Programming Assignment - 3

Name:

```
In [1]:
#Import required packages here
import numpy as np
```

Question 1

Use the Gaussian elimination with scaled row-partial pivoting code to answer the following.

```
## Gaussian Elimination: Scaled Row Pivoting
## This function is based on the pseudo-code on page-148 in the Text by Kincaid and Cheney
def GE rsp(A):
    (r,r,r)
   This function returns the P'LU factorization of a square matrix A
   by scaled row partial pivoting.
    In place of returning L and U, elements of modified A are used to hold values of L and U.
   m,n = A.shape
   L = np.eye(n) # Not being used
   U = np.zeros like(A) # Not being used
   if m !=n:
       sys.exit("This function needs a square matrix as an input.")
    # The initial ordering of rows
   p = list(range(n))
    # Scaling vector: absolute maximum elements of each row
   s = np.max(np.abs(A), axis=1)
   print("Scaling Vector: ",s)
    \# Start the k-1 passes of Guassian Elimination on A
   for k in range (n-1):
        print("\n PASS {}: \n".format(k+1), A)
        # Find the pivot element and interchange the rows
        pivot index = k + np.argmax(np.abs(A[p[k:], k])/s[p[k:]])
        # Interchange element in the permutation vector
        if pivot index !=k:
           temp = p[k]
           p[k]=p[pivot index]
           p[pivot index] = temp
           print("permutation vector: ",p)
        print("\n Pivot Element: {0:.2f} \n".format(A[p[k],k]))
        if np.abs(A[p[k],k]) < 10**(-20):
             sys.exit("ERROR!! Provided matrix is non-singular.")
        \# For the k-th pivot row Perform the Gaussian elimination on the following rows
        for i in range(k+1, n):
           # Find the multiplier
           z = A[p[i],k]/A[p[k],k]
           #Save z in A itself. You can save this in L also
           A[p[i],k] = z
            #Flimination operation. Changes all elements in a row simultaneously
```

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##
              A[p[i], k+1:] -= z*A[p[k], k+1:]
    return A, p
## Example on page number 146 (Kincaid Cheney).
## Example solved manually in class
A = np.array([[2, 3, -6], [1, -6, 8], [3, -2, 1]], dtype=float)
print("\n Given A: \n ",A)
A,p = GE rsp(A)
print("\n After Gaussian Elimination with RSPP: \n", A)
print("\n The permutation Vector is: \n", p)
   [[ 2. 3. -6.]
  [ 1. -6. 8.]
[ 3. -2. 1.]]
 Scaling Vector: [6. 8. 3.]
  PASS 1:
  [[ 2. 3. -6.]
  [ 1. -6. 8.]
  [ 3. -2. 1.]]
 permutation vector: [2, 1, 0]
  Pivot Element: 3.00
  PASS 2:
  [[ 0.66666667 4.33333333 -6.66666667]
  [ 0.33333333 -5.33333333 7.66666667]
  [ 3. -2. 1.
 permutation vector: [2, 0, 1]
  Pivot Element: 4.33
  After Gaussian Elimination with RSPP:
  [[ 0.66666667 4.33333333 -6.66666667]
```

(A) Modify this code to write a function that solves a linear system Ax =b. Test this in the case when b = [3,1,1]^T, and the matrix A = [1 6 0; 2 1 0; 0 2 1]. Only display the solution in the output.

```
In []:
# Your code come here
```

• (B) Modify this code to find the determinant of any square matrix A. Note that

[2, 0, 1]

$$PA = LU \Rightarrow \det A = \pm \det U.$$

The sign depends of the number of row-swaps in the elimination process. Use this code to find the determinant of any 10×10 matrix that you randomly generate. Compare your result with the built-in NumPy method.

```
In []:
#Your code comes here
```

• (C) Modify the system-solver that you have created to find the inverse of a square matrix. Use this code to display the inverse of A = [1 6 0; 2 1 0; 0 2 1].

```
In []:
# Your code comes here
```