



21AI637 Deep Learning 3-0-2-4  
( S2 MTech AI)

21AM645 Deep Learning 3-0-2-4  
( S2 M.Tech CS(AI/ML)

PhD Coursework

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Amritapuri Campus



# Class Timings

- Tuesday 11 am to 11 : 40 am
- Wednesday 11 am to 11 : 40 am
- Thursday 8:50 am to 9:40 am
- Lab – Tuesday( 3.00PM to 4:50PM)

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# Course Objectives

- To introduce to students,
  - Different deep neural network architectures,
  - Training strategies/algorithms, possible challenges, tools and techniques available in designing and deploying solutions to different practical/ Engineering problems.

# Course Outcomes

- After the course completion, the students will be able to,
  - **CO1:** Be able to design, train, deploy neural networks for solving different practical/engineering problems and analyse and report its efficacy
  - **CO2 :** Have a good level of knowledge (Both Conceptual and Mathematical) on different neural network settings to pursue Research in this Field
  - **CO3:** Build skills in using established ML tools/libraries and in building self-learning skills in the field
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- Prerequisites • Linear Algebra and Probability • Computational Methods for Optimisation

# Syllabus

- Neural Networks basics – Linear Separable Problems and Perceptron –
- Multi layer neural networks and Back Propagation, Practical aspects of Deep Learning: Train/ Dev / Test sets, Bias/variance, Vanishing/exploding gradients, Gradient checking, Hyper Parameter Tuning
- Convolutional Neural Networks – Basics and Evolution of Popular CNN architectures – Transfer Learning– Applications : Object Detection and Localization, Face Recognition,
- Neural Style Transfer Recurrent Neural Networks – GRU – LSTM – NLP – Word Embeddings – Transfer Learning –
- Attention Models – Applications : Sentinel Classification, Speech Recognition, Action Recognition
- Restricted Boltzmann Machine – Deep Belief Network –
- Auto Encoders – Applications: SemiSupervised classification, Noise Reduction, Non-linear Dimensionality Reduction Goal Oriented Decision Making – Policy and Target Networks –
- **Deep Quality Network for Reinforcement Learning**
- Introduction to GAN – Encoder/Decoder, Generator/Discriminator architectures Challenges in NN training –
- Data Augmentation – Hyper parameter Settings – Transfer Learning– Developing and Deploying ML Models (e.g., Matlab/Tensor Flow/PyTorch)

# Deep Learning Models ( Big Picture)

- **Deep Neural Networks**

- Neural Networks
- Deep Neural Networks/Feed forward Networks

- **Convolutional Neural Networks ( CNN)**

- LeNet
- AlexNet
- VGG
- ResNet
- GoogleNet

- **Object Detection models**

- RCNN
- Yolo

- **Generative models**

- Generative Adversarial Networks,(GAN)

- **Sequential Models**

- RNN
- LSTM
- Encoder – Decoder models
- Attention mechanism
- **Transformers**
- **Transformers, Transformer-XL, Masked Language Modelling**
- **Generative Pre-trained Transformer 3 (GPT-3)**

- **Autoregressive models**

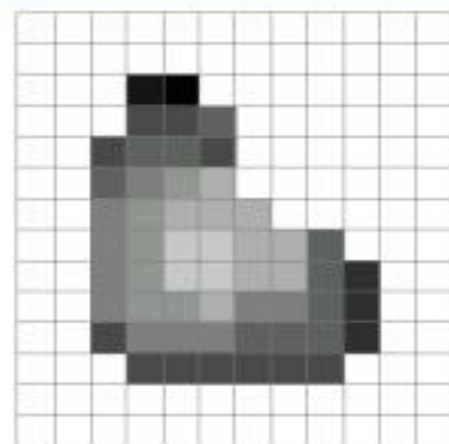
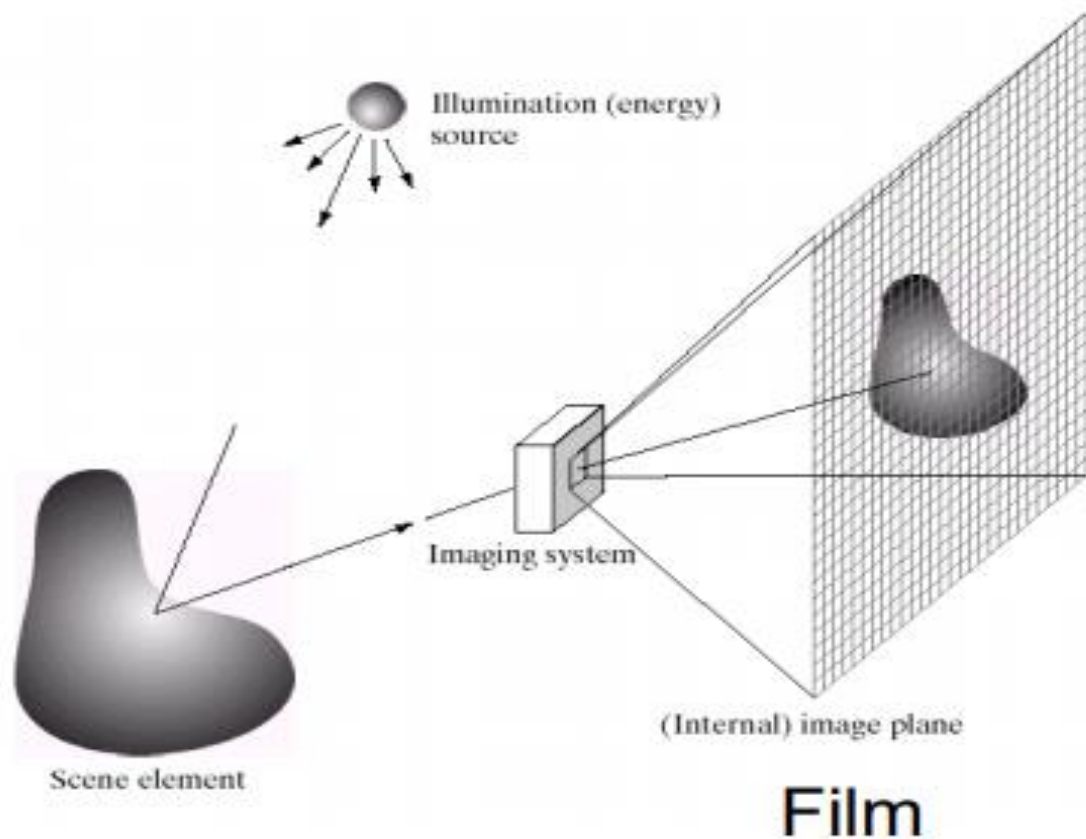
- Time series forecasting
- **Generative Pre-trained Transformer 3 (GPT-3)**
- **NADE, MADE(Masked Autoencoder Density Estimator), PixelRNN**



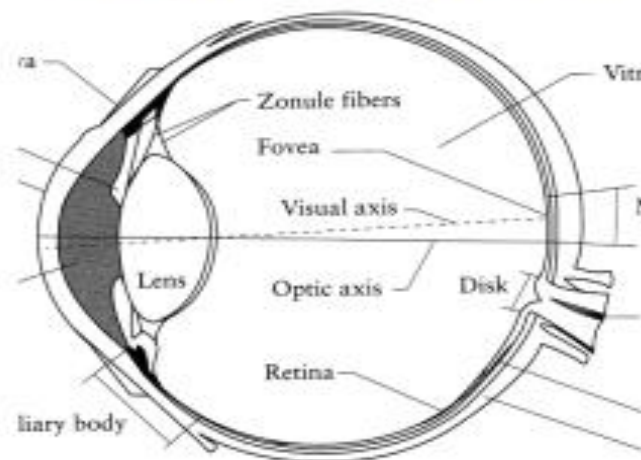


# Introduction to Computer Vision

# Image Formation: Simple Model



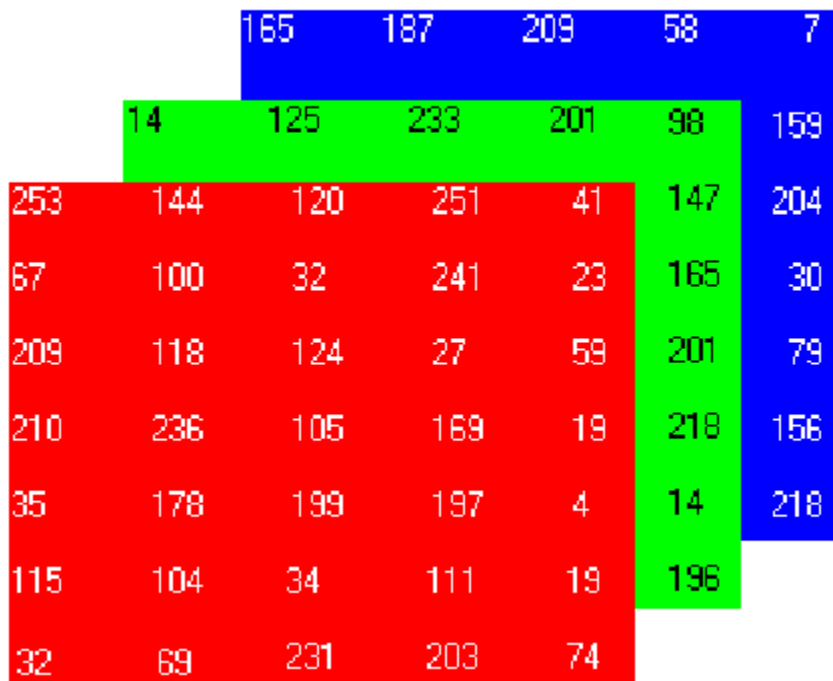
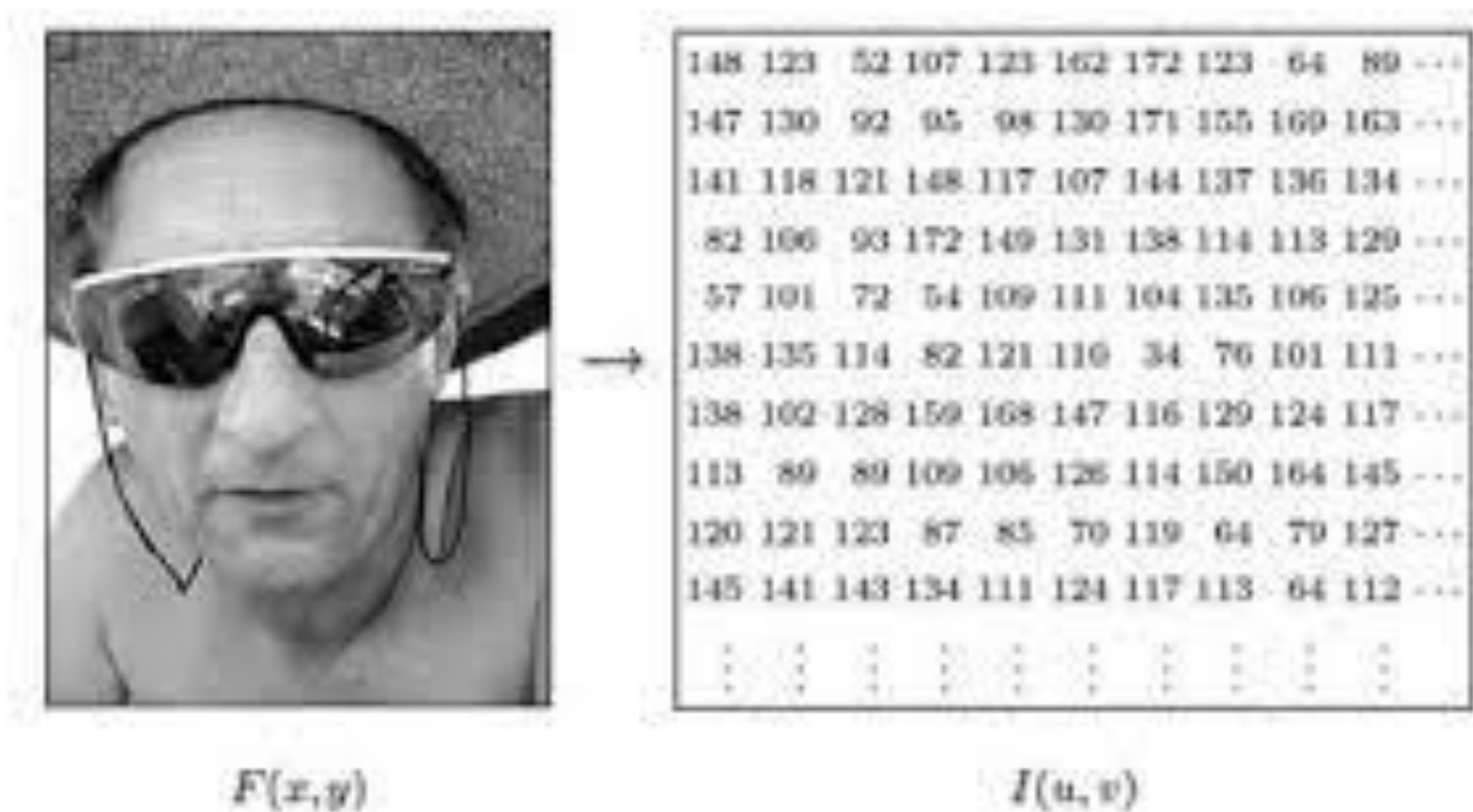
Digital Camera



