

Potential Energy

- Recall: A force is conservative if the work done by the force does not depend on path chosen

- Recall: Work-Energy theorem

$$\Delta KE = W_{\text{net}}$$

↓
add up all forces

$$\Delta KE = W_{\text{cons}} + W_{\text{nc}}$$

$$\Delta KE + (-W_{\text{cons}}) = W_{\text{nc}}$$

IS ~~W~~ no non-cons. forces then

$$\Delta KE + (-W_{\text{cons}}) = 0$$

⏟
call it
 ΔPE

$$\Delta KE + \Delta PE = 0$$

$$KE_f - KE_i + PE_f - PE_i = 0$$

$$KE_f + PE_f = KE_i + PE_i$$

Note: Since ΔPE doesn't depend on path it only ~~it~~ depends on position $PE(\vec{r})$

PE is a function of object's location

Potential Energy - I

A mass 5 kg moves from 1 m above the Earth's surface to 7 m above the Earth's surface?

- How much work did gravity do on the mass?
- What is the change in gravitational potential energy of the mass?

$$-\Delta PE = W_c$$

$$-\Delta PE_g = W_g$$

$$\vec{F}_g = -mg\hat{k}$$

$$\begin{aligned}\Delta \vec{r} &= (x_f\hat{i} + z_f\hat{k}) - (x_i\hat{i} + z_i\hat{k}) \\ &= (x_f - x_i)\hat{i} + (z_f - z_i)\hat{k}\end{aligned}$$

$$\begin{aligned}W_g &= \vec{F}_g \cdot \Delta \vec{r} \\ &= (-mg\hat{k}) \cdot [(x_f - x_i)\hat{i} + (z_f - z_i)\hat{k}]\end{aligned}$$

$$= -mg(z_f - z_i)$$

$$W_g = -29.4\text{ J}$$

$$\begin{aligned}\Delta PE_g &= -W_g = -(-mg(z_f - z_i)) \\ &= mg(z_f - z_i)\end{aligned}$$

$$\Delta PE_g = 29.4\text{ J}$$

Last Example:

Found

$$x_i \hat{i} + z_i \hat{k} \quad \rightarrow \quad x_f \hat{i} + z_f \hat{k}$$

$$\Delta PE = mg(z_f - z_i)$$

Potential Energy is a function of position

$$x \hat{i} + y \hat{j} + z \hat{k} \quad \rightarrow \quad \vec{r}$$

$$\Delta PE = mg(z - z_i)$$

going from \vec{r}_i to \vec{r}

fixed by "where started"
but essentially
arbitrary

$$PE(\vec{r}) = mgz + C$$

analogous
to a definite
integral

$$\int x^n dx = \frac{1}{n+1} x^{n+1} + C$$

analogous to
indefinite integral

PE is defined up to an arbitrary constant



$$\Delta PE \approx 1000J$$

Useful Fact:

$$\vec{F}_c = -\nabla PE(\vec{r})$$

$$\left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right)$$

"Partial Derivative"
take derivative
by z but
pretend all
other variables
(x, y) constant

$$PE(\vec{r}) = mgz + C$$

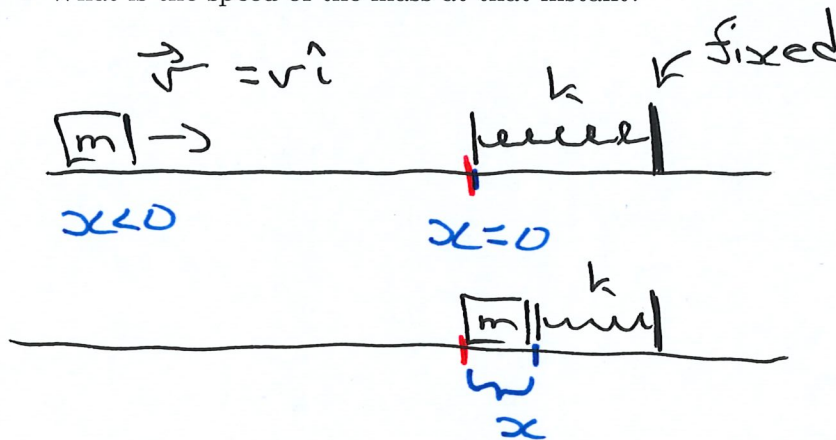
$$\begin{aligned} \vec{F}_g &= -\nabla PE(\vec{r}) \\ &= -\left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (mgz + C) \\ &= -(\hat{i} 0 + \hat{j} 0 + \hat{k} mg) \\ &= -mg\hat{k} \end{aligned}$$

