```
BOM:
C1 = 100n (50V 0805)
                                              D1 = 1N4007
                                                                                             R1 = 100k (0805)
C2 = 100n (50V 0805)
                                              D2 = 1N4007
                                                                                             R2 = 470R (0805 1\% 0.125W)
C3 = 10\mu (50V RM2.5/5mm)
                                                                                             R3 = 10k (0805 1\% 0.125W)
C4 = 100n (50V 0805)
                                              DZ1 = 9V1 (9.1V Zener Diode THT)
                                                                                             R4 = 0.1R 1W 0.1\% (1206 0.25W 0.5\%)
C5 = 10\mu (16V 0805 MLCC)
                                                                                             R5 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C6 = 100n (50V 0805)
                                              IC1 = L78L33 (T092 3.3V Vreg)
                                                                                             R6 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C7 = 100n (50V 0805)
                                              IC2 = PIC24F16KA101
                                                                                             R7 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C8 = 1\mu (0805 16V - do not mount)
                                              IC3 = INA219B S0T23-8
                                                                                             R8 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C9 = 10\mu (50V RM2.5/5mm)
                                                                                             R9 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C10 = 100n (50V 0805)
                                              LCD1 = 128x64 i2C SSD1306 OLED
                                                                                             R10 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C11 = 100n (50V 0805)
                                              LCD2 = Nokia5110 PCD8544 LCD (SPI)
                                                                                             R11 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
C12 = 10\mu (16V 0805 MLCC)
                                                                                             R12 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
|C13 = 100n (50V 0805)
                                              SPK1 = Piezo buzzer (2.4kHz 12mm RM6.5mm)
                                                                                             R13 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
CN1 = DCIN (DC Jack 5.5/2.1mm)
                                                                                             R14 = 1R \ 0.5\% \ (1206 \ 0.25W \ 0.5\%)
                                              P1 = 10k-50k LIN (ALPS RK09L114001T)
CN2 = ICSP (5pin Microchip ICSP)
                                                                                             R15 = 0R(10R) (0805 1\% 0.125W)
CN3 = DCOUT (DC Jack 5.5/2.1mm)
                                                                                             R16 = 0R(10R) (0805 1\% 0.125W)
                                              Q1 = AP4435GJ (PMOS - 30V 21m0hm)
CN4 = OLED_I2C (4 pin header RM2.54)
                                                                                             R17 = 2k2 (0805 1\% 0.125W)
CN5 = I2C \overline{(4 pin header RM2.54)}
                                                                                             R18 = 2k2 (0805 1\% 0.125W)
CN6 = UART (4 pin header RM2.54)
                                                                                             R19 = 47R (1206 \ 0.25W)
CN7 = SPI/5110 LCD (9 pin header RM2.54)
                                                                                             R20 = 10k (0805 1\% 0.125W)
|CN8| = RB1 (3 pin header RM2.54)
CN9 = UART (4 pin header RM2.54)
```

## UART (9600 baud 8b 1Sb NP) commands NORMAL MODE:

data output format, copy of the LCD display lcd data output format, raw numbers separated by semicolons raw stops updating the data via UART stop start/resume the data update in 1 second intervals start **rstcnt** resets the measurement counter to 0 **getcnt** returns the actual masurement counter value calrst resets the INA219 calibration constant to theoretic calculated stock value (8192) INA219 secodary recalibration mode used to increase the precision. recal Requires a separate at least 4.5 digit mA/A meter as a reference. getcal return the actual INA219 calibration constant value yep! I confirm

## **RECAL MODE:**

n

no, thanks.

xxxx.xx waits for the reference current value (xxxx.xx[mA] format) exit cancel the calibration and return to NORMAL mode

Project Name:

## POWER MONITOR

PIC24F16KA101 + INA219 mini dev board

Author:

PIOTR ZAPART www.hexequitar.com Date: 05-07.2014

License:

