

# CSC 226

Algorithms and Data Structures: II

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# Weighted Graphs

- A ***weighted graph*** is a graph model where we associate ***weights*** (or ***costs***) with each edge
- That is, for each edge  $e$ , we have a numeric label associated with it, denoted  $w(e)$ .
- We will look at algorithms for solving three general problems of weighted graphs
  - Minimum spanning trees
  - Shortest Paths
  - Network Flow

# Weighted edge API

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Edge abstraction needed for weighted edges.

```
public class Edge implements Comparable<Edge>
```

```
    Edge(int v, int w, double weight)
```

*create a weighted edge v-w*

```
    int either()
```

*either endpoint*

```
    int other(int v)
```

*the endpoint that's not v*

```
    int compareTo(Edge that)
```

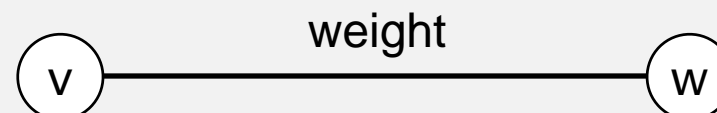
*compare this edge to that edge*

```
    double weight()
```

*the weight*

```
    String toString()
```

*string representation*



Idiom for processing an edge *e*: `int v = e.either(), w = e.other(v);`

# Weighted edge: Java implementation

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```
public class Edge implements Comparable<Edge>
{
    private final int v, w;
    private final double weight;

    public Edge(int v, int w, double weight)
    {
        this.v = v;
        this.w = w;
        this.weight = weight;
    }

    public int either()
    { return v; }

    public int other(int vertex)
    {
        if (vertex == v) return w;
        else return v;
    }

    public int compareTo(Edge that)
    {
        if (this.weight < that.weight) return -1;
        else if (this.weight > that.weight) return +1;
        else return 0;
    }
}
```

← constructor

← either endpoint

← other endpoint

← compare edges by weight

# Edge-weighted graph API

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```
public class EdgeWeightedGraph
```

```
    EdgeWeightedGraph(int V)
```

*create an empty graph with V vertices*

```
    EdgeWeightedGraph(In in)
```

*create a graph from input stream*

```
    void addEdge(Edge e)
```

*add weighted edge e to this graph*

```
    Iterable<Edge> adj(int v)
```

*edges incident to v*

```
    Iterable<Edge> edges()
```

*all edges in this graph*

```
    int V()
```

*number of vertices*

```
    int E()
```

*number of edges*

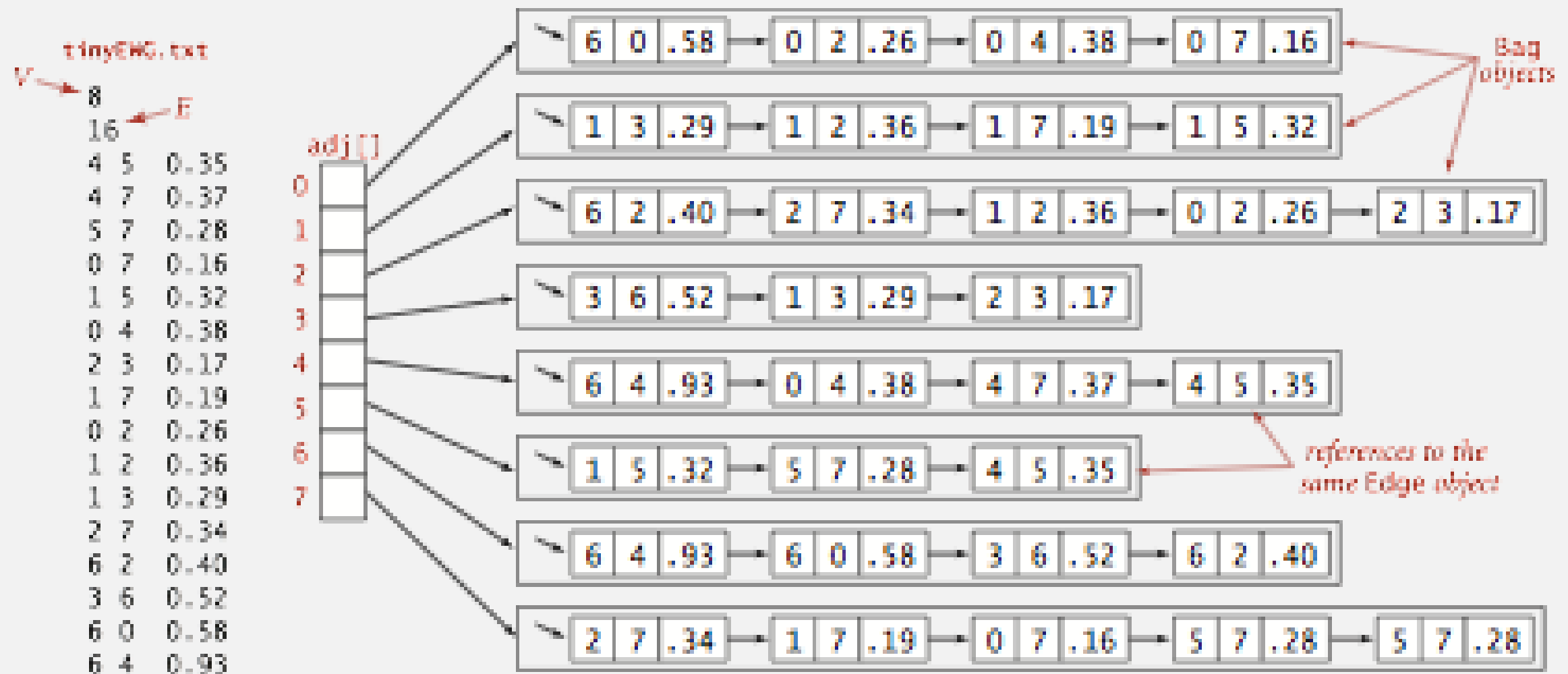
```
    String toString()
```

*string representation*

**Conventions.** Allow self-loops and parallel edges.

# Edge-weighted graph: adjacency-lists representation

Maintain vertex-indexed array of Edge lists.



# Edge-weighted graph: adjacency-lists implementation

---

```
public class EdgeWeightedGraph
{
    private final int V;
    private final Bag<Edge>[] adj;

    public EdgeWeightedGraph(int V)
    {
        this.V = V;
        adj = (Bag<Edge>[]) new Bag[V];
        for (int v = 0; v < V; v++)
            adj[v] = new Bag<Edge>();
    }

    public void addEdge(Edge e)
    {
        int v = e.either(), w = e.other(v);
        adj[v].add(e);
        adj[w].add(e);
    }

    public Iterable<Edge> adj(int v)
    { return adj[v]; }
}
```

← same as Graph, but adjacency lists  
of Edges instead of integers

← constructor

← add edge to both  
adjacency lists

# Minimum Spanning Tree

## Definition

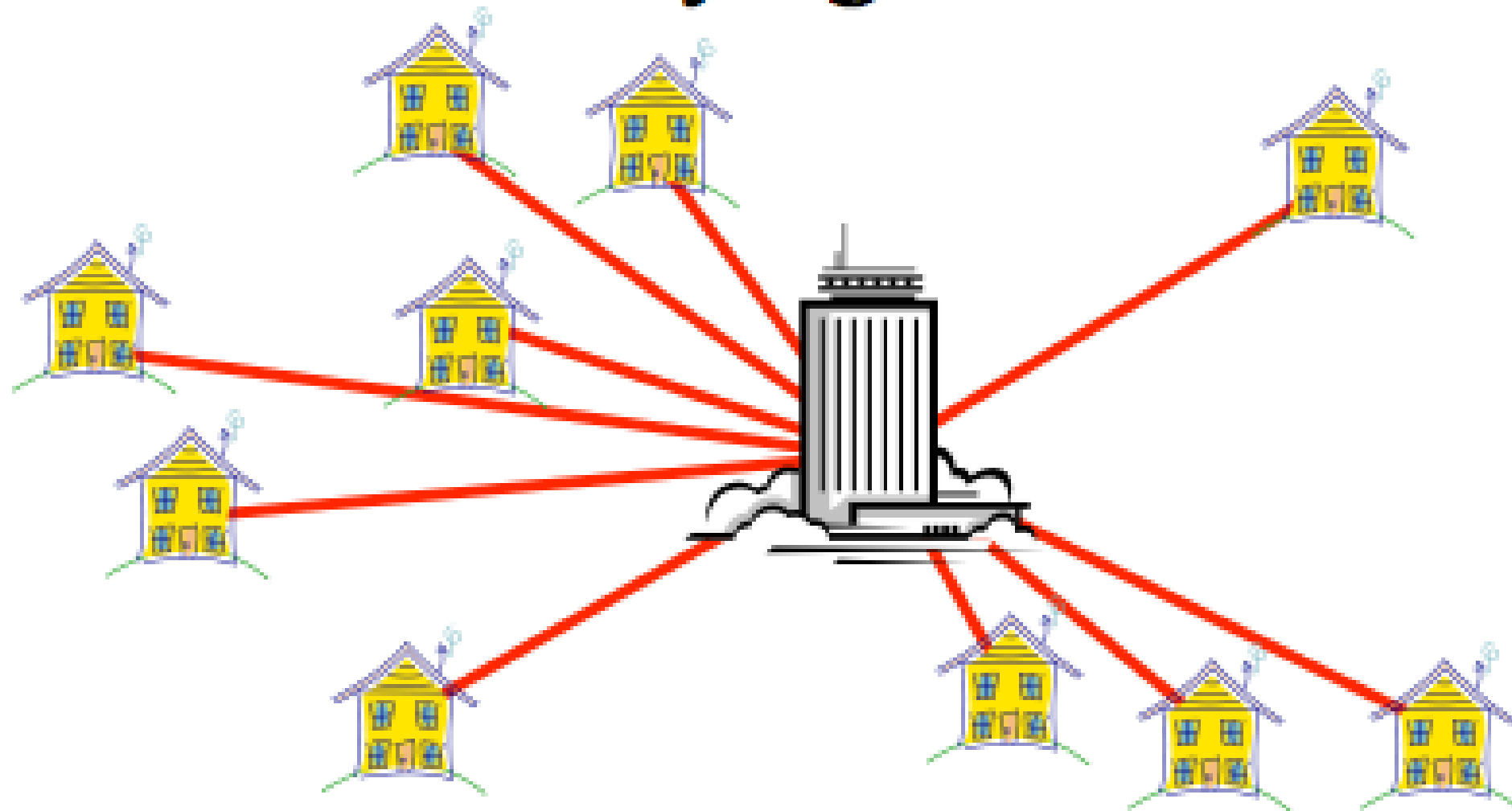
- *Input:* A weighted, connected graph  $G = (V, E)$  consisting of vertices (or nodes),  $V$ , and edges,  $E$ , with edge weights
- *Output:* A *minimum spanning tree* (MST)  $T = (V, E_T)$  of  $G$ . That is,  $T$  is a connected subgraph of  $G$  ( $E_T \subseteq E$ ) such that  $T$  is acyclic, and the total weight of  $T$ ,

$$w(T) = \sum_{e \in E_T} w(e)$$

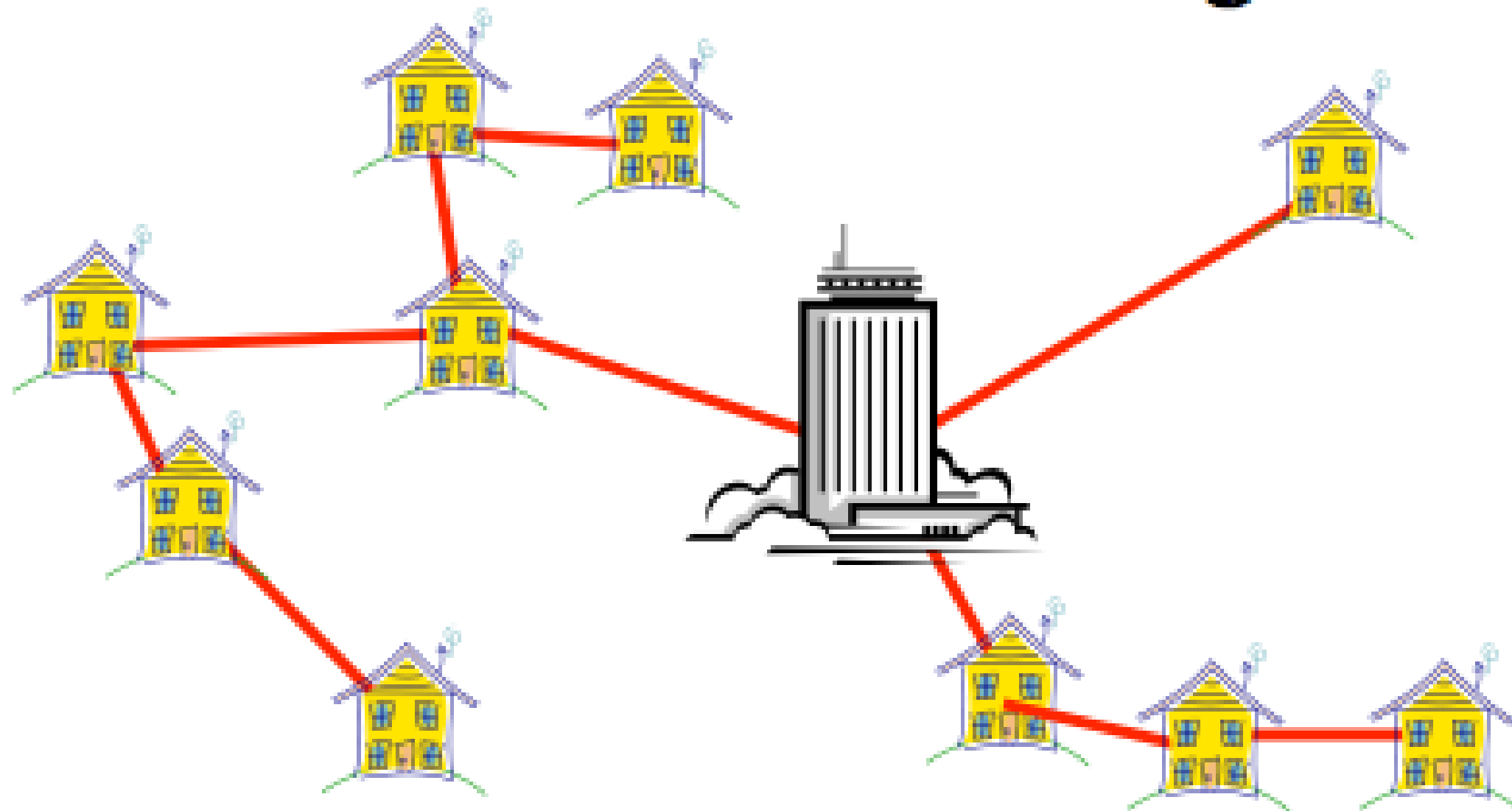
is minimized.



