

**Game def:** goals, rules, feedback, voluntary participation

## **MDA**

First order design: rules, mechanics, systems

Second order: player experiences (aesthetics) by manipulating mechanics/dyn

- ex: 1st=puzzle piece rotation mechanic
- 2nd=players feel accomplished when solving puzzle

Goal of MDA: Bridge game design and game analysis

**Mechanic:** basic rule or action available to the player (rules and systems of the game)

- ex: press A to jump, hold B to run

**Dynamic:** behavior of the system during gameplay (game in motion). Actions taken by players that arise from engaging with the game's mechanics

- ex: chess.
- Mech=pieces have specific movement rules
- Dynamics=strategic interactions between players emerge as they plan moves. Sacrifice pieces, and adapt to their opponent.
- Aesthetics=challenge, competition

**Aesthetics:** emotional responses define the feel of a game; mech + dyn = aesthetics

## **Approaches to game design**

1) mechanics-first: paraglider in an obstacle course vs narrative adventure

2) aesthetics-first: designing for exploration, storytelling, or player expression

## **Aesthetics**

1. Sensation: immersive sensory experience, memorable AV fx (just dance)
2. Fantasy: role-playing/cosplaying and imagining alternate lives (FIFA)
3. Narrative: drama, immersion, world-building (Skyrim)
4. Challenge: overcoming obstacles (super meat boy)
5. Fellowship: social interaction and cooperation (among us)
6. Discovery: exploring, finding, learning (Minecraft)
7. Expression: customization, user-generated content (the sims)
8. Abnegation (submission): passing time, losing oneself (powerwash simulator)
9. Competition: dominance over others (smash)

## **Analyzing menus and controls**

Menus reveal design priorities and what the developers consider important.

Frequently used actions are often mapped to the most accessible buttons.

Adjustable settings reflect design choices and compromises.

## **First Order Optimal Strategies**

- strategies that give high power with low effort
- Players naturally exploit these strays unless forced to evolve
- Competitive games encourage skill development beyond FOOS

## **Street Fighter II**

- crouch block defensive strategy created a low-risk playstyle that frustrated aggressive opponents
- Fixed with chip damage and grab moves

## **Breakpoints in games**

Identify where games fail to function as intended

2 types of breakpoints:

- systemic - unintended interactions that exploit game mechs (infinite money glitch)
- Technical - bugs that affect gameplay (clipping, camera issues)

## **Fullerton's Ludicrous structure of games**

Players - relationship between players and the game

Objectives - goals, both designer-driven and-driven

Procedures - actions of play, limited by rules

Rules - define game params, part of the "magic circle"

Resources - valuable objects as defined by rules

Conflict - hindrances to objective

Boundaries - limits of the game world

Outcome - uncertainty toward an ultimate goal

## **Wizards of the coast profiles**

1. Tammy/timmy - seeks excitement and big, memorable moments. Enjoys flashy, powerful plays
2. Jenny/johnny - prefers creativity and self-expression. Enjoys winning with style and unique strategies
3. Spike - focuses on winning at all costs. Enjoys competition and optimization
4. Melanie/melvin - engages with game mechanics deeply. Enjoys understanding and exploiting intricate systems.
5. Vorthos - values theme and storytelling. Enjoys immersive worlds and rich narratives.

## **Bartle's 4 types of online games**

Achiever - overcome challenges, gather rewards

Explorer - discover, understand game worlds

Socializer - interact and roleplay

Griefer - distress other players in the game

## **Formal elements**

Elements easy to define early (players, primary objectives, outcomes, boundaries)

## **Player interaction patterns**

- Single player v game (Solitaire)
- Player vs player (chess)
- Multiple players vs game (bingo)
- Unilateral competition (Scotland Yard- 1 v all)
- Multilateral competition (monopoly)
- Cooperative play (overcooked)
- Team competition (team v team)