The Eye



# Image Matrix- pixel,resolution( spatial, graylevel)



Color image

Gray Scale image 8 bit gray scale image 0-255 0-black, 255- white

## Classification



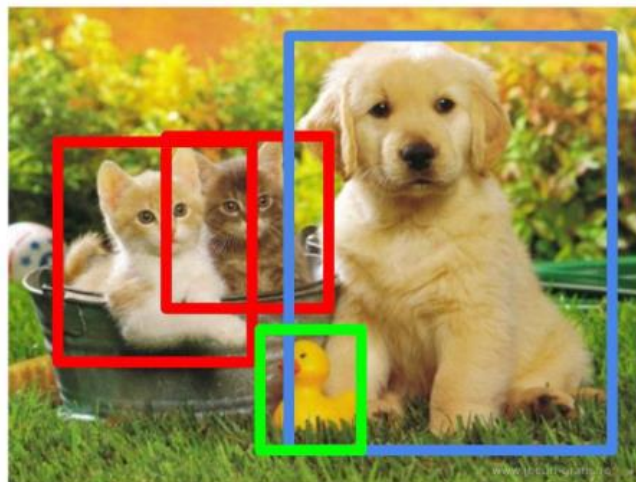
CAT

## Classification + Localization



CAT

## Object Detection



CAT, DOG, DUCK

## Instance Segmentation



CAT, DOG, DUCK

Single object

Multiple objects



### Classification



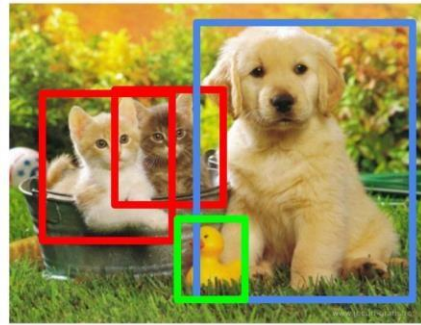
CAT

### Classification + Localization



CAT

### Object Detection



CAT, DOG, DUCK

### Instance Segmentation

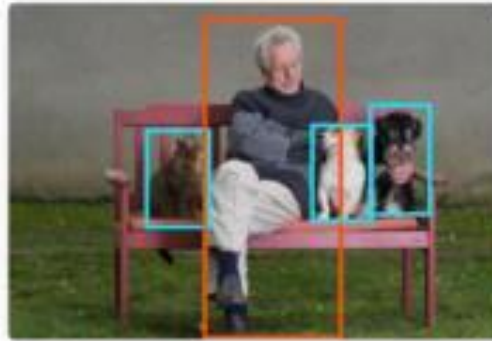


CAT, DOG, DUCK

PERSON, CAT, DOG



(A) Classification

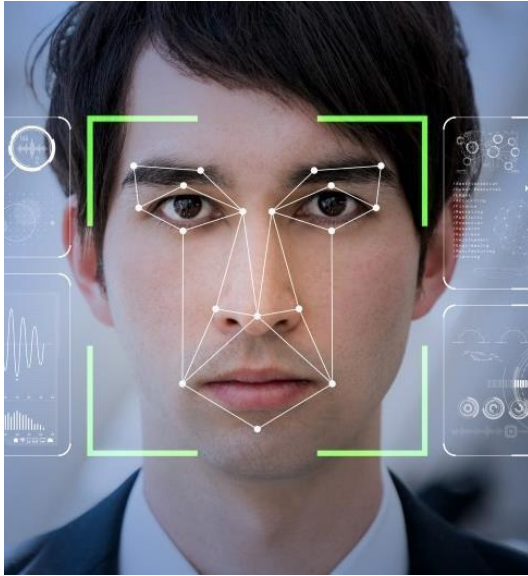


(B) Detection



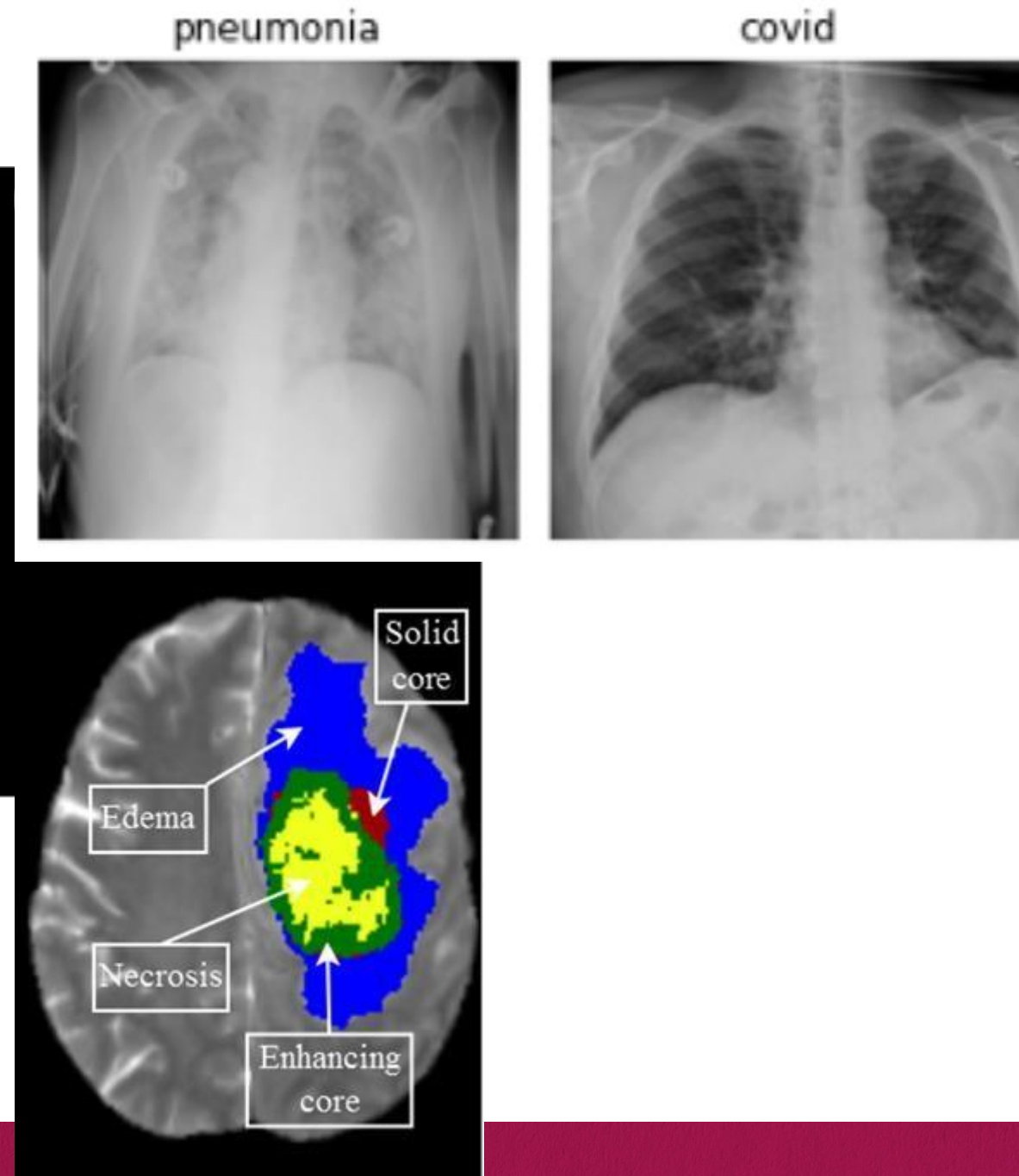
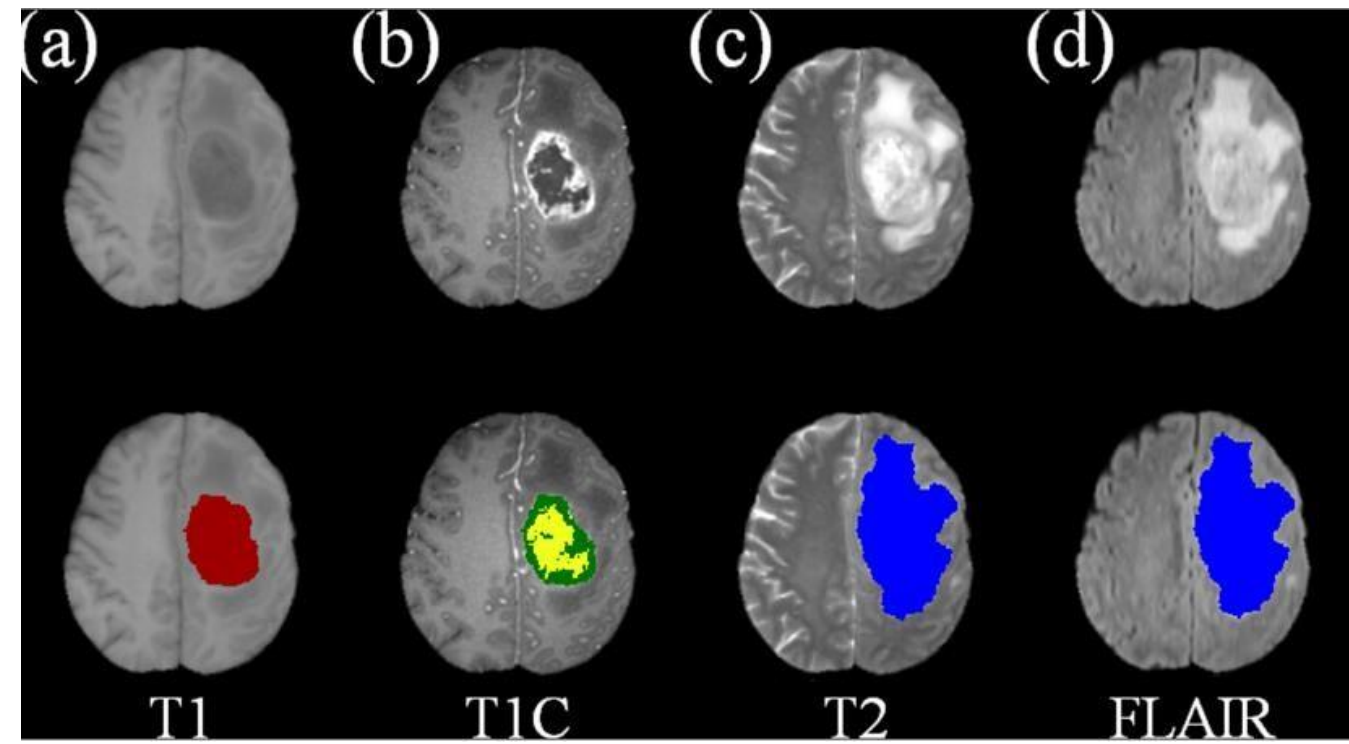
(C) Segmentation