# Problem: Laying Cable TV Wire



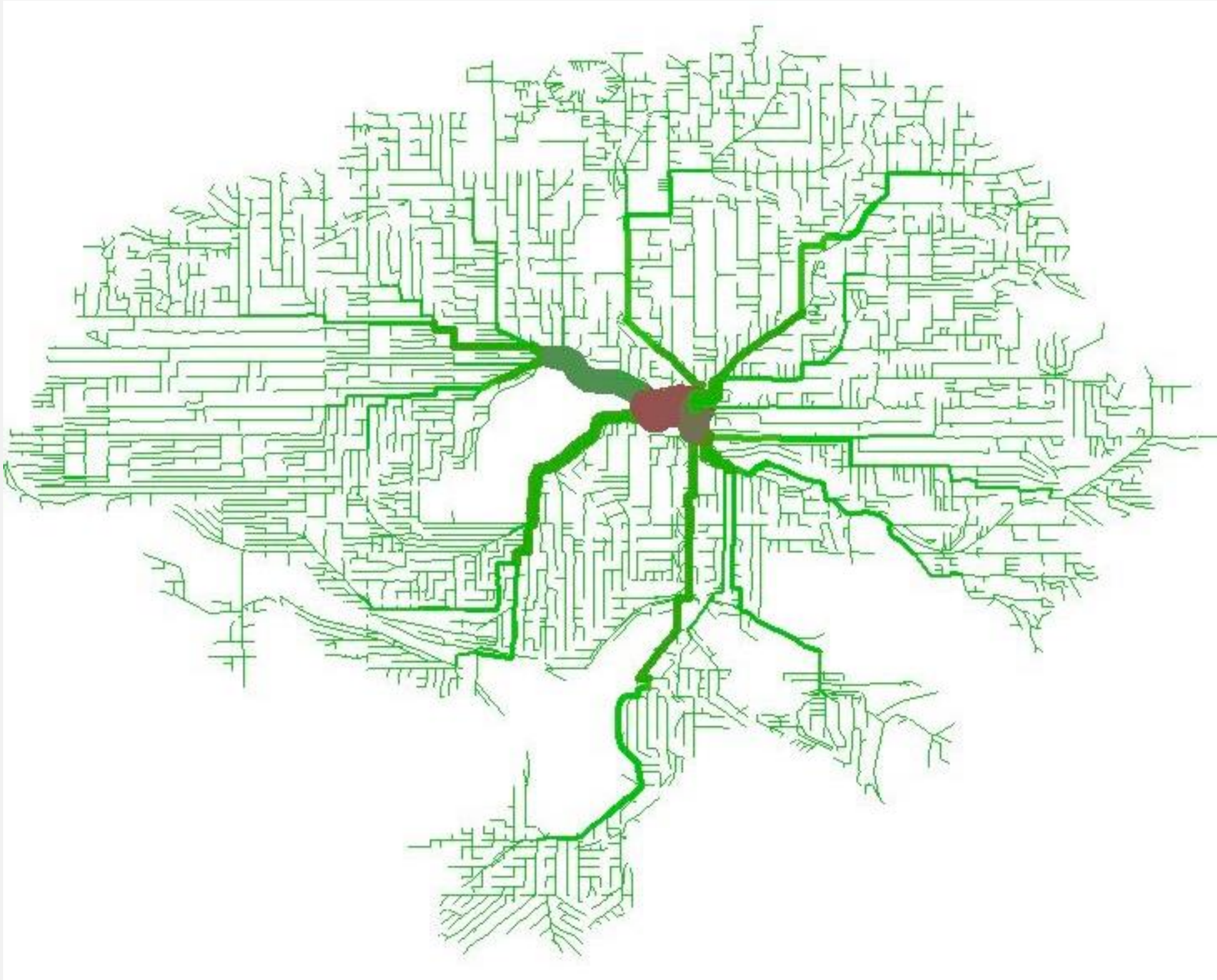
# Minimize Wiring



# Network design

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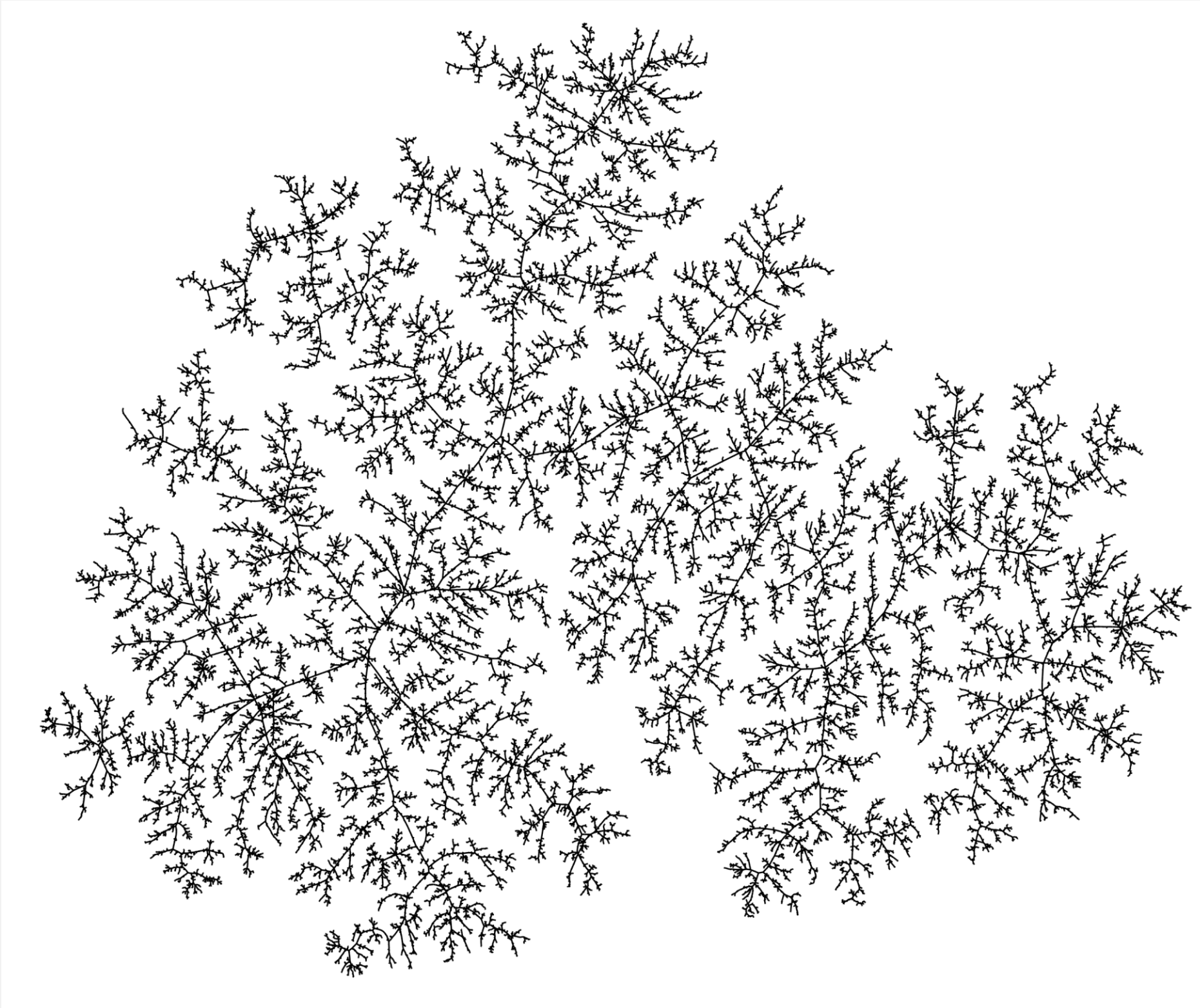
MST of bicycle routes in North Seattle



# Models of nature

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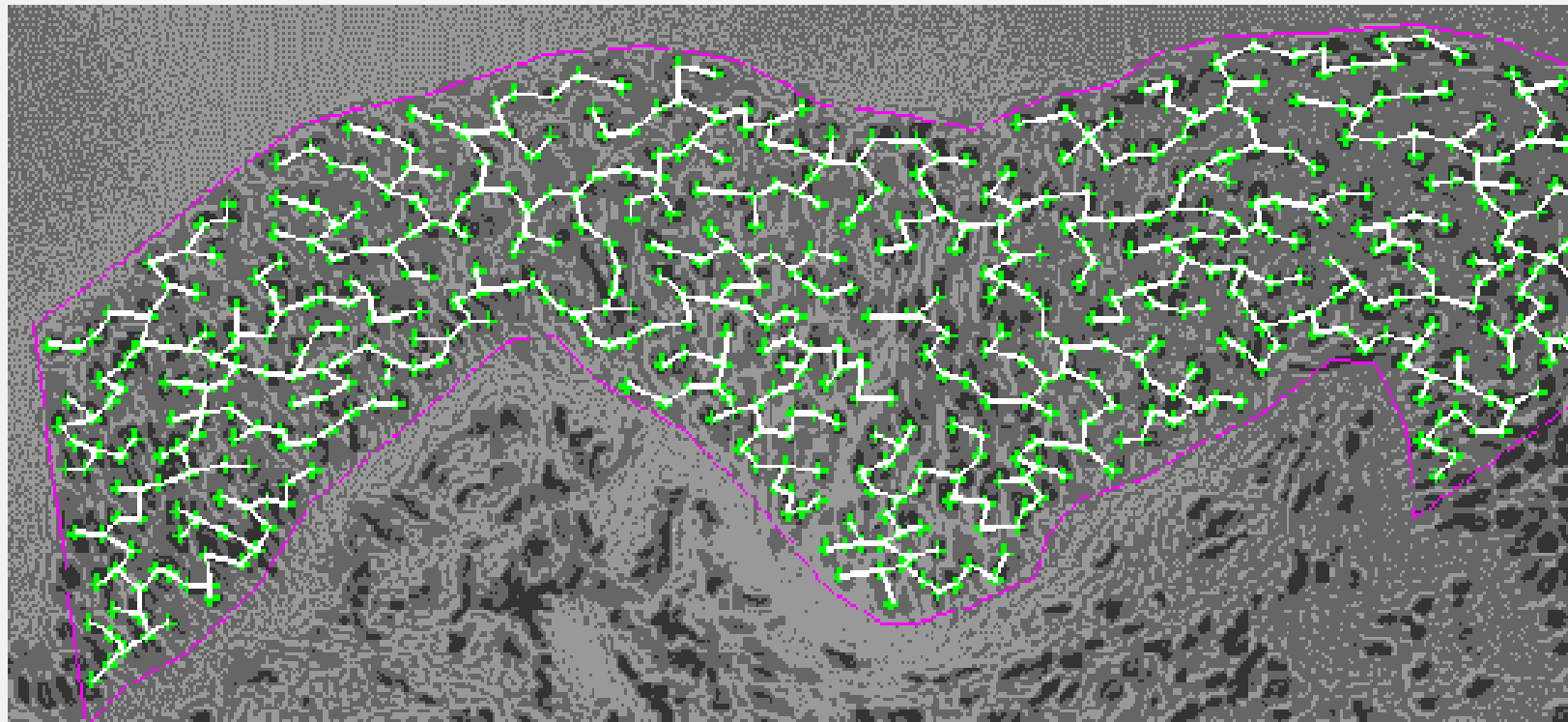
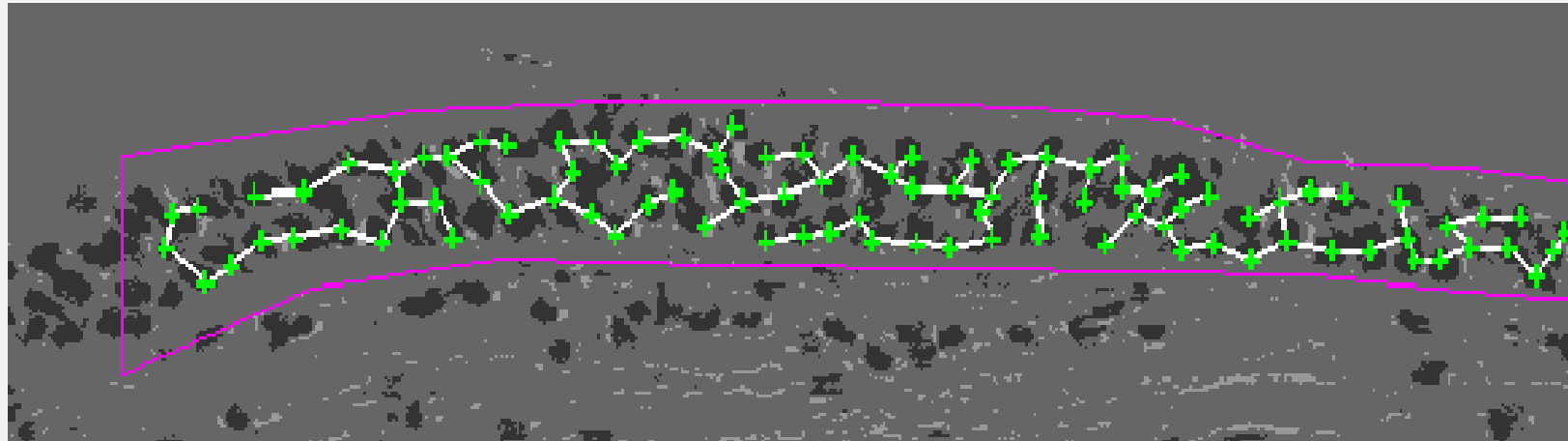
MST of random graph



# Medical image processing

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MST describes arrangement of nuclei in the epithelium for cancer research

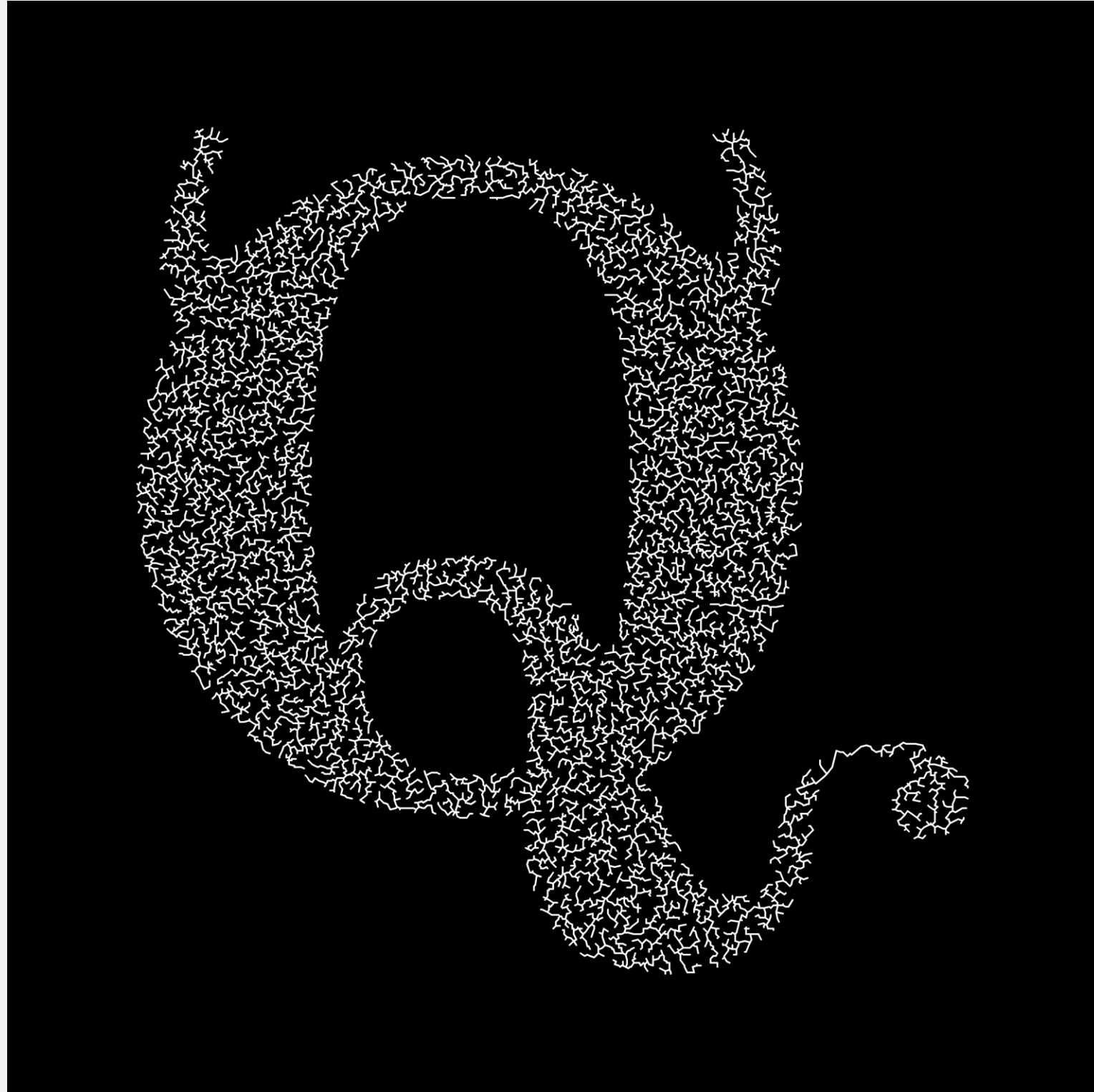


[http://www.bccrc.ca/ci/ta01\\_archlevel.html](http://www.bccrc.ca/ci/ta01_archlevel.html)

# Dithering

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MST dithering



<http://www.flickr.com/photos/quasimondo/2695389651>

MST is fundamental problem with diverse applications.

- Dithering.
- Cluster analysis.
- Max bottleneck paths.
- Real-time face verification.
- LDPC codes for error correction.
- Image registration with Renyi entropy.
- Find road networks in satellite and aerial imagery.
- Reducing data storage in sequencing amino acids in a protein.
- Model locality of particle interactions in turbulent fluid flows.
- Autoconfig protocol for Ethernet bridging to avoid cycles in a network.
- Approximation algorithms for NP-hard problems (e.g., TSP, Steiner tree).
- Network design (communication, electrical, hydraulic, computer, road).  
<http://www.ics.uci.edu/~eppstein/gina/mst.html>

# Determining MST by Brute Force

- Create all spanning trees
- Pick the lightest
- Not feasible!!
- A complete graph (every pair of vertices is connected by an edge) has  $|V|^{|V|-2}$  many spanning trees (Cayley's Formula [1889])



# Greedy Algorithm Design Technique

- Applied to optimization problems
  - an objective function is *minimized* or *maximized*
- Characterized by the *greedy-choice property*:
  - a global optimal configuration can be reached by a series of locally optimal choices
  - starting from a well-defined configuration, optimal choices are choices that are best from among the possibilities available at the time

# Minimum Spanning Tree algorithms

- 1926 Barůvka  $O(m \log n)$
- 1930 Prim-Jarník's
  - 1930 Jarník
  - 1957 Dijkstra
  - 1959 Prim
  - 1964 with Heaps  $O(m \log n)$
  - 1987 Fredman and Tarjan with Fibonacci Heaps  $O(m + n \log n)$
- 1956 Kruskal's algorithm
  - 1956 Kruskal
  - 1974 Aho, Hopcroft and Ullman with Union-Find Disjoint Set  $O(m \log n)$
- 1975 Yao  $O(m \log \log n)$
- 1976 Cheriton and Tarjan  $O(m \log \log n)$
- 1995 Karger, Klein and Tarjan Randomized MST based on Barůvka and Kruskal  $O(m)$
- 2000 Chazelle  $O(m \alpha(m, n))$

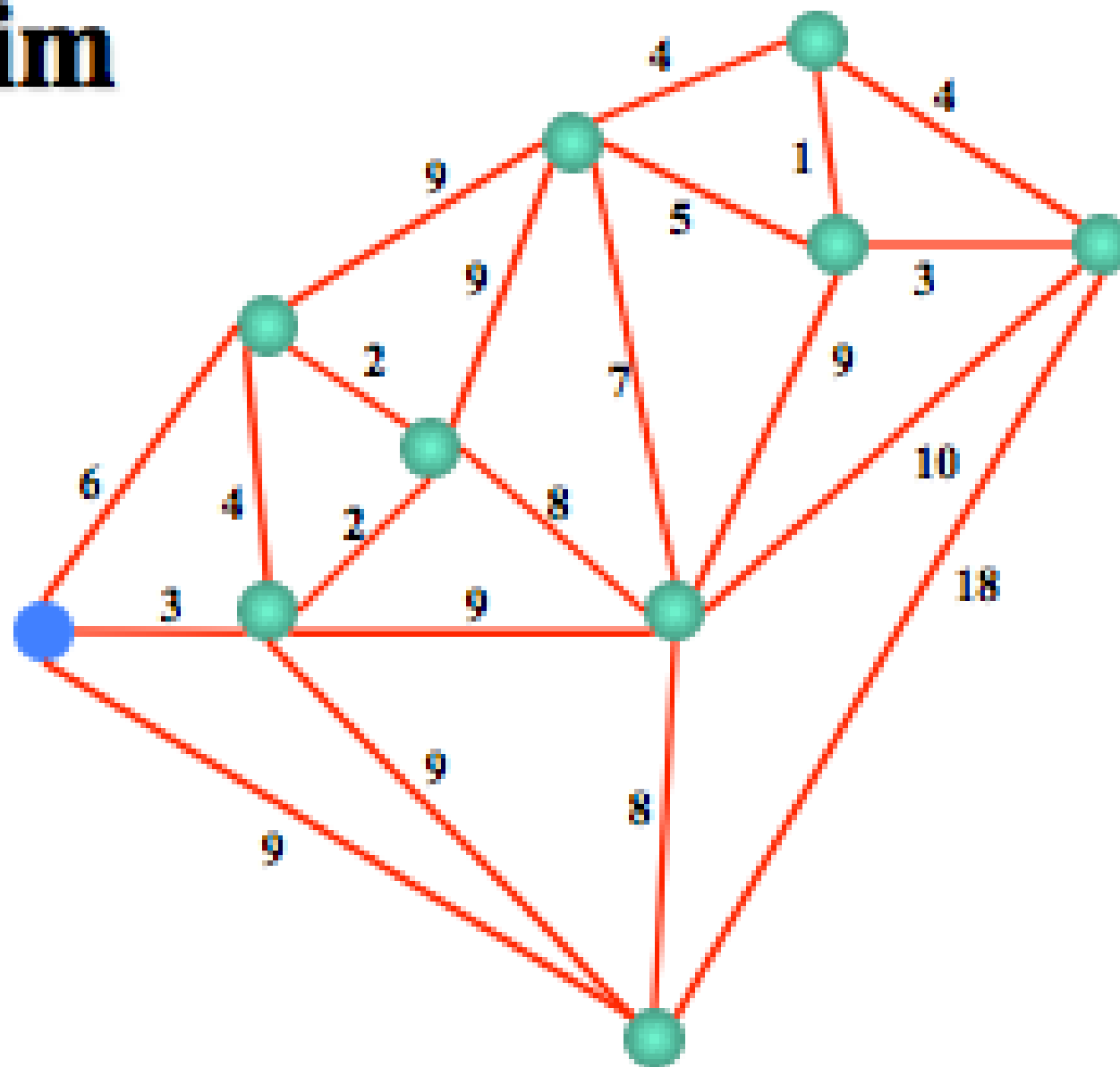
$n$ : number of vertices  
 $m$ : number of edges

