

INTER PROCESS COMMUNICATION

OPERATING SYSTEMS LABS



LAB TASK # 06

Submitted By

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Exercise # 01

```
#include <unistd.h>
#include <stdio.h>
#include<signal.h>
#include <sys/types.h>

void Child(int pid){
    printf("Child PID = %d\n", pid);
    printf("I am the Child with PID = %d\n", getpid());
}

void Parent(int pid){
    char* command = "ps";
    char* argument_list[] = {"ps", "aux", NULL};
    printf("Parent of = %d\n", pid);
    printf("I am the Parent with PPID = %d\n",getppid());
    kill(pid,SIGTERM);
    if (fork() == 0) {
        int status = execvp(command, argument_list);
        if (status != -1) {printf("Operation Succeeded\n");}
    }
    sleep(120);
}

int main()
{
    int pid;
    pid = fork();
    if(pid == 0){
        Child(pid);}
    else{
        Parent (pid);}}
```

Exercise # 02

```
#include <unistd.h>
#include <stdio.h>
#include<signal.h>
#include <sys/types.h>

void Child(int pid){
    char* command = "ps";
    char* argument_list[] = {"ps", "aux", NULL};
    printf("Child PID = %d\n", pid);
    printf("I am the Child with PID = %d\n", getpid());
    kill(pid,SIGTERM);
    if (fork() == 0) {
        int status = execvp(command, argument_list);
        if (status != -1) {printf("Operation Succeeded\n");}
    }
    sleep(120);
}

void Parent(int pid){
    printf("Parent of = %d\n", pid);
    printf("I am the Parent with PPID = %d\n",getppid());
}

int main(){
    int pid;
    pid = fork();
    if(pid == 0){
        Child(pid);}
    else{
        Parent(pid);}}
```