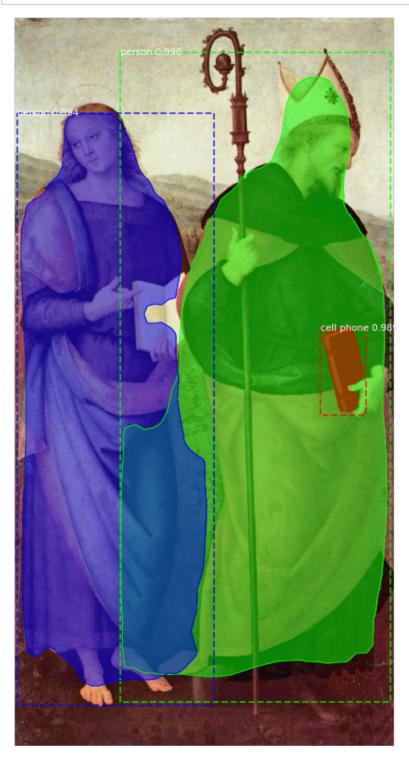
```
In [ ]: import os
           import sys
           import random
           import math
           import numpy as np
           import skimage.io
           import matplotlib
           import matplotlib.pyplot as plt
           import mrcnn.model as modellib
           sys.path.append(os.path.join("samples/coco/"))
           import coco
           from mrcnn import utils
           from mrcnn import visualize
           %matplotlib inline
           # Directory to save logs and trained model
           MODEL_DIR = os.path.join("logs")
           # Local path to trained weights file
           COCO_MODEL_PATH = os.path.join("mask_rcnn_coco.h5")
           # Download COCO trained weights from Releases if needed
           if not os.path.exists(COCO MODEL PATH):
                 utils.download_trained_weights(COCO_MODEL_PATH)
           # Directory of images to run detection on
           IMAGE_DIR = os.path.join("images_examp")
In [2]: class InferenceConfig(coco.CocoConfig):
                 # Set batch size to 1 since we'll be running inference on
                 # one image at a time. Batch size = GPU_COUNT * IMAGES_PER_GPU
                 GPU COUNT = 1
                 IMAGES PER GPU = 1
           config = InferenceConfig()
In [ ]: | # Create model object in inference mode.
           model = modellib.MaskRCNN(mode="inference", model_dir=MODEL_DIR, config=confi
           g)
           # Load weights trained on MS-COCO
           model.load_weights(COCO_MODEL_PATH, by_name=True)
In [4]: # COCO Class names
           # Index of the class in the list is its ID. For example, to get ID of
           # the teddy bear class, use: class_names.index('teddy bear')
           classes = ['BG', 'person', 'bicycle', 'car', 'motorcycle', 'airplane',
                                'bus', 'train', 'truck', 'boat', 'traffic light',
'fire hydrant', 'stop sign', 'parking meter', 'bench', 'bird',
'cat', 'dog', 'horse', 'sheep', 'cow', 'elephant', 'bear',
'zebra', 'giraffe', 'backpack', 'umbrella', 'handbag', 'tie',
'suitcase', 'frisbee', 'skis', 'snowboard', 'sports ball',
'kite', 'baseball bat', 'baseball glove', 'skateboard',
                                'surfboard', 'tennis racket', 'bottle', 'wine glass', 'cup',
                                'fork', 'knife', 'spoon', 'bowl', 'banana', 'apple',
'sandwich', 'orange', 'broccoli', 'carrot', 'hot dog', 'pizza',
'doughnut', 'cake', 'chair', 'couch', 'pot plant', 'bed',
'dining table', 'toilet', 'tv', 'laptop', 'mouse', 'remote',
'keyboard', 'cell phone', 'microwave', 'oven', 'toaster',
'sink', 'refrigerator', 'book', 'clock', 'vase', 'scissors',
                                'teddy bear', 'hair drier', 'toothbrush']
```



probs shape: (1, 1000, 81) min: 0.00000 max: 1.00000 float32

INFO: Time-matrix loaded correctly

INFO: Class person . No need to apply time-matrix

INFO: Class person . No need to apply time-matrix

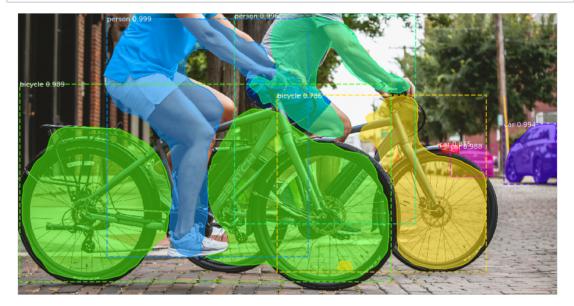
INFO: Matrix of possible classes for class cell phone