# Biometric Applications

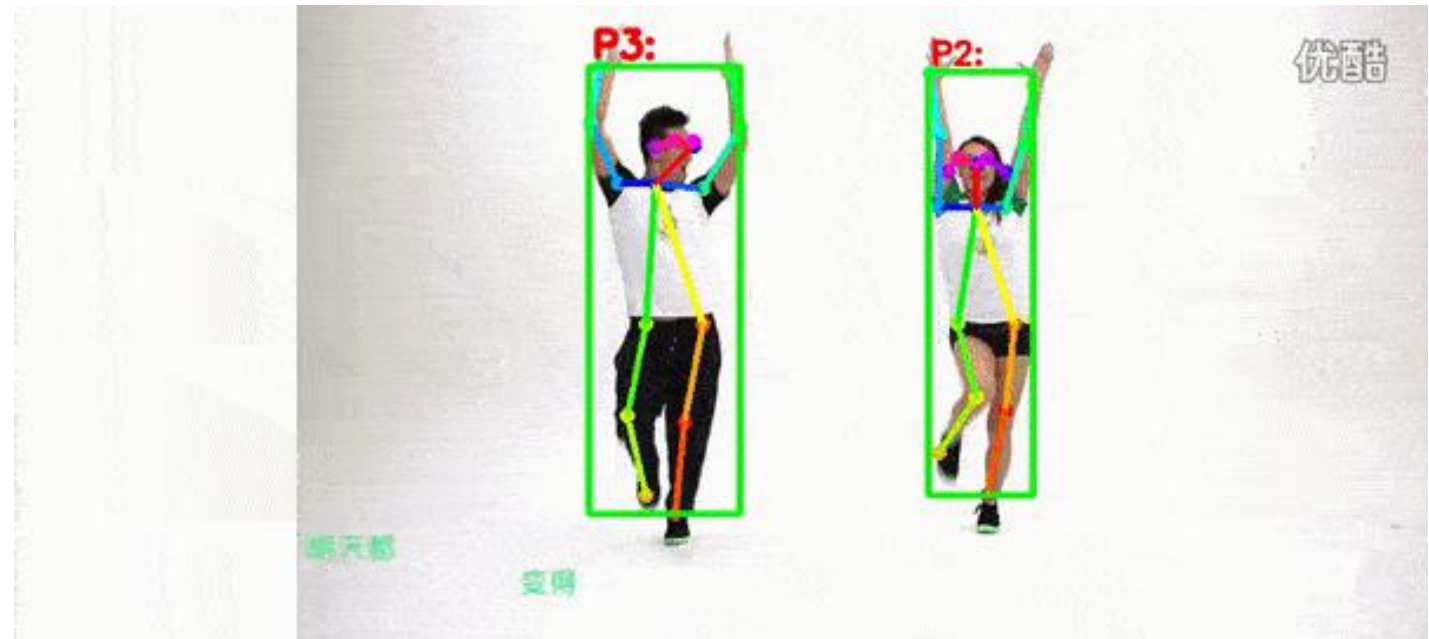
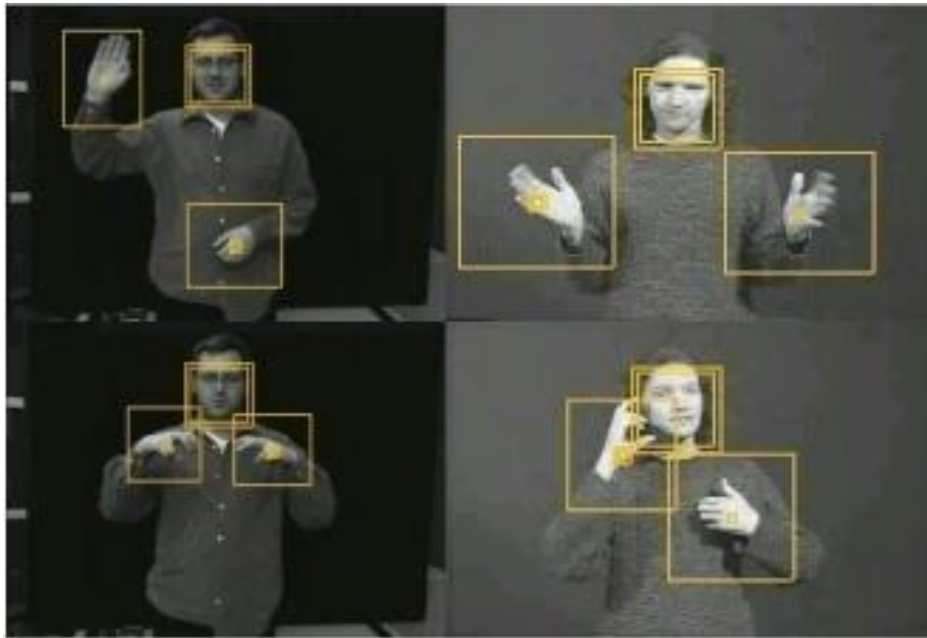




# Medical Image Analysis

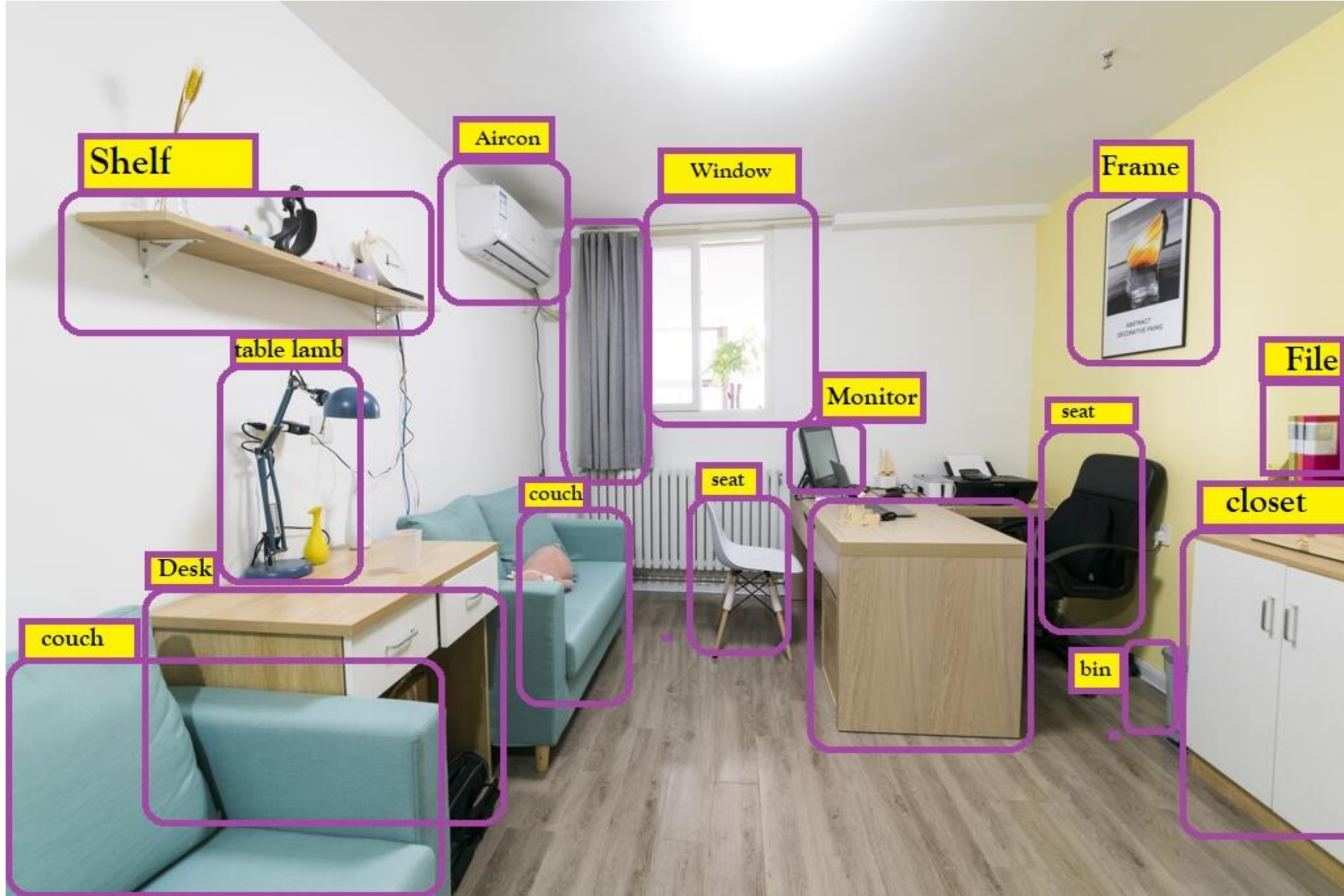


# Video Processing - Gesture Recognition/Action Recognition





# Scene Understanding



Foil



Yes

No



What is the sandwich laying on?

What is the food on?

Is this a sandwich?

Has the sandwich been cut?

