AREZOU KESHAVARZ

EDUCATION

September 2007 – Present

Stanford University

Stanford, CA

Electrical Engineering

Masters of Applied Science

Relevant Courses: Convex Optimization, Dynamic Programming and Control, Information Theory, Linear Dynamical Systems, Statistical Signal Processing, Digital Communication, Digital Signal Processing

September 2003 – June 2007

University of Toronto

Toronto, ON

Electrical Engineering

 Bachelor of Applied Science RELEVANT EXPERIENCE **GPA**: 3.93 **Technical GPA**: 4.00

Rank: 1-3

June 2006 – August 2006

Wireless Sensor Networks Lab at Stanford University

Stanford, CA

Research Assistant

- Conducted research on **Smart Home Care Networks** to develop a system which would allow caregivers to monitor elderly patients. Collaborative reasoning is used to arrive at the final judgment.
 - O The work if filed for patent and its results are published in 4th International Workshop on Video Surveillance & Sensor Networks, and at the Workshop on Distributed Smart Cameras (DSC06).

May 2004 – June 2006 Artificial Perception Laboratory at University of Toronto

Toronto, ON

Government-funded Research Assistant

- Conducted research on Acoustic Object Tracking techniques as part of a larger hardware-based all-in-one system aimed to perform sound localization, speech enhancement and voice recognition.
- Worked on phase-based Speech Enhancement techniques, specifically to develop a relationship between signal-to-noise ratio and phase for microphone pairs
- Designed and implemented a Sound Localization-based adaptive user interface, enabling navigation through a set of objects by localizing the sound source in space. (Applications: navigational interface for the disabled, stage presentations)
 - o The results of the sound localization-based adaptive interface research are submitted in the form of a paper published in the *IEEE International Symposium on Multimedia*
- Successfully established a remote real-time robot navigation platform through the TCP/IP connection using MATLAB. The platform was used by 19 students in their design project competition.
- Successfully established a remote navigation system for a helicopter through hand movements in 3D space using MATLAB.

September 2006 – June 2007

IEEE Student Branch at University of Toronto

Toronto, ON

IEEE Vice Chair

• Coordinated and managed various events to increase academic and professional awareness among the ECE class. The main events hosted in the previous semester were the **IEEE Graduate Information Sessions** (9 events spread out during a week) and the **IEEE Wine & Cheese recruitment event**.

AWARDS

- Stanford Graduate Fellowship (SGF) 2007-2010
- National Science and Engineering Research Council Post-Graduate Fellowship (Canada) 2007-2009
- Three-times-winner of the Adel S. Sedra Outstanding Student Award 2004, 2005 and 2006
- ECE NSERC USRA Scholarship 2005, 2006
- Walberg Undergraduate Scholarship 2006
- Two-times-winner of the University of Toronto Scholar Award July 2004 and 2005

AREZOU KESHAVARZ

PROJECTS

Optimal Trading Strategy of an Informed Trader in the Presence of a less-informed Competitor

Course: Independent Study with Professor Van Roy

April 2008 – September 2008

- o Calculating the optimal trading strategy for both traders resulting in a Perfect Bayesian Equilibrium
- o Analyzed and formulated the problem using Dynamic Programming
- o Worked on an algorithm to calculate the PBE numerically using DP

Modiface: A Face Fusion Application

May 2006 – May 2007

Course: Final year Design Project

- O Design and implementation of an application to simulate the results of a cosmetic surgery.
- o Research involved face detection, feature localization and feature blending techniques
- o The result of the surgery is simulated using image processing performed in MATLAB.
- o An interactive web-application is designed to display the results, available at **Modiface.com**.

Sound Localization: human ears vs. computers

September 2006 – November 2006

Course: Sensory Communications

O Performed a thorough study of the quality of sound localization as performed automatically by a computer versus human ears.

Optical Telephone

September 2005 – November 2005

Course: Analog Electronics

o Designed and implemented an optical telephone, composed of a transmitter, receiver, and optical transmission unit.

Sound and Speech Processing

March 2005 – April 2005

Course: Computer Organization

- O Designed and implemented a system, using **Assembly**, which recorded and performed various operations on sound signals.
- o Some features of this project are up-sampling, down-sampling and reverse playback.

Server Design and Implementation

January 2005 – April 2005

Course: Engineering Design II

o Established an HTTP/1.1 compatible server successfully using C++ through team collaboration in a group of five students

■ FPGA Implementation of Tic-Tac-Toe

November 2005

Course: Digital Circuit Design

- o Created an FPGA version of the famous Tic-Tac-Toe mind game using Verilog.
- o The results of the game were shown on the VGA display, which was controlled using an advanced state machine design.

Scanner Robot

March 2003 - May 2003

Course: Secondary School Computer Engineering course

O Devised and built a scanner robot using Lego Mindstorms ®

SKILLS

- MATLAB, CVX: proficient with various toolboxes through previous research and course work
- JavaScript, HTML, PHP, Perl: through undergraduate final design project
- Java, C++, PISCES, PSpice, Orcad Capture, Verilog, Assembly: through course projects
- LaTex, Microsoft Office

INTERESTS, ACTIVITIES AND COMMUNITIES

- Director of Business Alliance Persian Student Association at Stanford (2008-209)
- Vice chair of the IEEE student branch at the University of Toronto (2006-2007)
- Member of the Dean's Circle (2003-2007)
- Member of the Golden Key International Honor Society
- Enjoy photography, running, hiking, and skiing
- Other interests include Literature, Economics, Cognitive Science, and Philosophy of Mind