## **Procedures and rules**

Procedures - actions that players can take to achieve their objectives

Rules - define the game constraints and set limits on the player procedures

## **Resources**

Elements of the game that hold some value and have some notion of scarcity (lives, health, time, currency, ammo)

## **Conflict**

Not only pvp, also pvg

- hard enough to promote player interest and play, easy enough that goal is eventually reachable

## **Boundaries**

Can be defined by rules, but also by the nature in which the game is being played

Types of boundaries

- physical (edges of map)
- Conceptual (defined by the game's rules and mechanics)
- temporal (time-based constraints on when the game begins/ends)
- Psychological (everyone agrees to enter the "magic circle")
- Social (multiplayer interactions and social norms)

**Outcome:** must be a finish of some kind, uncertain while game is played

## **Objectives**

- anything the player is striving for
- Primary - main objective of game
- Secondary - achievements, high score, etc
- Player driven - self-created goal

## **Categories**

Capture - take or destroy something

Race - race against something

Alignment - perfect positioning

Rescue/escape - get out of dungeon

Forbidden act - get someone to break rules

Construction - build something

Exploration - uncover all hidden things

## **Event-driven programming**

Paradigm where program behavior is triggered by events like user actions or system signals

- works well with desktop apps, mobile apps, web apps

## **Events in games: button press, character collision, timer countdown**

Video games are not entirely event-driven, things are updated continuously

- structure around a game loop
- For every frame of animation on the screen the game must update and draw the game state

**Update:** receive player input, process player actions, process NPC actions, Post-process (physics)

**Draw:** cull non-visible objects, transform visible objects, draw to backing buffer, display backing buffer

**Game state:** comprised of the current values of all variables for all objects in the game world at that precise moment. Snapshot of the game

**Game loop:** update= get all input from the user, making calls based on rules/procedures/actions, changing all the values in the world that need to change.

## **Draw=put new game state onto screen**

Step 1: Player input

Typically polled during game loop, but can only read input once per game loop cycle

Step 2: process actions

Collision? New object created? Add to current game state

Step 3: process NPCs

Anything that has agency in the world that isn't you. Sense-plan-act: what can it see?

How smart? Computer can move things perfectly, do we want that?

Step 4: process the world

Physics, lighting, networking, etc

Step 5: prepare to draw

Only draw what is actually on screen

Step 6: pre-draw to buffer

Video cards/drivers have robust buffering. Draw all the pixels of the frame to a temporary buffer. When buffer is full/ready, swap it with the current frame on screen. Reduces screen tearing

Step 7: swap buffer to screen

This step is rarely done by a game designer with a modern game engine

## **Procedures and rules**

Procedures - actions that players can take to achieve their objectives

Rules - define the game objects and set

Ex: chess - procedure: the player can move the knight.

rules: knight must move in L-shape, must be player's turn

Procedures map to the input device you are using

Controller complexity

- complex control schemes can overwhelm new players, but appeal to experienced ones

## **Actions vs interactions**

Action - procedure that is mapped to a control input: jump, move

Interaction - outcome of the game state, may not be the result of a direct action from the player. Can happen without any input.

Collisions, Line of sight, resource change

Game mechanic - relationship and combination of any number of actions and interactions

Each relationship/combination could be considered a separate rule in the game world

Ex: Super Mario. Actions = run left and right, jump

interactions = collision with opponent

rule = if collision is on top of enemy, enemy changes state according to rule set, otherwise take damage according to rule set

## **Designing actions**

- verbs; enough to avoid being too simple, too many clutter

• Primary = things you must do to overcome obstacles and complete the objective - core of the gameplay loop. Need to feel perfect

• Secondary - enhance gameplay but I red to complete the core objective

• Avoid using verb proxies (use an item = what does it do?). Use outcome-oriented verbs

## Emergent behavior

When simple mechanics combine to create complex or surprising gameplay that wasn't explicitly programmed (arrow + fire)