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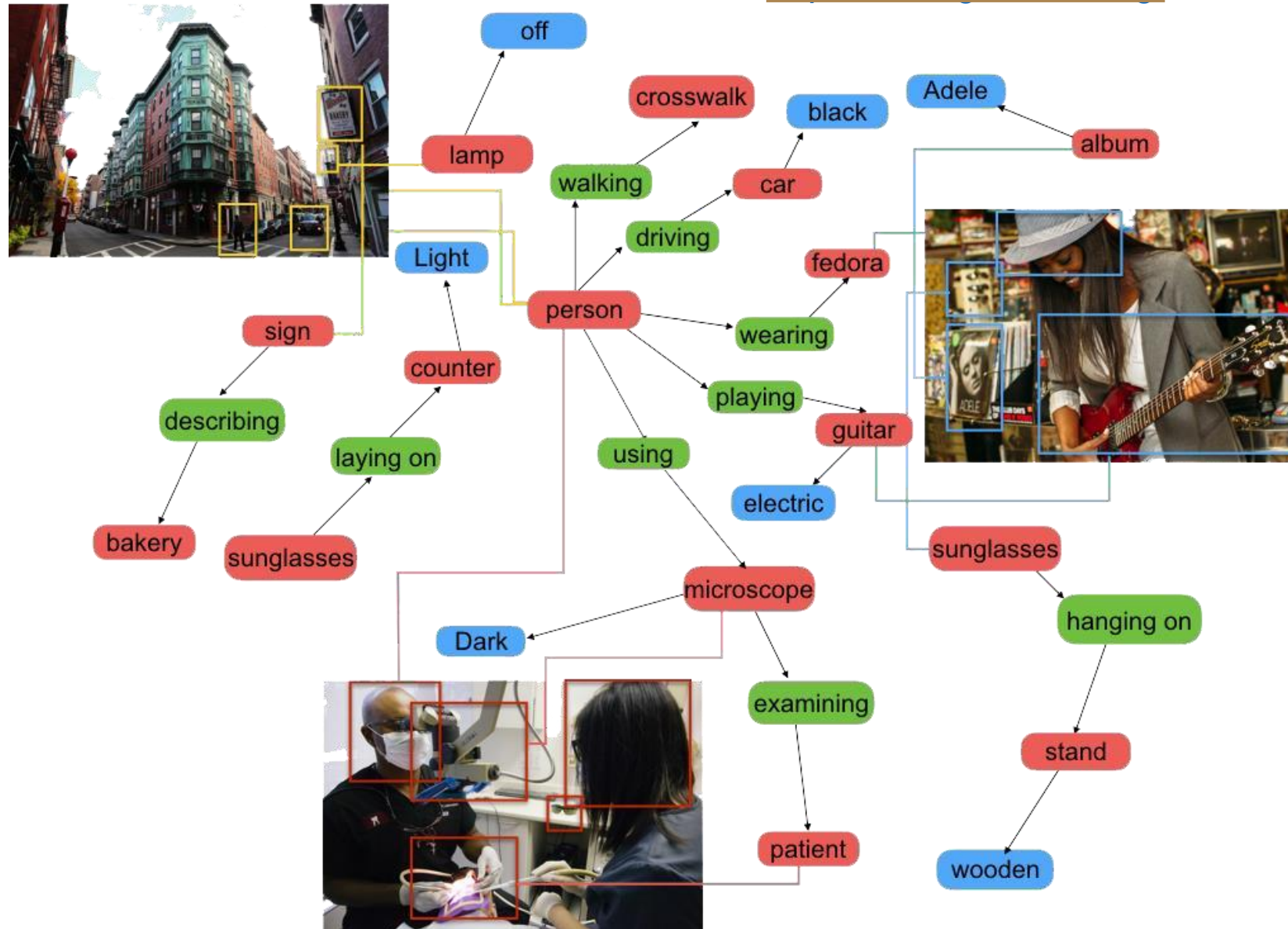
Is the boy wearing a hat?

Is the boy playing baseball?

Is this a professional baseball player?

Did the boy hit the ball?