# Prim's Algorithm

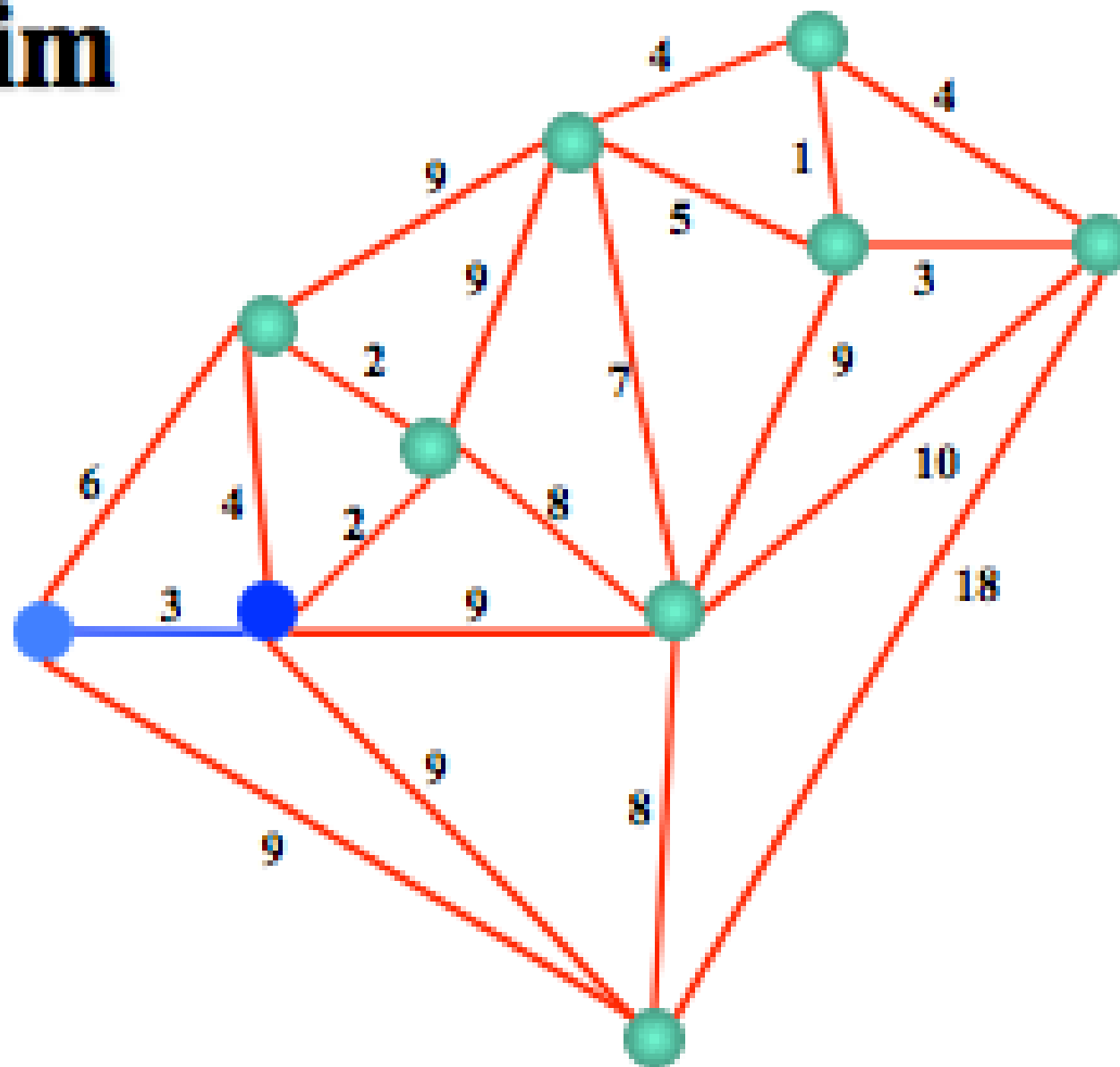
## Idea

- Initialize tree with single chosen vertex
- Grow tree by finding lightest adjacent edge not yet in tree and connect it to the tree; repeat until all vertices are in the tree
- *Example of greedy algorithm*