Name Prob

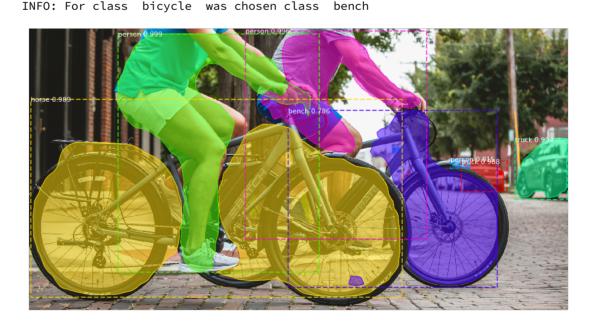
2 remote 0.004145 1 bottle 0.003263 0 book 0.001450

INFO: For class cell phone was chosen class book





```
In [20]: century=14
         res_time=model.time_matrix_application(image,century,classes)
         visualize.display_instances(image, res_time['rois'], res_time['masks'], res_ti
         me['class_ids'],
                                    classes, res_time['scores'])
         probs
                                  shape: (1, 1000, 81)
                                                                       0.00000 max:
                                                               min:
         0.99999 float32
         INFO: Time-matrix loaded correctly
         INFO: Class person . No need to apply time-matrix
         INFO: Class person . No need to apply time-matrix
         INFO: Matrix of possible classes for class car
                  Name
                            Prob
           truck 0.012431
motorcycle 0.003825
person 0.000885
         2
                   bus 0.000112
         0
         INFO: For class car was chosen class truck
         INFO: Matrix of possible classes for class bicycle
                  Name
                            Prob
            motorcycle 0.021593
         2
                 horse 0.010329
                 bench 0.009906
         0
                 chair 0.004155
         1
         INFO: For class bicycle was chosen class horse
         INFO: Matrix of possible classes for class car
                  Name
                           Prob
                 truck 0.012431
         1 motorcycle 0.003825
                person 0.000885
         2
                  bus 0.000112
         INFO: For class car was chosen class truck
         INFO: Matrix of possible classes for class car
                  Name
                         Prob
         1 motorcycle 0.003825
                person 0.000885
         2
                   bus 0.000112
         0
         INFO: For class car was chosen class person
         INFO: Matrix of possible classes for class bicycle
                  Name
                            Prob
           motorcycle 0.021593
                 bench 0.009906
         0
                 chair 0.004155
         1
```



```
In [168]: from shapely.geometry import Polygon
          import heapq
          def overlap_detection(rect1, rect2):
                  p1 = Polygon([(rect1[0],rect1[1]), (rect1[1],rect1[1]),(rect1[2],rect1
          [3]),(rect1[2],rect1[1])])
                  p2 = Polygon([(rect2[0],rect2[1]), (rect2[1],rect2[1]),(rect2[2],rect2
          [3]),(rect2[2],rect2[1])])
                  return(p1.intersects(p2))
              except:
                  return True
          def time_matrix_application(img,century):
              detection = model.detect([image],verbose=0)
              # Visualize results
              r = detection[0]
              mrcnn = model.run_graph([img], [("probs", model.keras_model.get_layer("mrc
          nn_class").output)])
              time_matrix=pd.read_csv("time_matrix.csv")
              print("INFO: Time-matrix loaded correctly")
              final_prob=pd.DataFrame()
              for i in mrcnn['probs'][0]:
                  prob=pd.DataFrame()
                  prob_data=[]
                  for j in i:
                      prob_data.append("{:.12f}".format(float(j)))
                  prob["Name"]=class_names
                  prob["Prob"]=prob_data
                  final_prob=pd.concat([final_prob,prob],axis=0, ignore_index=True)
              final_prob["Prob"]=final_prob["Prob"].astype(float)
              for object_id in range(0,len(r["class_ids"])):
                  object_time=time_matrix[time_matrix["Item"]==class_names[r["class_id
          s"][object_id]]]
                  #print(object_time)
                  if object_time.reset_index().loc[0,"Cent"]>century:
                      d_object=class_names[r["class_ids"][object_id]]
                      middle_prop=pd.DataFrame(columns=["Name","Prob"])
                      for i in range(0,len(final_prob),81):
                          probs=[]
                          for j in range(i,i+81):
                               # print(prob.loc[j,"Prob"])
                               probs.append(final_prob.loc[j,"Prob"])
                          #print(probs)
                          items=heapq.nlargest(4, range(len(probs)), key=probs.__getitem
          __)
                          if class_names[items[0]]==d_object:
                               for it in range(1,len(items)):
                                   if items[it] not in r["class_ids"]:
                                       middle_prop.loc[len(middle_prop)]=[class_names[ite
          ms[it]], probs[items[it]]]
                                       position=np.where(r["class_ids"]==items[it])[0]
                                       #print(position)
                                       overlap_flag=False
                                       for pos in position:
                                           if overlap_detection(r["rois"][pos],r["roi
          s"][object_id])==True:
                                               overlap_flag=True
                                               #print(pos)
                                       if overlap_flag==False:
                                           middle_prop.loc[len(middle_prop)]=[class_names
          [items[it]], probs[items[it]]]
                      middle_prop=middle_prop[middle_prop["Name"]!="BG"]
                      print("INFO: Matrix of possible classes for class ",d_object)
                      print(middle_prop.groupby("Name", as_index=False).mean().sort_valu
          es(by=["Prob"],ascending=False))
                      position_obj=0
```