Pe	C	1	2	3	4	5	6	7	8	9	0	1	2	3	4	5	6	7
0		F	D		M													
4																		
8																		
С																		
10																		
14																		
18																		
10																		
20																		
24																		
		1									1	I		1	1			
Po	<b>C</b> 1	F			D			E		M			W					
0		1			2			3		4			5					
4																		
8																		
С																		
10	0																	
14	4																	
18	8																	
10	С																	
20	0																	
24	4																	
				_			_	T_	_		1_				Ι.	L		
Pe		1	2	3	4	5	6	7	8	9	0	1	2	3	4	5	6	7
0								-										
4																		
8								-										
С								-										
10																		
14								-										
18								-										
10																		
20																		
24	4																	

PC	F	D	E	M	W	
0						
4						
8						
С						
10						
14						
18						
1c						
20						

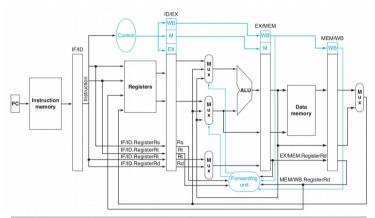


FIGURE 4.56 The datapath modified to resolve hazards via forwarding. Compared with the datapath in Figure 4.51, the additions are the multiplexors to the inputs to the ALU. This figure is a more stylized drawing, however, leaving out details from the full datapath, such as the branch hardware and the sign extension hardware.

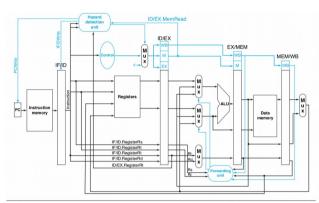
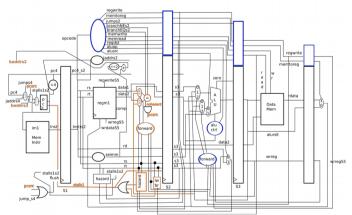
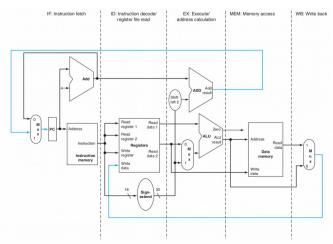


FIGURE 4.60 Pipelined control overview, showing the two multiplexors for forwarding, the hazard detection unit, and the forwarding unit. Although the D and EX stages have been simplified—the sign-extended immediate and branch logic are missing—this drawing the sense of the forwarding hazard requirements.





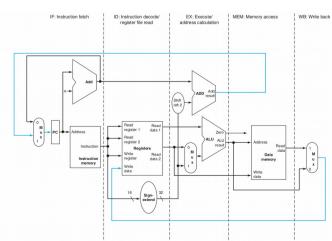


FIGURE 4.33 The single-cycle datapath from Section 4.4 (similar to Figure 4.17). Each step of the instruction can be mapped onto