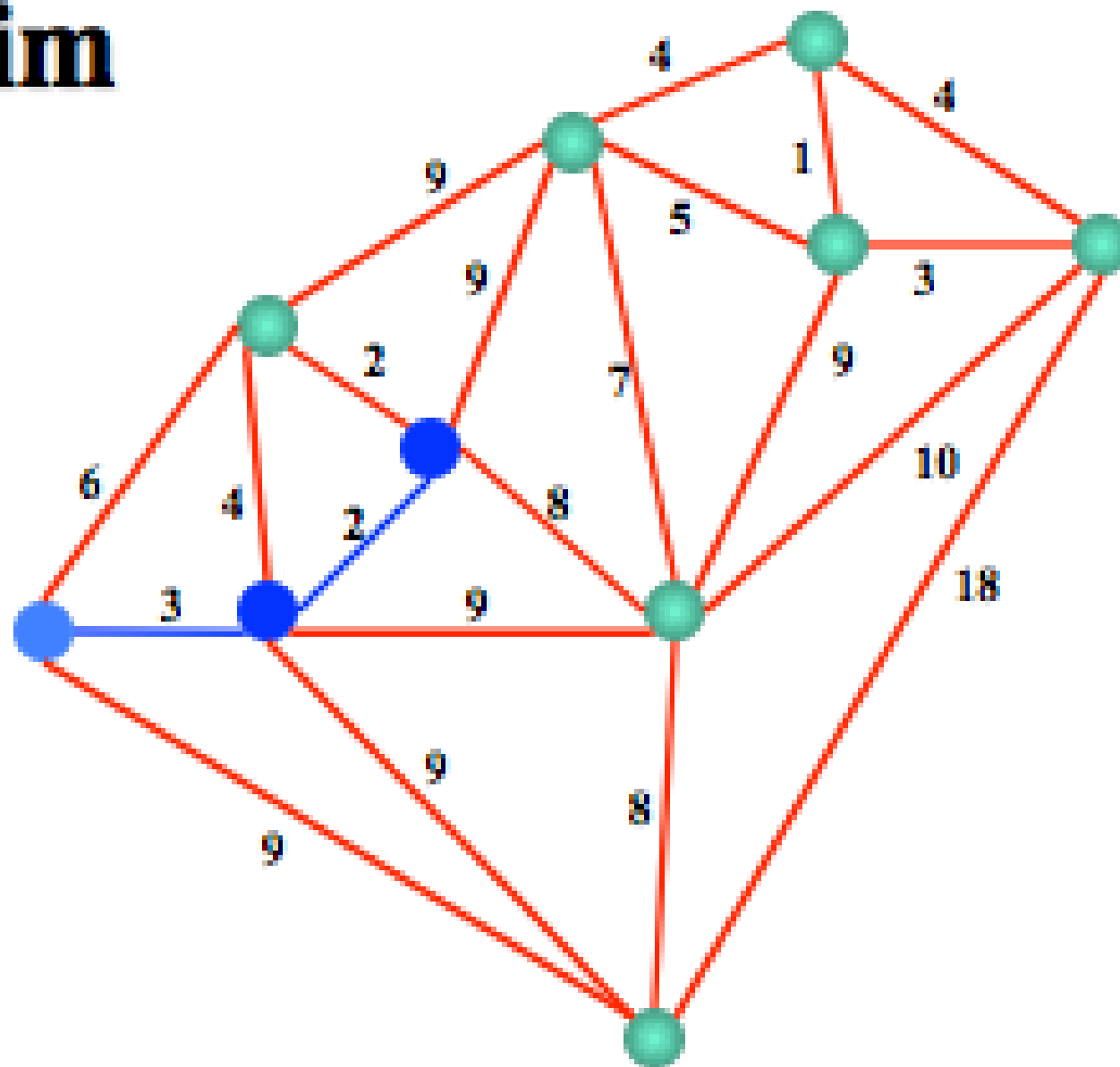
# Prim



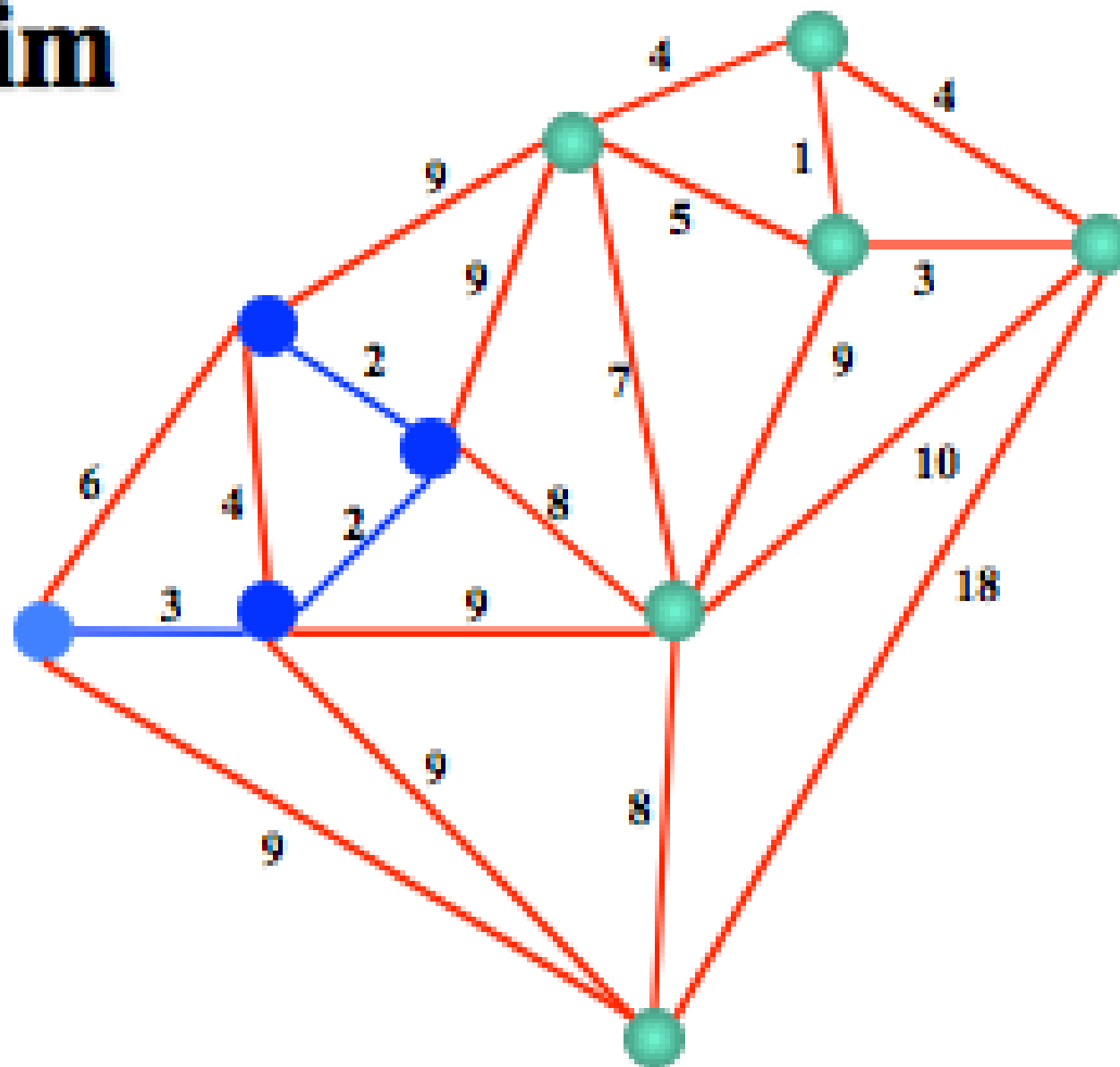
# Prim



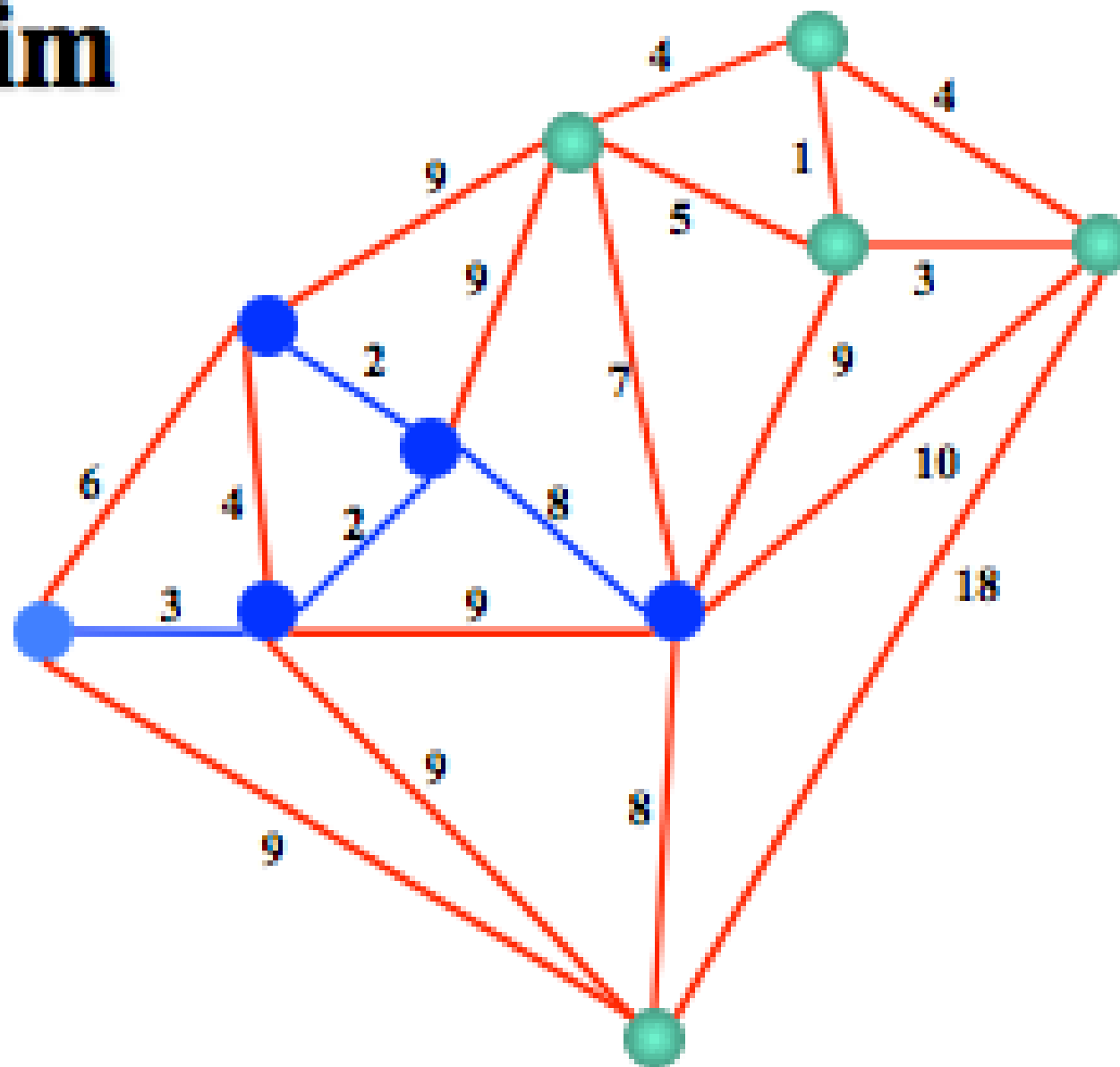
# Prim



# Prim

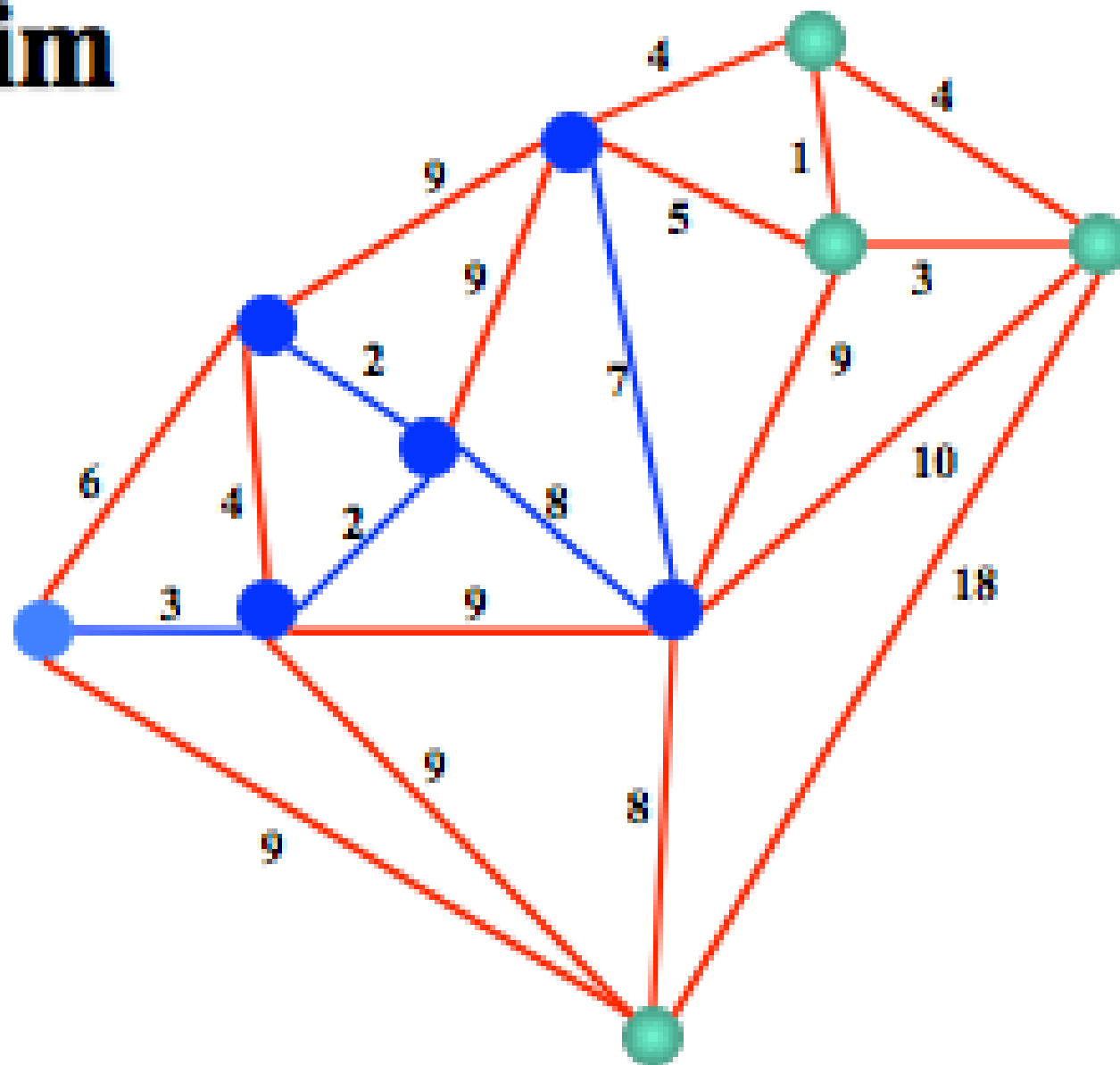


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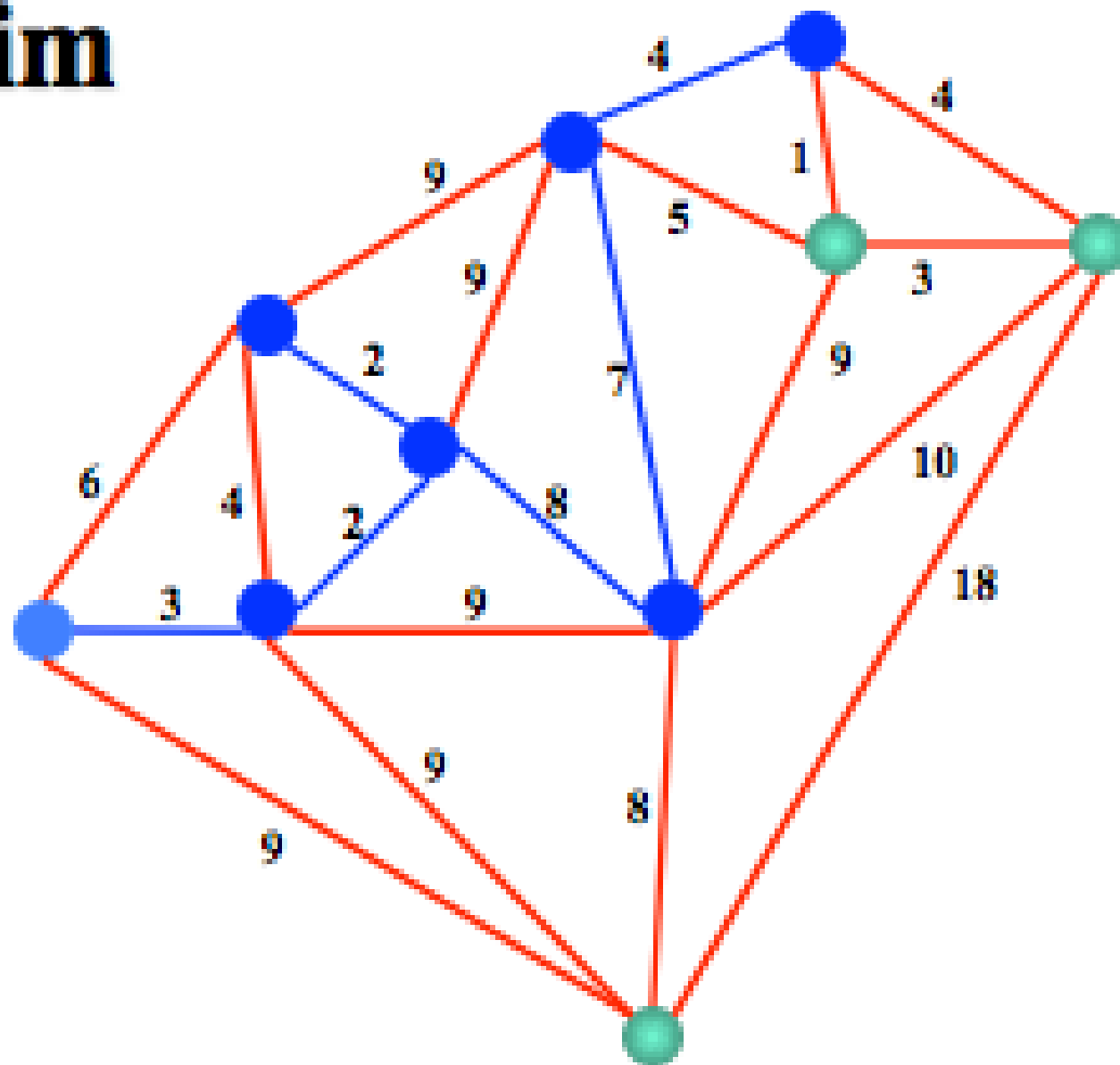




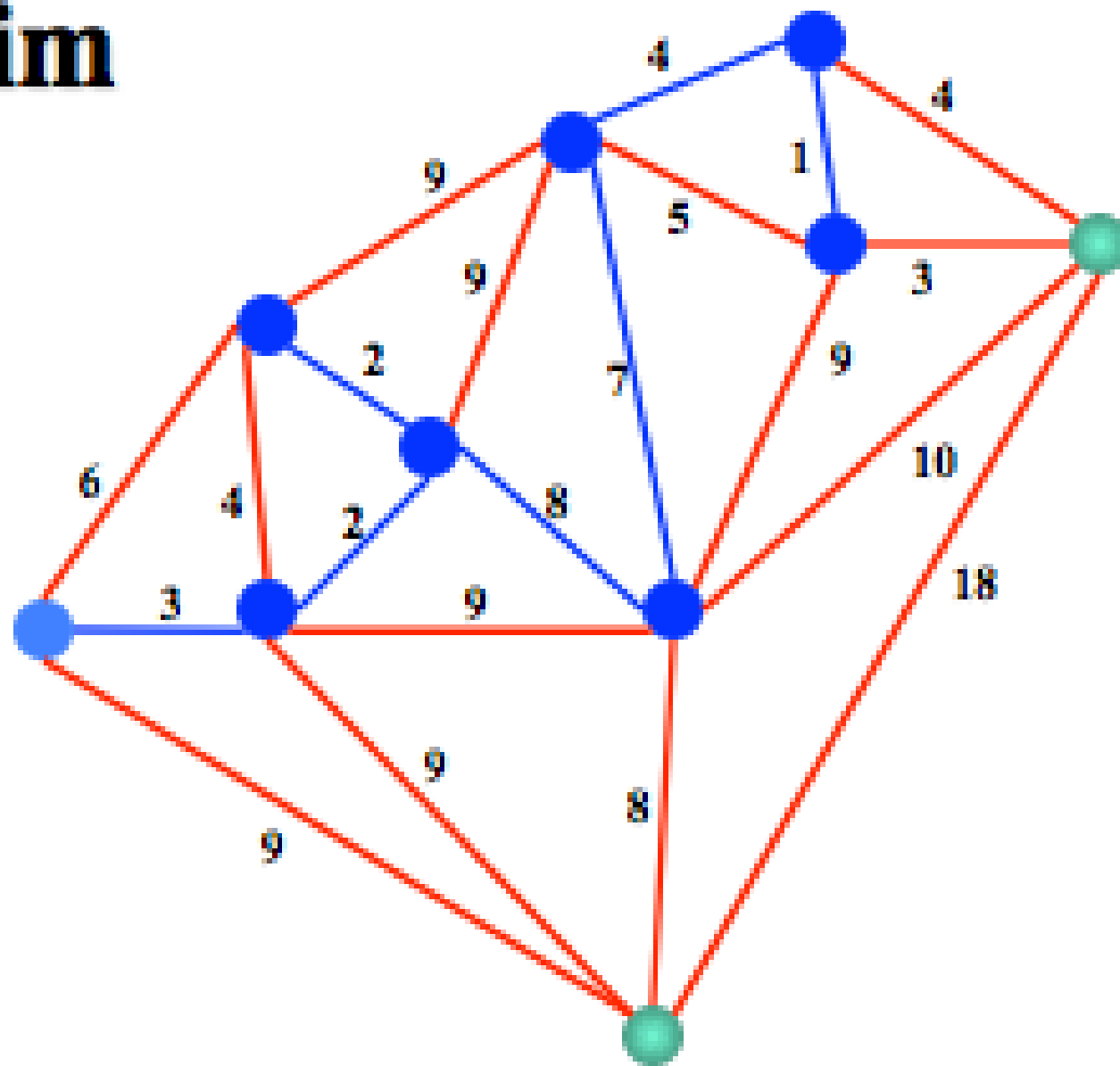
# Prim



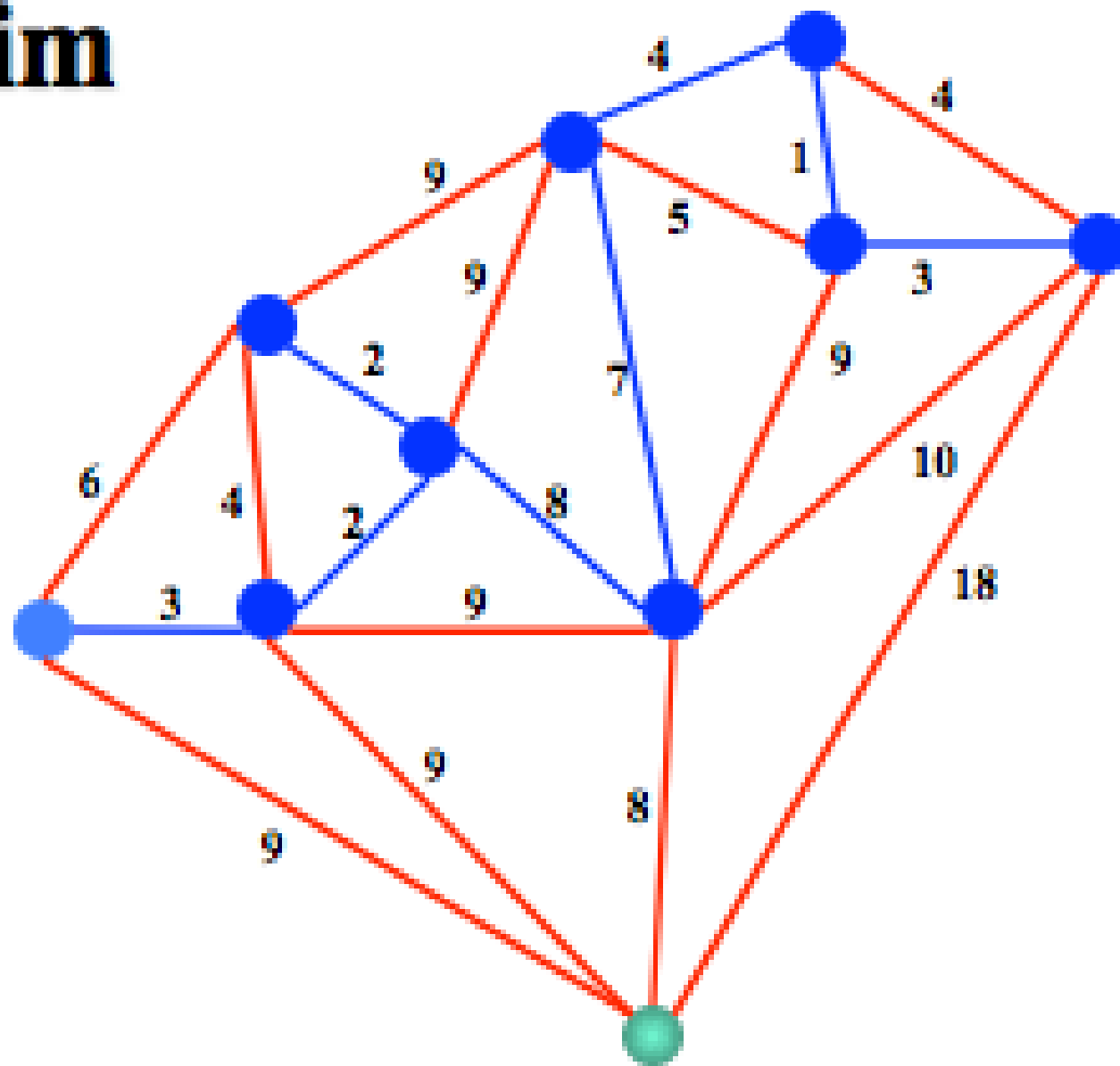
# Prim



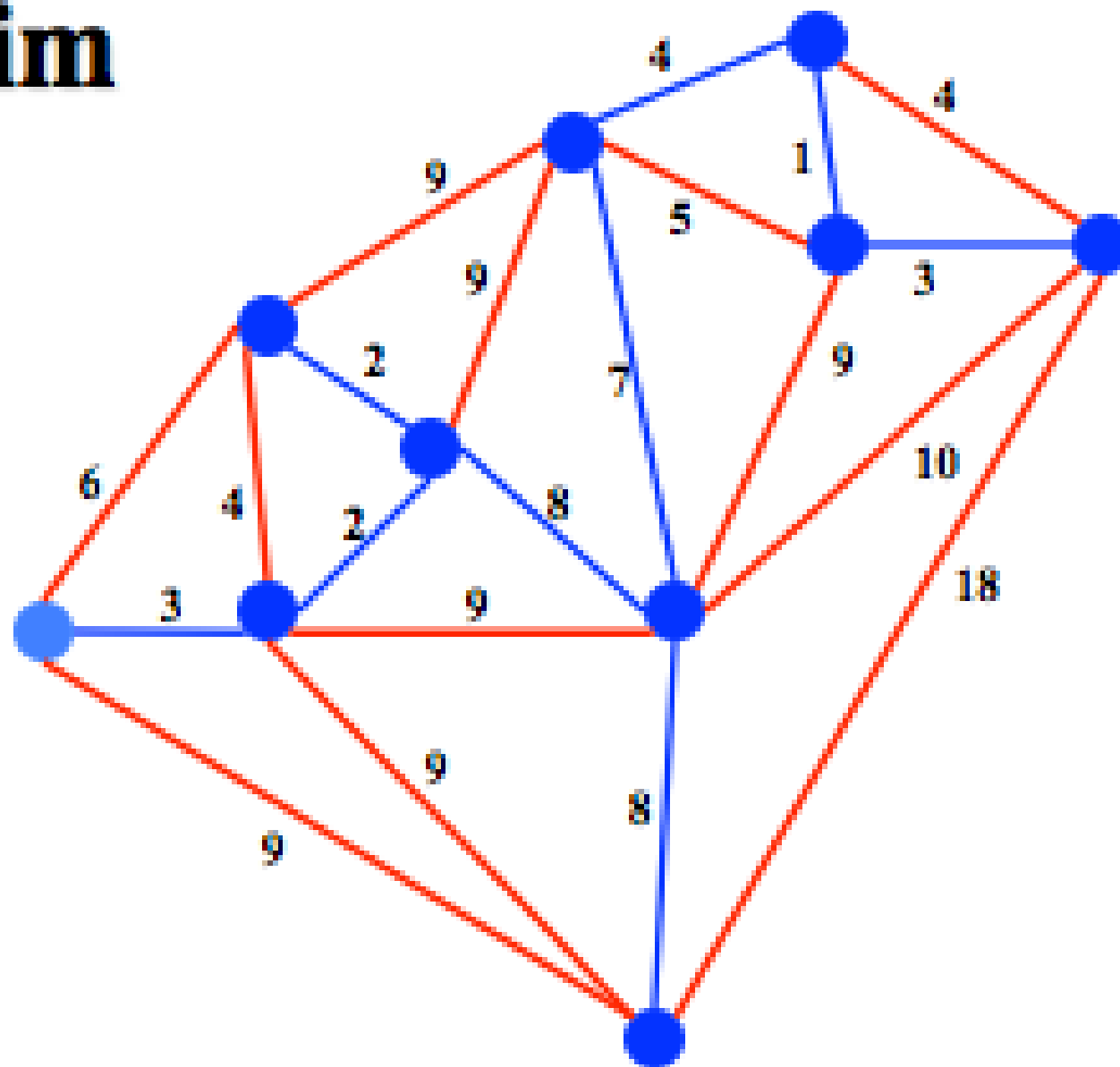
# Prim



## Prim

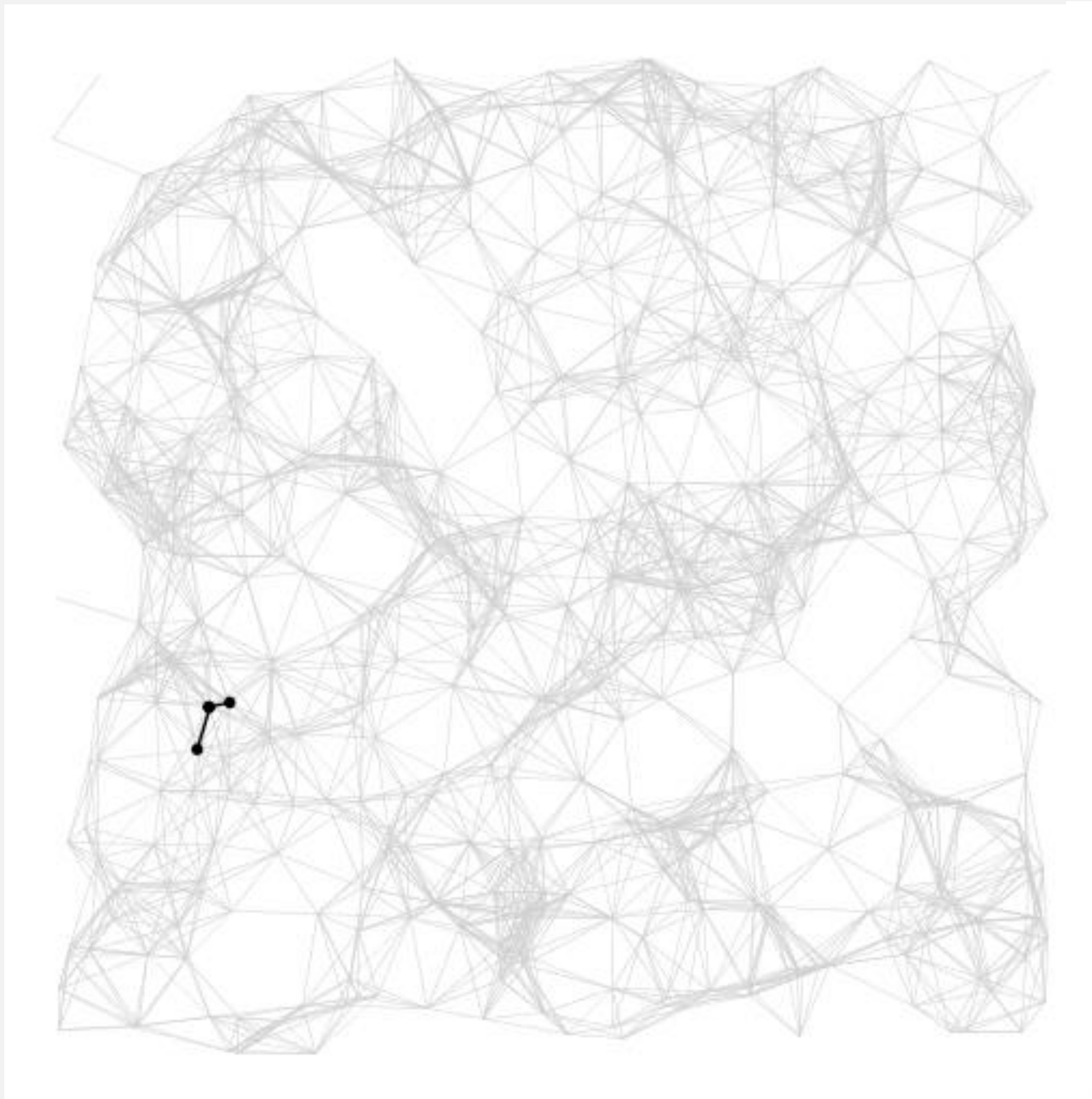


# Prim



# Prim's algorithm: visualization

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# Prim's Algorithm

## Idea

- Initialize tree with single chosen vertex
- Grow tree by finding lightest edge not yet in tree and connect it to tree; repeat until all vertices are in the tree
- *Example of greedy algorithm*