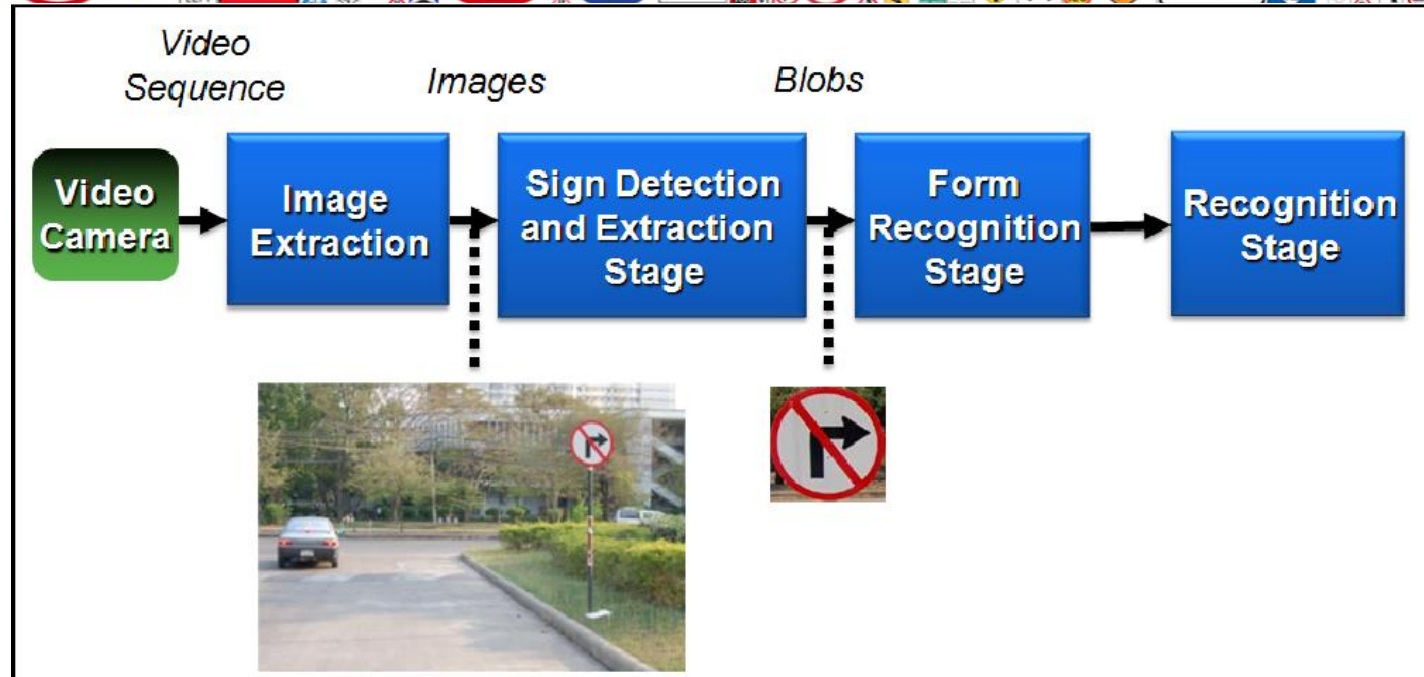


# Traffic Sign Recognition





# Traffic Sign Recognition

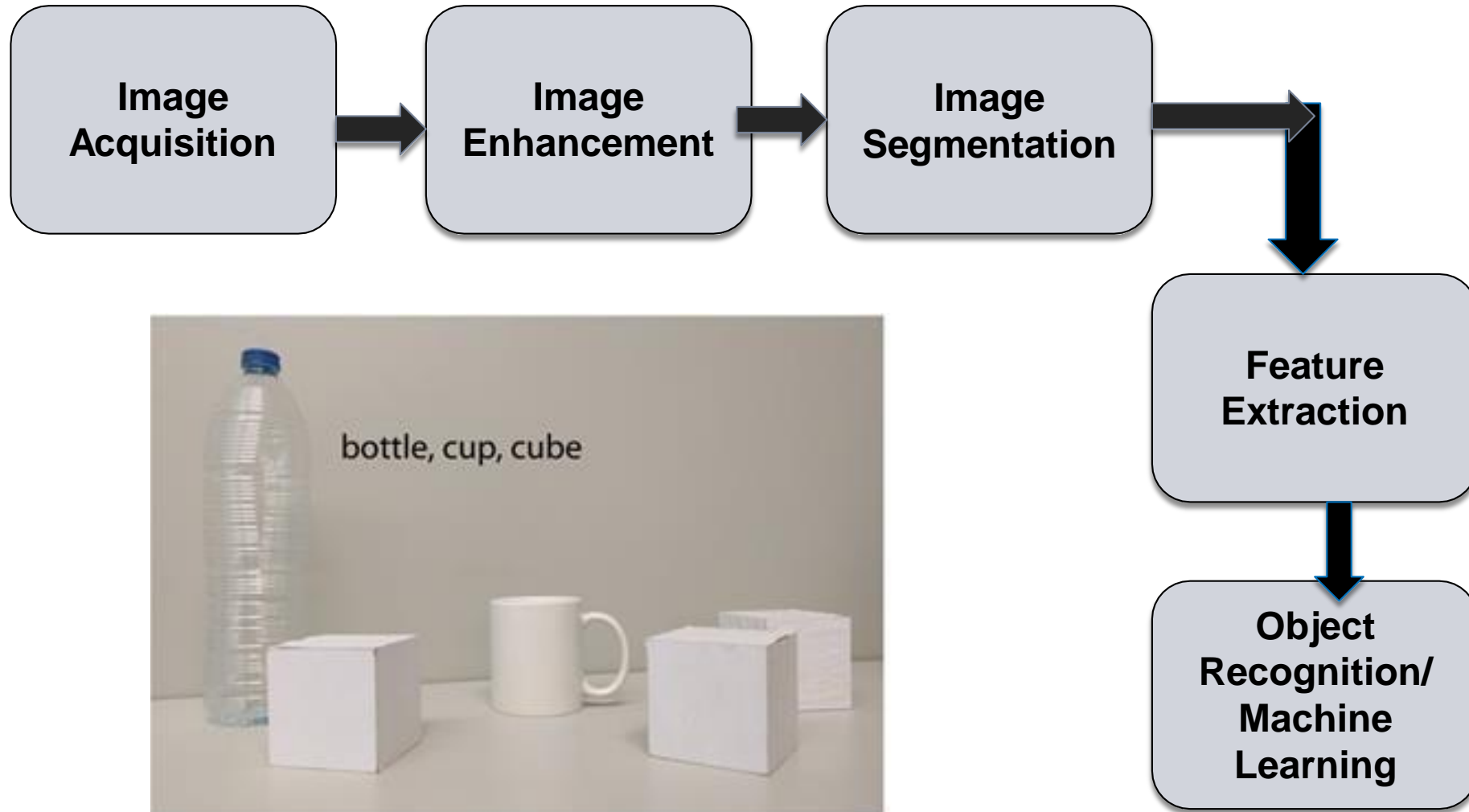


# Static Sign Language Recognition

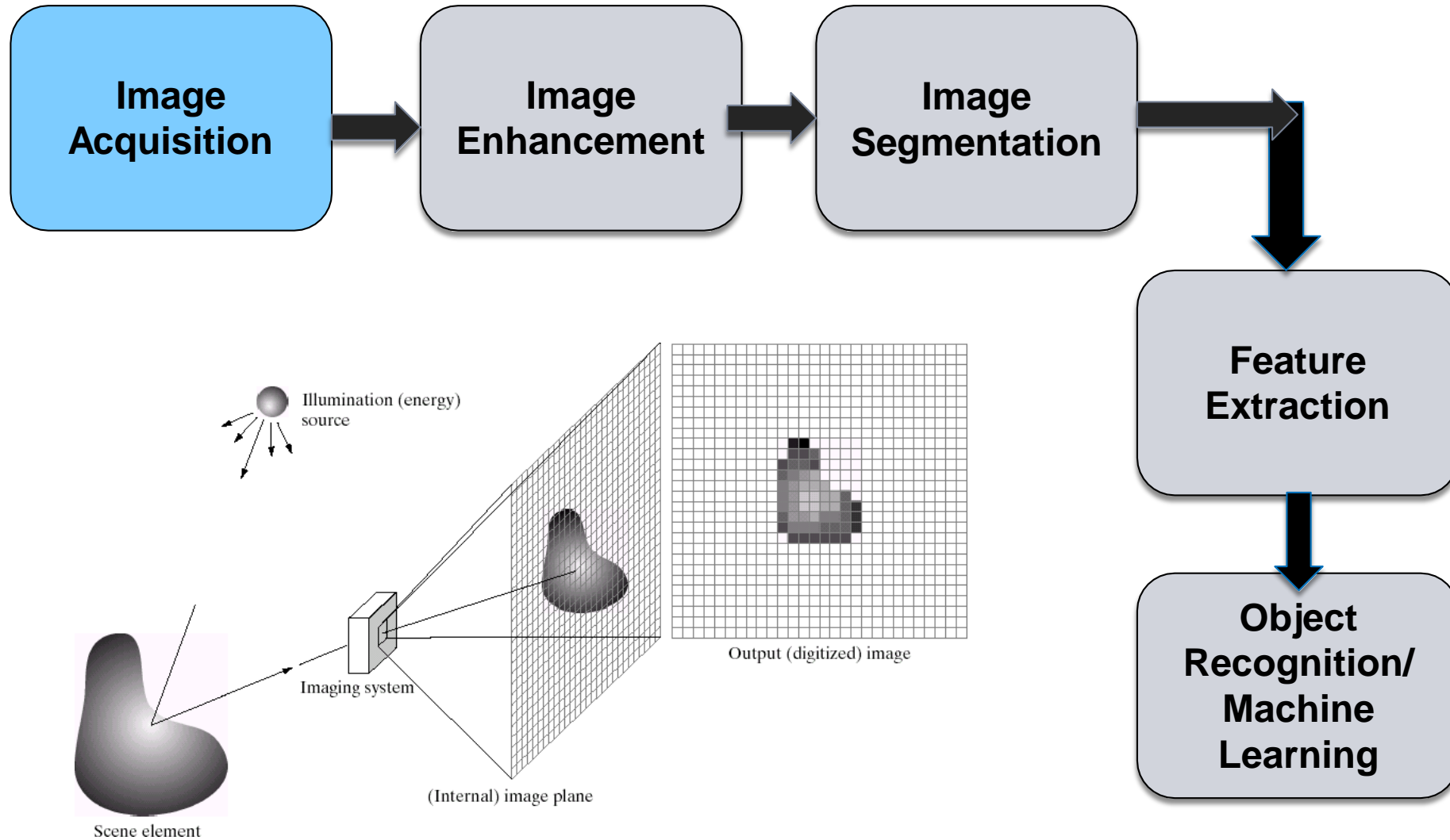




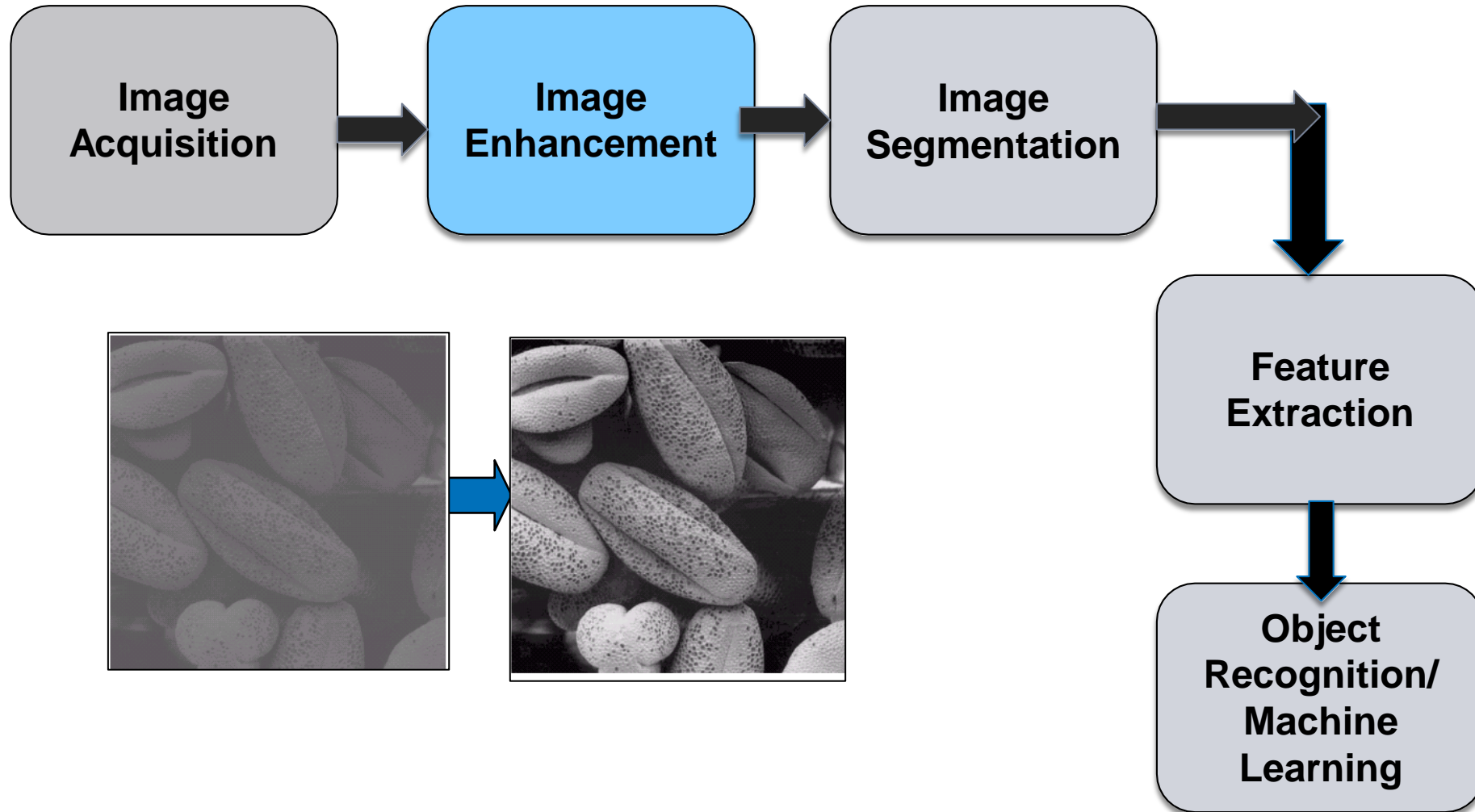
# KEY STEPS-IMAGE ANALYSIS



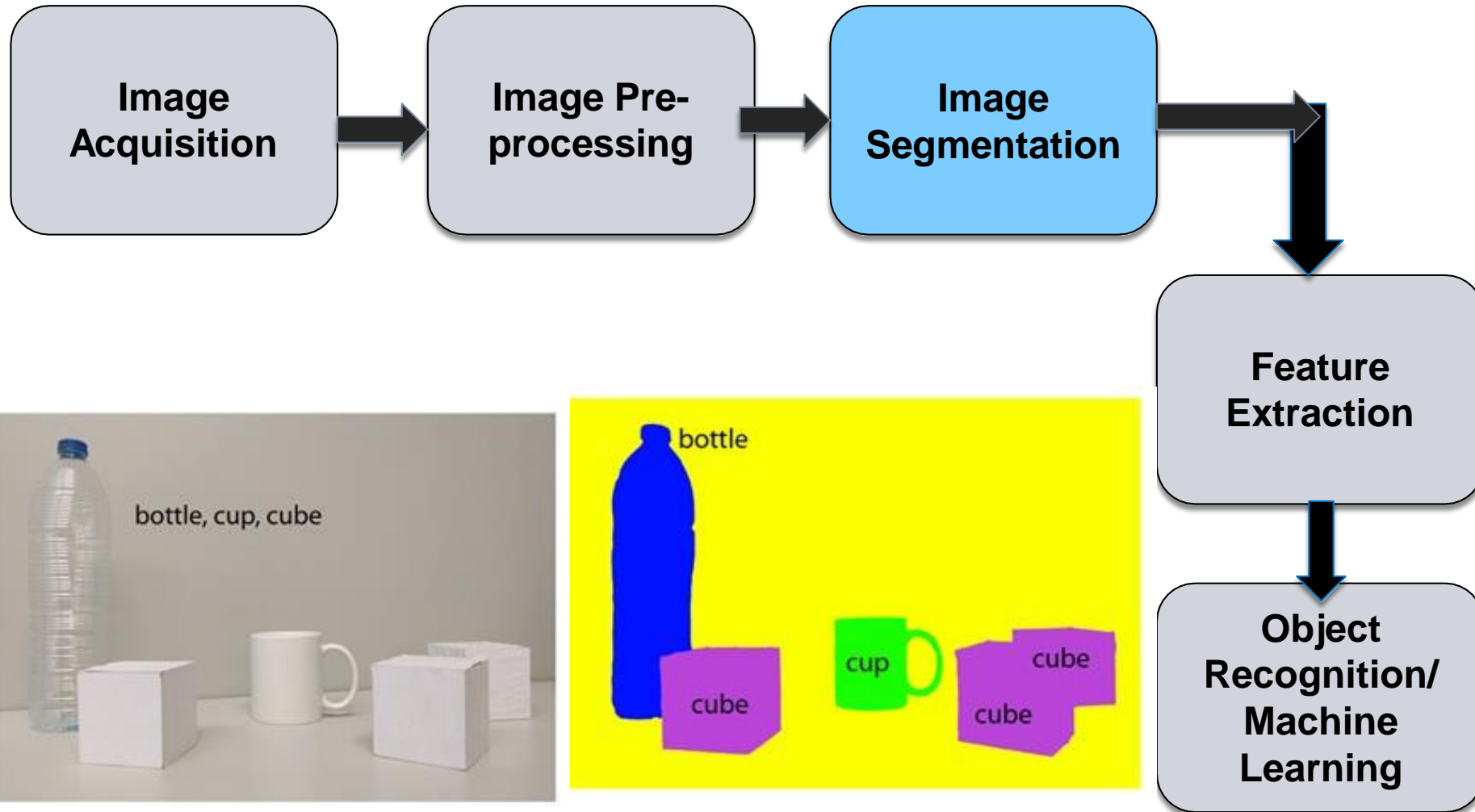
# KEY STEPS-IMAGE ANALYSIS



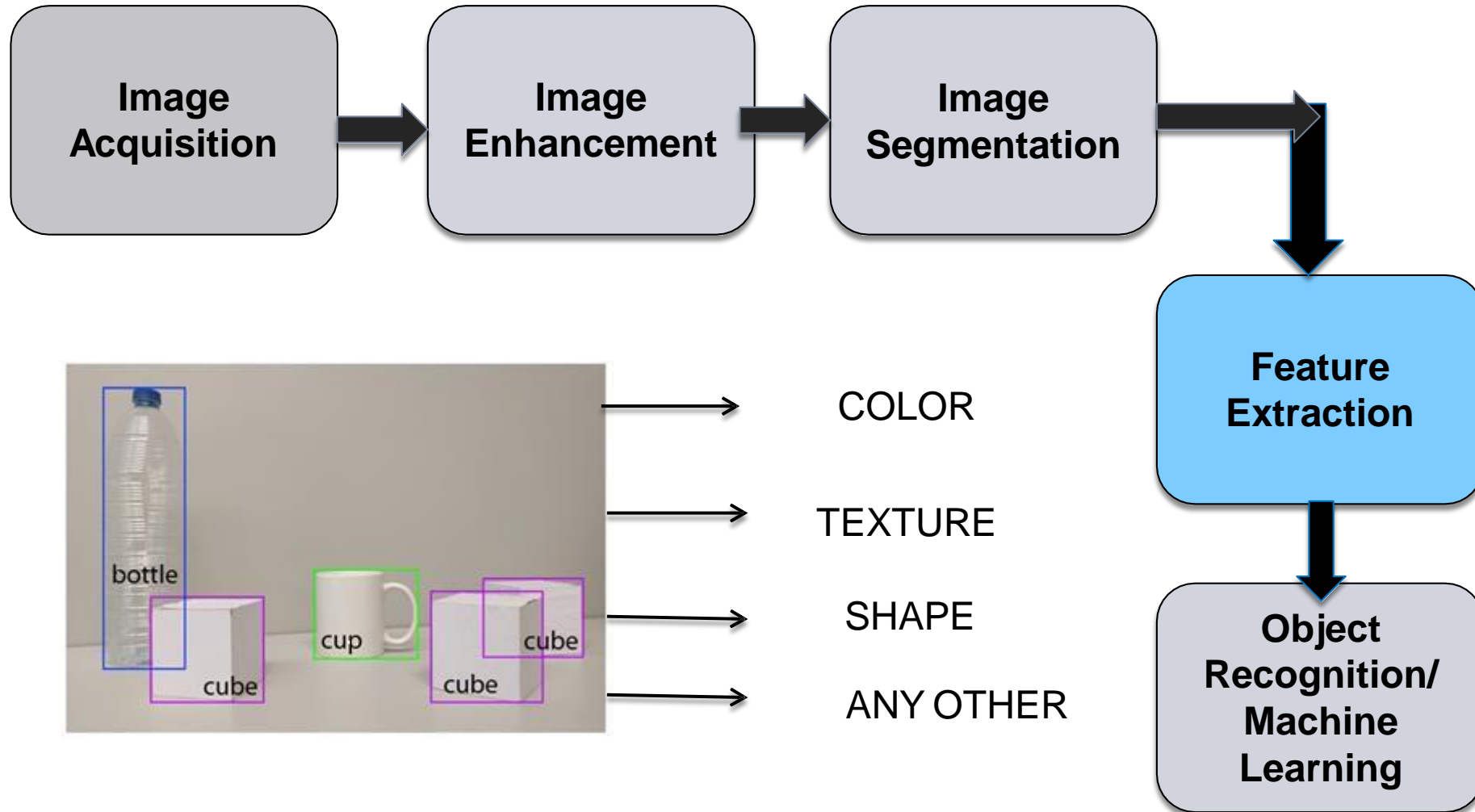
# KEY STEPS-IMAGE ANALYSIS



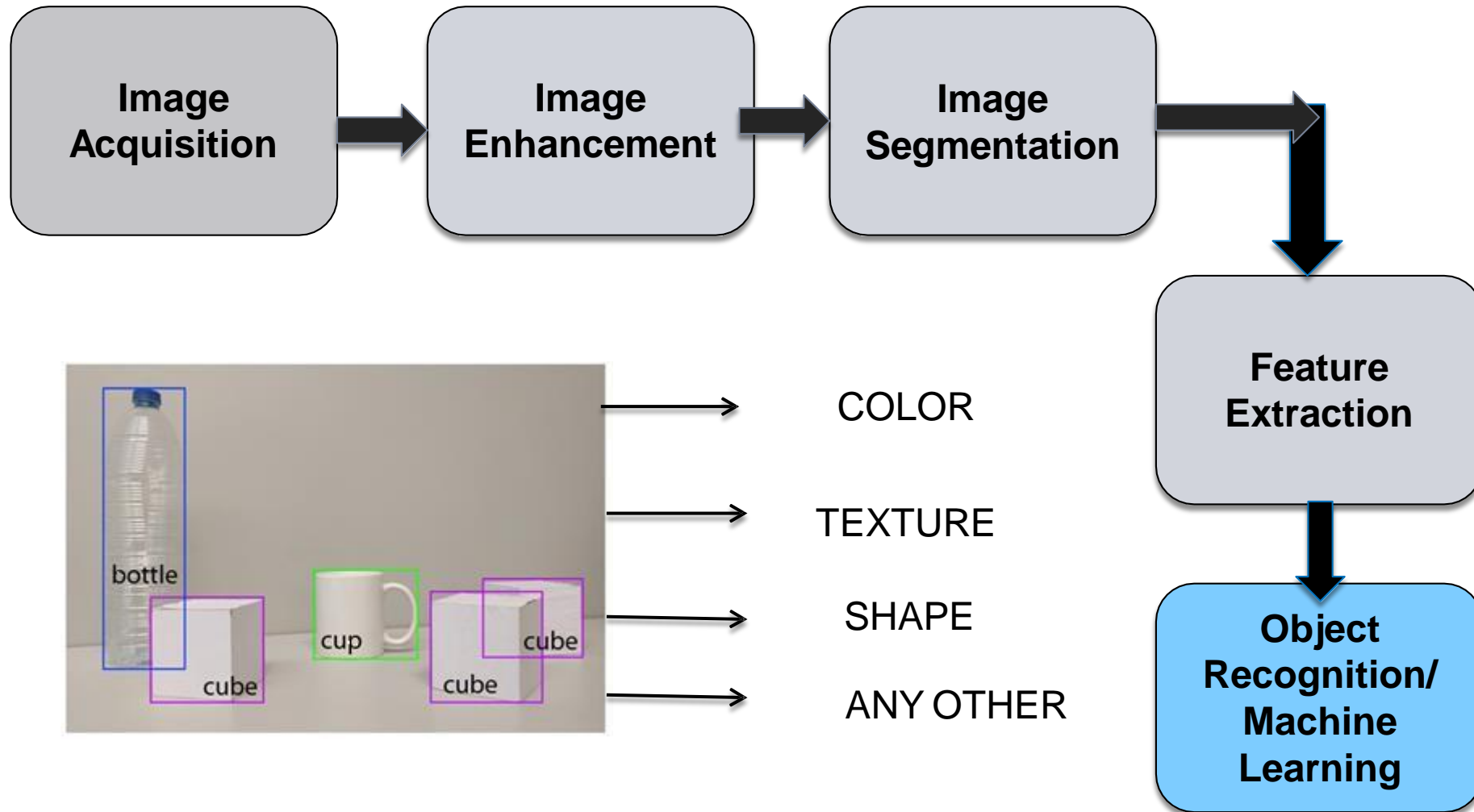
# KEY STEPS-IMAGE ANALYSIS



# KEY STEPS-IMAGE ANALYSIS

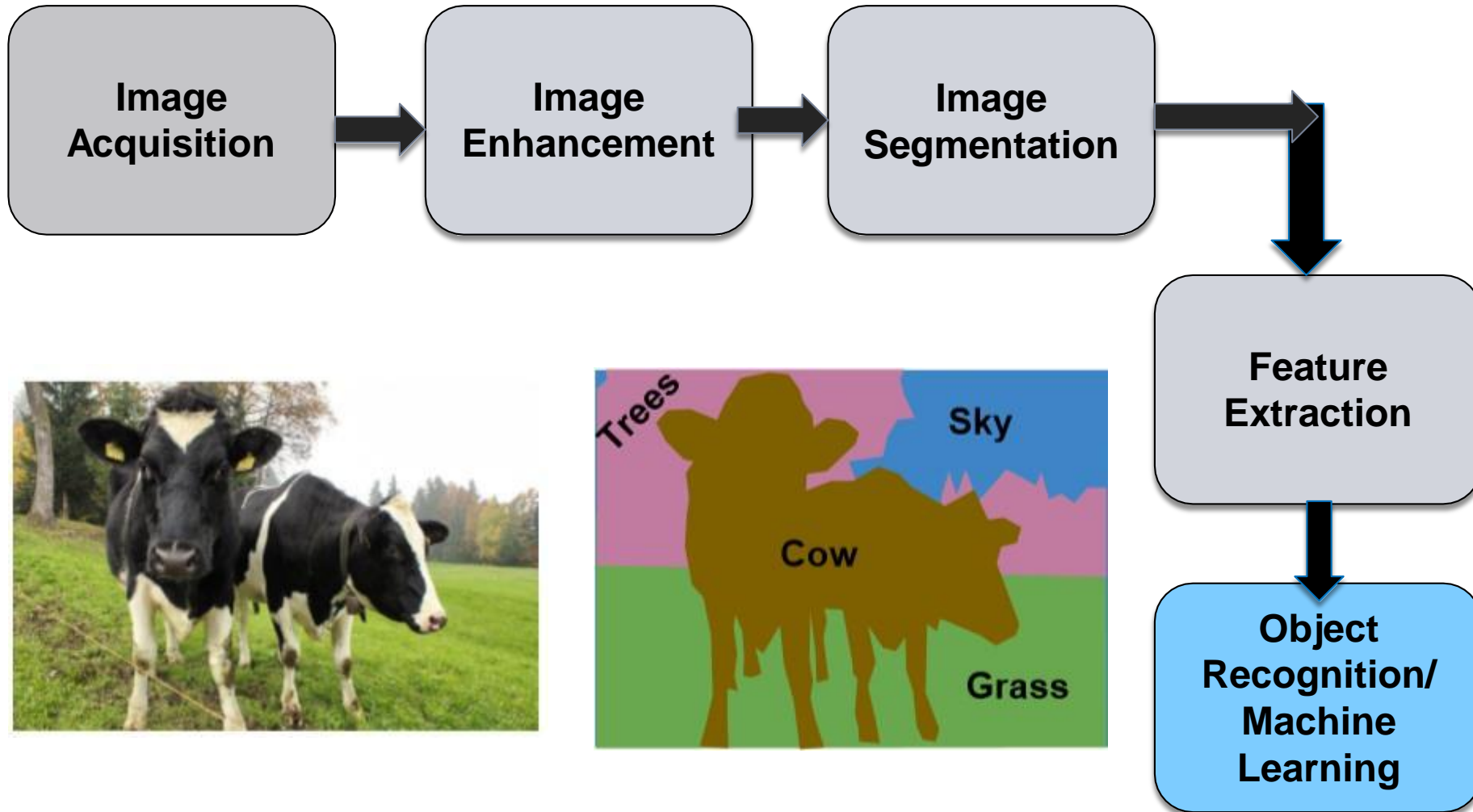


# KEY STEPS-IMAGE ANALYSIS

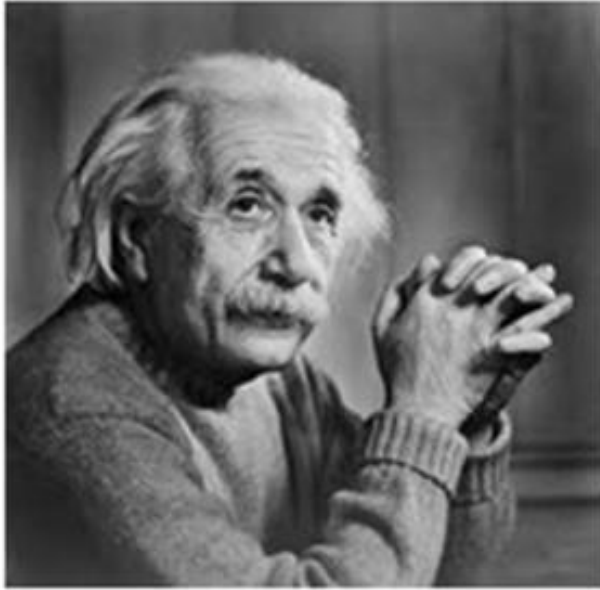




# KEY STEPS-IMAGE ANALYSIS



# Image Negative



- Spatial domain enhancement methods can be generalized as