Potential energy - II

A 2kg mass slides at $5\frac{\text{m}}{\text{s}}$ on a horizontal frictionless surface. It collides with an ideal spring with spring constant $500\frac{\text{N}}{\text{m}}$. It contacts the end of the spring and begins to compress it.

When the spring has been compressed by 0.2m ,

- How much work has the spring done?
- What is the change in the potential energy stored in the spring?
- What is the change in the mass's kinetic energy?
- What is the speed of the mass at that instant?



$$\Delta PE = -W_c$$

$$\Delta PE_s = -W_s$$

force by spring change

$$W_s = \int \vec{F}_s \cdot d\vec{r}$$

Parametrize the path

$$\vec{r}(s) = x \hat{i}$$

$$\begin{array}{c} 0m \\ \downarrow \\ x_i \leq s \leq x_f \end{array} \quad \begin{array}{c} 0.2m \\ \downarrow \end{array}$$

$$\text{Find } d\vec{r} = \left(\frac{d\vec{r}(s)}{ds} \right) ds$$

$$= (1 \hat{i}) ds$$

$$= ds \hat{i}$$

$$\text{Find } \vec{F}_s(s)$$

$$|\vec{F}_s| = k |\Delta \vec{r}|$$

500 N/m

spring
compressed
by s

direction opposite
a restoring force

$$\vec{F}_s = -k s \hat{i}$$

$$\text{Find } \vec{F} \cdot d\vec{r} = (-k s \hat{i}) \cdot (ds \hat{i})$$

$$= (-k s)(ds)$$

$$= -k s ds$$

$$W_s = \int_{x_i}^{x_f} (-k s ds) = -k \int_{x_i}^{x_f} s ds$$

$$= -k \left(\frac{x_f^2}{2} - \frac{x_i^2}{2} \right)$$

$$\begin{array}{l} \int_a^b x dx \\ = \frac{x^2}{2} \Big|_a^b \\ = \frac{b^2}{2} - \frac{a^2}{2} \end{array}$$

$$\text{Put in #'s} = -10J$$

What is ΔPE_s ?

$$\Delta PE_s = -W_s \rightarrow 10J$$

$$\Delta PE_s = PE_s - PE_i = -\left(-k\left(\frac{x_s^2}{2} - \frac{x_i^2}{2}\right)\right)$$

$$PE_s - PE_i = \frac{kx_s^2}{2} - \frac{kx_i^2}{2} + C(-C)$$

$$PE_s = \frac{kx_s^2}{2} + C$$

$$PE_i = \frac{kx_i^2}{2} + C$$

$$PE_s = \frac{k}{2} (\Delta l)^2 + C$$

Often pick $C=0$ so $PE=0$ at unstretched length

$$\begin{aligned}\Delta KE &= W_{\text{net}} = W_c + \cancel{W_{nc}} \\ &= -\Delta PE \\ &= -10J\end{aligned}$$

0 b/c frictionless

$$KE_s - KE_i = -10J$$

$$KE_s - \frac{1}{2} 2\text{kg} (5\text{m/s})^2 = -10J$$

$$KE_s = 15J$$

$$\frac{1}{2} (2\text{kg}) |\vec{v}_s|^2 = 15J \Rightarrow |\vec{v}_s| = 3.9\text{m/s}$$