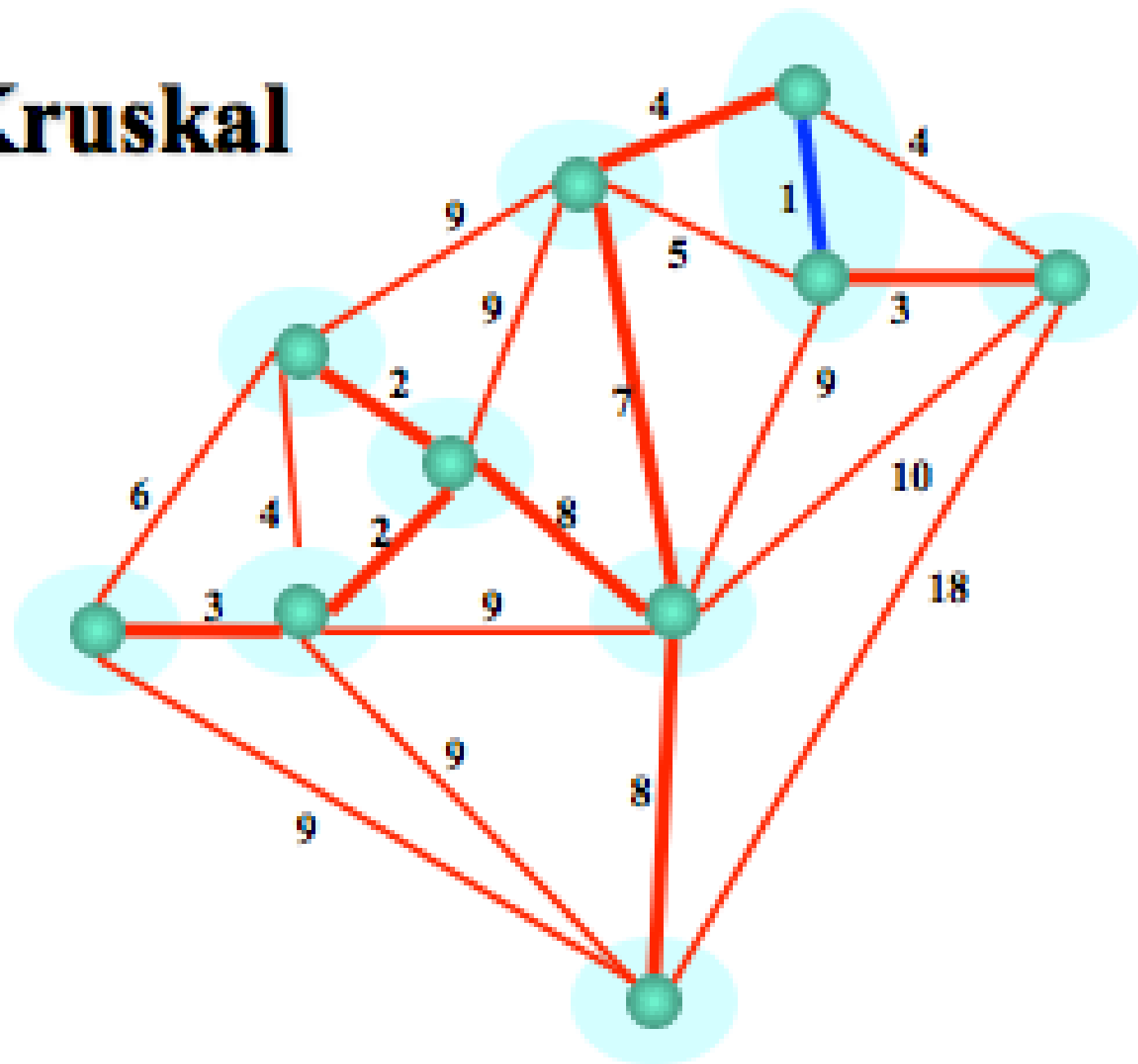
# Kruskal's Algorithm

## Idea

- Initialize a forest consisting of all nodes
- Pick a (non-selected) minimum weight edge and, if it connects two different trees of the forest, select it, otherwise discard it; repeat
- *Example of greedy algorithm*



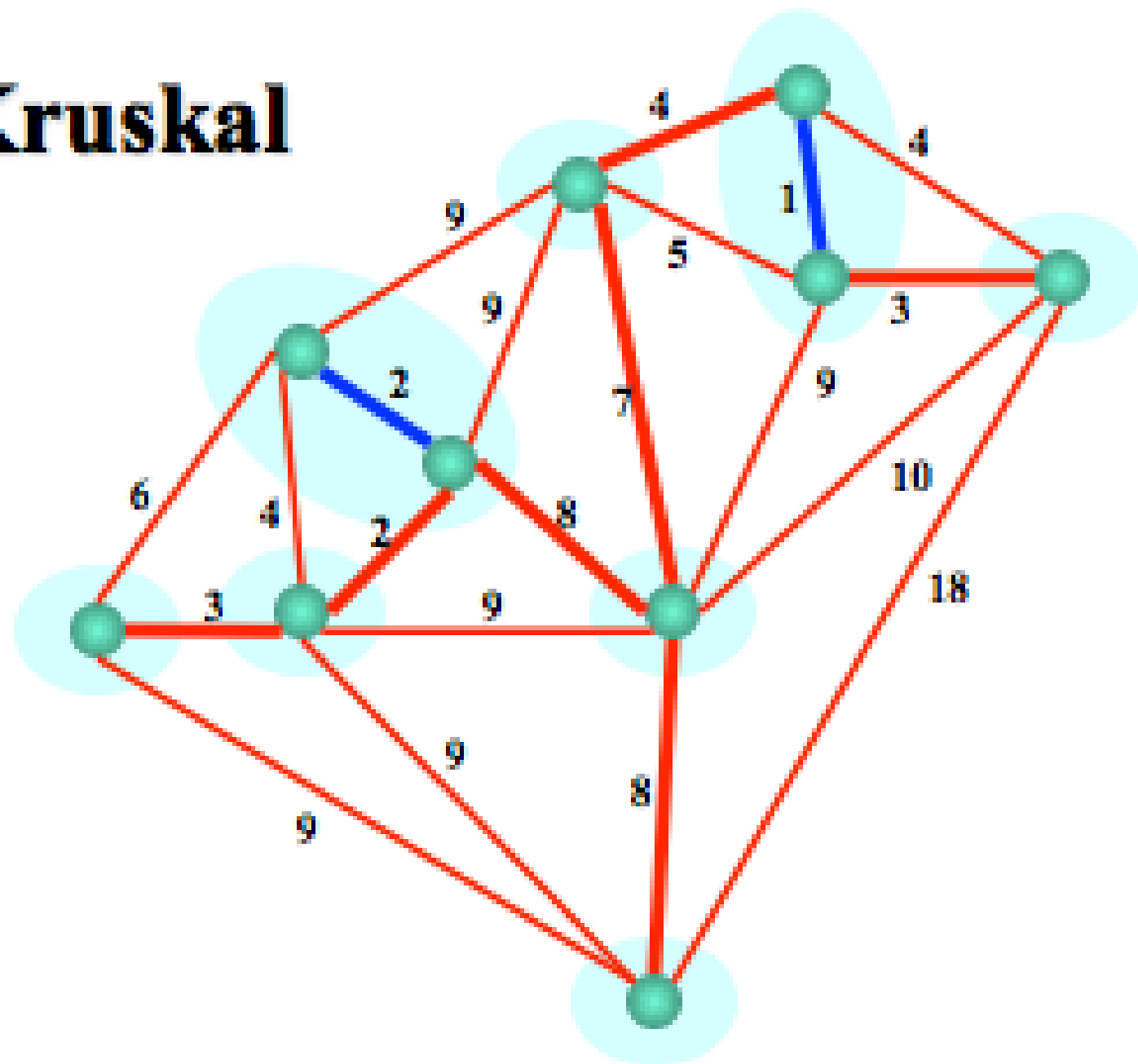
# Kruskal



Sorted edge weights

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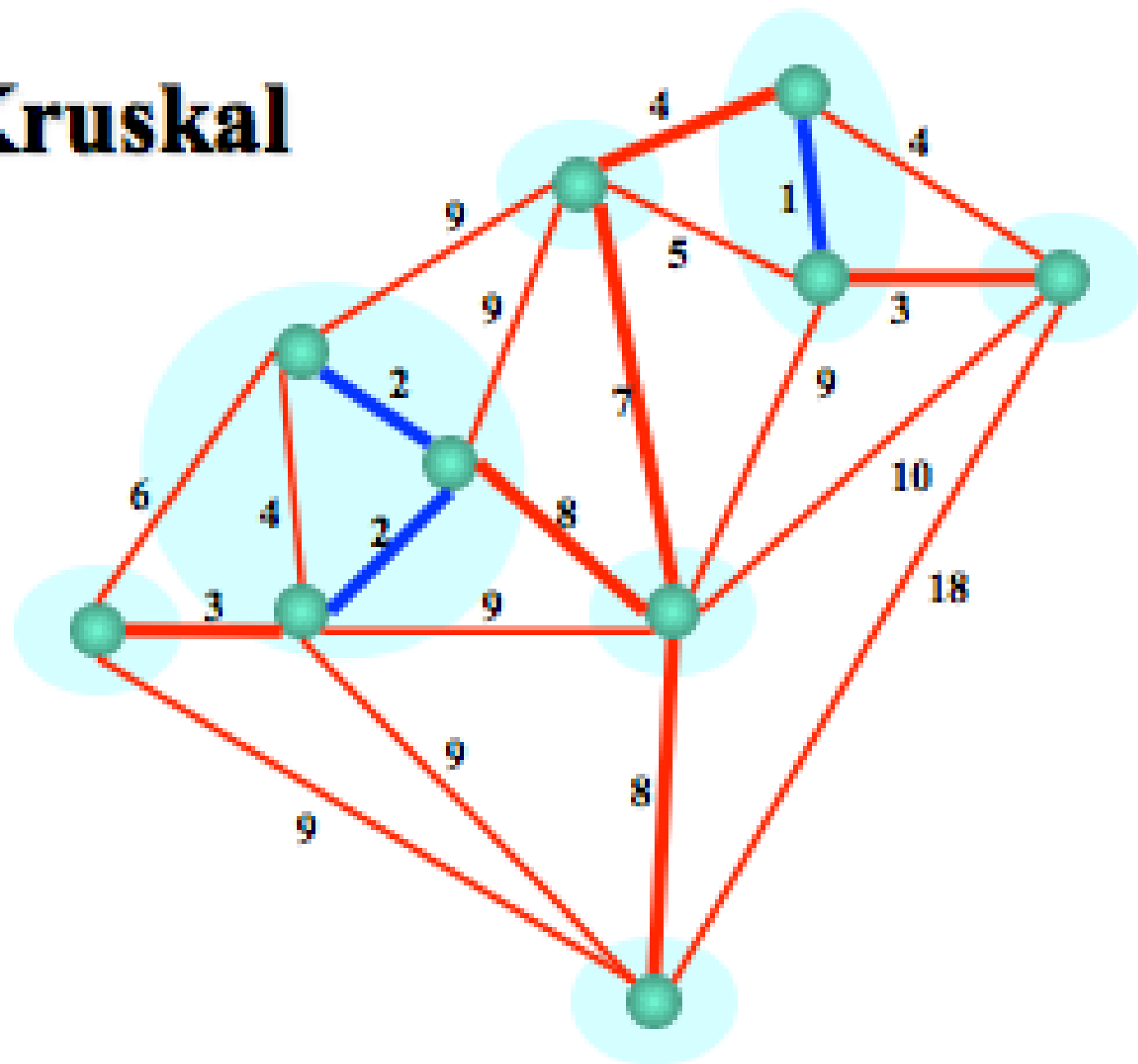
# Kruskal



Sorted edge weights

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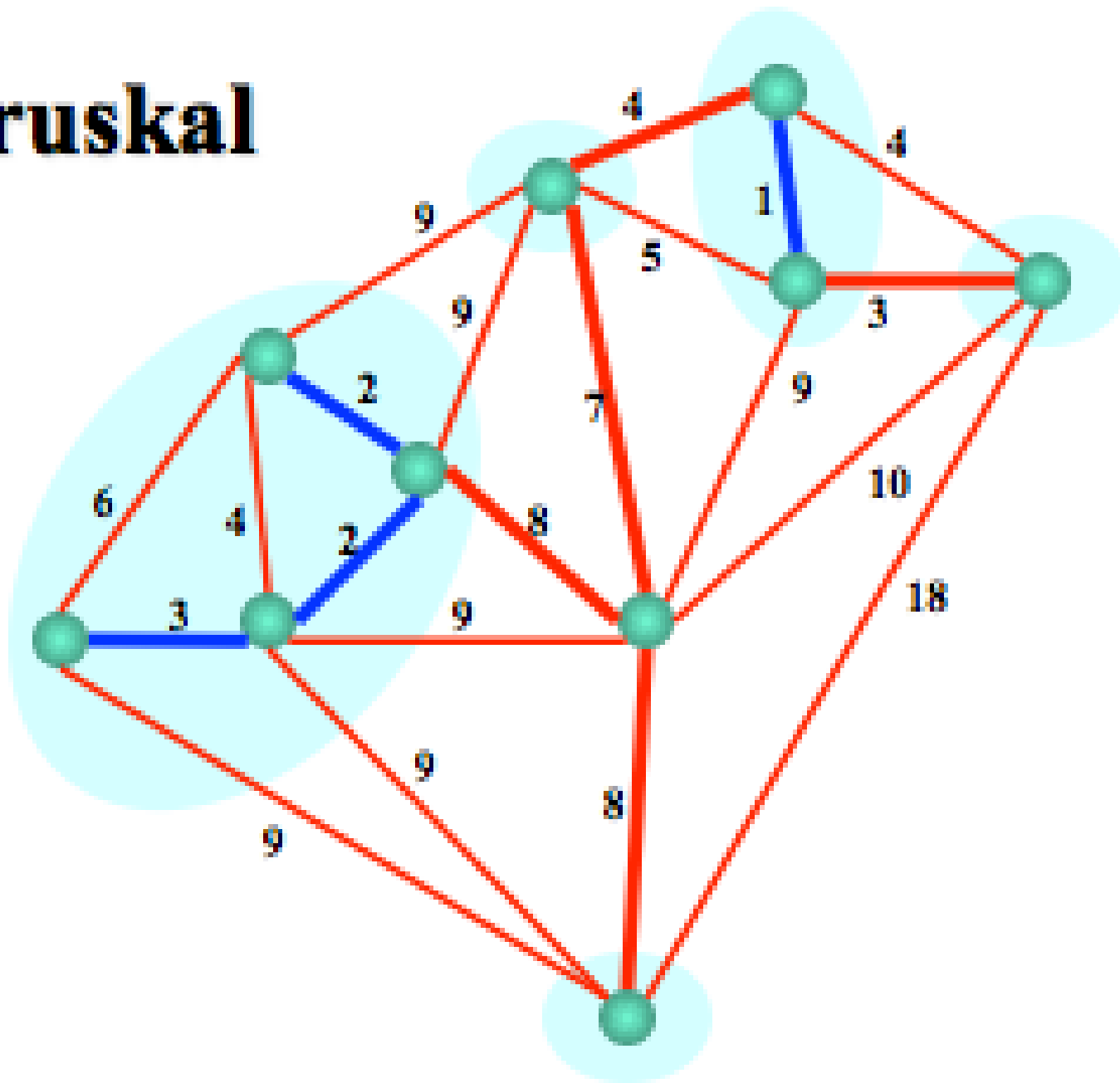
# Kruskal