$$\square g(x,y) = T[f(x,y)]$$

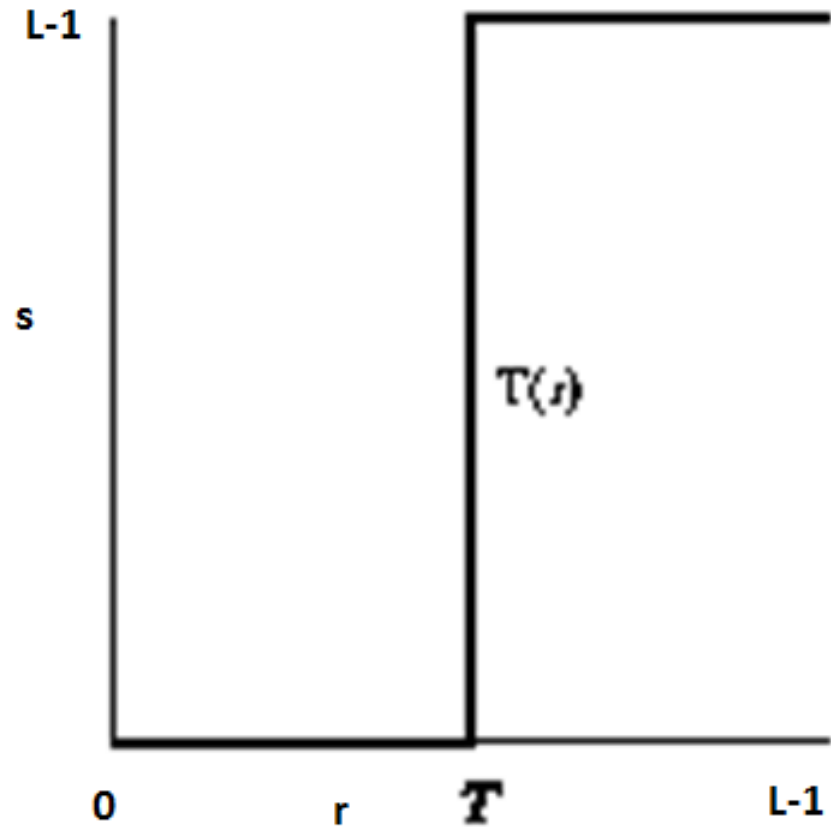
$f(x,y)$ : input image

$g(x,y)$ : processed (output) image

$T[*]$ : an operator on  $f$  (or a set of input images), defined over neighborhood of  $(x,y)$

Image Negative:  $s = L - 1 - r$

# Thresholding Function



## Thresholding Example



Original Image



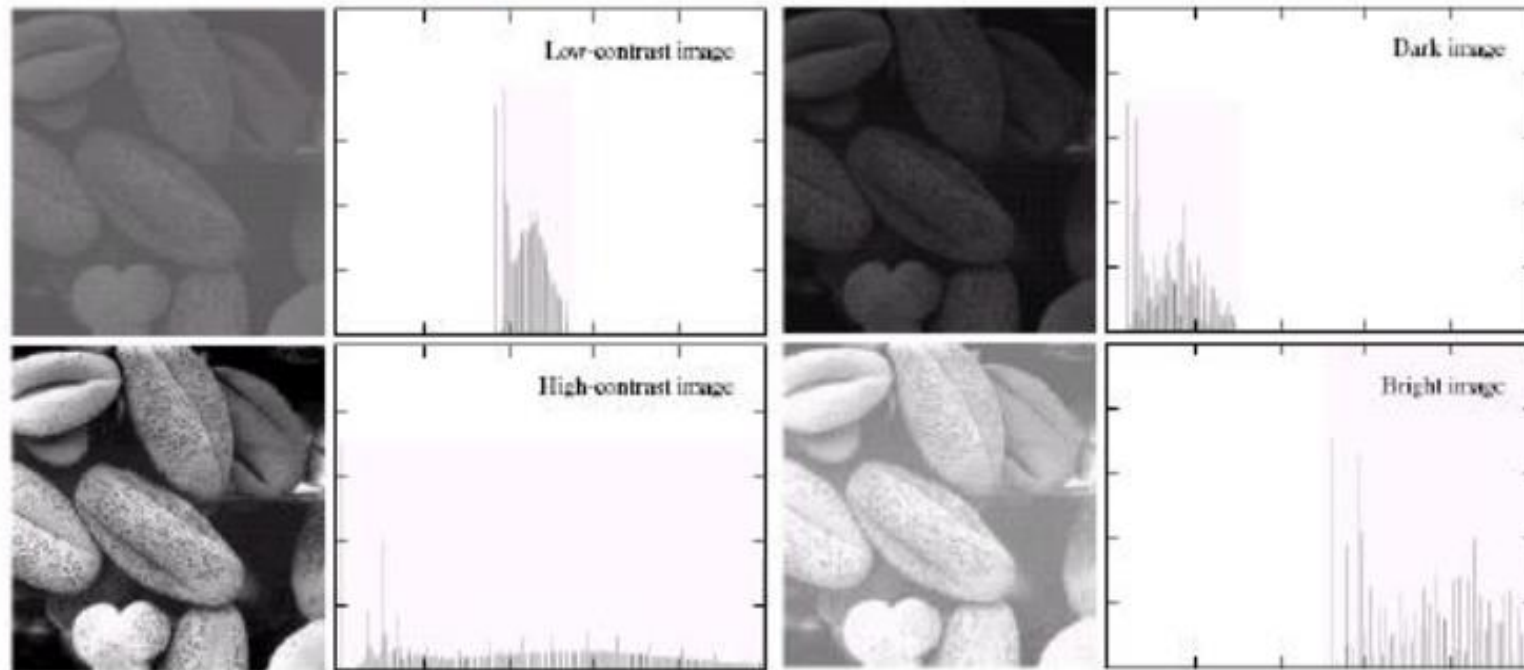
Thresholded Image

# Gama Correction



# Histogram : Example

- A selection of images and their Histograms
- Note that the high contrast image has the most evenly spaced histogram
- Histograms of low contrast images are located in certain portions and not in the entire gray scale range

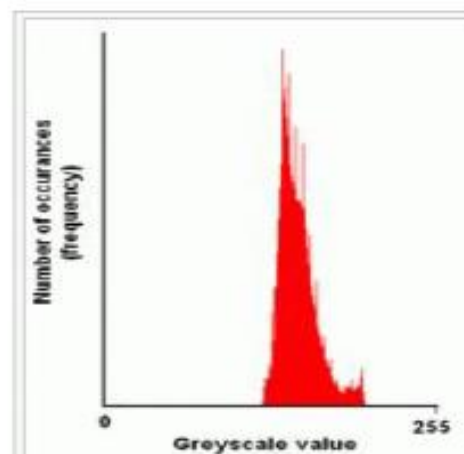