## Interactions

Specifically NOT the direct action of a player. Outcome of the game state. Can happen without player input. (Collisions)

## Procedures vs rules

Rules are formal schemas. In general, 3 types of rules:

- Operational: English rules of a game as the player understands it  
"in Mario, you can run and jump and land on top of goombas and they die" .. very high level
- Constitutive: underlying math and logic behind operational rules  
goomba dies only if the bottom of the Mario's sprite collides with the top of the goombas sprite
- Implicit: extra rules understood by the players to make the game move forward  
agreed upon rules of a game that are not part of the formal rule set but are important to make the game work (time limit)

## Designing good rules

- should lead players to interesting choices. Players must be able to make decisions and system must respond and give feedback.
- Bad rules: pure luck based, lack of interaction, doesn't relate to goal

## Mechanics vs rules

Mechanics are created by game designers in the framework of rules. Dynamics are created by players as interpretations of mechanics within the rules. Rules are the formal implementation of the game world.

## Depth vs complexity

Depth=amount of meaningful choices that come from the gameplay experience

Complexity = cognitive load of the player

Goal is high depth with low complexity

## Graphics vs visual design

You need to have the right graphics, not the best

## Sprites

Abstraction of all graphical content

Common sprite components: image/texture, position, animation frames, collision geometry, additional game-specific data

## Sprites and sprite sheets

Asset management is important for any game. It's impractical to save every single frame of animation in a separate file. A sprite sheet is a single image, broken up in a regular pattern where all the images needed for animation are stored.

## Animation

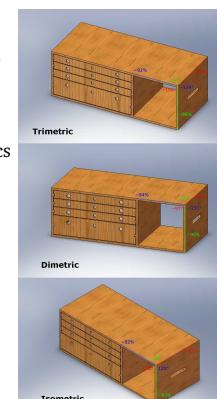
sprite sheet is split into frames and then sets of frames are assigned to various actions

## Drawing sprites

Draw back to front to create proper layering of objects. 3. Ordinate systems at the same time: screen, world, object

## Scrolling

- What moves? Sprite, camera, world? Each uses diff coord math.
- Offscreen objects: drawing them? The engine won't display them but they still consume resources. Every frame position updates, physics checks still happen.
- impact on game loop: managing and updating offscreen objects is extra work. Optimize how you create/destroy objects



## Parallax scrolling

Multiple layers of background, scrolling at different speeds to give the illusion of depth

## Types of cameras - orthographic

- perpendicular to the plane of the game
- Fixed along one axis: Z=top down, Y=side scroll, X=vertical scroll
- Handy for artists: art is done as tiles and easy to manage
- Forces 2D gameplay on,y.

## Axonometric

- off axis view, allows for some 3D gameplay.  
Isometric is most common form (all axes equal).  
Can have other forms by shortening/lengthening some axes for artistic reasons.

## Trimetric, dimetric, isometric cameras

### Raycasting (swept collision detection)

Predict future collisions. Extend hitbox along movement path, sphere becomes capsule for detection. Move to impact point, resolve collision, continue

### Problems with raycasting

Issue with networked games: future predicts rely on exact state of world at present time. Due to packet latency , current state not always coherent. Assumes constant velocity and zero acceleration over simulation step. Has implications for physics model and choice of integrator

### Determining hit box collisions

Collision detection complexity - worst case is  $O(n^2)$  checking every object against every other.