Sorted edge weights

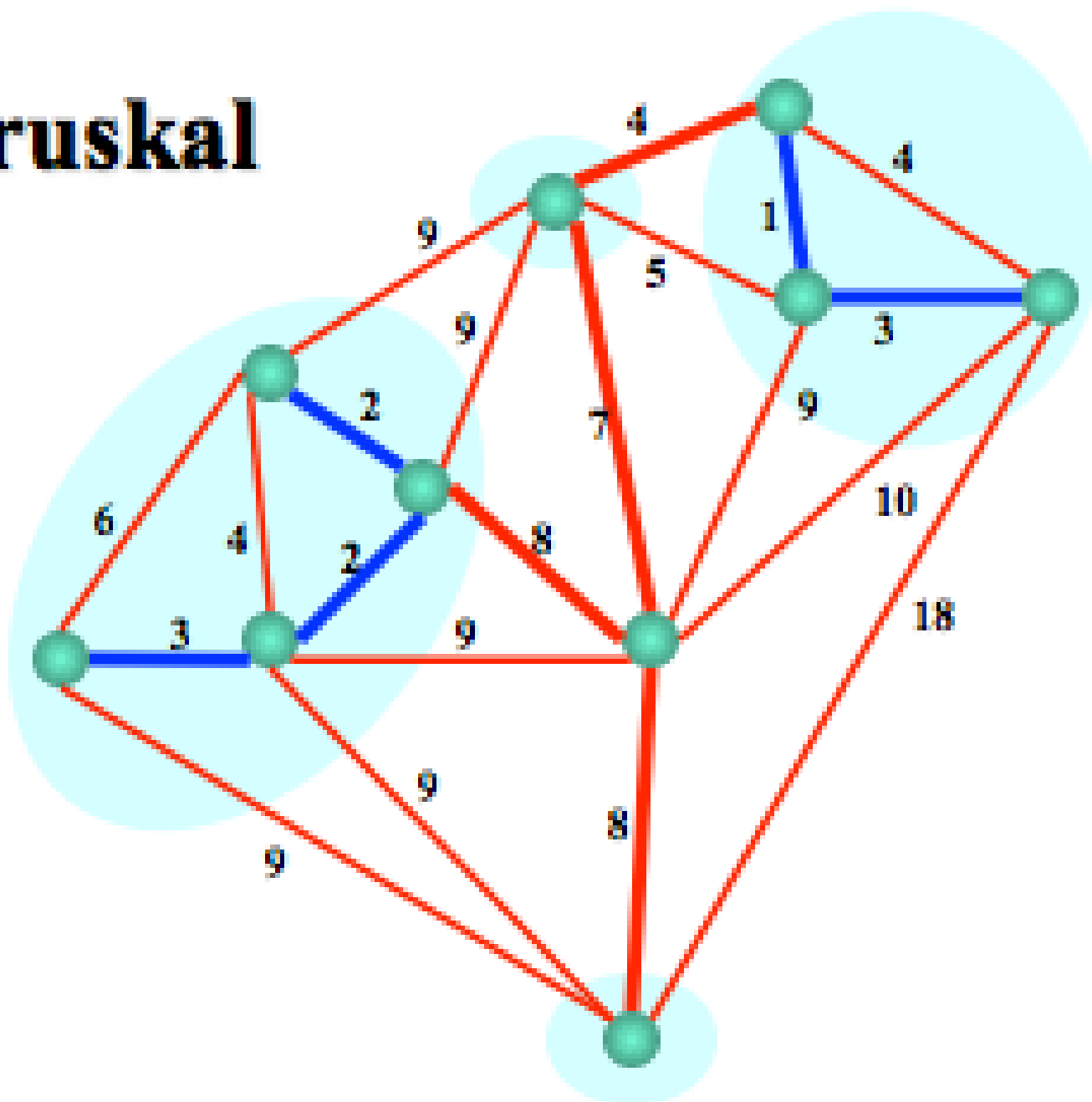
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# Kruskal



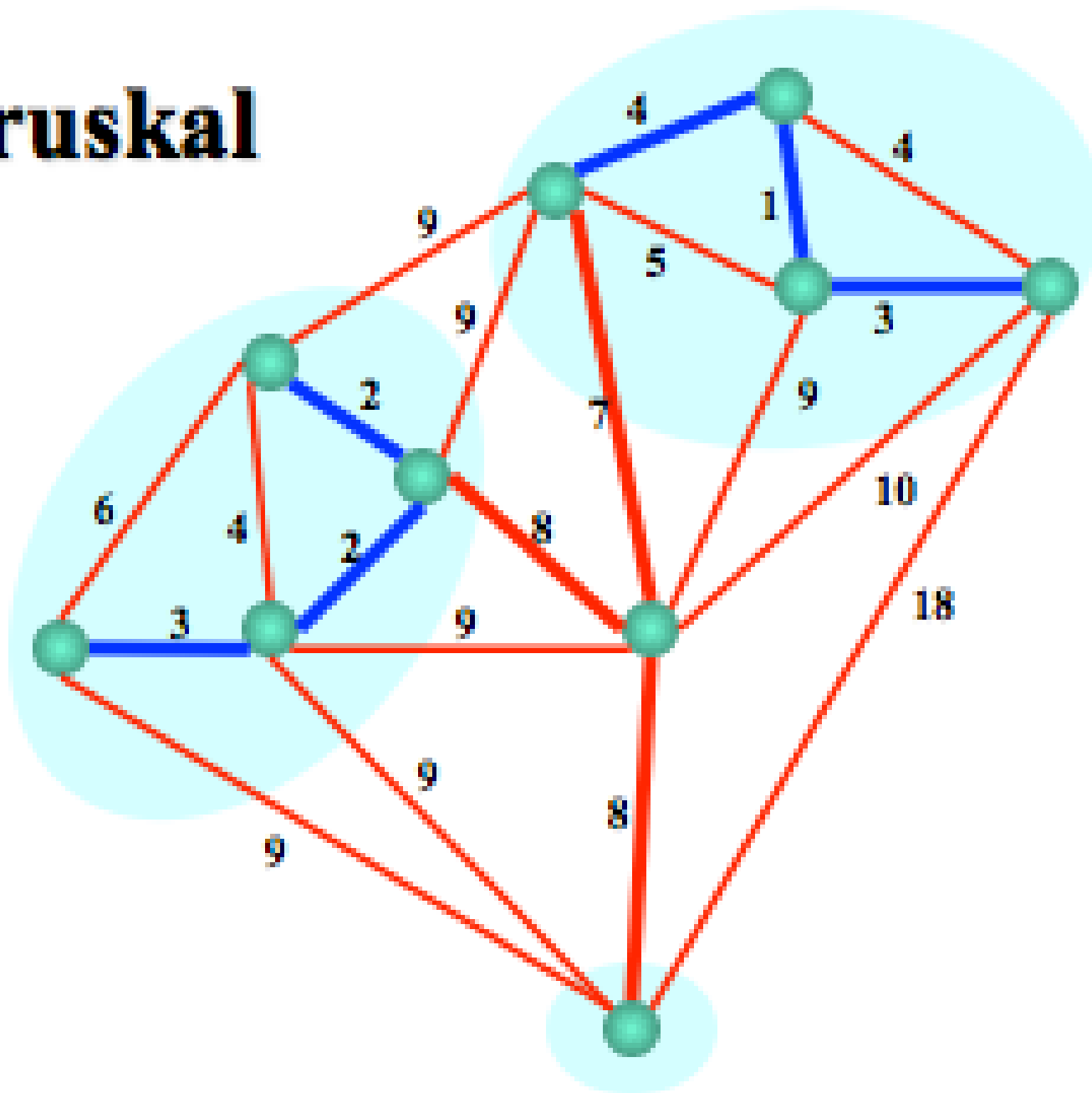
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# Kruskal



Sorted edge weights  
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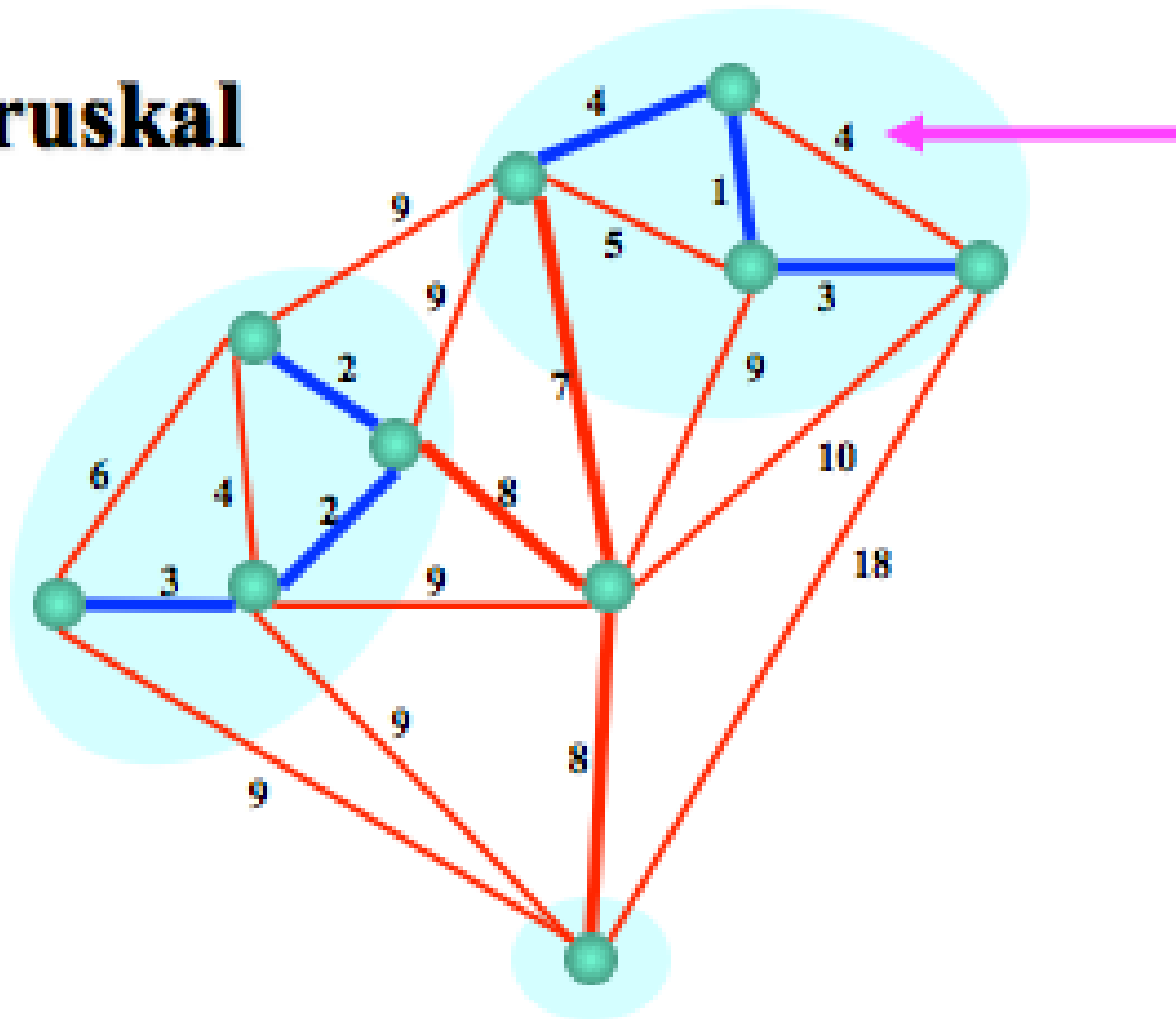
# Kruskal



Sorted edge weights

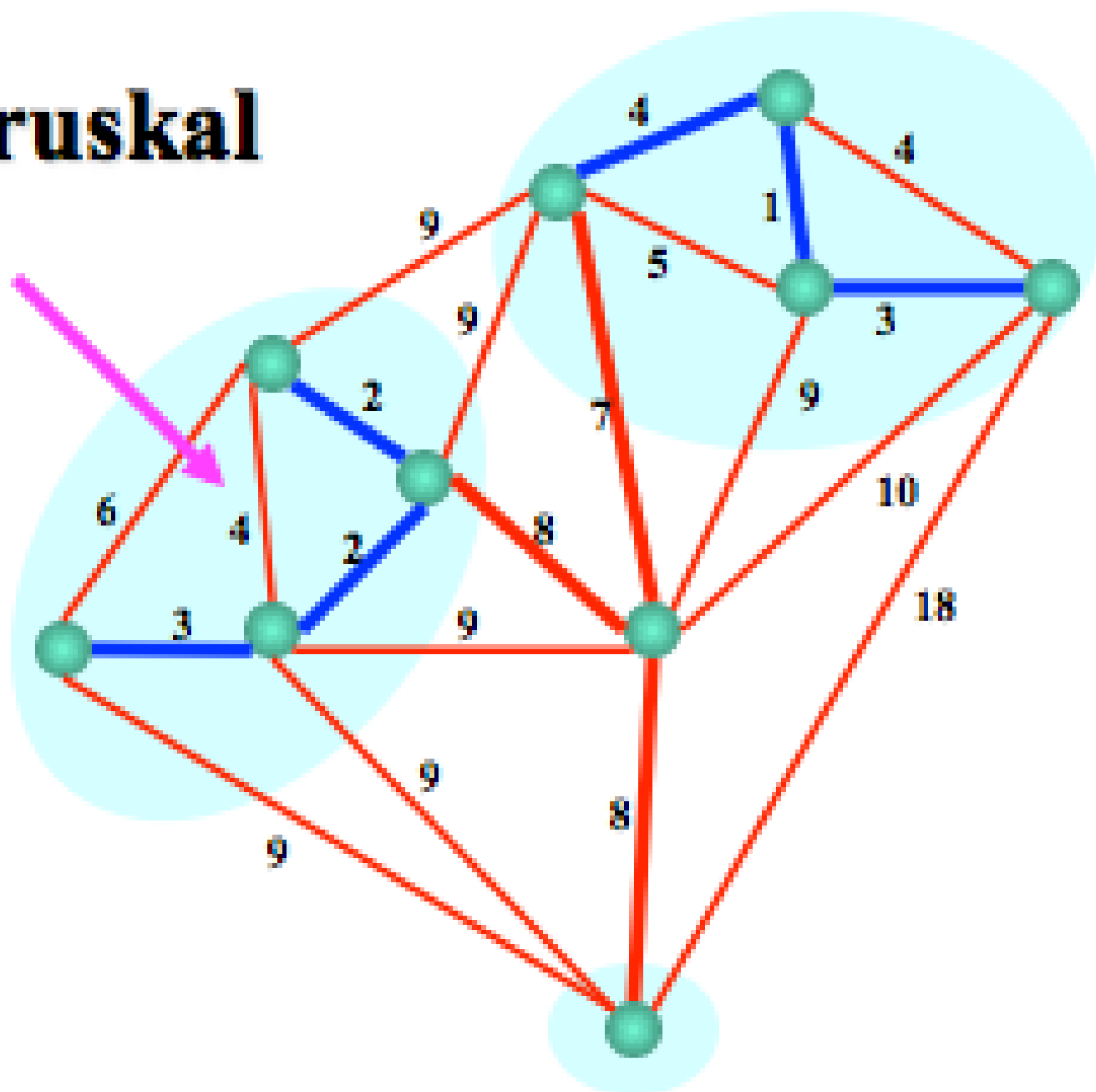
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# Kruskal



Sorted edge weights  
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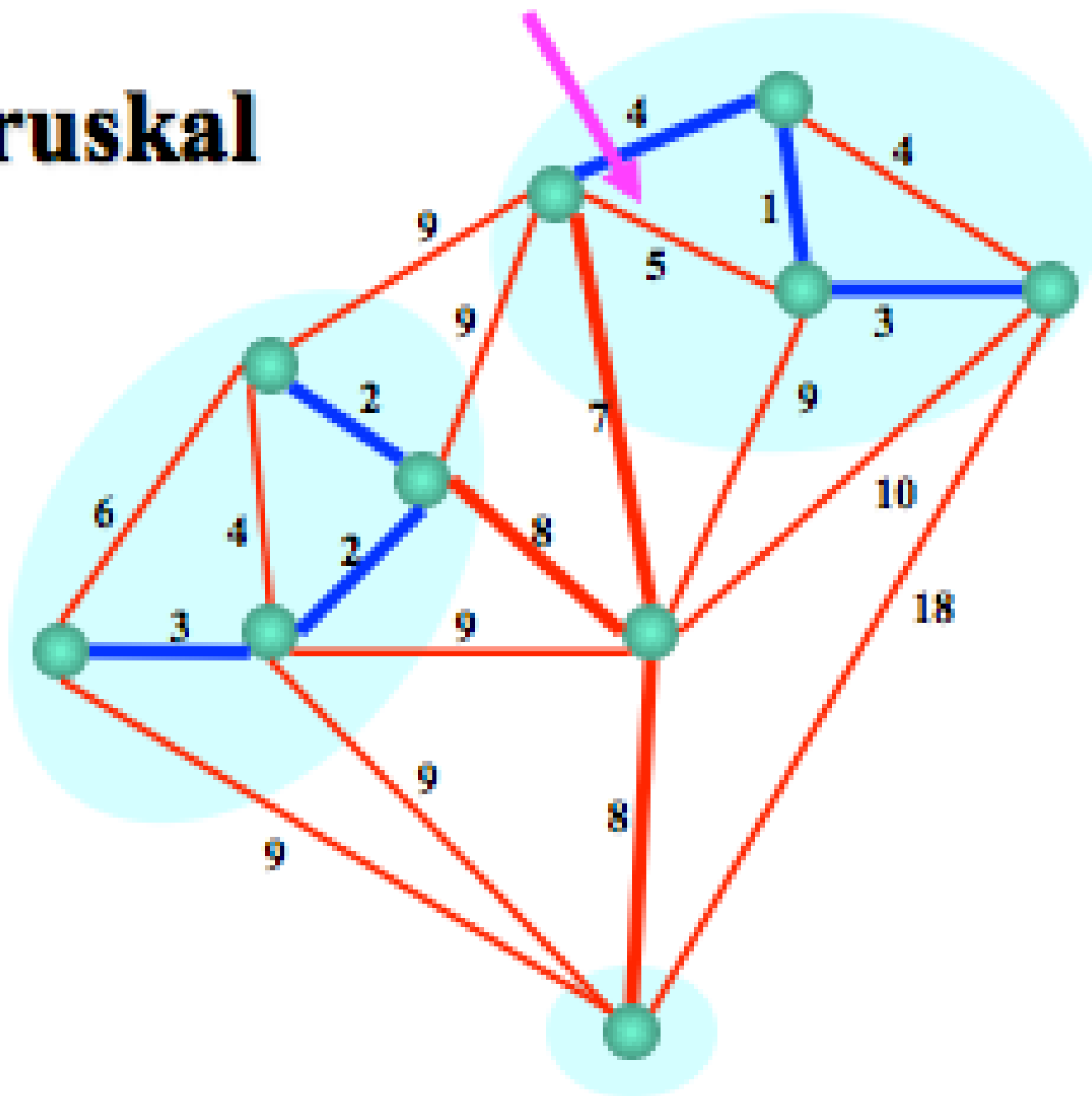
## Kruskal



