

COMPSCI 201 MIDTERM 2 REFERENCE SHEET

Arrays

- `.asList()`, `.toArray()`, List to Array with loop

Strings

- `+=` concatenation $O(n)$ because immutable
- `StringBuilder.append()` = $O(1)$ per char; large capacity until overflow, geometric growth

ArrayList

- implements List with Array, by keeping an array with extra space at the end
 - Array out of space \rightarrow make one twice as large and copies old over
- `get()` = $O(1)$, `contains()` = $O(n)$, `size()` = $O(1)$
- `add()` = $O(1)$ at end (amortized bc copying), $O(n)$ at beginning (has to shift over)
- `remove()` = $O(N)$, have to shift all elements

HashSet

- unordered but efficient; internally creates a HashMap to store elements of set
- `add()`, `remove()`, `contains()`, `size()` = $O(1)$

HashMaps

- calculates hash (int) of a key with `.hashCode()` to see where to store values (diff keys can have same hash)
- puts it in a "bucket" of k, v pairs with that hash index
- `put()` adds to hash index bucket, updates if present = $O(1)$
- `get()` gets value at computed location to get hash bucket iterates over hashBucket keys to find `.equals()` key = $O(1)$
- `containsKey()` checks if location empty = $O(1)$

TreeSet/TreeMap

- ordered set/map, slightly less efficient than HashSet/HashMap
- keeps values (for Set) and keys (for Map) sorted by "natural ordering," uses special kind of binary tree
- most methods are runtime complexity $O(\log n)$

Big O

- `outer(inner(n))` \rightarrow runtime of inner + runtime of outer on return value of inner

$O(2^N)$	Exponential	Calculate all subsets of a set
$O(N^3)$	Cubic	Multiply $N \times N$ matrices
$O(N^2)$	Quadratic	Loop over all <i>pairs</i> from N things
$O(N \log(N))$	Nearly-linear	Sorting algorithms
$O(N)$	Linear	Loop over N things
$O(\log(N))$	Logarithmic	Binary search a sorted list
$O(1)$	Constant	Addition, array access, etc.

LinkedList

- each node has value and reference to another node
 - `next` returns node, not value
- `add()` and `remove()` at front = $O(1) \rightarrow$ change pointers
 - removing first \rightarrow save reference to second, set first node to null (break connection), set first to second
- `get()` = $O(N)$, loops through each element until null
- `contains()` = $O(N)$, loops through list until you find it
- traverse with a while loop (`list != null`)
- null pointer exc if you call method/variable on null node

recursion

- base case and recursive calls (get answer on input subset)
- method calls a clone with its own frame, doesn't call self
 - call stack of methods in a cue
- invariant: true statement while loop is running
- ex: reverse
 - iterative \rightarrow `temp = list.next` `list.next = rev` `rev = list` `list = temp` (rev is reversed so far)
 - recursive ($O(N)$) \rightarrow base case if `list` or `list.next == null`, store recursive call on `list.next`, set `list.next.next` to `list`, set `list.next` to null, return stored recursive call

recursion cont'd

- recursive runtime
 - $T(N) = a * T(g(N)) + f(N)$
 - $T(N)$: runtime of method with input size N
 - a : number of recursive calls
 - $g(N)$: how much input size decreases on each recursion
 - $f(N)$: runtime of non-recursive code on N

Recurrence	Algorithm	Solution
$T(n) = T(n/2) + O(1)$	binary search	$O(\log n)$
$T(n) = T(n-1) + O(1)$	sequential search	$O(n)$
$T(n) = 2T(n/2) + O(1)$	tree traversal	$O(n)$
$T(n) = T(n/2) + O(n)$	qsort partition, find k^{th}	$O(n)$
$T(n) = 2T(n/2) + O(n)$	mergesort, quicksort	$O(n \log n)$
$T(n) = T(n-1) + O(n)$	selection or bubble sort	$O(n^2)$

insertion sort without recursion → $O(N^2)$

- loop through original list, maintain a new sorted list, insert one value at a time in order (looping through new sorted list)

mergesort

- base case → size 1, return list
- recursive case → mergesort(first half), mergesort(second half), return merged sorted halves with helper merge(first, second)
- merge() → add to a new list, traverse listA and listB with 2 indices with looping, compare the value at each of 2 indices and add the smaller
- $O(N \log(N))$ → halves at each level so $O(\log(N))$ levels, merge at each level with $O(N)$
- merge() → $O(nA + nB)$ = linear

comparisons in mergesort

- one comparison per loop / per element merged
- $O(CN \log(N))$, where C is complexity of compareTo() or compare() that may not be a constant value

Java API sort → Collections.sort() Arrays.sort()

- Timsort (like Mergesort) = $O(N \log(N))$
- sorts in place, mutates input instead of making new

stable: does not reorder elements if not needed (ex: 2 elements are equal)

Comparable

- class objects that implement Comparable interface can be sorted → have a naturalOrder
- compareTo() → method is in class of this object type
 - < 0 if this comes before parameter, 0 if equal, > 0 if this comes after parameter
 - ^ if it's in the right order, return negative

Comparator

- use Comparator when not changing the object itself to compare non natural order
- Comparator c, c.compare(a,b)
 - < 0 if a comes before b, 0 if equal, > 0 if a comes after b
 - method is part of Comparator
- Collections.sort(list, Comparator.comparing(ObjType::methodName))
- to combine sequence of comparison → Comparator.comparing(_::_).thenComparing(_::_)
- with lambdas (for comparing something without a getter)
 - Comparator<ObjType> c = (a,b) -> (what c.compare(a,b) should return)
 - ex: (a,b) -> (a[0] - b[0]) for first elements
 - can use sort(list, createdComparator)

binary search → needs sorted list

- $O(\log(N))$ → cut down search space by half at each step
- low (initially 0) and high (initially N-1) mark the limits of active search space
- loop while (low = high) → while there's anything left to search
 - loop invariant → if target is in array/list, it is in [low, high]
- compare mid ((low+high)/2) to target
- search in lower (high = mid-1) or upper half (low = mid+1)
 - not high = mid or low = mid to prevent infinite loop in edge cases
- does not guarantee the first or last index of a match if there are multiple