# Histogram Equalization: Example



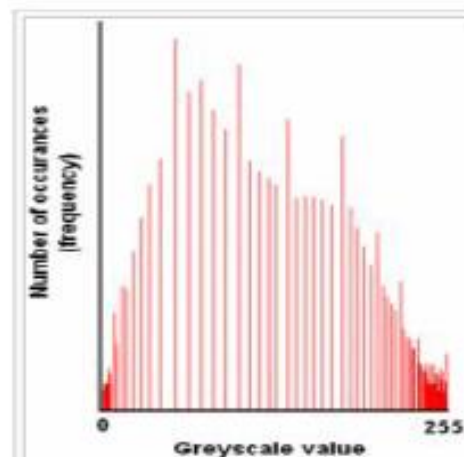
An unequalized image



Corresponding histogram



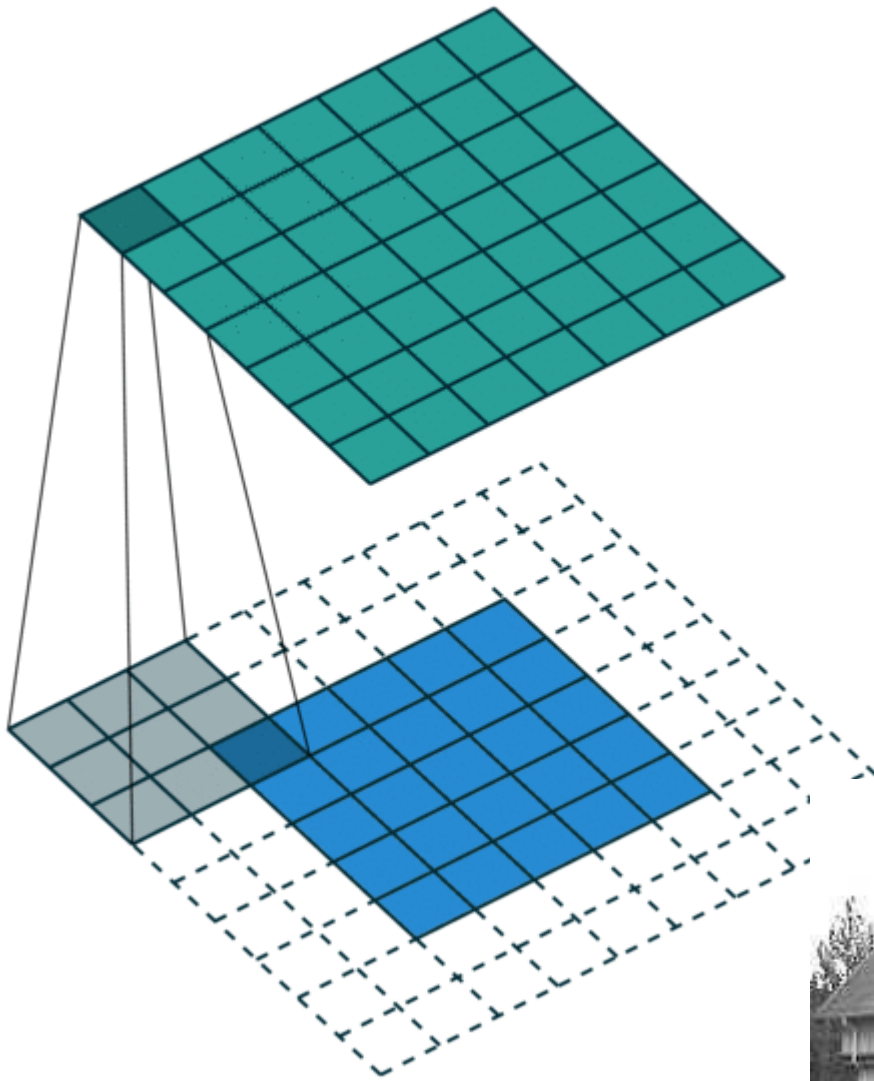
The same image after histogram equalization



Corresponding histogram



# Convolution operation in images



Image

100	100	200	200
100	100	200	200
100	100	200	200
100	100	200	200

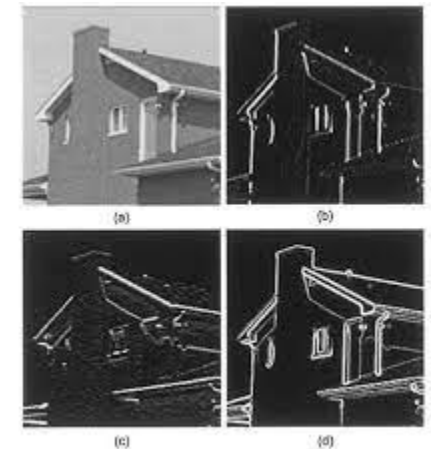
Kernel/Filter

-1	0	1
-2	0	2
-1	0	1

-100
-200
-100
200
400
<u>+200</u>
=400



Edge detection using sobel operator



# Smoothing Spatial Filters

- One of the simplest **spatial filtering** operations we can perform is a smoothing operation
  - Simply **average** all of the pixels in a neighbourhood around a central value
  - Especially useful in removing noise from images