Optimizations for speed: sort objects in one dimension (bucket sort)

- use temporal coherence (track nearby object pairs)
- Estimate likely collisions based in speed
- Use simpler, cheaper tests first

## Kinematics vs dynamics

Kinematics = motion (position, velocity, acceleration). Games use Kinematics for control and predictability

Dynamics = forces (gravity, friction, collisions). Fake dynamics to make movement feel real

## Physical simulation in games

- Goal is believable physics. Good physics enhances gameplay and creates new dynamics. Game physics != real world physics
- role of physics: detect collisions, accumulate forces, numerical integration, enforce constraints

## Newton's laws in games

- objects stay in motion unless acted upon
- Force = mass x acceleration
- Every action has an equal and opposite reaction

Good physics feels natural and when not realistic

## Variables

$t_x$  = final time for the period we are examining

$t_0$  = initial time

$\Delta t$  = Change in time ( $t_x - t_0$ ) for period

$\Delta v$  = Change in velocity ( $v_x - v_0$ )

$\Delta a$  = Change in acceleration ( $a_x - a_0$ )

Change in Velocity

$$v_t = v_0 + \frac{F}{m} \Delta t \quad \text{or} \quad v_t = v_0 + a \Delta t, \text{ you choose } \Delta t$$

Velocity at a given time is the sum of initial velocity and change due to acceleration

$$\text{Change in Position : } p_t = p_0 + v_0 \Delta t + \frac{F}{2m} \Delta t^2$$

Position at a given time is the sum of initial position, position change due to initial velocity, position change due to acceleration

## Rigid body physics: more complexity

- Objects have mass and volume, not just position
- Center of mass determines movement
- forces can cause rotation (torque)
- More calcs needed for realistic physics

## Problem with time step physics

If delta t is too big: imprecise physics, no smooth trajectories

If delta t is too small: processor can't handle it

If everything happens in a single frame: all variables snap to next state

## What if there are no collisions?

Simpler calcs; pick your forces: gravity, air resistance, the force. Computer acceleration and velocity.

Update position, draw the next frame.

## Physics with collisions

Force directly changes acceleration. Bigger mass = bigger force. Force puts things in motion, but also can bring things to a halt.

## Momentum and impulse

Momentum (p) - the force that keeps an object moving:  $p = m \cdot v$

Impulse (delta p) - change in momentum. Delta  $p = F \cdot \Delta t$

## Law of conservation of momentum

Momentum is conserved in collisions. Total momentum before = total momentum after. Direction may change, but magnitude remains constant. Valid if no external forces act on the system.

Coefficient of restitution (COR) - measures an object's elasticity in collisions (how much an object regains its shape after. 0 = inelastic (no bounce, energy absorbed). 1 = elastic (perfect bounce, momentum conserved))

## Hitboxes

Goal is good enough precision. Use bounding boxes/spheres for faster checks. Can be layered for more precision. Hit box (attack zone) - deals damage. Hurtbox can be hit, collision/pushbox (physical space) - prevents overlap

## Bounding boxes

Axis aligned vs object aligned. Axis aligned bounding box change as object moves.

Spherical hitboxes - put everything in a bubble (cheap to detect)

Overlap testing - may cause minor errors (false positives/negatives). For each delta t, check if objects overlap. Optimizations reduce performance issues.

## Finding the moment of collision

Use sub-stepping to detect the exact moment of collision.

## Problems with overlap testing

What is delta t is too big? Fails with objects that move too fast. Unlikely to catch time slice during overlap. Possible solutions: design constraint on speed of objects, reduce simulation step size

## Cheaper distance tests

- avoid expensive quads root calcs. Compare  $d^2$  instead of sqrt. Use ,angsts. Distance for an approximate fast check ( $|x_1 - x_2| + |y_1 - y_2|$ )

## Achieving $O(n \log n)$ complexity: Plane sweep geometry

## Achieving $O(n)$ complexity: partition space algorithm

## Collision resolution

What do you do after you detect the collision? Rocket slams into wall: rocket disappears.

Explosion spawned na so suns effect, wall charred.

Resolution has prologue, collision, epilogue

Prologue: collision known to have occurred. Check if collision should be ignored. Other events might be triggered (sound,p fx, send collision notifs)

Collision: place objects at point of impact. Assign new velocities using physics or some other decision logic

Epilogue: propagate post collision fx. Possible fx: destroy one or both objects, play sound, inflict damage. Many effects can be done either in the prologue or epilogue.