Sorted edge weights



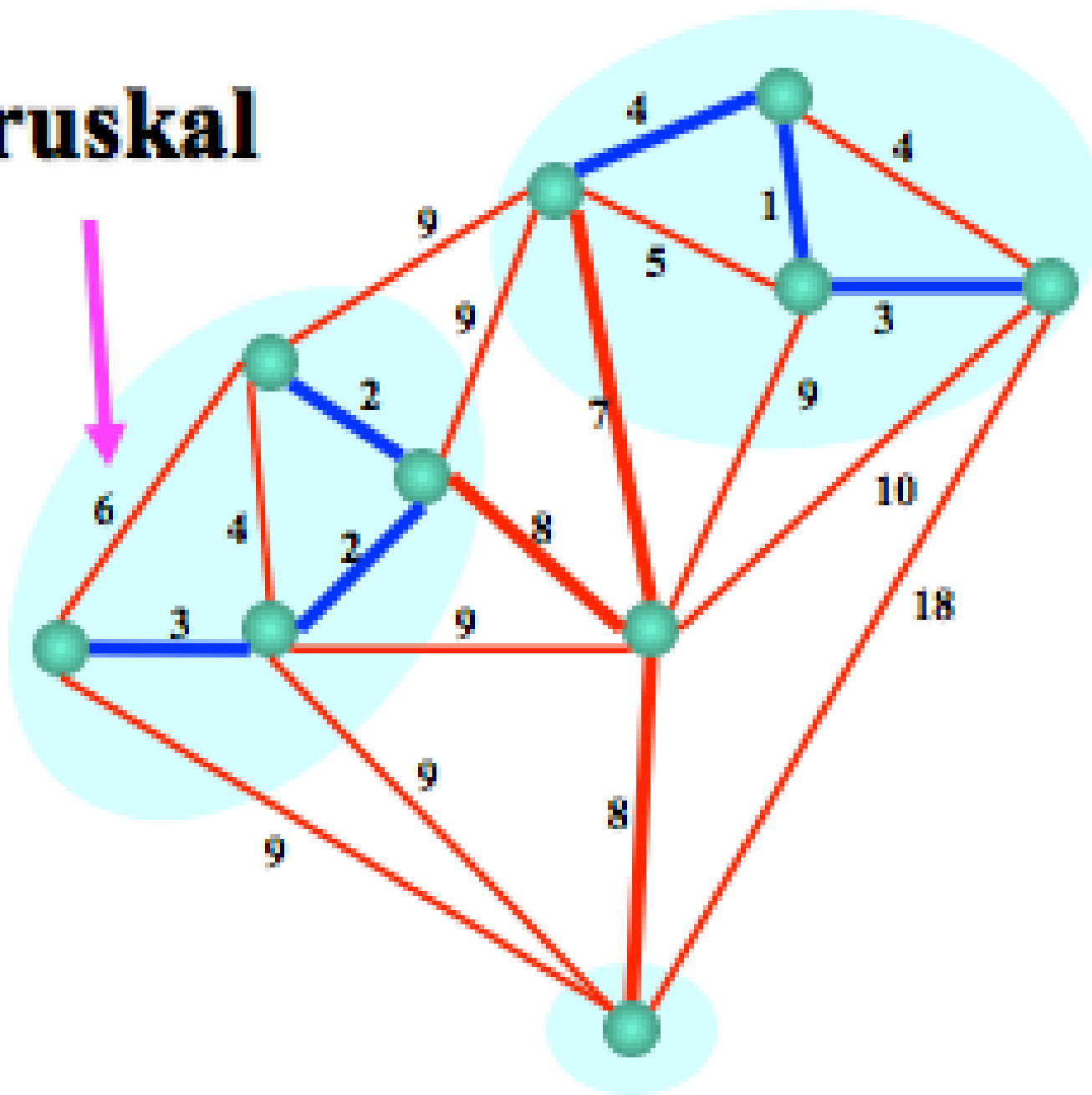
# Kruskal



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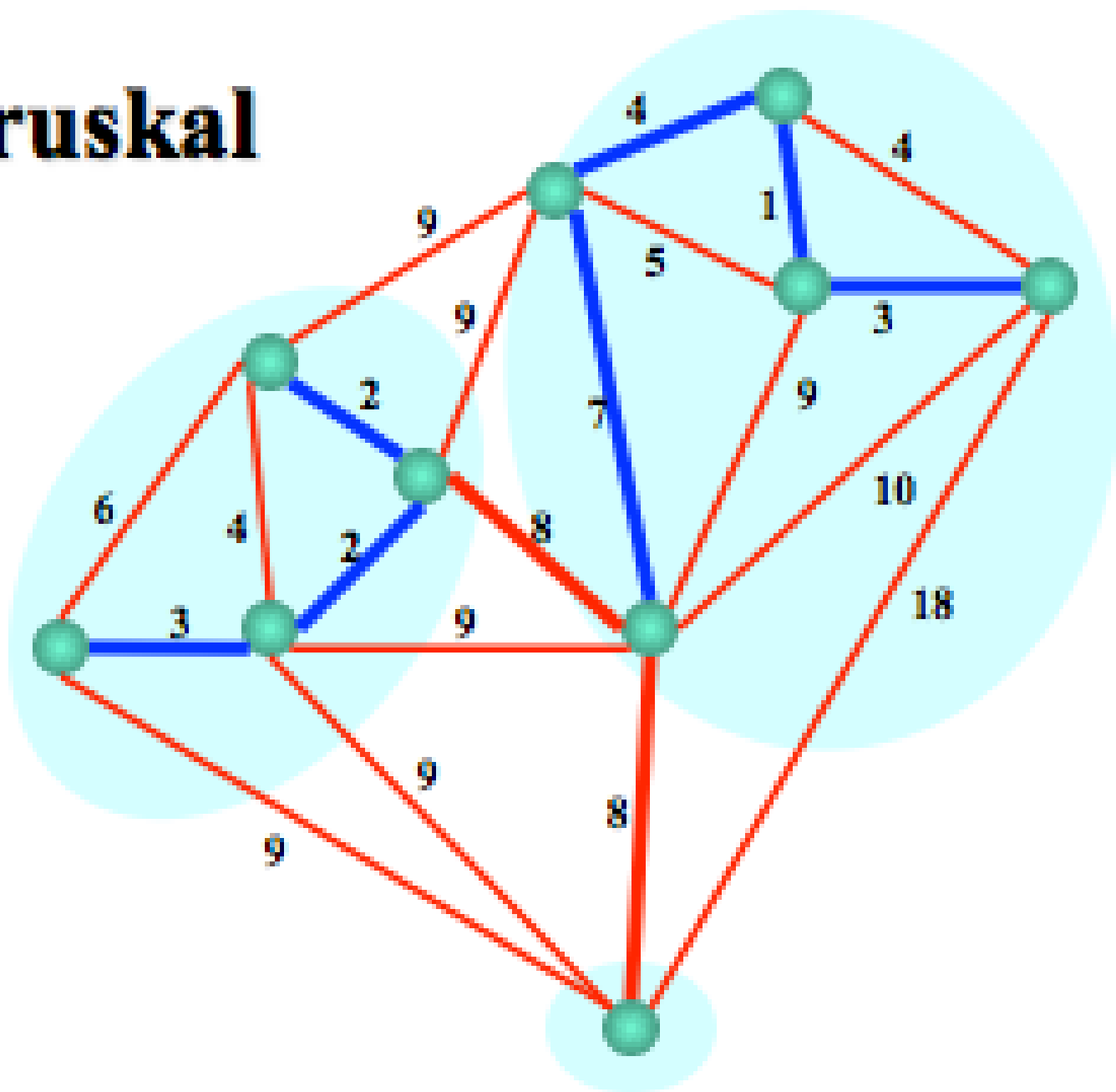
# Kruskal



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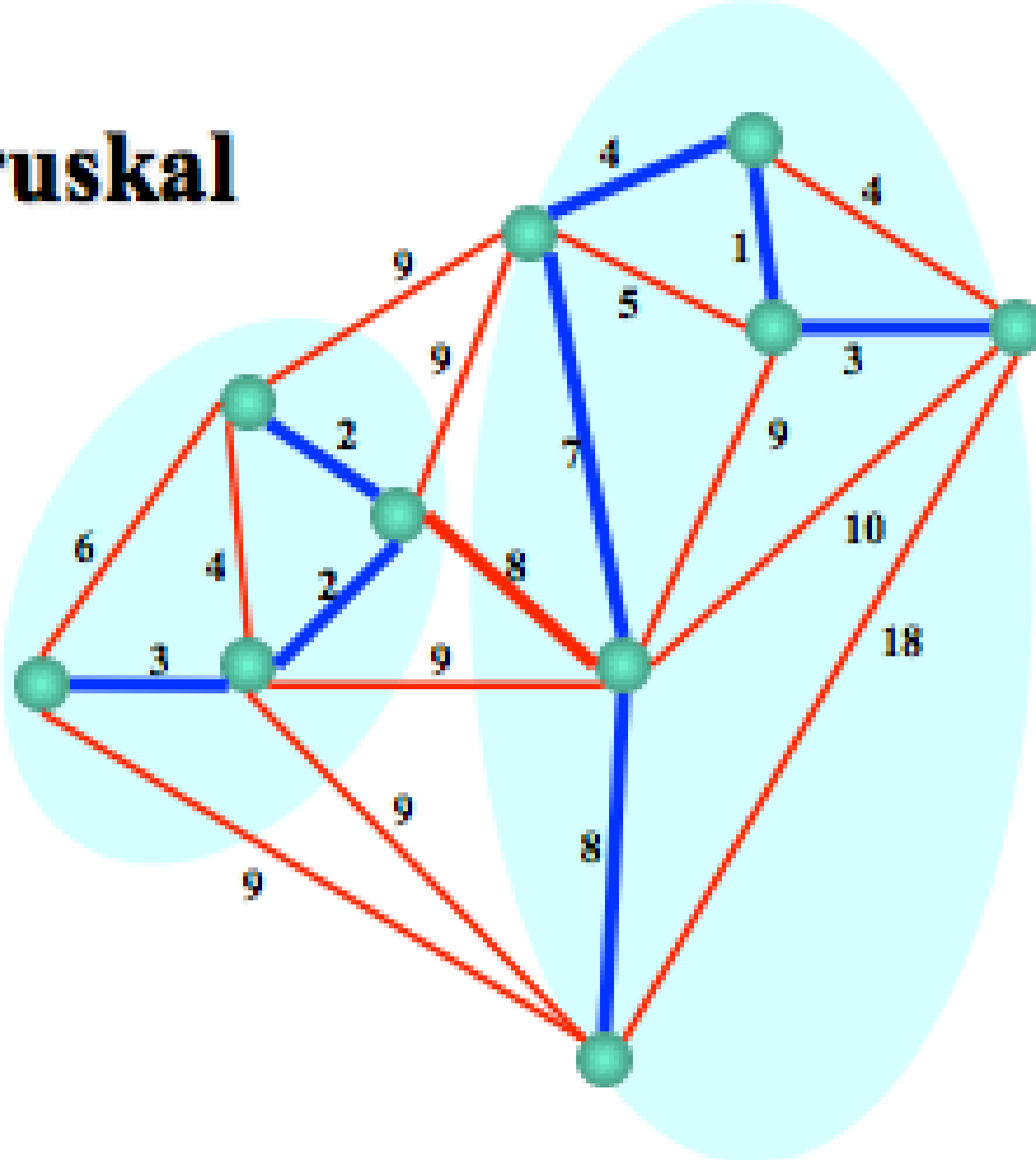
# Kruskal



Sorted edge weights

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# Kruskal



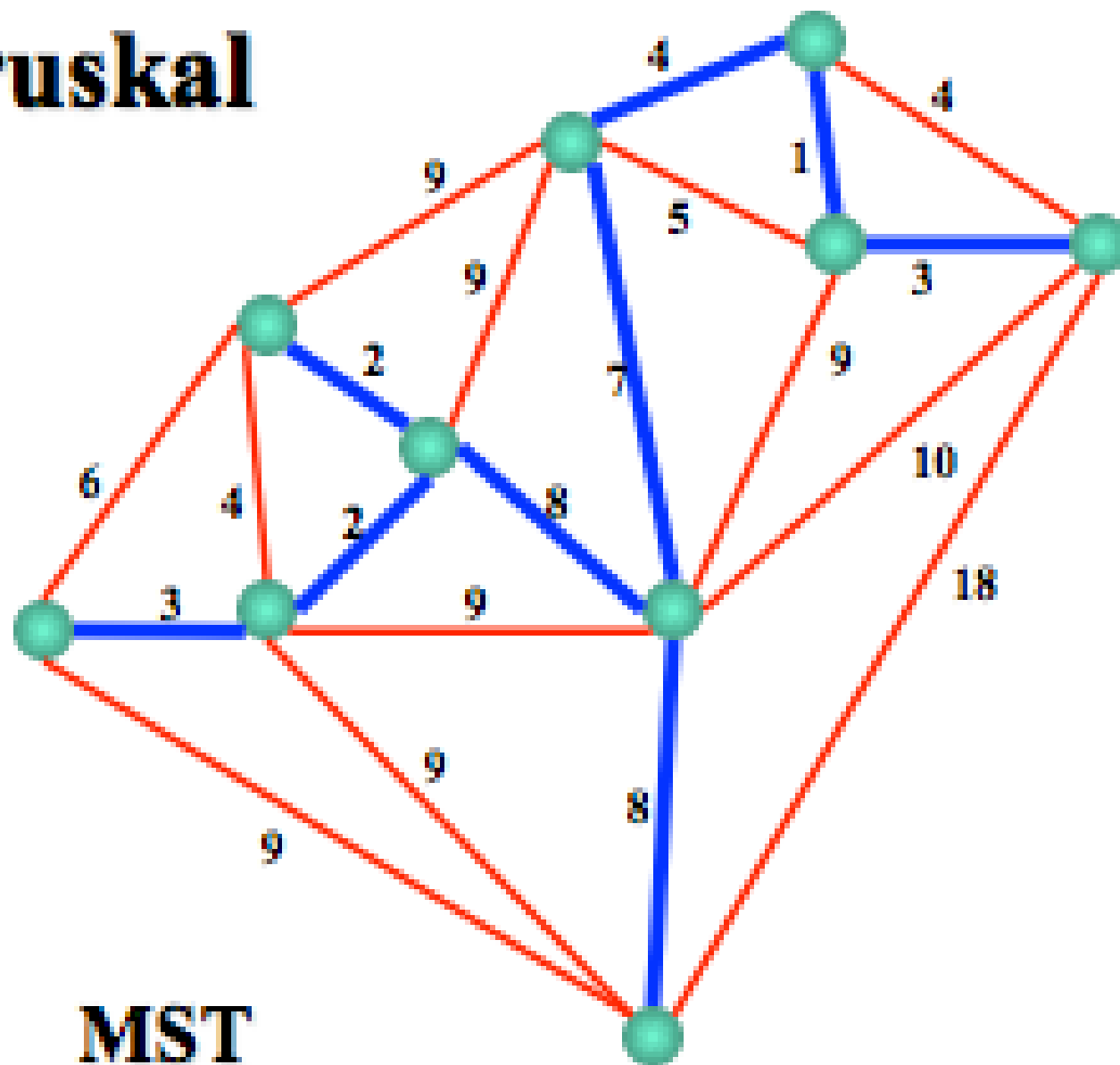
Sorted edge weights

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**uskaal**

Sorted edge weights

# Kruskal

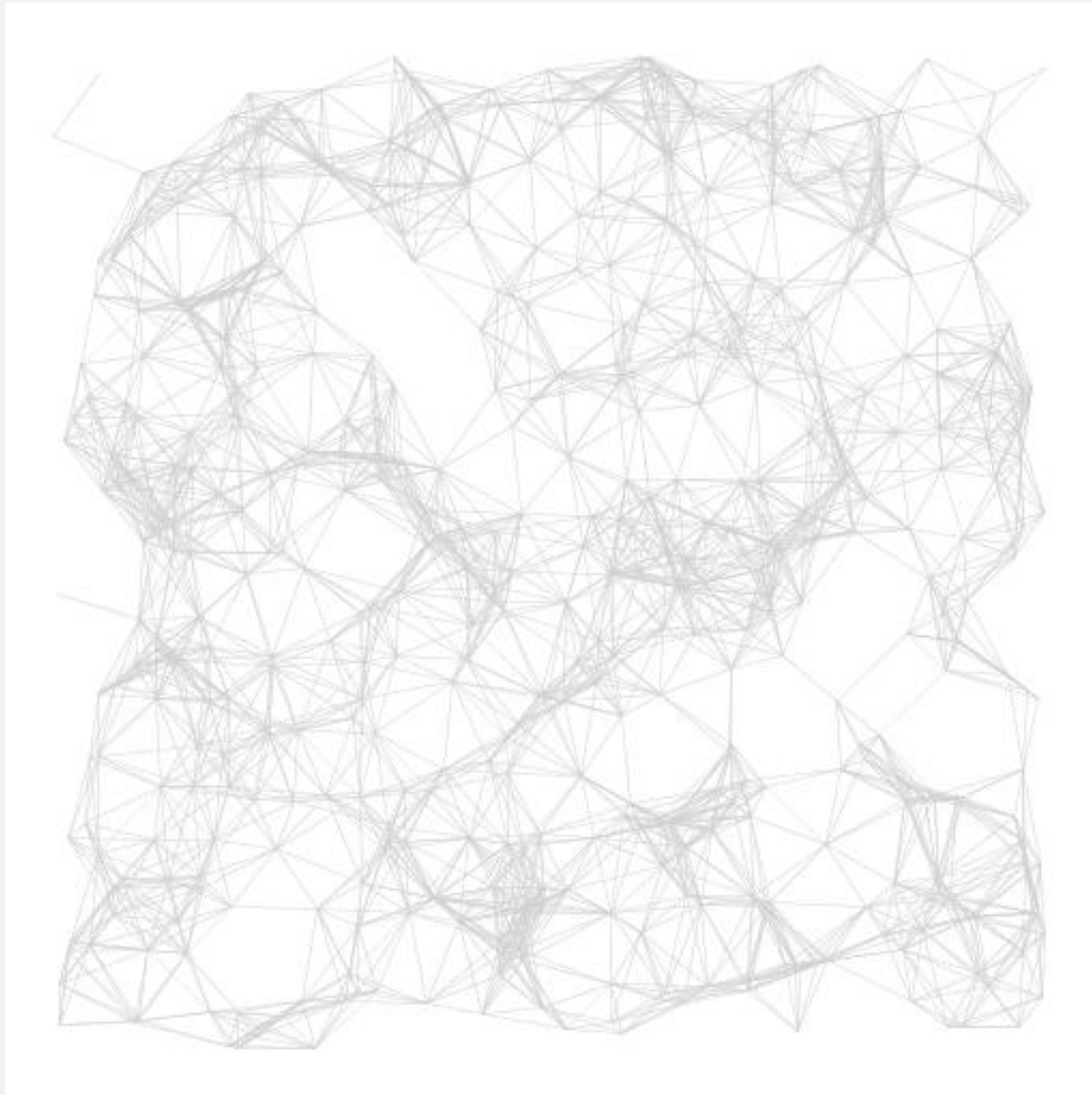


**MST**

Sorted edge weights  
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# Kruskal's algorithm: visualization

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# Kruskal's Algorithm

## Idea

- Initialize a forest consisting of all nodes
- Pick a (non-selected) minimum weight edge and, if it connects two different trees of the forest, select it, otherwise discard it; repeat
- *Example of greedy algorithm*

