psi_j(a,b) \\ \varphi_j(b \mid x) \end{bmatrix}$$

# Example

$$F(y,x) = \sum_{j=1}^{M} \left[ \theta_2^T \psi_j(y^j, y^{j-1}) + \theta_1^T \varphi_j(y^j \mid x) \right]$$

**Basic formulation** only had first part

$$\varphi_{j,b}(x) = \begin{bmatrix} e_{x^{j}} \\ 1_{[x^{j} \in animal]} \\ e_{x^{j-1}} \end{bmatrix}$$

$$\varphi_{j,b}(x) = \begin{bmatrix} e_{x^j} \\ 1_{[x^j \in animal]} \\ e_{x^{j-1}} \end{bmatrix} \qquad \varphi_j(b \mid x) = \begin{bmatrix} 1_{[b=1]} \varphi_{j,1}(x) \\ 1_{[b=-1]} \varphi_{j,2}(x) \\ \vdots \\ 1_{[b=-100]} \varphi_{j,100}(x) \\ \vdots \end{bmatrix}$$
 All 0's except 1 sub-vector

Various attributes of x

Stack for each label y<sup>j</sup>=b

# **Summary: CRFs**

- "Log-Linear" 1st order sequence model
  - Multiclass LR + 1<sup>st</sup> order components
  - Discriminative Version of HMMs

$$P(y | x) = \frac{\exp\{F(y, x)\}}{\sum_{y'} \exp\{F(y', x)\}}$$

$$F(y,x) = \sum_{j=1}^{M} \left[ \theta_2^T \psi_j(y^j, y^{j-1}) + \theta_1^T \varphi_j(y^j \mid x) \right]$$

- Predict using Viterbi, Train using Gradient Descent
- Need forward-backward to differentiate partition function

## **Next Week**

- Structural SVMs
  - Hinge loss for sequence prediction
- More General Structured Prediction
- Next Recitation:
  - Optimizing non-differentiable functions (Lasso)
  - Accelerated gradient descent
- Homework 2 due in 12 days
  - Tuesday, Feb 3<sup>rd</sup> at 2pm via Moodle