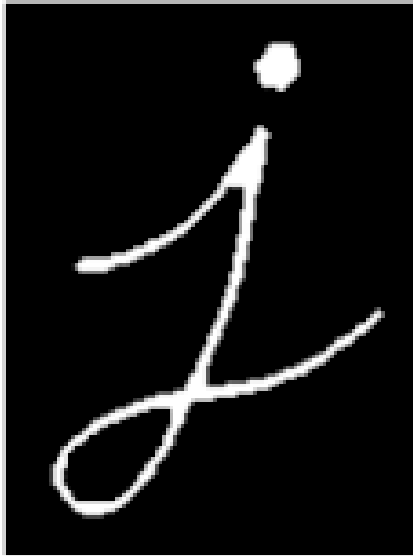
$1/9$	$1/9$	$1/9$
$1/9$	$1/9$	$1/9$
$1/9$	$1/9$	$1/9$

or

$\frac{1}{9} \times$	1	1	1
	1	1	1
	1	1	1

**Simple Averaging Filter**

# Image Preprocessing- Erosion and dilation



erosion



original



dilation

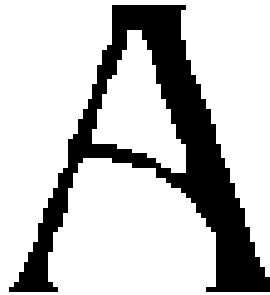
字母“j”:(左) 侵蚀, (中) 原始图像, (右) 扩张

# Erosion Example 1

**Watch out:** In these examples a 1 refers to a black pixel!



Original image



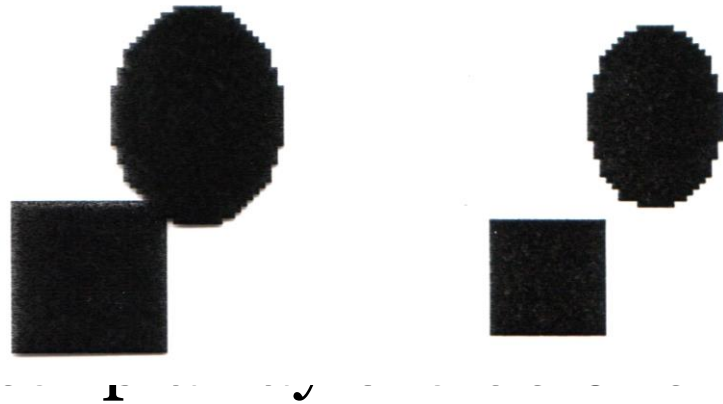
Erosion by 3\*3  
square structuring  
element



Erosion by 5\*5  
square structuring  
element

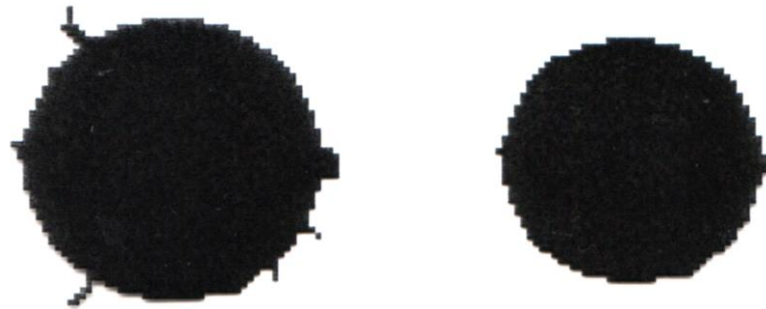
# What Is Erosion For?

Erosion can split apart joined objects



Erosion can

**Watch out:**





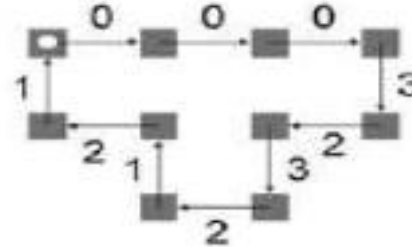
# Feature Extraction and Classification



# Feature Extraction- Hand Crafted

- Chaincode (shape)
- Fourier Descriptors (shape)
- Harris Corner Detection
- Gray Level Co-Occurrence Matrix (GLCM)- texture
- Histogram of Oriented Gradients (HOG)- shape
- Moment based feature ( shape)
- Haar Cascades
- Color features- color spaces
- Scale-Invariant Feature Transform (SIFT)- keypoint based
- Speeded Up Robust Feature (SURF)- keypoint
- Lot more.....

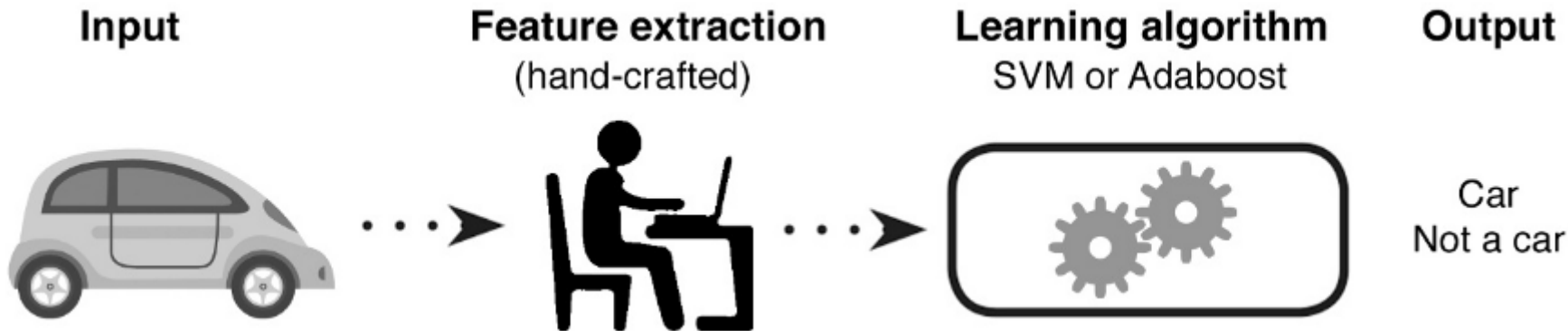
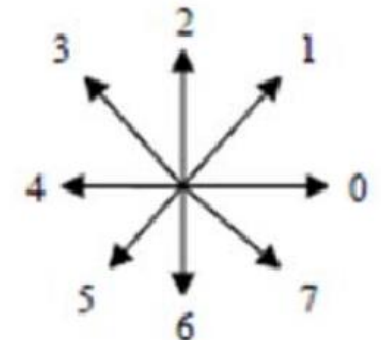
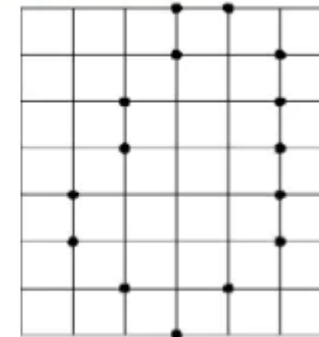
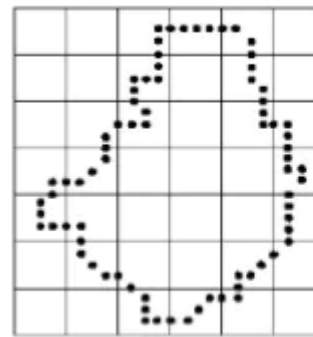
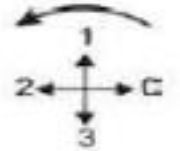
## A simple example –chain code



Chain code: 0 0 0 3 2 3 2 1 2 1

First difference: 3 0 0 3 3 1 3 3 1 3

Shape number: 0 0 3 3 1 3 3 1 3 3

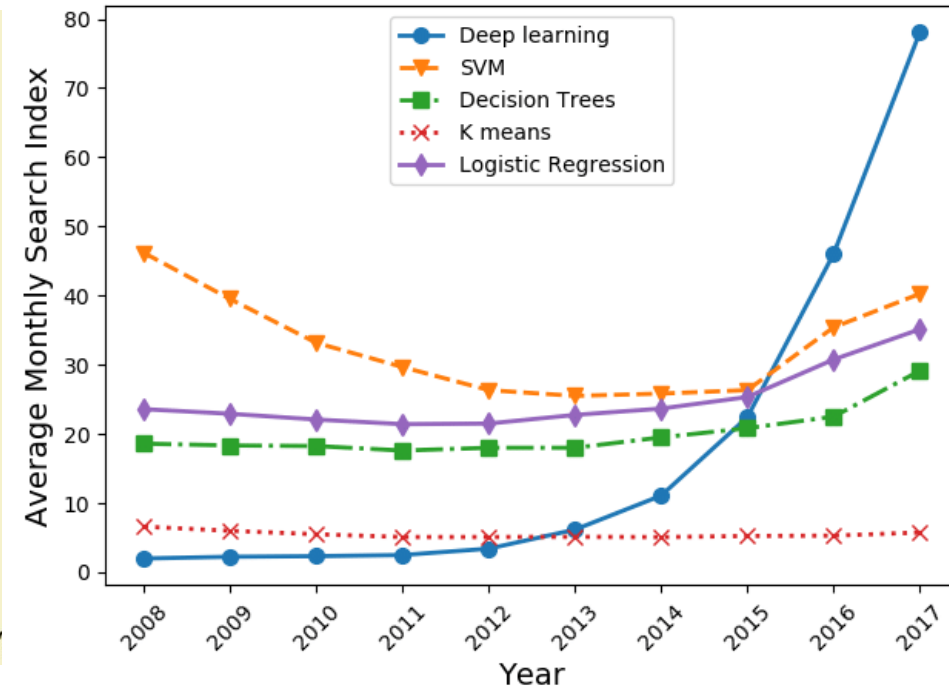
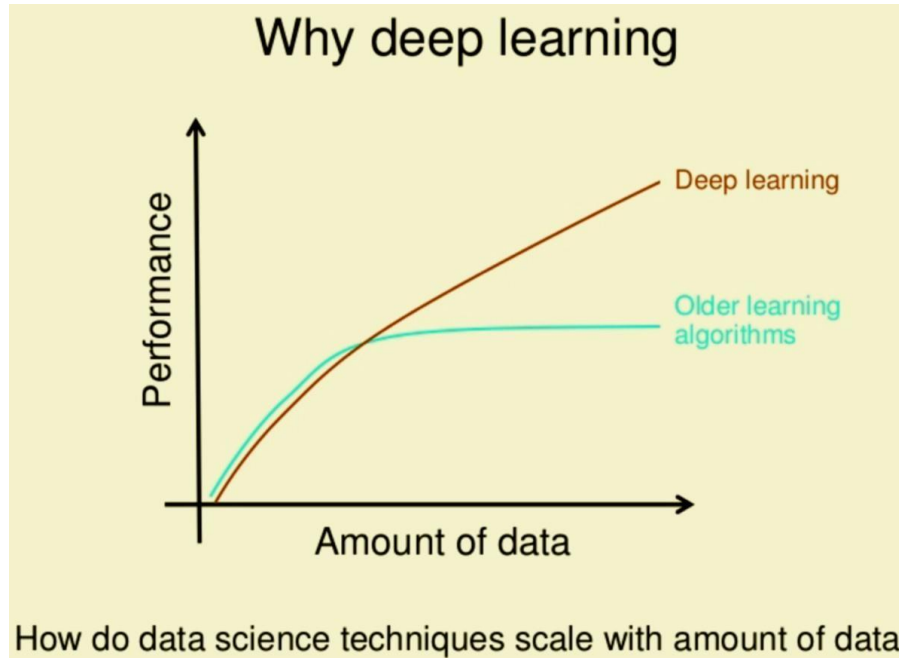




## **Deep Learning- A breakthrough**

**Given the Availability of Data, Deep Learning performance has surpassed all traditional algorithms**

# Artificial Intelligence Paradigmshift!- Machine Learning and Deep Learning?



**Promising results if trained with lot of data!**

Thank you