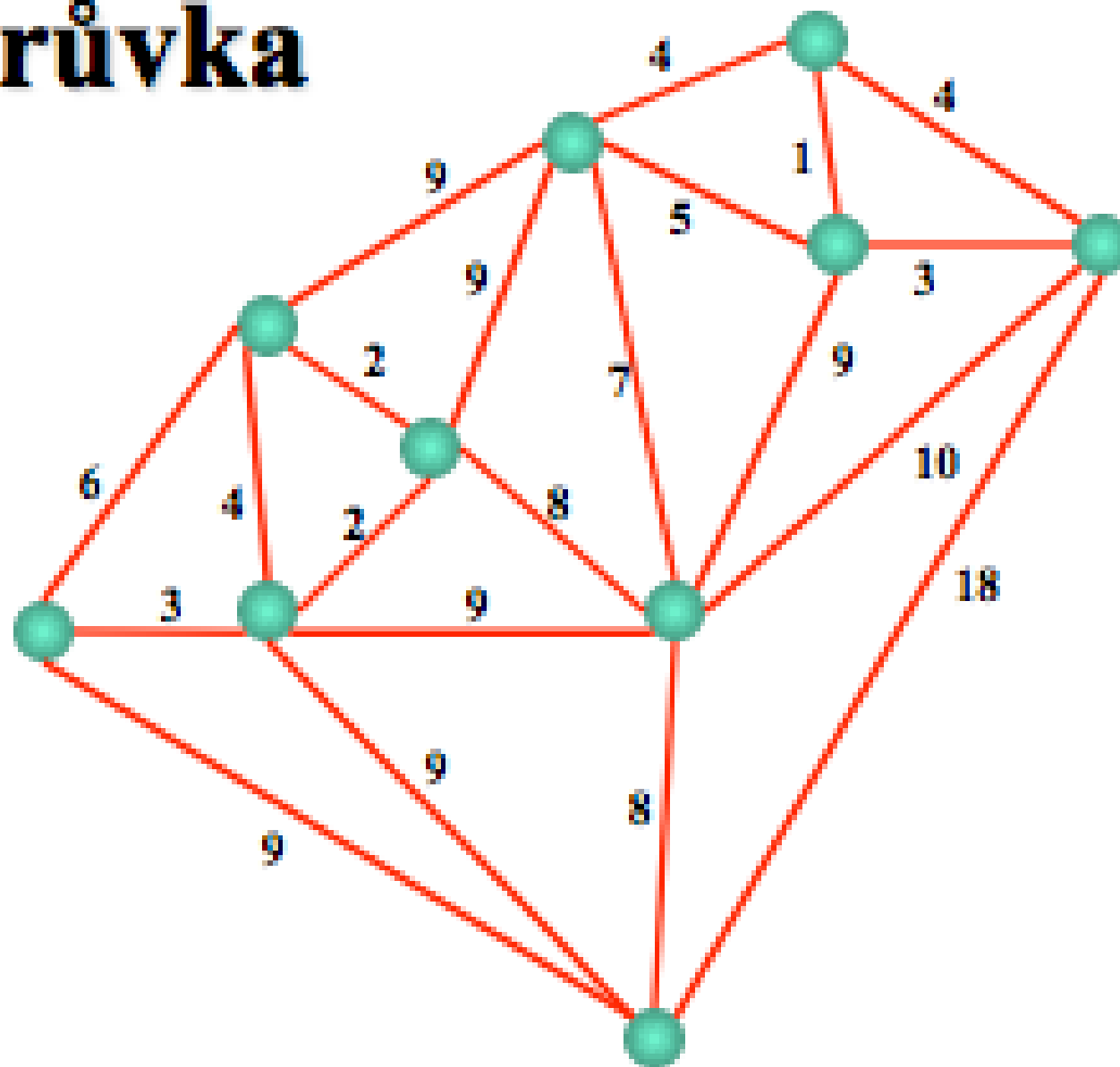


# Borůvka's Algorithm

## Idea

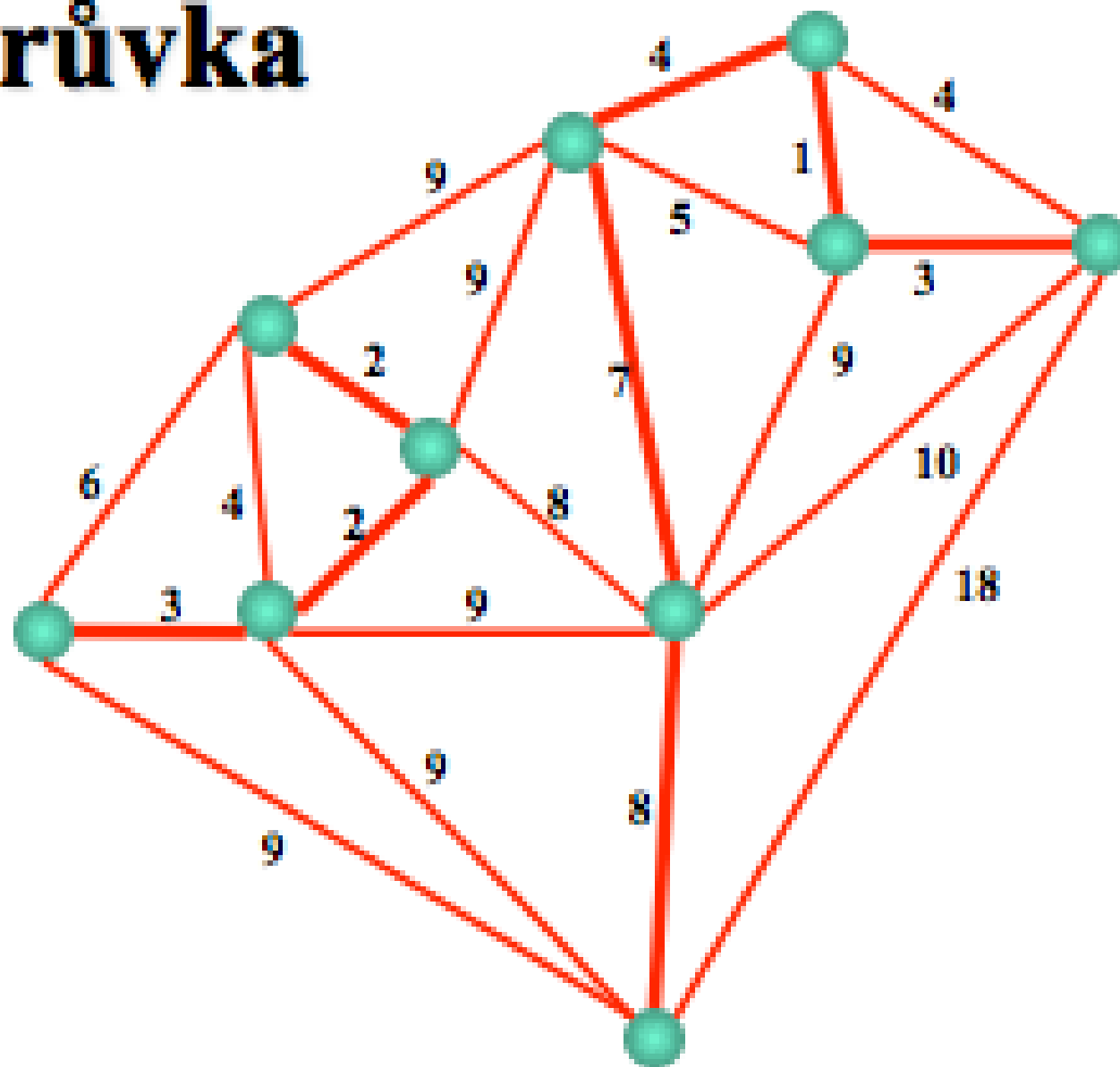
- Often assume every edge has a unique weight.
- Initially, each vertex is considered a separate component.
- The algorithm merges disjoint components as follows; repeating the step until only one component exists.
- In each step, every component is merged with some other using the cheapest outgoing edge of the given component.

# Borůvka

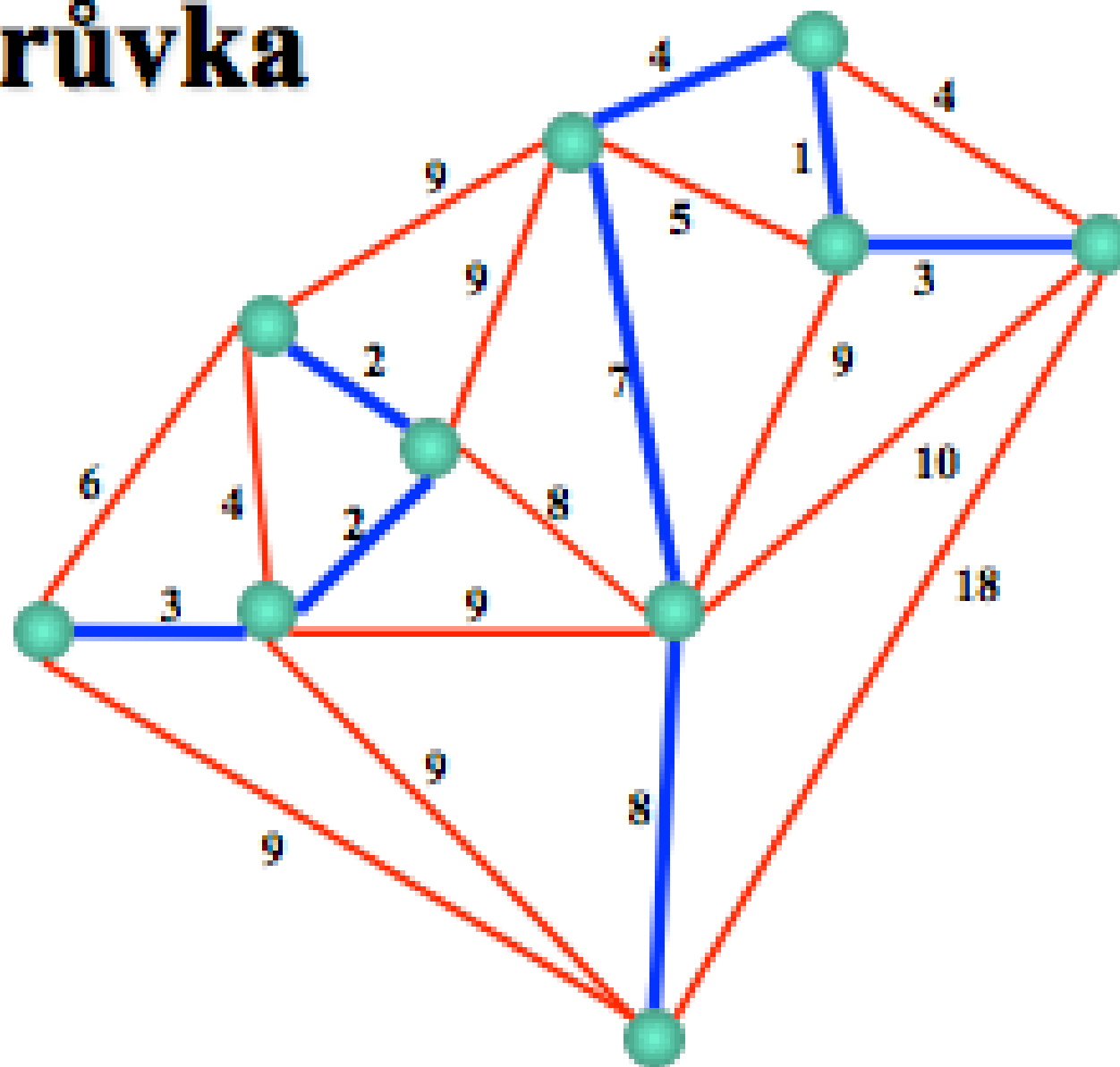


Every  
vertex is a  
tree

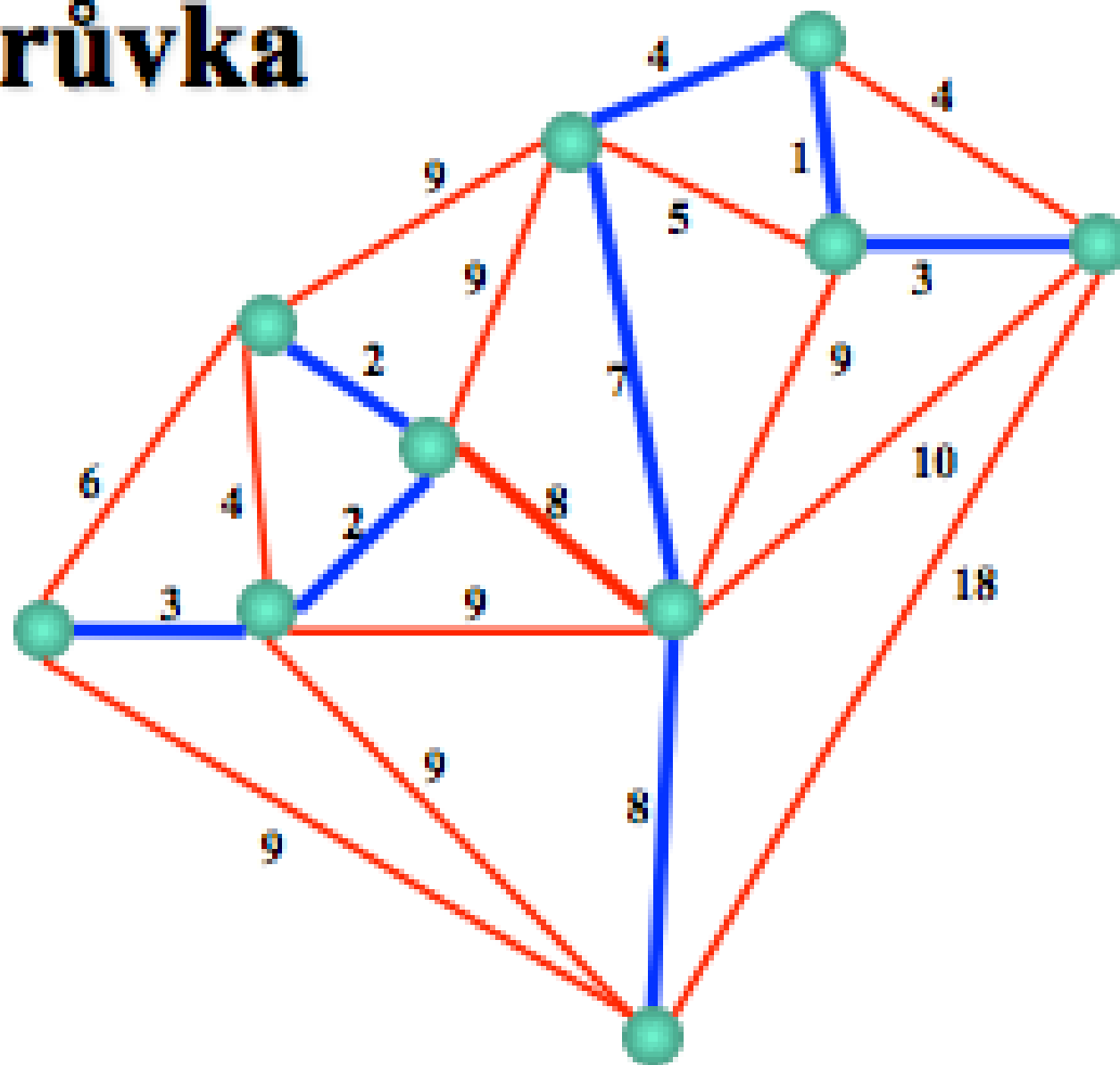
# Borůvka



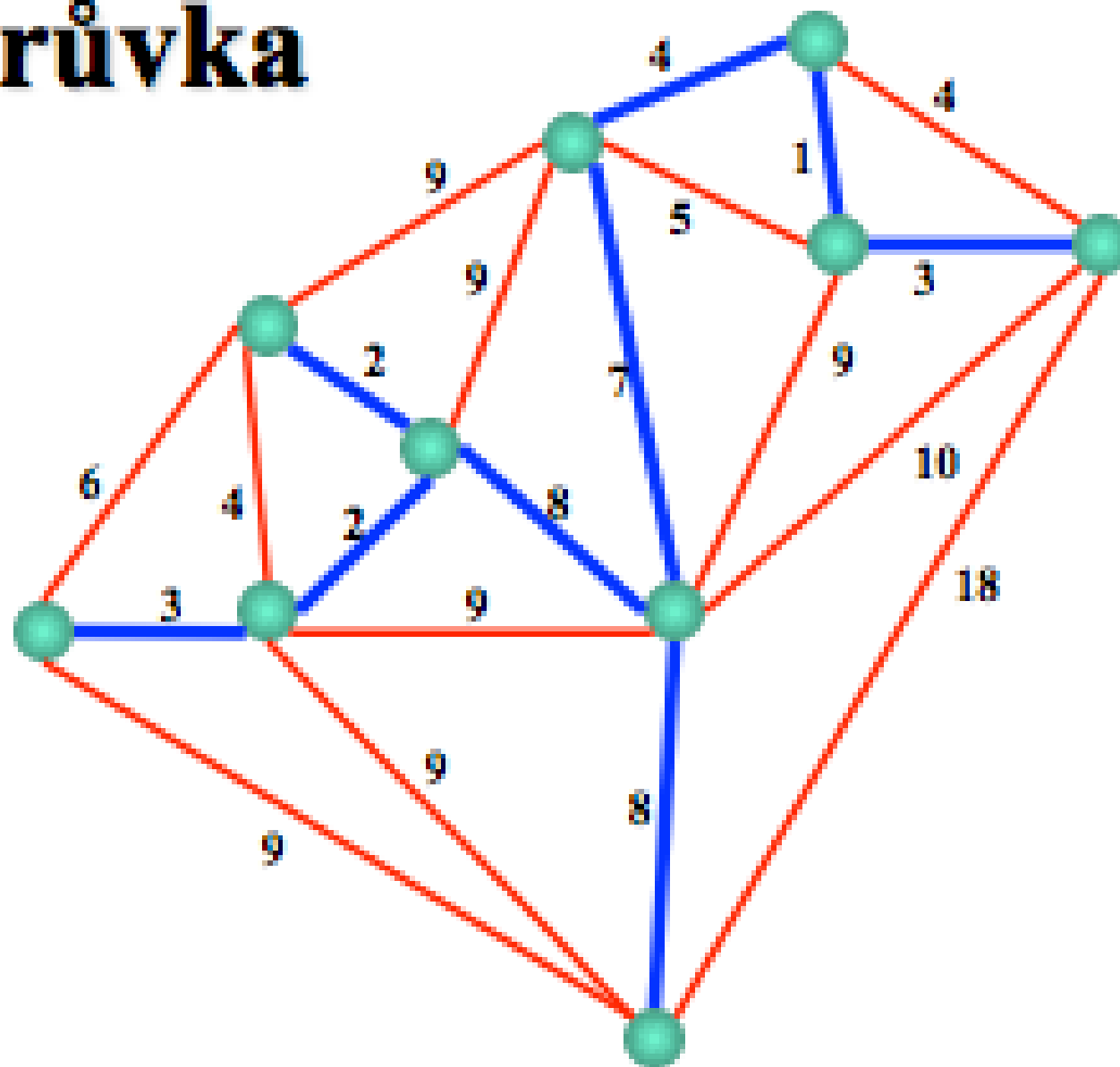
# Borůvka



# Borůvka



# Borůvka



# Borůvka's Algorithm

## Idea

- Initially, each vertex is considered a separate component.
- The algorithm merges disjoint components as follows; repeating the step until only one component exists.
- In each step, every component is merged with some other using the cheapest outgoing edge of the given component.

# To come

- Why do these algorithm ideas work (and produce correct MSTs)?
- How do we implement these algorithms efficiently?  
What are good data structures?